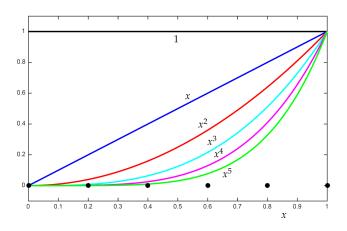
# Interpolation

Marcin Kuta

### Ill-conditioned base of monomials



### Lagrange interpolation

$$\ell_j(t) = \frac{\prod_{k=1, k \neq j}^n (t - t_k)}{\prod_{k=1, k \neq j}^n (t_i - t_k)} \quad j = 1, \dots, n$$
 (1)

$$\ell_j(t_i) = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}, \quad i, j = 1, \dots, n$$
 (2)

$$p_{n-1}(t) = y_1 \ell_1(t) + y_2 \ell_2(t) + \dots + y_n \ell_n(t)$$
 (3)

### Newton interpolation

$$\pi_j(t) = \prod_{k=1}^{j-1} (t - t_k) \quad j = 1, \dots, n$$
 (4)

$$\pi_j(t_i) = 0 \quad \text{for } i < j \tag{5}$$

$$p_{n-1}(t) = x_1 \pi_1(t) + x_2 \pi_2(t) + \dots + x_n \pi_n(t)$$

$$= x_1 + x_2(t - t_1) + x_3(t - t_1)(t - t_2) + \dots$$

$$+ x_n(t - t_1)(t - t_2) \dots (t - t_{n-1})$$
(6)

$$p_{n-1}(t) = f[t_1]\pi_1(t) + f[t_1, t_2]\pi_2(t) + \cdots + f[t_1, t_2, \dots, t_n]\pi_n(t)$$

## Evaluation of polynomial

Evaluation of polynomial p(t) of degree n

Base	number of multiplications
monomials	n(n+1)/2 (naive approach)
	n (Horner's scheme)
Lagrange polynomials	2n(n+1)
Newton polynomials	n(n+1)/2 (naive approach)
	2n-1

### Vandermonde matrix

Points:  $x_1, \ldots, x_n$ 

#### Vandermonde matrix:

$$\begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \cdots & x_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \cdots & x_n^{n-1} \end{bmatrix}$$

#### Vandermonde matrix

Data points:  $(x_1, y_1) \dots, (x_n, y_n)$ 

In the monomial basis, coefficient  $a_1, \ldots, a_n$  of polynomial interpolating points  $(x_1, y_1), \ldots, (x_n, y_n)$  can be found from equation:

$$\begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \cdots & x_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \cdots & x_n^{n-1} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

#### Vandermonde matrix

Data points:  $(x_1, y_1) \dots, (x_n, y_n)$ 

In the basis  $\phi_1(x), \ldots, \phi_n(x)$ , coefficient  $a_1, \ldots, a_n$  of polynomial interpolating points  $(x_1, y_1), \ldots, (x_n, y_n)$  can be found from equation:

$$\begin{bmatrix} \phi_{1}(x_{1}) & \phi_{2}(x_{1}) & \phi_{3}(x_{1}) & \cdots & \phi_{n}(x_{1}) \\ \phi_{1}(x_{2}) & \phi_{2}(x_{2}) & \phi_{3}(x_{2}) & \cdots & \phi_{n}(x_{2}) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \phi_{1}(x_{n}) & \phi_{2}(x_{n}) & \phi_{3}(x_{n}) & \cdots & \phi_{n}(x_{n}) \end{bmatrix} \begin{bmatrix} a_{1} \\ a_{2} \\ \vdots \\ a_{n} \end{bmatrix} = \begin{bmatrix} y_{1} \\ y_{2} \\ \vdots \\ y_{n} \end{bmatrix}$$

#### References

- [1] Michael T. Heath, Scientific Computing. An Introductory Survey, 2nd Edition, Chapter 7: Interpolation 2002
- [2] Michael T. Heath, Chapter 7: Interpolation http://heath.cs.illinois.edu/scicomp/notes/cs450\_ chapt07.pdf