

Power and FTDI

Power.sch

MCU

MCU.sch

Peripherals

Peripherals.sch

Headers and Debug

Headers.sch

Garnet Tanner
Andromeda
SOAR

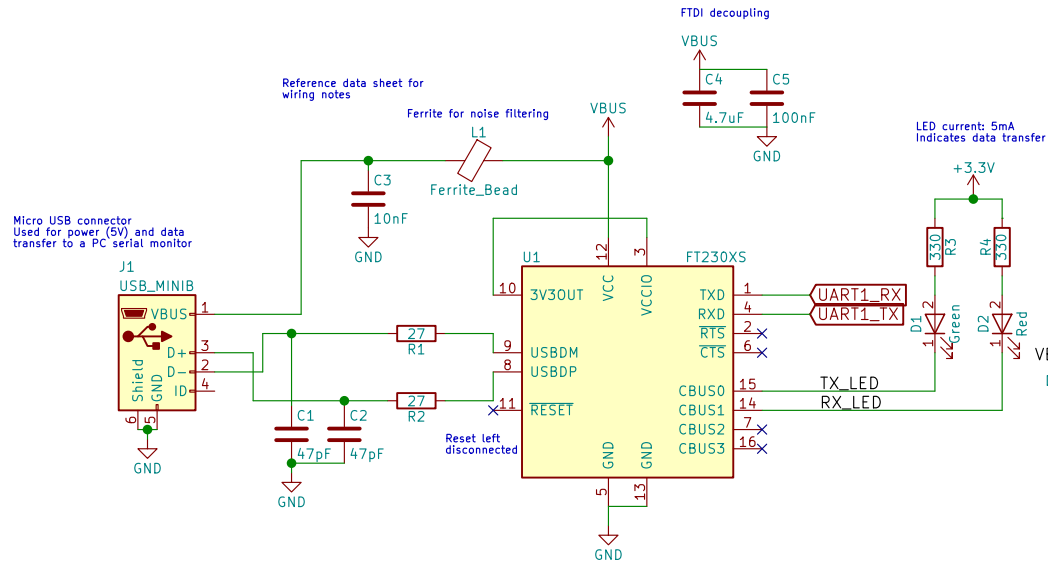
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File: STM32_SOAR_Reference_Board.sch

Title: SOAR Avionics Development Board

Size: USLetter Date: 2017-12-03
KiCad E.D.A. kicad 4.0.7

Rev: 1
Id: 1/5

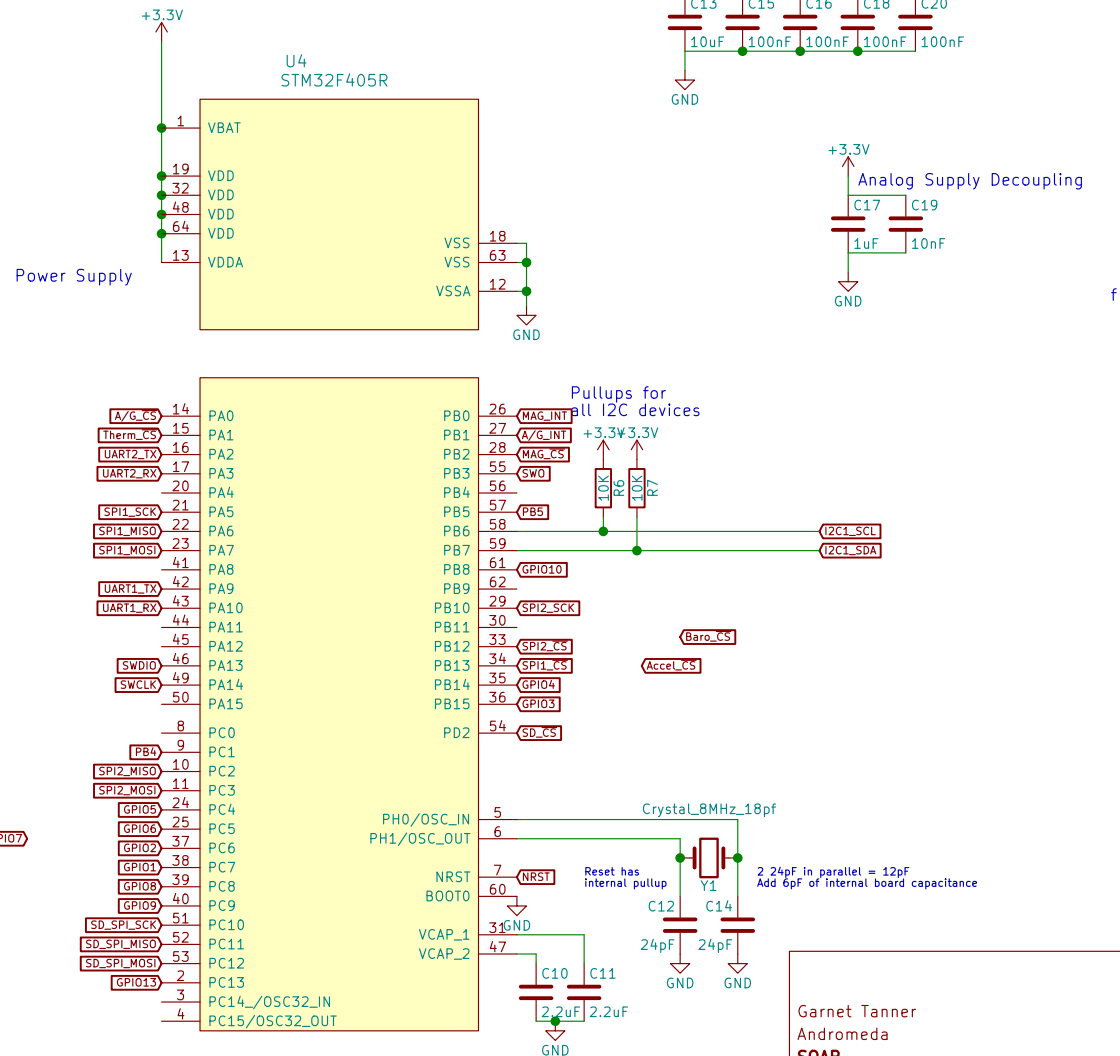
USB Power



See STM32 Hardware Design Guide for schematic example

STM32F405

Same family as F407 on Discovery boards



Digital Decoupling
1 100nF for each power supply (place close to each VDD pin)
plus 1 10uF

Analog Supply Decoupling
C17 1uF
C19 10nF

Pullups for
all I2C devices

CrystaL8MHz_18pf
Reset has
internal pullup
2 24pF in parallel = 12pF
Add 6pF of internal board capacitance

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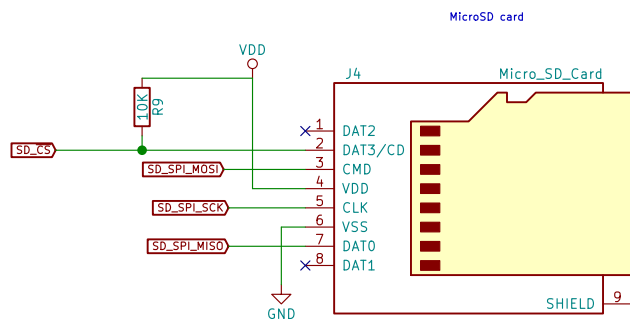
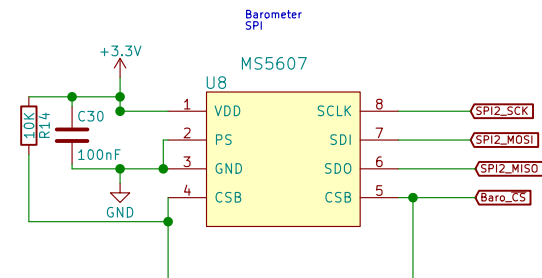
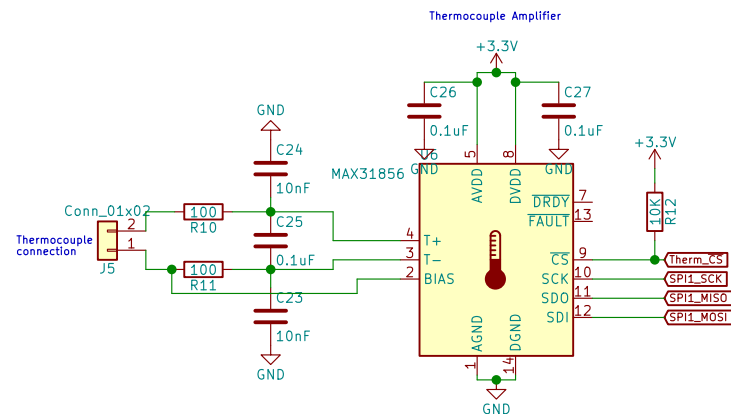
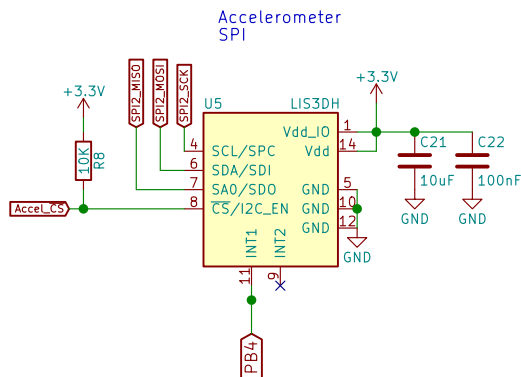
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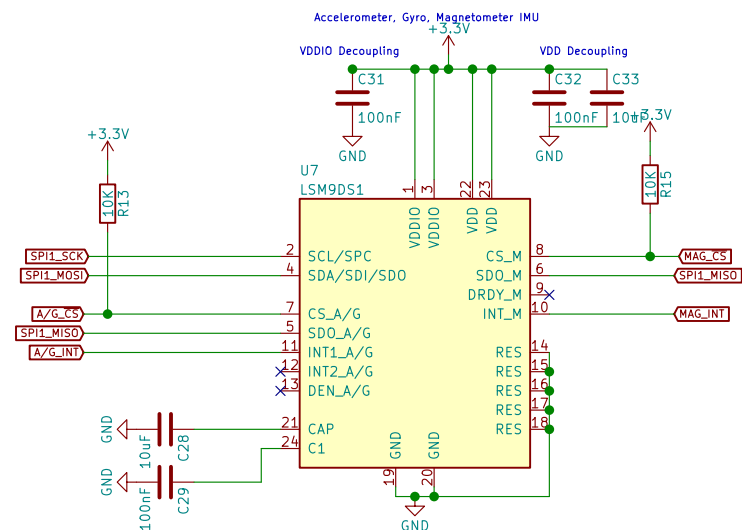
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SD card uses a lot of power. (100mA)
Consider turning off SPI clock when not using to save power

SD card placed on its own SPI channel (SPI3)



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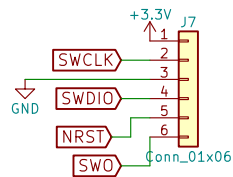
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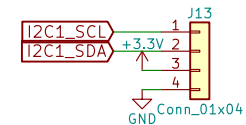
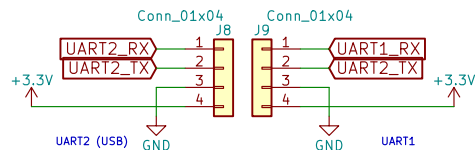
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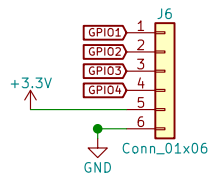
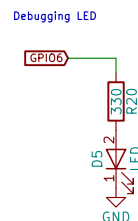
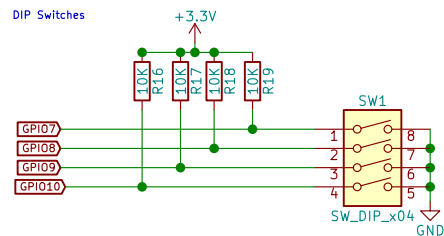
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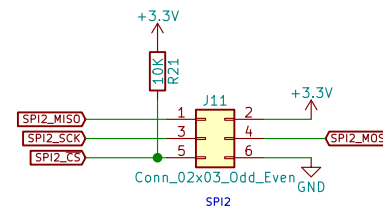
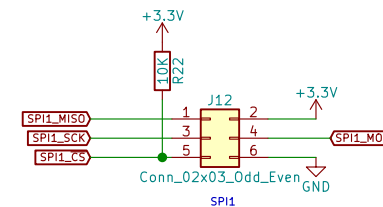
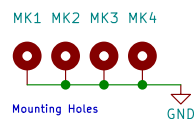
SWD Programming
For use with ST-Link V2 programmer
or discovery board



I2C1
Pullups on MCU sheet



Debug GPIO



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