



Tetris Battle 2.0 DEMO

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Github Link:

https://github.com/Gting6/NTUEE_EMBED_LAB/tree/main/Final

Outline

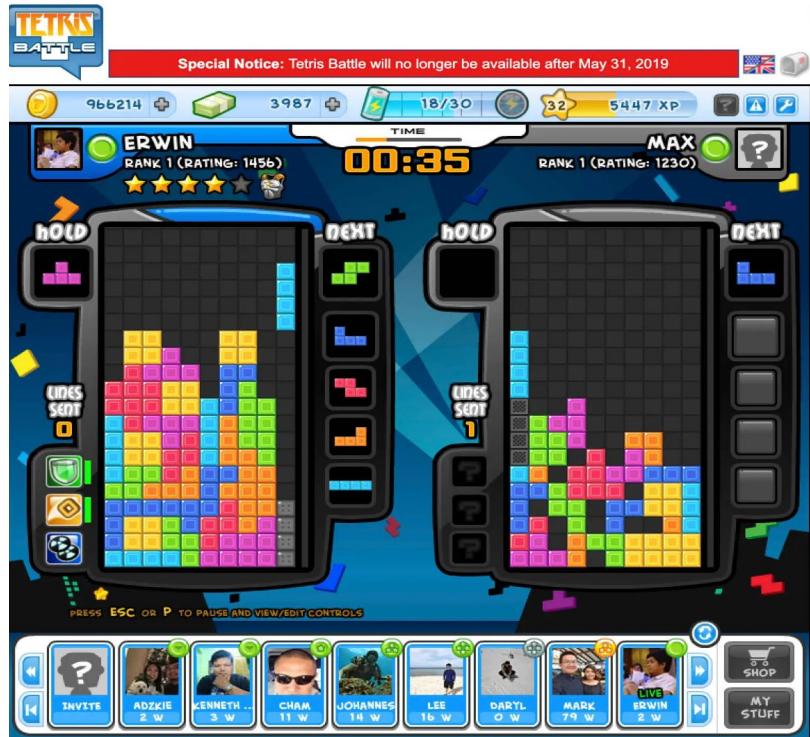
- Introduction
- Demo
- Technical Details
 - Tetris Game: Socket Programming + Multi-thread
 - LED Display: Mutex, FIFO
 - Joystick: STM32 Optimization

Motivation

This well-known little game, Tetris Battle on Facebook brought lots of joys in our childhood

However, this game was out of service on March 31, 2020

We decide to make it alive again!
(and we successed!)



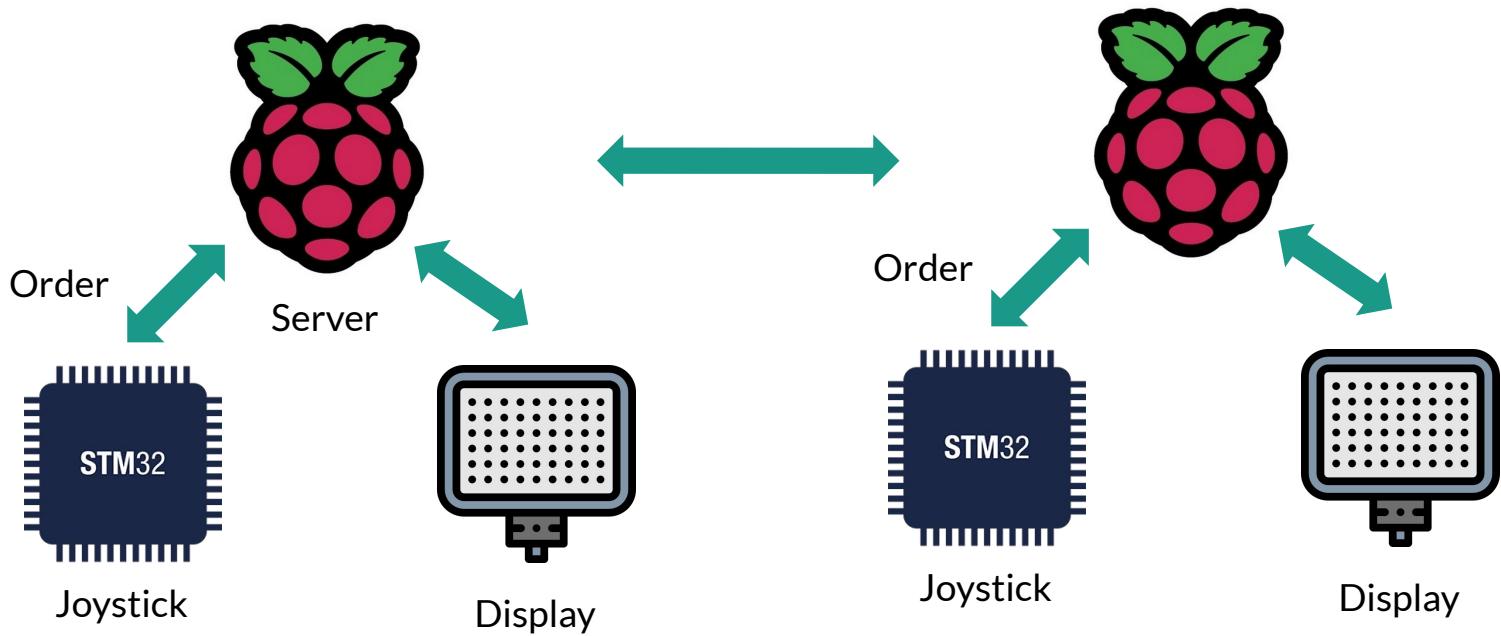


Expected Result

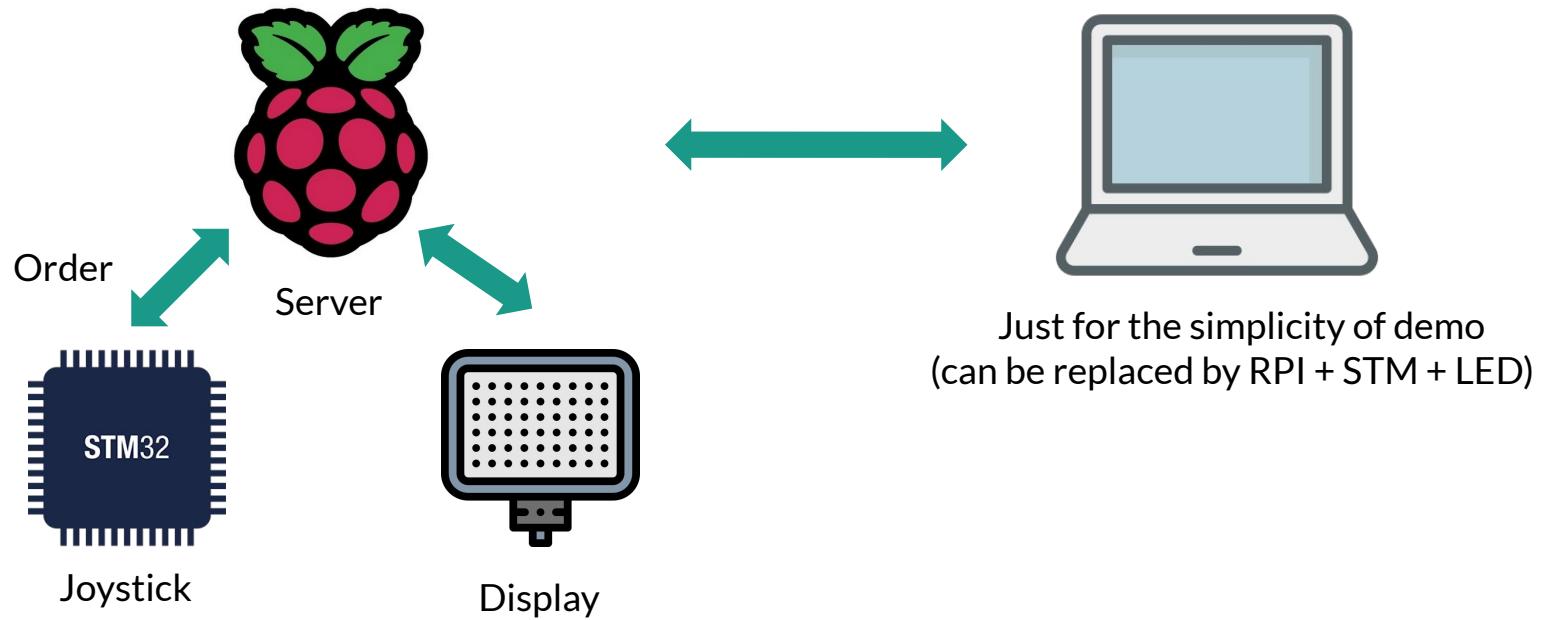
1. 1 Player Tetris
2. 2 Player Tetris Battle
3. Tetris Battle on LED screen

Use STM32 as joysticks, RPI to run the program, Screen or LED Board to display

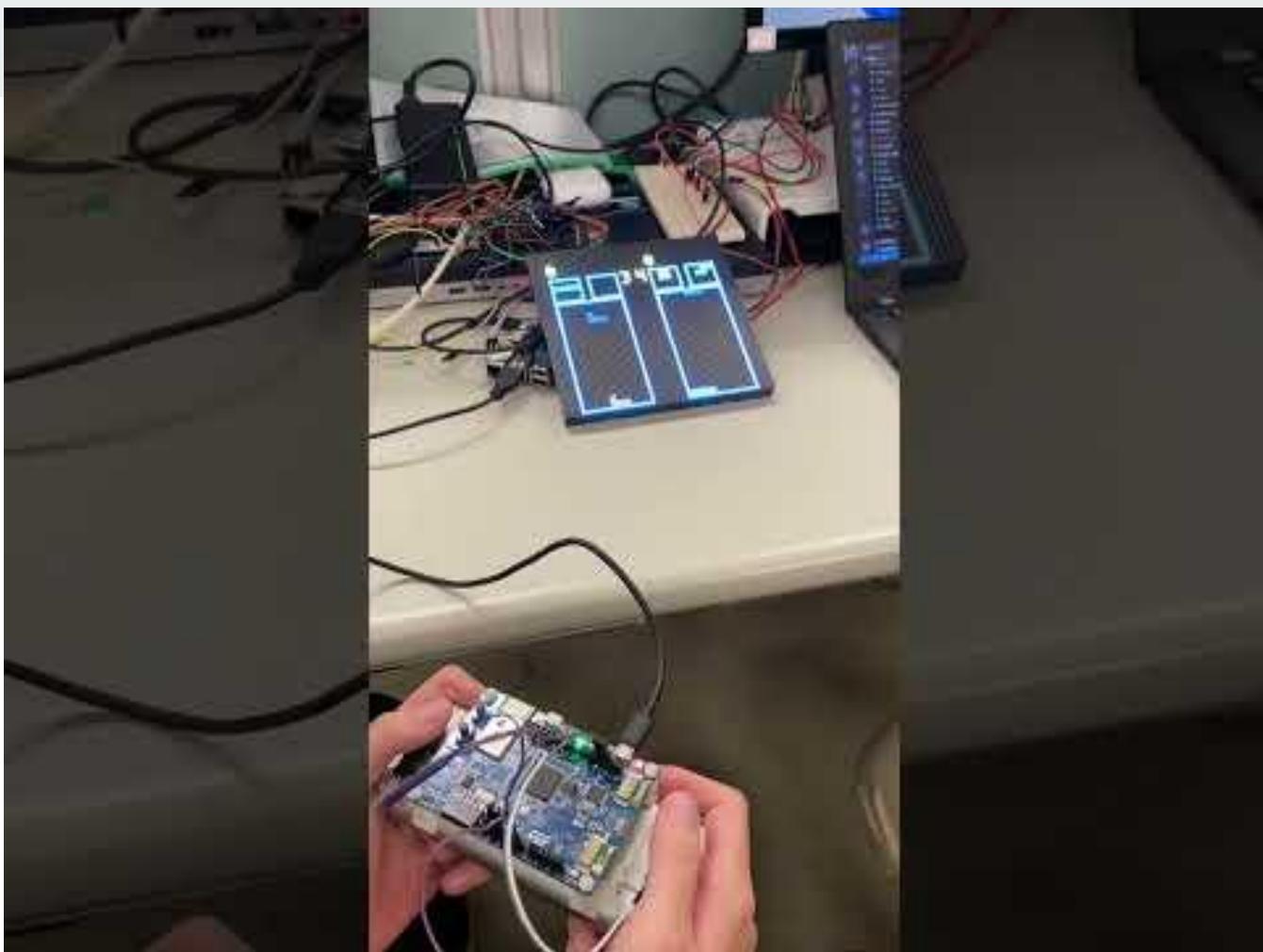
Expected Result



Expected Result

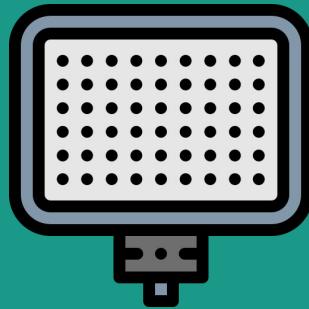
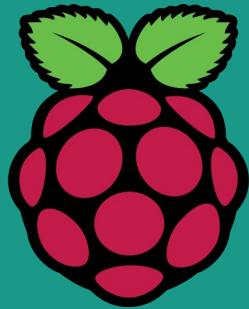


Demo

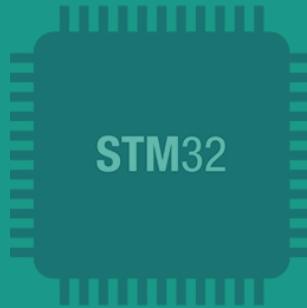
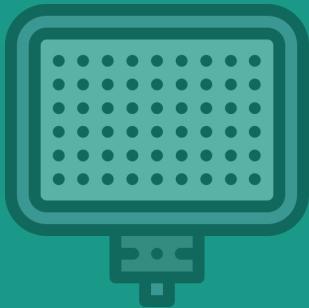
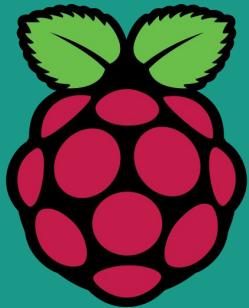


<https://youtu.be/rcX75-qD13I>

Take a closer look



Take a closer look



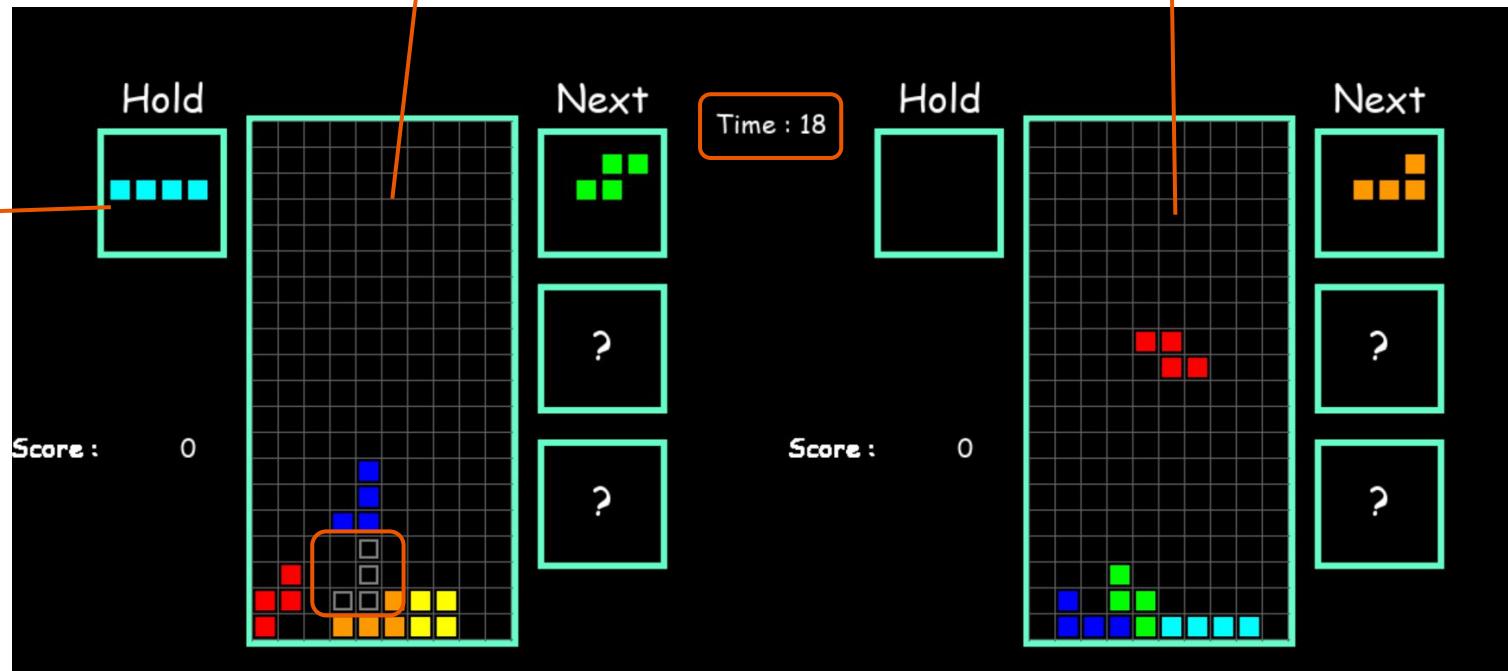
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10 x 20 Matrix

RPI: Tetris Client + STM Listener

Get Opponent's Info from server

4 x 4
Matrix



RPI: Tetris Client + STM Listener

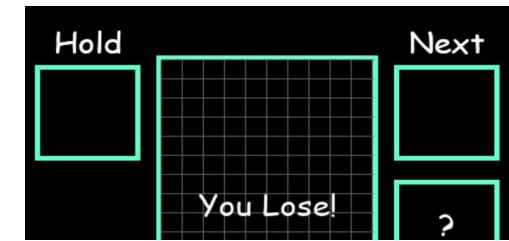
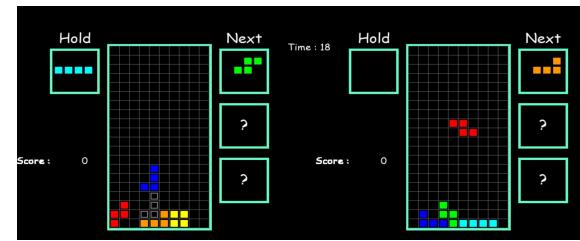
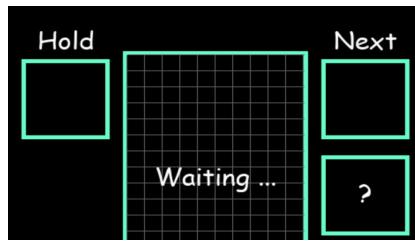
Use 3 Thread + Socket programming

1. Listen to STM32 , push into queue
2. Main logic of tetris game (Retrieve info from queue).
Send info and retrieve the status
 - a. Rerender the scene
 - b. Write to the FIFO for LED (Use ctype library to transfer data from python to C)
3. Countdown the time
 - a. Once receive state change from server

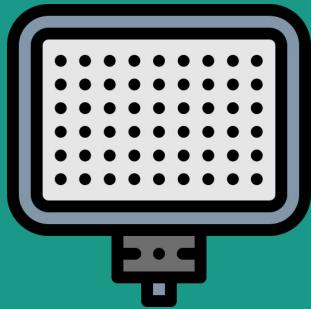
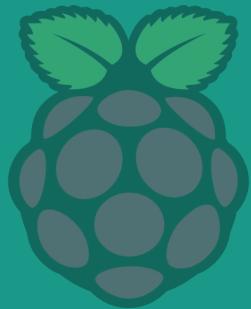
RPI: Tetris Server - Exchange status

- Status // Main screen
- Game // Game status, only received from server
- Shift0
- Next0
- Combo
- Point

RPI: Tetris Server - Control State of the game



Take a closer look

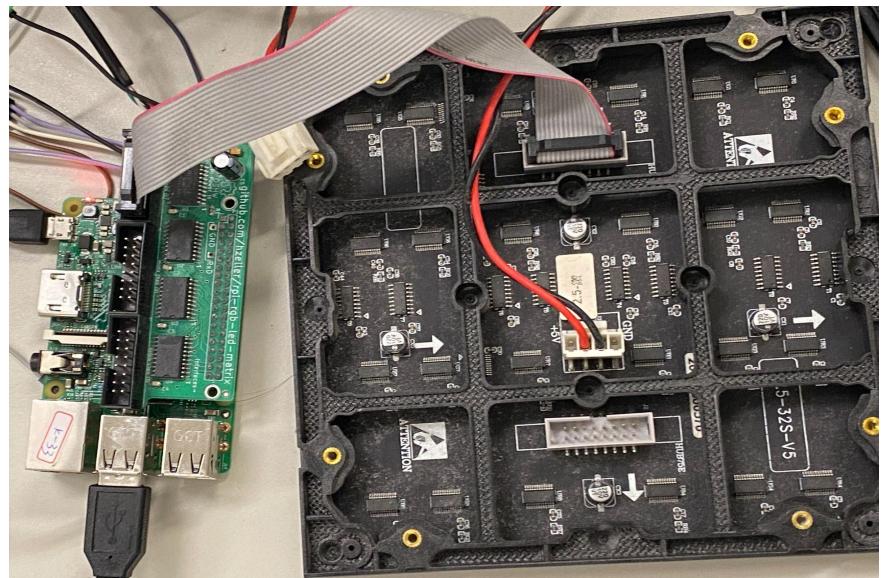
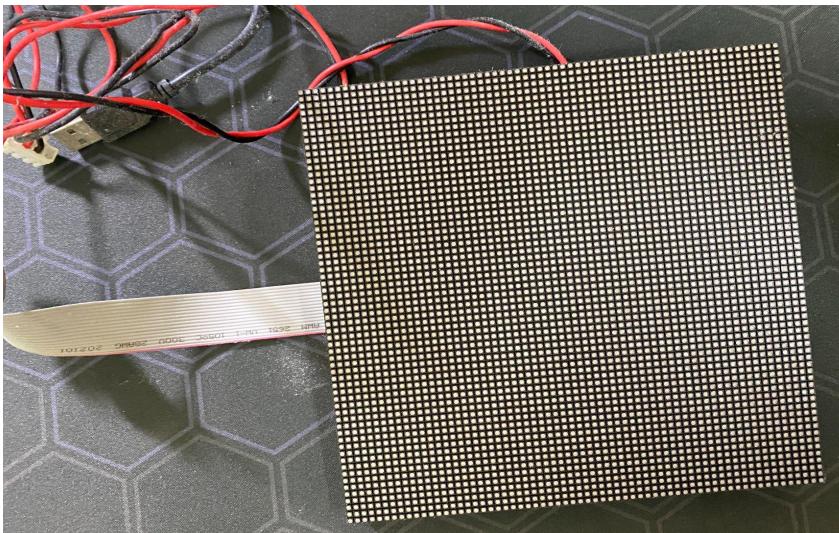




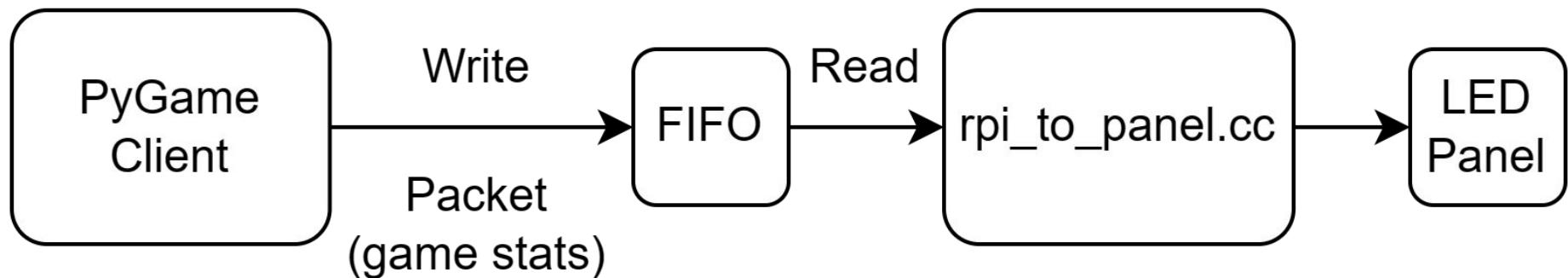
LED Display

- 64 x 64 pixels RGB panel
- reference: <https://github.com/hzeller/rpi-rgb-led-matrix>

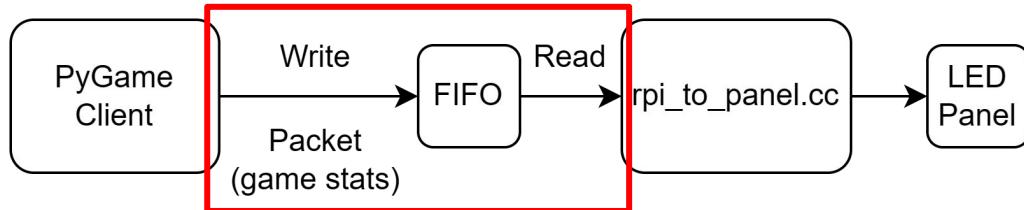
LED Display (hardware)



LED Display

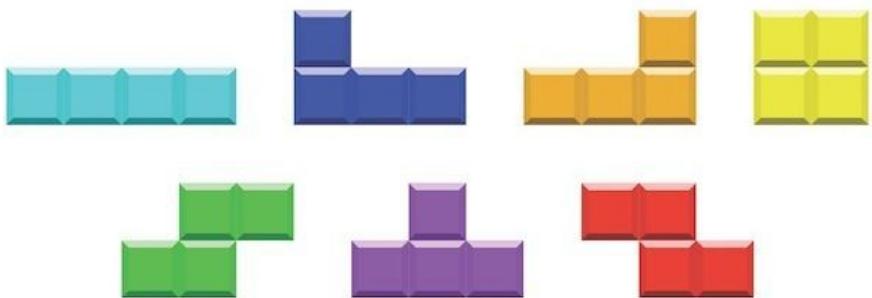


LED Display



```
typedef struct Stats {  
    int player0_main[10][20];  
    int player0_shift[4][4];  
    int player0_next[4][4];  
    int player0_pts;  
    int player0_cbs;  
    int player1_main[10][20];  
    int player1_shift[4][4];  
    int player1_next[4][4];  
    int player1_pts;  
    int player1_cbs;  
    int game;  
    int time;  
} Stats;
```

LED Display

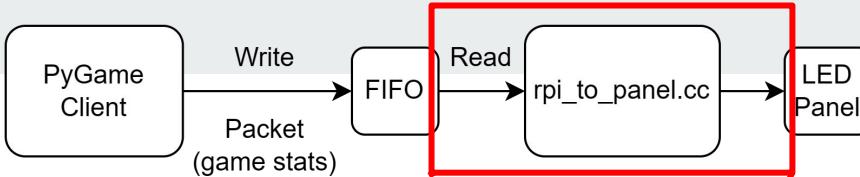


```
rgb_matrix::Color bg(100, 255, 200);           // bright blue background
rgb_matrix::Color score(255, 0, 255);          // bright yellow
rgb_matrix::Color combo(255, 0, 102);          // combo
rgb_matrix::Color text(255, 0, 0);             // text

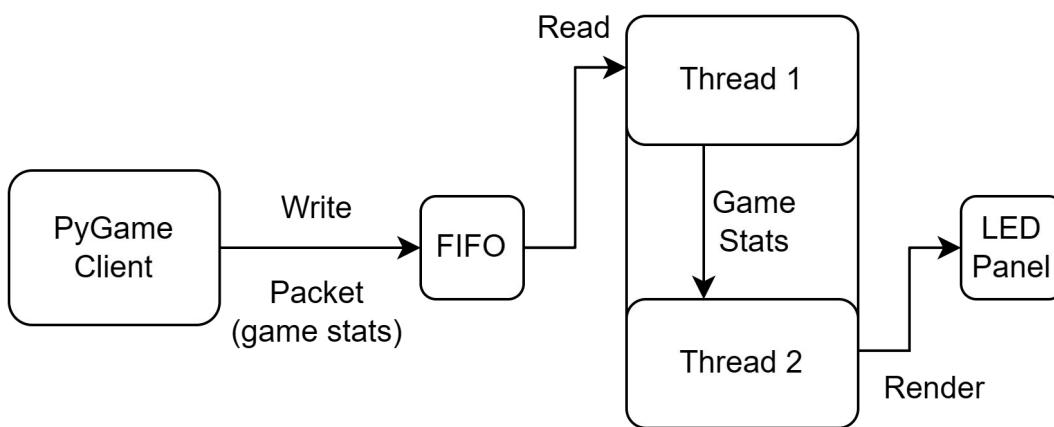
rgb_matrix::Color EMPTY(0, 0, 0);              // void black
rgb_matrix::Color SHADOW(128, 128, 128);        // gray
rgb_matrix::Color I(23, 238, 222);             // light blue
rgb_matrix::Color J(3, 174, 65);               // deep blue
rgb_matrix::Color L(255, 28, 151);             // orange
rgb_matrix::Color O(255, 0, 213);              // yellow
rgb_matrix::Color S(114, 59, 203);             // green
rgb_matrix::Color T(118, 175, 55);             // purple
rgb_matrix::Color Z(255, 19, 50);              // red

> void RGB(rgb_matrix::Color& color) { ...

unordered_map<int, rgb_matrix::Color> id2color = {
    {0, EMPTY},
    {1, I},
    {2, L},
    {3, J},
    {4, O},
    {5, S},
    {6, Z},
    {7, T},
    {8, SHADOW}
};
```



LED Display



```

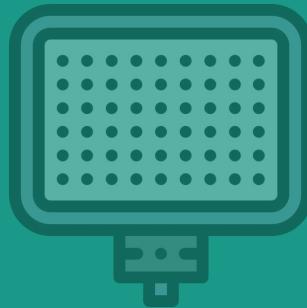
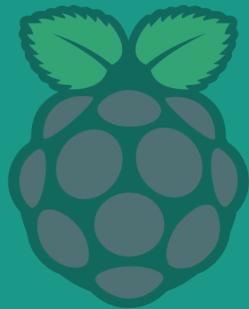
int ready;

fd_set readset;
timeval timeout;
FD_ZERO(&readset);
FD_SET(fifo_fd, &readset);
timeout.tv_sec = 1;
timeout.tv_usec = 0;

while (!interrupt_received) {
    cerr << "thread loop" << endl;
    ready = select(fifo_fd+1, &readset, NULL, NULL, &timeout);
    if (ready == 1) {
        cerr << "ready" << endl;
        read(fifo_fd, &packet, sizeof(Stats));
        /* TODO: write to stats */
        int ret = pthread_mutex_trylock(&stats_lock);
        if (ret == 0) {
            stats = packet;
            pthread_mutex_unlock(&stats_lock);
        }
    } else if (ready == -1) {
        cerr << "select error" << endl;
        exit(1);
    }
}

```

Take a closer look



STM Controller

Use two external **button** to control left and right shift

Right rotate to preservation the tetris

Shake to rotate and instant drop

Left shift

Rotate



Preservation



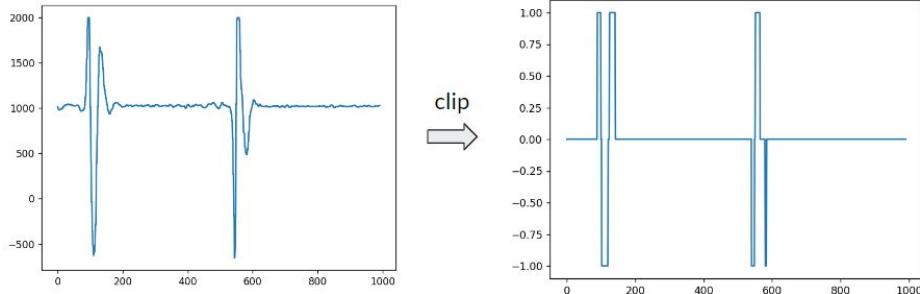
Instant drop

STM Controller (button)

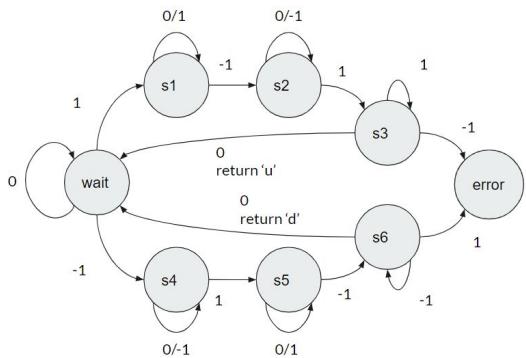
Use mbed **InterruptIn** api to implement left and right button.

- void fall(Callback< void()> func)
- void rise(Callback< void()> func)

STM Controller



clip



old method



accelerometer

gyroscope

new method

STM Controller (rotate & shake) (old method)

Only accelerometer data to judge up and down by using fsm.

It's easy to misjudge up and down with right rotate.

STM Controller (rotate & shake) (new method)

Gyroscope y-axis data integral to degree



ROTATE

Gyroscope x-axis data integral to degree
Accelerometer z-axis data to determine moving



UP/DOWN

Reference

1. <https://github.com/hzeller/rpi-rgb-led-matrix>
2. [Tetris Battle | Tetris](#)
3. [Socket Programming in Python \(Guide\) – Real Python](#)
4. [threading — Thread-based parallelism — Python 3.11.1 documentation](#)
5. [ctypes — A foreign function library for Python — Python 3.11.1 documentation](#)
6. https://github.com/NTUEE-ESLab/2020-Pikachu-volleyball?fbclid=IwAR2OjNHmuji6J_A953Bmx-v4b5ptkjRtIIE-pMu8KrmLBQ7Pl4QIVhcfSbs
7. [Linux Tutorial: POSIX Threads \(cmu.edu\)](#)

Thanks!

