

CS329 Machine Learning

Homework #5

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Question 1

Consider a regression problem involving multiple target variables in which it is assumed that the distribution of the targets, conditioned on the input vector \mathbf{x} , is a Gaussian of the form

$$p(\mathbf{t}|\mathbf{x}, \mathbf{w}) = \mathcal{N}(\mathbf{t}|\mathbf{y}(\mathbf{x}, \mathbf{w}), \Sigma)$$

where $\mathbf{y}(\mathbf{x}, \mathbf{w})$ is the output of a neural network with input vector \mathbf{x} and weight vector \mathbf{w} , and Σ is the covariance of the assumed Gaussian noise on the targets.

(a) Given a set of independent observations of \mathbf{x} and \mathbf{t} , write down the error function that must be minimized in order to find the maximum likelihood solution for \mathbf{w} , if we assume that Σ is fixed and known.

(b) Now assume that Σ is also to be determined from the data, and write down an expression for the maximum likelihood solution for Σ . (Note: The optimizations of \mathbf{w} and Σ are now coupled.)

Solution (a)

The likelihood function:

$$p(\mathbf{T}|\mathbf{X}, \mathbf{w}) = \prod_{n=1}^N \mathcal{N}(\mathbf{t}_n|\mathbf{y}(\mathbf{x}_n, \mathbf{w}), \Sigma)$$

The error function to be minimized:

$$E(\mathbf{w}, \Sigma) = \frac{1}{2} \sum_{n=1}^N \left\{ [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n]^T \Sigma^{-1} [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n] \right\} + \frac{N}{2} \ln|\Sigma| + \frac{N}{2} \ln(2\pi)$$

If Σ is known and fixed,

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \left\{ [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n]^T \Sigma^{-1} [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n] \right\} + \text{const}$$

By minimizing this error function, we obtain \mathbf{w}_{ML} .

Solution (b)

The error function:

$$E(\mathbf{w}, \Sigma) = \frac{1}{2} \sum_{n=1}^N \left\{ [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n]^T \Sigma^{-1} [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n] \right\} + \frac{N}{2} \ln|\Sigma| + \frac{N}{2} \ln(2\pi)$$

Let the gradient of the error function with respect to Σ be 0:

$$\frac{\partial}{\partial \Sigma} E(\mathbf{w}, \Sigma) = -\frac{1}{2} \sum_{n=1}^N \left\{ \Sigma^{-1} [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n] [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n]^T \Sigma^{-1} \right\} + \frac{N}{2} \Sigma^{-1} = 0$$

Solve the equation, we obtain Σ_{ML} :

$$\Sigma_{\text{ML}} = \frac{1}{N} \sum_{n=1}^N [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n] [\mathbf{y}(\mathbf{x}_n, \mathbf{w}) - \mathbf{t}_n]^T$$

Question 2

The error function for binary classification problems was derived for a network having a logistic-sigmoid output activation function, so that $0 \leq y(\mathbf{x}, \mathbf{w}) \leq 1$, and data having target values $t \in \{0, 1\}$. Derive the corresponding error function if we consider a network having an output $-1 \leq y(\mathbf{x}, \mathbf{w}) \leq 1$ and target values $t = 1$ for class \mathcal{C}_1 and $t = -1$ for class \mathcal{C}_2 . What would be the appropriate choice of output unit activation function?

Hint. The error function is given by:

$$E(\mathbf{w}) = - \sum_{n=1}^N \{t_n \ln y_n + (1 - t_n) \ln(1 - y_n)\}.$$

Solution

Scaling and shifting the binary outputs from $[0,1]$ to $[-1,1]$:

$$y = 2\sigma(a) - 1 \in [-1, 1]$$

The conditional distribution:

$$p(t|\mathbf{x}, \mathbf{w}) = \left[\frac{1 + y(\mathbf{x}, \mathbf{w})}{2} \right]^{\frac{1+t}{2}} \left[\frac{1 - y(\mathbf{x}, \mathbf{w})}{2} \right]^{\frac{1-t}{2}}$$

where the conditional probability is $p(\mathcal{C}_1|x) = \frac{1+y(\mathbf{x}, \mathbf{w})}{2}$.

Hence we obtain the error function:

$$\begin{aligned} E(\mathbf{w}) &= - \sum_{n=1}^N \left\{ \frac{1+t_n}{2} \ln \frac{1+y_n}{2} + \frac{1-t_n}{2} \ln \frac{1-y_n}{2} \right\} \\ &= - \frac{1}{2} \sum_{n=1}^N \{ (1+t_n) \ln(1+y_n) + (1-t_n) \ln(1-y_n) \} + N \ln 2 \end{aligned}$$

So we obtain the activation function:

$$y(a) = 2\sigma(a) - 1 = \frac{1 - e^{-a}}{1 + e^{-a}} = \frac{e^{\frac{a}{2}} - e^{-\frac{a}{2}}}{e^{\frac{a}{2}} + e^{-\frac{a}{2}}} = \tanh\left(\frac{a}{2}\right)$$

Question 3

Verify the following results for the conditional mean and variance of the mixture density network model.

(a)

$$\mathbb{E}[\mathbf{t}|\mathbf{x}] = \int \mathbf{t} p(\mathbf{t}|\mathbf{x}) \, d\mathbf{t} = \sum_{k=1}^K \pi_k(\mathbf{x}) \mu_k(\mathbf{x}).$$

(b)

$$s^2(\mathbf{x}) = L \sum_{k=1}^K \pi_k(\mathbf{x}) \sigma_k^2(\mathbf{x}) + \left\| \mu_k(\mathbf{x}) - \sum_{l=1}^K \pi_l(\mathbf{x}) \mu_l(\mathbf{x}) \right\|^2.$$

Solution (a)

$$\begin{aligned} \mathbb{E}[\mathbf{t}|\mathbf{x}] &= \int \mathbf{t} p(\mathbf{t}|\mathbf{x}) \, d\mathbf{t} \\ &= \int \mathbf{t} \sum_{k=1}^K \pi_k(\mathbf{x}) \mathcal{N}(\mathbf{t}|\mu_k, \sigma_k^2) d\mathbf{t} \\ &= \sum_{k=1}^K \pi_k(\mathbf{x}) \int \mathbf{t} \mathcal{N}(\mathbf{t}|\mu_k, \sigma_k^2) d\mathbf{t} \\ &= \sum_{k=1}^K \pi_k(\mathbf{x}) \mu_k(\mathbf{x}). \end{aligned}$$

Solution (b)

Noticing that $\mathbb{E}[\mathbf{t}^T A \mathbf{t}] = \text{Trace}[A\sigma^2] + \boldsymbol{\mu}^T A \boldsymbol{\mu}$, let $A = \mathbf{I}$, we obtain

$$\mathbb{E}[\mathbf{t}^2] = \int \|\mathbf{t}\|^2 \mathcal{N}(\mathbf{t}|\boldsymbol{\mu}, \sigma^2 \mathbf{I}) d\mathbf{t} = L\sigma^2 + \|\boldsymbol{\mu}\|^2$$

where L is the dimension of \mathbf{t} .

Therefore

$$\begin{aligned} s^2(\mathbf{x}) &= \mathbb{E}[\|\mathbf{t} - \mathbb{E}[\mathbf{t}|\mathbf{x}]\|^2|\mathbf{x}] \\ &= \mathbb{E}[\mathbf{t}^2|\mathbf{x}] - \mathbb{E}[\mathbf{t}|\mathbf{x}]^2 \\ &= \int \|\mathbf{t}\|^2 \sum_{k=1}^K \pi_k(\mathbf{x}) \mathcal{N}(\boldsymbol{\mu}_k, \sigma_k^2) d\mathbf{t} - \left\| \sum_{l=1}^K \pi_l(\mathbf{x}) \boldsymbol{\mu}_l(\mathbf{x}) \right\|^2 \\ &= \sum_{k=1}^K \pi_k(\mathbf{x}) (L\sigma_k^2(\mathbf{x}) + \|\boldsymbol{\mu}_k(\mathbf{x})\|^2) - \left\| \sum_{l=1}^K \pi_l(\mathbf{x}) \boldsymbol{\mu}_l(\mathbf{x}) \right\|^2 \\ &= L \sum_{k=1}^K \pi_k(\mathbf{x}) \sigma_k^2(\mathbf{x}) + \sum_{k=1}^K \pi_k(\mathbf{x}) \|\boldsymbol{\mu}_k(\mathbf{x})\|^2 - \left\| \sum_{l=1}^K \pi_l(\mathbf{x}) \boldsymbol{\mu}_l(\mathbf{x}) \right\|^2 \\ &= L \sum_{k=1}^K \pi_k(\mathbf{x}) \sigma_k^2(\mathbf{x}) + \left\| \boldsymbol{\mu}_k(\mathbf{x}) - \sum_{l=1}^K \pi_l(\mathbf{x}) \boldsymbol{\mu}_l(\mathbf{x}) \right\|^2 \end{aligned}$$

Question 4

Can you represent the following boolean function with a single logistic threshold unit (i.e., a single unit from a neural network)? If yes, show the weights. If not, explain why not in 1-2 sentences.

A	B	$f(A, B)$
1	1	0
0	0	0
1	0	1
0	1	0

Solution

Yes, this function is linearly separable.

$$y = [A \quad B] \begin{bmatrix} 2 \\ -1 \end{bmatrix} - 1 = 2A - B - 1$$

We use a threshold as the activation function:

If $y > 0$, then $f(A, B) = 1$, otherwise $f(A, B) = 0$.

Question 5

Below is a diagram of a small convolutional neural network that converts a 13x13 image into 4 output values. The network has the following layers/operations from input to output: convolution with 3 fil-

ters, max pooling, ReLU, and finally a fully-connected layer. For this network we will not be using any bias/offset parameters (b). Please answer the following questions about this network.

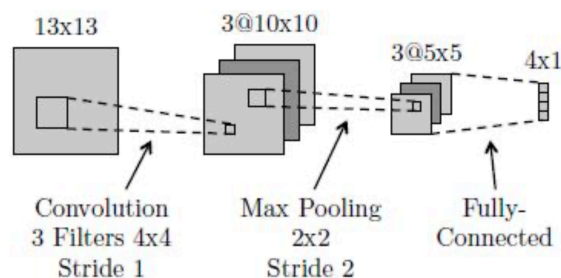


Figure 1: The Convolutional Neural Network for Question 5

- How many weights in the convolutional layer do we need to learn?
- How many ReLU operations are performed on the forward pass?
- How many weights do we need to learn for the entire network?
- True or false: A fully-connected neural network with the same size layers as the above network ($13 \times 13 \rightarrow 3 \times 10 \times 10 \rightarrow 3 \times 5 \times 5 \rightarrow 4 \times 1$) can represent any classifier?
- What is the disadvantage of a fully-connected neural network compared to a convolutional neural network with the same size layers?

Solution

(a) $3 * 4 * 4 = 48$

(b) $3 * (10/2) * (10/2) = 75$

(c) $3 * 4 * 4 + 3 * 5 * 5 * 4 = 348$

(d) False. The fully-connected neural network can capture a wide range of functions, but it may not be able to represent highly complex or nonlinear decision boundaries. However, the fully-connected neural network can represent any classifier that the convolutional neural network can represent.

(e)

- Fully-connected neural networks lack translation invariance, meaning that they may not recognize patterns in different spatial locations.
- In fully-connected neural networks, each neuron in a layer is connected to every neuron in the previous and subsequent layers. This leads to a large number of parameters, resulting in increased computational requirements and the risk of overfitting, especially when dealing with high-dimensional data like images.

Question 6

The neural networks shown in class used logistic units: that is, for a given unit U , if A is the vector of activations of units that send their output to U , and W is the weight vector corresponding to these outputs, then the activation of U will be $(1 + \exp(W^T A))^{-1}$. However, activation functions could be anything. In this exercise we will explore some others. Consider the following neural network, consisting of two input units, a single hidden layer containing two units, and one output unit:

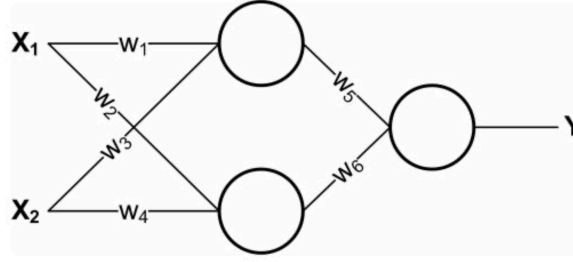


Figure 2: The Neural Network for Question 6

- (a) Say that the network is using linear units: that is, defining W and A as above, the output of a unit is $C * W^T A$ for some fixed constant C . Let the weight values w_i be fixed. Re-design the neural network to compute the same function without using any hidden units. Express the new weights in terms of the old weights and the constant C .
- (b) Is it always possible to express a neural network made up of only linear units without a hidden layer? Give a one-sentence justification.
- (c) Another common activation function is a threshold, where the activation is $t(W^T A)$ where $t(x)$ is 1 if $x > 0$ and 0 otherwise. Let the hidden units use sigmoid activation functions and let the output unit use a threshold activation function. Find weights which cause this network to compute the XOR of X_1 and X_2 for binary-valued X_1 and X_2 . Keep in mind that there is no bias term for these units.

Solution (a)

$$y = [X_1 \ X_2] \begin{bmatrix} C(w_1 * w_5 + w_2 * w_6) \\ C(w_3 * w_5 + w_4 * w_6) \end{bmatrix}$$

Therefore the new weight is

$$w'_1 = C(w_1 * w_5 + w_2 * w_6)$$

$$w'_2 = C(w_3 * w_5 + w_4 * w_6)$$

Solution (b)

No, it is not always possible to express a neural network made up of only linear units without a hidden layer as it would be equivalent to a single-layer perceptron, which cannot capture non-linear relationships in the data.

Solution (c)

Inequations:

$$w_5 * \sigma(w_1) + w_6 * \sigma(w_2) > 0$$

$$w_5 * \sigma(w_3) + w_6 * \sigma(w_4) > 0$$

$$w_5 * \sigma(w_1 + w_3) + w_6 * \sigma(w_2 + w_4) \leq 0$$

$$w_5 + w_6 \leq 0$$

A solution to this system is

$$W = \begin{bmatrix} -1.180893 \\ -0.859961 \\ -1.121304 \\ -0.829760 \\ 0.884250 \\ -0.954182 \end{bmatrix}$$

The code for randomly seeking the weight vector is shown below:

```
#include <math.h>
#include <stdbool.h>
#include <stdio.h>
#include <stdlib.h>

#define MYRAND(x) (((double)rand() / RAND_MAX) * (x) * 2 - (x))
#define SIGMOID(x) (1 / (1 + exp(x)))

bool satisfy(double w[])
{
    return
    (
        w[4] * SIGMOID(w[0]) + w[5] * SIGMOID(w[1]) > 0 &&
        w[4] * SIGMOID(w[2]) + w[5] * SIGMOID(w[3]) > 0 &&
        w[4] * SIGMOID(w[0] + w[2]) + w[5] * SIGMOID(w[1] + w[3]) <= 0 &&
        w[4] + w[5] <= 0
    );
}

double w[6] = {0};

int main()
{
    srand(42);
    while (!satisfy(w))
    {
        for (int i = 0; i < 6; i++)
        {
            w[i] = MYRAND(1.5);
        }
    }
    printf("[%lf, %lf, %lf, %lf, %lf, %lf]", w[0], w[1], w[2], w[3], w[4], w[5]);
}
```