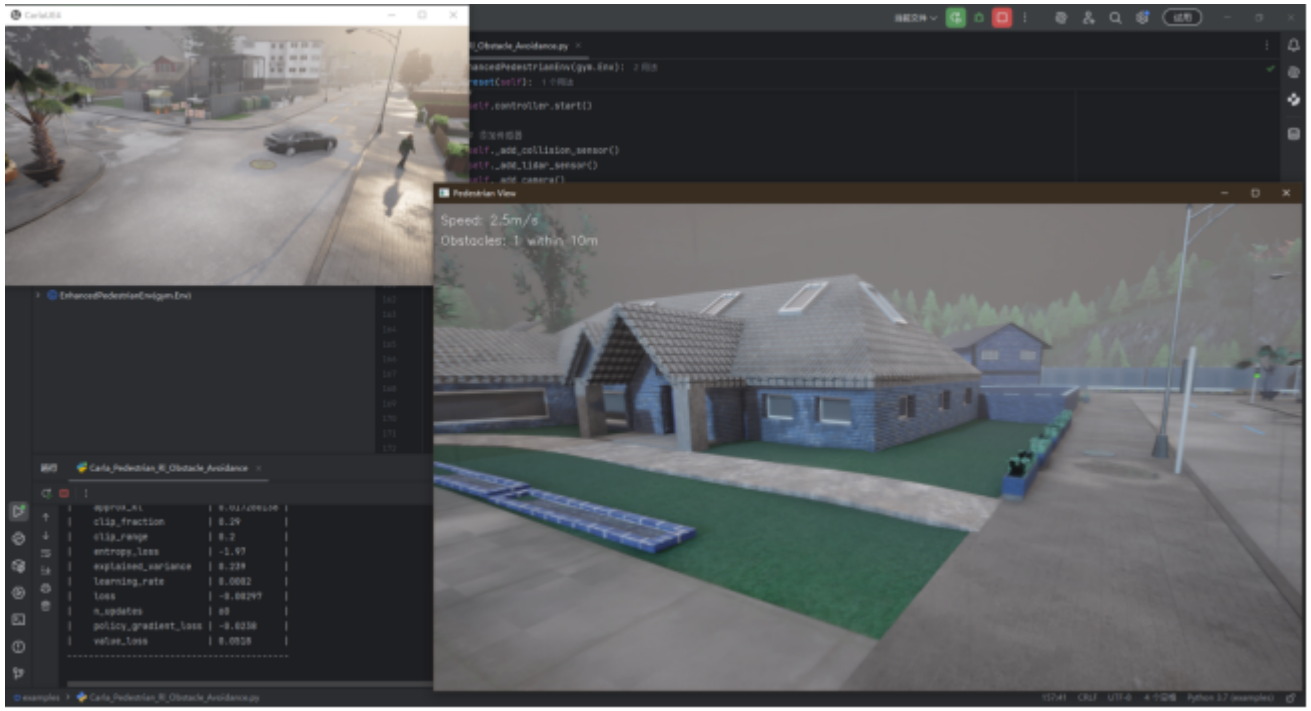
Pedestrian View
Speed: 2.5m/s
Obstacles: 1 within 10m
clip_fraction | 0.29
clip_range | 0.2
entropy_loss | -1.97
explained_variance | 0.239
learning_rate | 0.0002
loss | -0.00297
n_updates | 40
policy_gradient_loss | -0.0230
value_loss | 0.0510