XINLEI ZHANG

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RESEARCH INTERESTS & GOAL

My research interests lie in the **theories** and **applications** in **robotics**, including **state estimation** & **system dynamics**, **nonlinear control**, and **reinforcement learning**. My goal is to advance robotics research by integrating artificial intelligence and control theory methods.

EDUCATION

South China University of Technology | **Intelligent Manufacturing** 09/2020 - 06/2024 (Expected)
Shien-Ming Wu School of Intelligent Engineering Guangzhou, China
Overall GPA 3.75/4.0
Related Courses

- Applied Calculus II 96/100, Linear Algebra 97/100, Probability and Statistics 89/100
- Artificial Intelligence Technology and Applications 90/100, Data Structure 91/100
- Sensor Technology and Applications 90/100, Mechatronics 92/100
- System Dynamics 91/100, Classical Control Theory 92/100

PUBLICATION & PATENT

On Ambiguity in 6-DoF Magnetic Pose Estimation | ***First Author*** 08/2023
Xinlei Zhang, Shuda Dong and Heng Wang
Submitted to IEEE Transaction on Robotics (**T-RO**), under the first-round review

A Virtual Ultrasonography Simulator for Skill Training Using Magnetic-Inertial Probe Tracking 03/2023
Heng Wang, Shuangyi Wang, Suqi Liu, Shuda Dong, Xinlei Zhang
CN Patent Pending, No.CN116312122A

RESEARCH EXPERIENCE

The Lab of Magnetic-Controlled Robot, SCUT 09/2021-Present
Research Assistant, advised by Dr. Heng Wang

6-DoF Magnetic-Inertial Pose Estimation 09/2021-12/2021

- **Innovation & Significance:** While most existing magnetic pose estimation systems consist of multiple magnetic sources, **only one magnetic source is required** in our work. 6-axis inertial and 3-axis magnetic measurements of the target were **fused** to estimate its pose with **uncertainties in sensor measuring** and **magnetic source modeling**. This technology could be applied to robotic systems requiring **millimeter-degree-scale accuracy**.
- **Contribution:** I participated in this project in **developing the 6-DoF pose estimation algorithm**, using the **state estimation technique (extended Kalman filter)**. During this project, I found the ambiguity issue in measurement systems and proposed this issue as my next research project.
- **Outcome:** 1.) one **CN patent** which is under pending; 2.) one new research project.

On Ambiguity in 6-DoF Magnetic Pose Estimation 01/2022-Present

- **Innovation & Significance:** In the last project, the system failed to provide 6-DoF estimation without the 6-axis inertial sensor. In this project, I **fundamentally investigated the ambiguity issue** in magnetic pose estimation systems, including its definition, categorization, identification algorithm and impact on pose estimation, which could serve as **a theoretical framework to analyze the ambiguity issue in any system**. The **most compact and energy-efficient 6-DoF Pose Estimation system** with only two magnetic sources was proposed. One equation was derived revealing the **dynamical nature** behind the ambiguity issue.
- **Contribution:** I **undertook** this project, and **investigated** the ambiguity issue in the theoretical level. I **developed identification algorithms** for ambiguous poses and **provided computer simulation verification**. Moreover, I **designed** and **conducted** experiments to demonstrate all my findings.
- **Outcome:** 1.) One **academic manuscript** has been submitted to IEEE Transaction on Robotics (**T-RO**); 2.) This project has earned recognition and funding through the **Chinese National Training Program of Innovation and Entrepreneurship for Undergraduates**, with a total funding amount of $1300.

Related Course Projects

Tendon-Driven and Flex Sensor Based Gesture Sensing Hand Exoskeleton | *Team Leader* Spring 2023

- **10 motors** are controlled to stretch tendons attached to the hand exoskeleton, achieving independent control of all five fingers. Moreover, **flex sensors** are fixed with fingers to measure their bending extent, providing gesture information, to construct the **closed-loop gesture control** of fingers.
- **Key words:** PID Motor Control, 3D Modeling and Manufacturing of Exoskeleton, Tendon-driven Mechanism, Bending Sensor, Closed-loop Gesture Tracking.

An Efficiency-Optimal Automated Assembly Line for the Luban Lock | *Team Leader* Spring 2023

- **Genetic algorithm**, an **evolutionary Optimization algorithm**, was employed to find the efficiency-optimal scheduling of nine production machines of one assembly line, which was a **Flexible Job Shop Problem**.
- **Key words:** Flexible Job Shop Problem, Genetic Algorithm, Plant Simulation.

Wireless-Powered Animation System Displayed by Rotating LEDs | *Team Leader* fall 2022

- **Multiple embedded system modules**, motor-driving, infrared-monitoring, wireless-charging and sounding-effect, were controlled to present the **self-designed animation** based on the principle of persistence of vision.
- **Key words:** Wireless-charging Coil & Circuit Design, Infrared Sensor, Sounding Module, Animation Presented by Rotating LED Stripe.

Omni-Motion, Bluetooth-control and Self-Reloading Automatic Catapult | *Team Leader* Spring 2022

- The **kinematic model** of the 4 omni-wheel motion was analyzed to achieve the **omni-direction control**. Remote operation was achieved using the **Bluetooth** device and **one self-designed android app**. Moreover, a self-reloading mechatronics device was developed by **3D printing, laser cutting and circuit design** technologies.
- **Key words:** Omni-motion UGV Design and Manufacturing, Bluetooth Module & Android App, Self-reloading Mechanism, Lever-Spring-Motor Shooting Mechanism.

Machine Learning & IMU Based Classifier on Ping-Pong Players' Motion | *Team Leader* Fall 2021

- **Neural network** and **decision tree** classifiers were ensembled to distinguish the motion of forehand drive and backhand stroke of a Ping-Pong player based on the inertial data. Moreover, **One-class SVM** and **Local outlier factor** were employed to detect wrong motions during training which may bring damage to the player's wrist.
- **Key words:** Inertial Sensor, Classifier: Neural Network & Decision Tree, Fault Detection: One-class SVM & Local Outlier Factor, Ping-Pong Training Monitoring.

Selected Awards & Honors

Mathematical Contest in Modeling 05/2023
Honorable Mention (Second-Class Award), Top 30%

Alibaba Cloud Programming Contest in SCUT 03/2023
Third-Class Award, Top 15%

Undergraduate Internship Scholarship, China Scholarship Council & University of Alberta 08/2022
Only 1 in South China University of Technology and total 9 in China

National Contest on Micro Sensing and Intelligent Technology 10/2021
National First Prize & Excellent Defense, Top 4%

South China University of Technology Student Scholarship Freshman Year
Third-Class University Scholarship, 7/55

Other-Research-activities

Journalist Volunteer for School Invited Academic Speeches 03/2023-Present
I write 5-minute reading summary news of academic speeches for School Social Media Public Account

Student Memberships of many famous academic research communities 2022-Present
Student memberships of IEEE CSS, RAS, and virtual academic seminars hosted by CMU and UoT

Skills

Languages: Chinese (Native), English (Fluent)
Programming: MATLAB & Simulink, Python, C, C++, R
Others: SolidWorks, CAD, Embedded System Development, Photo & Video Editing, LaTeX & Markdown