

①

Tutorial Sheet 7 - EE211

$$\underline{\text{Q1 (i)}} \quad \frac{1+2j}{2-j} = \frac{\sqrt{5} \angle \tan^{-1}(2)}{\sqrt{5} \angle \tan^{-1}(-\frac{1}{2})} \Rightarrow 1 \angle (\tan^{-1}(2) - \tan^{-1}(-\frac{1}{2}))$$

$$\Rightarrow \underline{\underline{1 \angle 90^\circ}}$$

$$\underline{\text{OR}} \quad 1 \cdot \cos(90^\circ) + j \cdot 1 \cdot \sin(90^\circ) \Rightarrow 0 + j \Rightarrow \underline{\underline{j}}$$

$$\underline{\text{Q1 (ii)}} \quad \frac{j(1-3j)}{(3-2j)(5+4j)} \Rightarrow \frac{1 \sqrt{10}}{\sqrt{13} \sqrt{41}} \angle (90^\circ + \tan^{-1}(-3) - \tan^{-1}(-\frac{2}{3}) - \tan^{-1}(\frac{4}{5}))$$

$$\Rightarrow \underline{\underline{0.137 \angle 13.47^\circ}}$$

$$\underline{\text{OR}} \quad \underline{\underline{0.133 + 0.032j}}$$

$$\underline{\text{Q2 (i)}} \quad G(s) = \frac{k}{(s+1)(s+2)}, \quad H(s) = 1, \quad k=1$$

$$s \rightarrow j\omega \Rightarrow GH(j\omega) = \frac{1}{(1+j\omega)(2+j\omega)}$$

$$= \frac{1 \angle 0^\circ}{\sqrt{1+\omega^2} \angle \tan^{-1}(\omega) \sqrt{4+\omega^2} \angle \tan^{-1}(\frac{\omega}{2})}$$

$$\therefore GH(j\omega) = \frac{1}{\sqrt{1+\omega^2} \sqrt{4+\omega^2}} \angle (-\tan^{-1}(\omega) - \tan^{-1}(\frac{\omega}{2}))$$

$$\cdot \omega = 0 \Rightarrow |GH(j0)| = \frac{1}{(1)(2)} \Rightarrow \frac{1}{2}$$

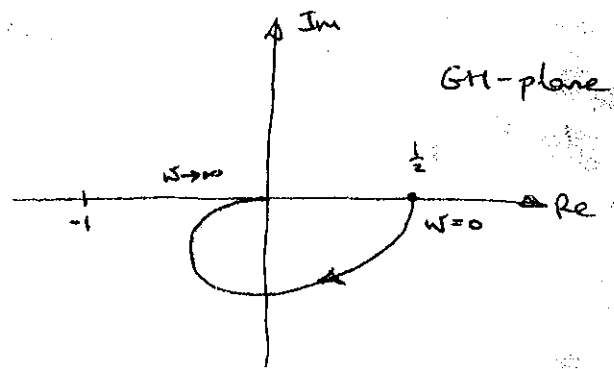
$$\angle GH(j0) = 0^\circ$$

$$\cdot \omega \rightarrow \infty \Rightarrow |GH(j\infty)| = \frac{1}{\omega^2} = 0$$

$$\angle GH(j\omega) = -2 \tan^{-1}(\infty) = -180^\circ$$

Q2 (i) cont.

Hence Nyquist sketch:



System is closed-loop stable $\forall k$

(ii)

$$G(s) = \frac{k(s+3)}{(s+1)(s+2)}, \quad H(s)=1, \quad k=1$$

$$\therefore GH(j\omega) = \frac{1 \cdot (3+j\omega)}{(1+j\omega)(2+j\omega)} \Rightarrow \frac{1 \angle 0^\circ \sqrt{9+\omega^2} \angle \tan^{-1}(\frac{\omega}{3})}{\sqrt{1+\omega^2} \angle \tan^{-1}(\omega) \sqrt{4+\omega^2} \angle \tan^{-1}(\frac{\omega}{2})}$$

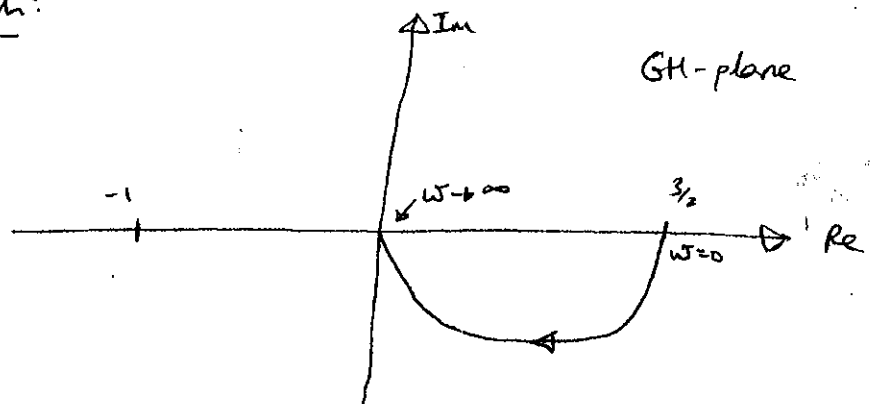
$$\Rightarrow GH(j\omega) = \frac{\sqrt{9+\omega^2}}{\sqrt{1+\omega^2} \sqrt{4+\omega^2}} \angle \tan^{-1}(\frac{\omega}{3}) - \tan^{-1}(\omega) - \tan^{-1}(\frac{\omega}{2})$$

$$\cdot \omega=0 \Rightarrow GH(j0) = \frac{3}{(1)(2)} \angle 0^\circ \Rightarrow \frac{3}{2} \angle 0^\circ$$

$$\cdot \omega \rightarrow \infty \Rightarrow GH(j\infty) = \frac{1}{\omega} \angle 90^\circ - 90^\circ - 90^\circ \Rightarrow \frac{1}{\omega} \angle -90^\circ$$

as $\omega \rightarrow \infty \Rightarrow 0 \angle -90^\circ$

Nyquist sketch:



System is closed-loop stable $\forall k$

(3)

Q3

$$GH(s) = \frac{27k}{(s+3)^2} \quad , k=1$$

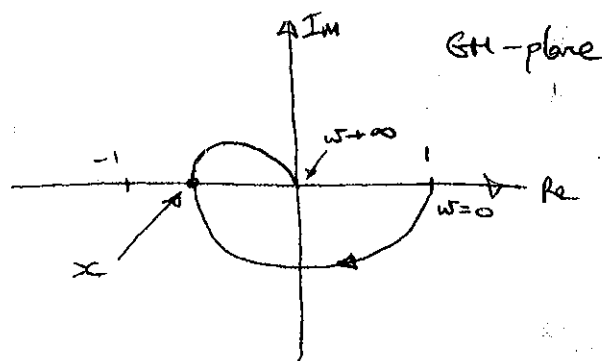
$$GH(j\omega) = \frac{27}{(3+j\omega)^2} = \frac{27 \angle 0^\circ}{(\sqrt{\omega^2+3^2})^2 \angle 3 \tan^{-1}(\frac{\omega}{3})}$$

$$\Rightarrow \frac{27}{(\sqrt{\omega^2+3^2})^2} \angle -3 \tan^{-1}(\frac{\omega}{3})$$

$$\bullet \omega=0 \Rightarrow GH(j0) = 1 \angle 0^\circ$$

$$\bullet \omega \rightarrow \infty \Rightarrow GH(j\infty) = 0 \angle -3 \cdot 90^\circ \Rightarrow 0 \angle -270^\circ$$

Nyquist sketch:



• If $x < -1$, system is stable!

$$\bullet \underline{\text{GAIN MARGIN}} = \frac{1}{x} \quad \text{where } x = |GH(j\omega)|_{\angle GH(j\omega) = -180^\circ}$$

$$\bullet \angle GH(j\omega) = -180^\circ = -3 \tan^{-1}(\frac{\omega}{3})$$

$$\Rightarrow 60^\circ = \tan^{-1}(\frac{\omega}{3}) \Rightarrow \omega = 3 \cdot \tan 60^\circ$$

$$\Rightarrow \underline{\underline{\omega = 5.196}}$$

$$\bullet |GH(j\omega)|_{\omega=5.196} = \frac{27}{(\sqrt{\omega^2+3^2})^2} \Big|_{\omega=5.196} \Rightarrow \frac{1}{8} (= 0.125)$$

$$\therefore \underline{\underline{\text{GAIN MARGIN}}} = \frac{1}{\frac{1}{8}} = \underline{\underline{8}} \quad (\pm 18\text{dB})$$

④

Q4 (i) $G(s) = \frac{k}{(s+1)(s+2)}$, $H(s) = \frac{1}{s+3}$ $k=10, 40, 100$

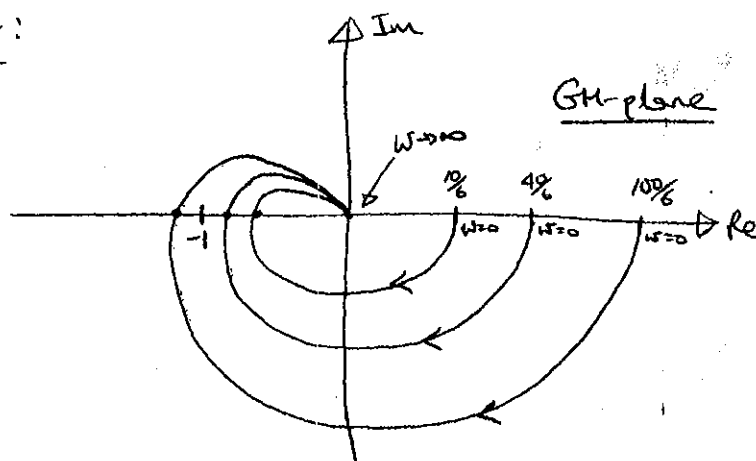
$$GH(j\omega) = \frac{k}{(1+j\omega)(2+j\omega)(3+j\omega)} = \frac{k \angle 0^\circ}{\sqrt{1+\omega^2} \angle \tan^{-1}(\omega) \sqrt{4+\omega^2} \angle \tan^{-1}(\omega/2) \sqrt{9+\omega^2} \angle \tan^{-1}(\omega/3)}$$

$$\Rightarrow \frac{k}{\sqrt{1+\omega^2} \sqrt{4+\omega^2} \sqrt{9+\omega^2}} \angle -\tan^{-1}(\omega) - \tan^{-1}(\omega/2) - \tan^{-1}(\omega/3)$$

• $\omega=0 \Rightarrow \frac{k}{1 \cdot 2 \cdot 3} \angle 0^\circ \Rightarrow \frac{k}{6} \angle 0^\circ$

• $\omega \rightarrow \infty \Rightarrow \frac{k}{\infty} \angle -3 \cdot 90^\circ \Rightarrow 0 \angle -270^\circ$

\therefore Sketch of Nyquist Plot:



(ii) Crosses negative real axis when $\angle GH(j\omega) = -180^\circ$

i.e. $-180^\circ = -\tan^{-1}(\omega) - \tan^{-1}(\omega/2) - \tan^{-1}(\omega/3)$

@ $\omega = \sqrt{11}$ gives $-179.99... \approx -180^\circ$

\therefore Nyquist plot crosses negative real axis @ $\omega = \sqrt{11}$ QED



(5)

Q4 (ii) cont. $GM = \frac{1}{|GH(j\omega)|} \Big|_{\omega=\sqrt{11}}$

$$\Rightarrow \frac{1}{\frac{k}{\sqrt{1+\omega^2}\sqrt{4+\omega^2}\sqrt{9+\omega^2}}} \Big|_{\omega=\sqrt{11}} \Rightarrow \frac{\sqrt{1+\omega^2}\sqrt{4+\omega^2}\sqrt{9+\omega^2}}{k} \Big|_{\omega=\sqrt{11}}$$

$$\Rightarrow \frac{\sqrt{12}\sqrt{15}\sqrt{20}}{k} \Rightarrow \frac{60}{k}$$

• For $k=10, 40, 100$

$$GM = \underbrace{6, 1.5 \text{ and } 0.6}_{\substack{\text{Stable as} \\ \underline{GM > 1}}} \quad \underbrace{\hspace{1cm}}_{\substack{\text{Unstable as } \underline{GM < 1}}}$$

Q4 (iii) $|GH(j\omega)| = \frac{k}{\sqrt{1+\omega^2}\sqrt{4+\omega^2}\sqrt{9+\omega^2}}$

• $k=10, \omega=1 \Rightarrow \frac{10}{\sqrt{2}\sqrt{5}\sqrt{10}} = \underline{1}$ QED

• $k=40, \omega=2.73 \Rightarrow \frac{40}{\sqrt{8.4529}\sqrt{11.4529}\sqrt{16.4529}} = \underline{1}$ QED

• $k=100, \omega=4.14 \Rightarrow 0.9988 \approx \underline{1}$ QED

$$PM = 180^\circ + \angle GH(j\omega) \Big|_{\omega=1, 2.73, 4.14}$$

$$\Rightarrow 180^\circ - \tan^{-1}(\omega) - \tan^{-1}\left(\frac{\omega}{2}\right) - \tan^{-1}\left(\frac{\omega}{3}\right) \Big|_{\omega=1, 2.73, 4.14}$$

This gives $PM = \underline{90^\circ}, \underline{14^\circ}$ and $\underline{-14.7^\circ}$ respectively.

Stable as $PM > 0^\circ$ Unstable as $PM < 0^\circ$

(6)

Q5(i)

$$GH(s) = \frac{1}{(s+1)(s+2)}$$

$$\therefore GH(j\omega) = \frac{1}{(j\omega+1)(j\omega+2)} = \frac{1}{(1+j\omega) \cdot 2(1+j\omega/2)}$$

$$\Rightarrow \frac{1}{1+j\omega} \cdot \frac{1}{1+j\omega/2} \cdot \frac{1}{2} \quad \underline{20\log_{10}(\frac{1}{2}) = -6\text{dB}}$$

- See Bode Plot $GH(j\omega)$ - Q5(i) on Page 7

- System is closed-loop stable as neither the 0dB line nor the -180° line is crossed (i.e. GM = PM = Infinite!)

(Note: an infinite PM effectively means $PM = 180^\circ$!)

$$\underline{\underline{Q5(ii)}} \quad GH(s) = \frac{k(s+3)}{(s+1)(s+2)}, \quad k=1$$

$$\therefore GH(j\omega) = \frac{1}{1+j\omega} \cdot \frac{1}{1+j\omega/2} \cdot \frac{1}{2} \cdot \underbrace{3 \cdot (1+j\omega/3)}$$

↗
 Can add this to part (i)
 to get new plot

- See Bode Plot $GH(j\omega)$ - Q5(ii) on Page 7

- System is closed-loop stable as $GM = \text{Inf}$ and $PM \approx 120^\circ$

[Note: MATLAB gives $PM = 127^\circ$ @ $\omega = 1 \text{ rad/sec}$]

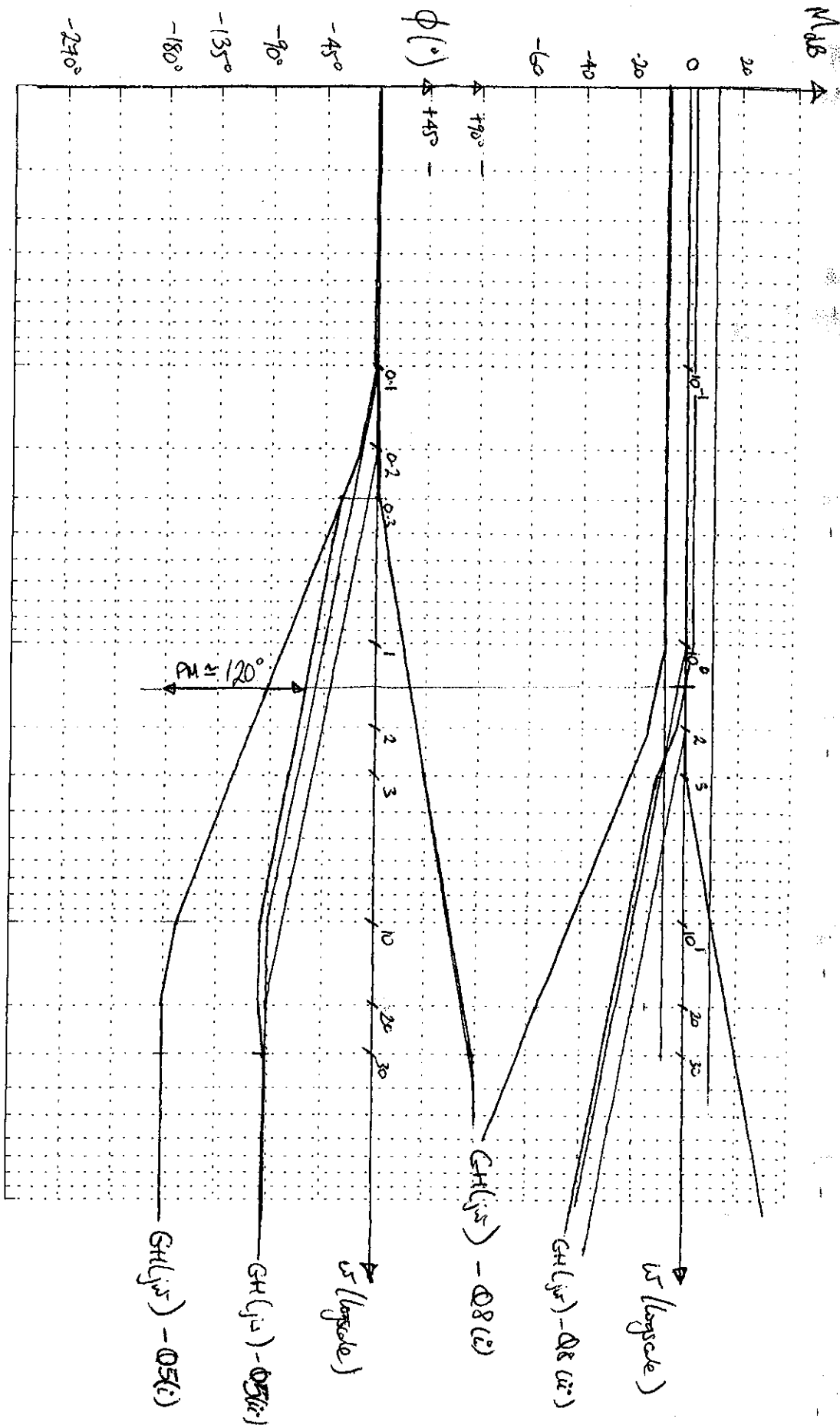


⑦

Q5 (i), (ii)

(i) $G_H(s) = \frac{1}{1+s} \cdot \frac{1}{1+s^{1/2}} \cdot \frac{1}{2}$

$20 \log_{10}(0.5) = \underline{\underline{-6 \text{ dB}}}$

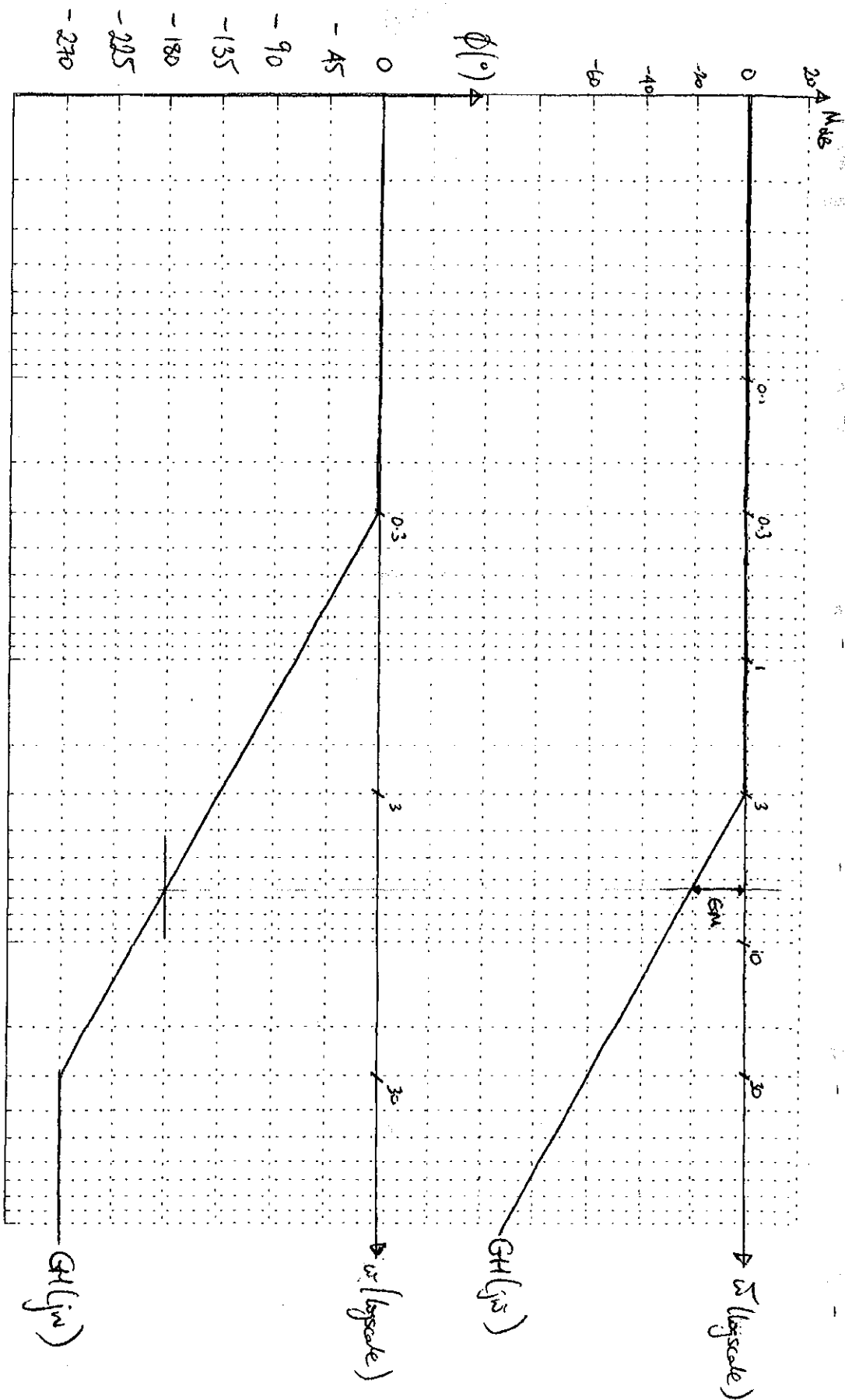


(ii) $\frac{1}{1+s} \cdot \frac{1}{1+s^{1/2}} \cdot \frac{1}{2} \cdot 3 \cdot (1+s^{1/3})$ $20 \log_{10}(3) = 9.54 \text{ dB}$

Q8

Q8

$$GH(j\omega) = \frac{27}{(j\omega + 3)^3} = \frac{27}{3^3 (1 + j\omega/3)^3} \Rightarrow \frac{1}{(1 + j\omega/3)^3}$$



$PM = 180^\circ$, $GM = 20dB$ [Analytically result is 180°]

⑥

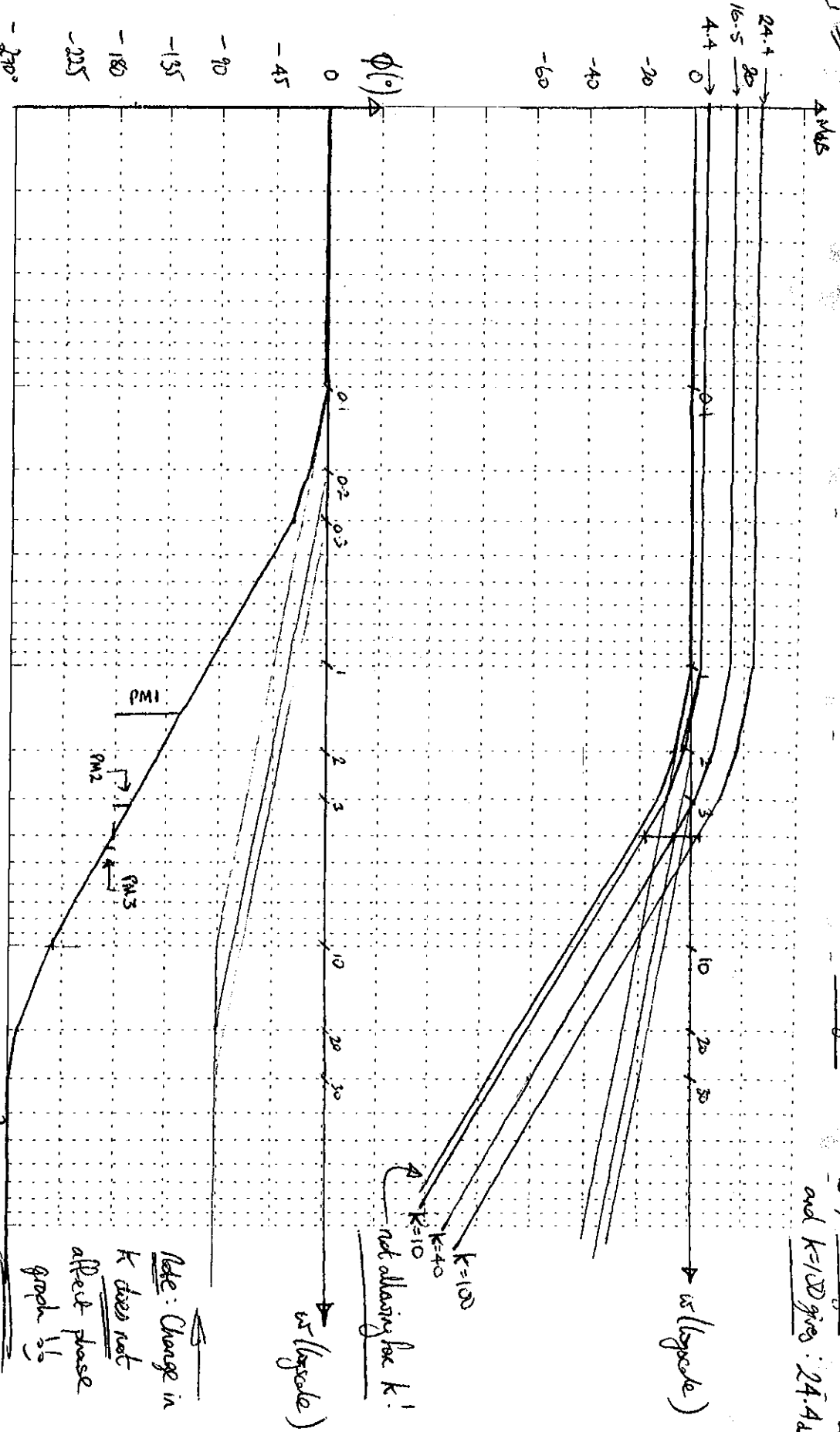
Q7

(i), (ii)

$$GH(j\omega) = \frac{k}{(1+j\omega)(2+j\omega)(3+j\omega)} \Rightarrow \frac{k}{1+j\omega} \cdot \frac{k}{1+j\omega} \cdot \frac{k}{1+j\omega} \cdot \frac{k}{\omega}$$

$$\angle GH(j\omega) = -15.5648 \text{ (} k=1 \text{)}$$

$k=10$ gives: $4-4.448$, $k=40$ gives: $16-5.48$
and $k=100$ gives: 24.448



not allowing for k !

Note: Change in k does not affect phase graph

(ii)

$k=10$: $\phi_M = 18.48$, $\phi_u = 55^\circ$
 $k=40$: $\phi_M = 5.48$, $\phi_u = 12^\circ$
 $k=100$: $\phi_M = -3.48$, $\phi_u = -8^\circ$

STABLE

UNSTABLE

NOTE: (1) Asymptotic Bode Plots
(2) IMAGINARY SECTIONS

\therefore Gross Approximations

$\angle GH(j\omega) (A_k)$