#### CS 162FZ: Introduction to Computer Science II

Lecture 10

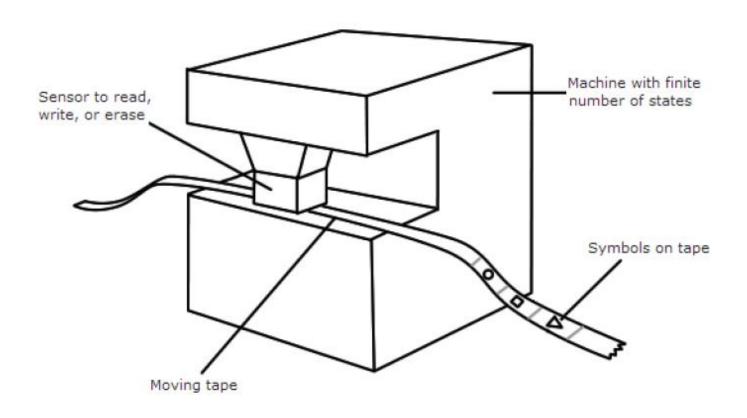
**Turing Machines** 

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#### Introduction

- A Turing Machine is a theoretical (universal) computer.
- It is a mathematical model of computation that can be used to simulate any computer algorithm, no matter how complicated it is.
- The Turing machine was invented in 1936 by British Computer Scientist Alan Turing.







- A Turing Machine (TM) is an idealised computing device consisting of a read/write head with a paper tape passing through it.
- The tape is of unbounded length.
- The tape is divided into squares, each square bearing a single symbol - '0' or '1', for example.
- The tape acts as the machine's general purpose storage medium, serving both as the means of input and output and also as a working memory for storing the results of intermediate steps of the computation
- The machine needs to keep **track of the previous state** it was in when it moves to a new state.



- There must be a finite number of symbols used in the alphabet that the Turing machine can recognise.
- The read/write head is programmable.
- To compute with the device, you program it, write the input on the tape, place the head over the square containing the leftmost input symbol, and set the machine in motion.
- Once the computation is completed, the machine will come to a halt with the head positioned over the square containing the leftmost symbol of the output (or elsewhere if so programmed).



There are just **six types of fundamental operation** that a Turing machine performs in the course of a computation. These are to:

- read the symbol that the head is currently over
- write a symbol on the square the head is currently over it will need to clear the symbol currently here, if any
- move the tape left one position
- move the tape right one position
- change state
- halt



- A program or 'instruction table' for a Turing machine is a finite collection of instructions, each calling for certain operations to be performed if certain conditions are met.
- Every instruction is of the form:

If the current state is *n* and the symbol under the head is *x*, then write *y* on the square under the head, go to state *m*, and move one square **left or right** 



# **Example of Instruction Table**

An example of one such table might be:

Current State	Current Symbol	Print Symbol	Move Tape	Next State
а	1	1	L	В
а	0	*	R	S
b	1	0	R	А



### **Example of Instruction Table**

- There are three special states: start state, accept state and reject state.
- The Turing Machine computes until it produces an output:
- It either accepts or rejects by entering designated halt states.
- If it never enters an accepting or rejecting state the Turing Machine goes on forever, never halting.

Current State	Current Symbol	Print Symbol	Move Tape	Next State
a	1	1	L	В
a	0	*	R	S
b	1	0	R	А



 Describe a TM M1 that multiplies an integer number by 10. If the input on the tape is:

The output should be:

- The alphabet of this TM is:  $\Gamma = \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9, \Delta\}$  where  $\Delta$  is the empty symbol.
- The input alphabet (what the TM can write on the tape) is:  $\Sigma = \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9\}$ .



 The instruction table for this TM might be:

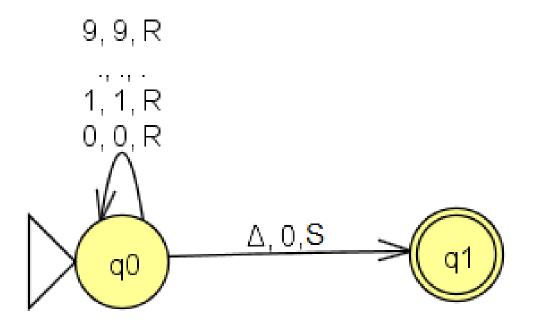
Current	Current	Print	Move	Next
State	Symbol	Symbol	Tape	State
<b>q</b> <sub>0</sub>	0	0	R	<b>q</b> <sub>0</sub>
<b>q</b> <sub>0</sub>	1	1	R	<b>q</b> <sub>0</sub>
<b>q</b> <sub>0</sub>	2	2	R	<b>q</b> <sub>0</sub>
<b>q</b> <sub>0</sub>	3	3	R	<b>q</b> <sub>0</sub>
<b>q</b> 0	4	4	R	<b>q</b> 0
<b>q</b> <sub>0</sub>	5	5	R	<b>q</b> <sub>0</sub>
<b>q</b> <sub>0</sub>	6	6	R	<b>q</b> <sub>0</sub>
<b>q</b> <sub>0</sub>	7	7	R	<b>q</b> <sub>0</sub>
<b>q</b> <sub>0</sub>	8	8	R	<b>q</b> <sub>0</sub>
<b>q</b> <sub>0</sub>	9	9	R	<b>q</b> <sub>0</sub>
<b>q</b> <sub>0</sub>	Δ	0	S	$q_1$



- q0 is the starting state for this TM.
- We will stay in this state reading symbols and moving right until we come across the first empty symbol Δ.
- Once we encounter this, we want to change this  $\Delta$  symbol to a 0 to represent multiplying the number by 10
- We move to state q1 which is the accepting state for this TM and halt (represented by the movement S (Stop)).



The graphical representation of this TM is:





- Design a TM that will perform the unary addition of two numbers. Unary representation can be defined as follows: 1 = 1, 2= 11, 3 = 111, 4 = 1111, 5 = 1111, ...
- Unary represents a number x by using x 1's written as 1<sup>x</sup>.
- The unary addition of 2(11) and 4 (1111) is:

$$11 + 1111 = 1111111$$
 (Equivalent to:  $1^2 + 1^4 = 1^6$ )

A sample input for the TM is:

1	+	1	1	Λ	
 _	•	_	•		

The output should be:

1 1	1	Δ	Δ	
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- What is the alphabet? What is the input alphabet?
   What is the instruction table? Can you design the graphical representation?
- The simplest way to solve this is to find the + symbol and change it to a 1.
- We must then move to the last 1 to the right and replace it with a  $\Delta$ .
- The alphabet is:  $\Gamma = \{1, +, \Delta\}$
- The input alphabet (what the TM can write on the tape) is:  $\Sigma = \{1, \Delta\}$



- Let us assume that we start at the first one of the first number to the left.
- Let us assume that this is state q0 we will stay in q0
  while we keep encountering 1's, writing 1's to the tape
  and moving right with each step.
- When we encounter the + symbol we need to first change this symbol from a + to a 1, move right to the next symbol and move to state q1.
- We move to this new state as we no longer need to worry about the first number or the + symbol.



- We now know we are at the start of the second number.
- We will keep reading 1's, writing 1's to the tape and moving right (all the time staying in q1) until we encounter a Δ symbol.
- When we encounter the  $\Delta$  symbol we write a  $\Delta$  to the tape and move back **left** we need to get to the last 1 to remove it from the tape.
- We will change state again to q2.
- We now know that we should encounter a 1 which needs to be overwritten with a Δ.
- This is the unary addition complete and we move to state q3 which is the **halting state**.

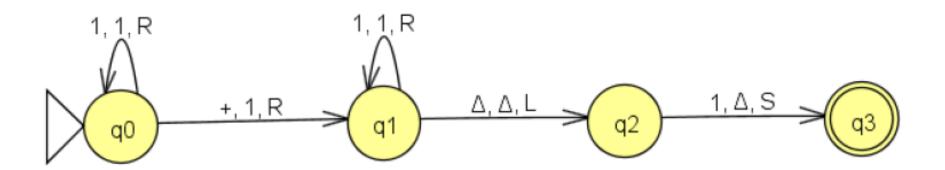


• The instruction table for this TM might be:

Current	Current	Print	Move	Next
State	Symbol	Symbol	Tape	State
<b>q</b> <sub>0</sub>	1	1	R	<b>q</b> 0
<b>q</b> <sub>0</sub>	+	1	R	q <sub>1</sub>
<b>q</b> 1	1	1	R	<b>q</b> 1
<b>q</b> <sub>1</sub>	Δ	Δ	L	q <sub>2</sub>
q <sub>2</sub>	1	Δ	S	<b>q</b> <sub>3</sub>



The graphical representation of this TM is:





#### **Church-Turing Thesis**

Any real-world computer can be simulated by a Turing machine.

- Proposed independently by Alonzo Church and Alan Turing.
- "Everything computable is computable by a Turing Machine".



- Turing Machine: Summary
   A Turing Machine (TM) is a theoretical (universal) computer. It is a mathematical model of computation that can be used to simulate any computer algorithm
- There are six types of fundamental operation that a TM performs in the course of a computation.
- These are to:
  - Read
  - Write
  - Move the tape to one left position
  - Move the tape to one right position
  - Change state
  - Halt
- Every TM can be represented by an 'instruction table' which is a finite collection of operating instructions



### **Turing Machine: Summary**

- There are three special states of a TM: start state, accept state and reject state
- The TM computes until it produces an output: it either accepts or rejects by entering designated halt states.
- If a TM never enters an accepting or rejecting state the TM goes on forever, never halting.
- Any real-world computer can be simulated by a Turing machine

