

Tutorial 6 - Solutions

1. Given an LTI system with frequency response

$$H(\omega) = \frac{1}{1 + j\omega} \quad (1)$$

Find the response to the input signal $x(t) = |\sin(t)|$.

Solution: First note that $x(t)$ is a periodic signal with period $T_0 = \pi$. The fundamental frequency is thus $f_0 = 1/\pi$. The important step to find the output of the system is compute the Fourier series of $x(t)$. The n th coefficient of the FS of $x(t)$ is given by

$$\begin{aligned} x_n &= \frac{1}{T_0} \int_0^{T_0} x(t) e^{-j2\pi n f_0 t} dt = \frac{1}{T_0} \int_0^{T_0} \sin(t) e^{-j2\pi n f_0 t} dt \\ &= \frac{1}{2jT_0} \int_0^{T_0} (e^{jt} - e^{-jt}) e^{-j2\pi n f_0 t} dt = \frac{1}{2jT_0} \int_0^{T_0} (e^{j(1-2\pi n f_0)t} - e^{-j(1+2\pi n f_0)t}) dt \\ &= \frac{1}{2jT_0} \left[\frac{1}{j(1-2\pi n f_0)} e^{j(1-2\pi n f_0)t} \Big|_{t=0}^{t=T_0} - \frac{1}{-j(1+2\pi n f_0)} e^{-j(1+2\pi n f_0)t} \Big|_{t=0}^{t=T_0} \right] \\ &= \frac{1}{2jT_0} \left[\frac{1}{j(1-2\pi n f_0)} (e^{j(1-2\pi n f_0)T_0} - 1) + \frac{1}{j(1+2\pi n f_0)} (e^{-j(1+2\pi n f_0)T_0} - 1) \right] \\ &= -\frac{1}{jT_0} \left[\frac{1}{j(1-2\pi n f_0)} + \frac{1}{j(1+2\pi n f_0)} \right] = \frac{2}{\pi(1-4n^2)} \end{aligned} \quad (2)$$

The system output is a period signal with the FS representation given by

$$y(t) = \sum_{n=-\infty}^{\infty} y_n e^{j2\pi n f_0 t} \quad (3)$$

where

$$y_n = x_n H(2\pi n f_0) = \frac{2}{\pi(1 + j2n)(1 - 4n^2)} \quad (4)$$

2. Consider an LTI system having an impulse response $h(t) = u(t)$. Find the output signal of the system if the input signal is $x(t) = e^{-2t}u(t+2)$. Compare with the result of Q7 in Tutorial 5.

Solution: Let $Y(\omega)$ be the Fourier transform of the system output. By the convolution theorem we have

$$Y(\omega) = X(\omega)H(\omega) \quad (5)$$

where $X(\omega)$ and $H(\omega)$ are the Fourier transform of $x(t)$ and $h(t)$ respectively. Using the FT table we have

$$H(\omega) = \left(\pi \delta(\omega) + \frac{1}{j\omega} \right) \quad (6)$$

To find the FT of $x(t)$ we write $x(t) = e^4 e^{-2(t+2)} u(t+2)$. Using the FT table we know that the FT of $e^{-2t} u(t)$ is $\frac{1}{2+j\omega}$. By the time-shifting property of FT, the FT of $e^{-2(t+2)} u(t+2)$ is given by $\frac{1}{2+j\omega} e^{j2\omega}$. Thus, FT of $x(t)$ is given by

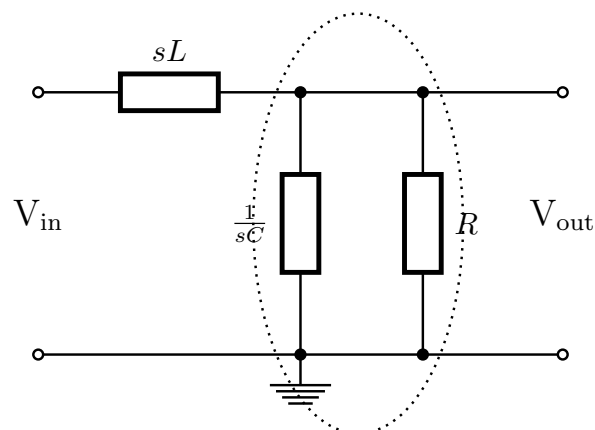
$$X(\omega) = e^4 e^{j2\omega} \frac{1}{2+j\omega} \quad (7)$$

Substitute (6) and (7), we have

$$\begin{aligned} Y(\omega) &= X(\omega)H(\omega) = e^4 (\pi\delta(\omega) + \frac{1}{j\omega}) \frac{1}{2+j\omega} e^{j2\omega} \\ &= e^4 \left(\frac{\pi}{2} \delta(\omega) + \frac{1}{j\omega(2+j\omega)} e^{j2\omega} \right) = \frac{e^4}{2} \left(\pi\delta(\omega) + \frac{1}{j\omega} - \frac{1}{(2+j\omega)} \right) e^{j2\omega} \end{aligned}$$

Taking the inverse FT of $Y(\omega)$, we have $y(t) = \frac{e^4}{2} (1 - e^{-2(t+2)}) u(t+2)$. We can see that this result is the same as what we derived in Q7 in Tutorial 5 using the convolution integral (i.e., in time domain).

3. (a) For low frequency, the inductor will act as a short circuit, meaning V_{in} is passed through the system. The opposite occurs for high frequencies. Thus the circuit is indeed a low-pass filter.
- (b) Equivalent circuit of the filter on the s -domain.



- (c) Equivalent impedance

$$Z_{RC} = \frac{R \times \frac{1}{sC}}{R + \frac{1}{sC}} = \frac{R}{sRC + 1}$$

- (d) The transfer function is

$$\begin{aligned} H(s) &= \frac{Z_{RC}}{Z_{RC} + Z_L} = \frac{\frac{R}{sRC+1}}{\frac{R}{sRC+1} + sL} = \frac{R}{sL + s^2RLC + R} \\ &= \frac{1}{s\frac{L}{R} + s^2LC + 1} \end{aligned}$$

Replace $s = j\omega$, we obtained the frequency response as

$$H(\omega) = H(s)|_{s=j\omega} = \frac{1}{1 - \omega^2 LC + \frac{j\omega L}{R}}$$

(e) The magnitude frequency response of the circuit $|H(\omega)|$ is given by

$$\begin{aligned} |H(\omega)| &= \frac{1}{\sqrt{(1 - \omega^2/\omega_0^2)^2 + (\frac{\omega L}{R})^2}} \\ &= \frac{1}{\sqrt{1 + (\omega/\omega_0)^4}} \end{aligned}$$

This is a second order low-pass filter.

4. Consider a discrete-time LTI system with the impulse response $h[n]$ given by

$$h[n] = \begin{cases} 1 & n = -1 \\ -1 & n = 0 \\ 2 & n = 1 \end{cases}$$

Determine its response $y[n]$ to the input

$$x[n] = \cos\left(\frac{\pi}{2}n\right)$$

Solution: $H(\omega) = \sum_{n=-\infty}^{\infty} h[n]e^{-j\omega n} = e^{j\omega} - 1 + 2e^{-j\omega}$. The output of the system is given by

$$y[n] = |H(\pi/2)| \cos\left(\frac{\pi}{2}n + \angle H(\pi/2)\right) \quad (8)$$

$H(\pi/2) = 2e^{-j\pi/2}$. Thus, $y[n] = \sqrt{2}\cos\left(\frac{\pi}{2}n + \frac{5\pi}{4}\right)$