Tutorb. Hanlin Cai

$$(i) \quad \dot{X} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} X + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u(t).$$

$$\begin{vmatrix} \lambda_1 & 0 \\ -\lambda & \lambda_{-2} \end{vmatrix} = 0 \Rightarrow \begin{vmatrix} \lambda_1 \\ \lambda_{-2} \end{vmatrix}$$

$$(\tilde{1}\tilde{1}) \dot{X} = \begin{bmatrix} 0 & 2 \\ -2 & -3 \end{bmatrix} \times + \begin{bmatrix} 2 \\ 1 \end{bmatrix} u(t).$$

$$\begin{vmatrix} \lambda_0 & 2 & | = 0 \\ -2 & \lambda + 3 \end{vmatrix} = 0 \Rightarrow \lambda(\lambda + 3) + 4 = 0$$

$$(\lambda + 4) + 4 = 0$$

$$(\lambda + 4) + 4 = 0$$

$$\frac{(\lambda+\psi)}{(\lambda+\psi)}$$

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$$(\tilde{1}\tilde{1}\tilde{1})$$
 $\tilde{\chi} = \begin{bmatrix} 0 & 1 \\ -1 & 5 \end{bmatrix} \times + \begin{bmatrix} 2 \\ 1 \end{bmatrix} \text{ (utt)}.$

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 \\ \\ \\ \end{array} \\

(IV)
$$\chi(k+1) = \begin{bmatrix} 0.4 & 0.8 \\ -0.4 & 0.2 \end{bmatrix}, \chi(k) + \begin{bmatrix} 0.3 \\ 1 \end{bmatrix}, u(k),$$

$$\begin{vmatrix} \lambda - 0.4 & 0.8 \\ -0.4 & \lambda - 0.2 \end{vmatrix} = 0 \implies \lambda_1 = \frac{1}{5} \quad \lambda_2 = \frac{1}{5}$$

AU | a | <1 => asymptotically stable.

(i)
$$\dot{X} = \begin{bmatrix} 1 & 0 \\ -2 & d \end{bmatrix} \times + \begin{bmatrix} \beta & \gamma & U(t) \\ 1 & \gamma & U(t) \end{bmatrix}$$

$$(2), \quad (\lambda - 1)(\lambda - 2) = 0$$

$$(\lambda), = 1$$

$$(\lambda), = 2$$

0 Because Re, $(\lambda_i) > 1$ already. Hence no matter α . β are, the system is unstable

(ii)
$$\dot{X} = \begin{bmatrix} 0 & \beta \\ -2 & -3 \end{bmatrix} \times + \begin{bmatrix} 2 \end{bmatrix} u(t)$$

$$\begin{vmatrix} \dot{\lambda} & \beta \\ -2 & \lambda + 3 \end{vmatrix} = 0 \qquad \Rightarrow \qquad \lambda^2 + 3\lambda + 2\beta = 0 \qquad \Delta = \frac{-b + \sqrt{b^2 + ac}}{2a}$$

$$\begin{vmatrix} \dot{\lambda} & \beta \\ -2 & \lambda + 3 \end{vmatrix} = 0 \qquad \Rightarrow \frac{-3 + \sqrt{9 - 8\beta}}{2a} \qquad 0$$

$$\begin{vmatrix} \dot{\lambda} & \lambda \\ \lambda & 2 \end{vmatrix} = \frac{-3 - \sqrt{9 - 8\beta}}{2a} \qquad 0$$

$$\frac{3+\sqrt{9-8\beta}}{2}$$

 λ_{2} < 0 already

O If system is asymptotically stable

then -3 + $\sqrt{9-8\beta}$ < 0 : $\beta \otimes > 0$ Q If system is marginally stable

then -3 + $\sqrt{9-8\beta}$ = 0 : $\beta = 0$

then
$$-3 + \sqrt{9-8\beta} = 0$$
 is $\beta = 0$

then B < 0

Tutor 6. $QQ (\overline{n}i) = \begin{bmatrix} p & 1 \\ -B & 2 \end{bmatrix} \times + \begin{bmatrix} 2 \\ 1 \end{bmatrix} u(t).$ $\begin{vmatrix} \lambda & 1 \\ -\beta & \lambda - \alpha \end{vmatrix} = 0 \iff \lambda(\lambda - \alpha) + \beta = 0$ $\lambda_1 = \frac{\alpha + \sqrt{\alpha^2 - 4\beta}}{2}$ $\sum_{\alpha} \lambda^2 - \alpha \lambda + \beta = 0 \qquad (\lambda_2 = \frac{\alpha}{2} + \sqrt{\alpha^2 - 4\beta})$ 1) If asymptotically stable, 52-48 >0 then $\begin{cases} x + \int \overline{z^2 + \beta} = 0 \\ x - \int \overline{z^2 - 4\beta} = 0 \end{cases} < 0$ @ If marginally stable then $\begin{cases} \alpha + \sqrt{\chi^2 - 4\beta} = 0 \implies \alpha = 0 \\ \beta = 0 \end{cases}$ But In this situation $\lambda_1 = \lambda_2 = 0 \implies unstable$ @ If unstable J (1) then & + J2 -4B >0 => <> 0 (β ∈R) (a) or & - 52-4B >0 => B>0 (deR). (3) And &=0 & B=0 0

```
Q2 (TV)
                                                                              x(k+1) = \begin{bmatrix} d-1 & 0 \\ -2 & B \end{bmatrix} x(k) + \begin{bmatrix} 3 \\ 1 \end{bmatrix} u(k)
                         sol. (λ-α+1)(λ-β) =0
                                                                              1) If asymptotically stable: 2 = 1 B < 0
                                                                       @ If marginally stable
                                                                   \begin{cases}
1) & \alpha = 1 & \beta < 0 \\
2) & \alpha < 1 & \beta = 0
\end{cases}
\begin{cases}
2) & \alpha < 1 & \beta = 0 \\
4) & \alpha = 1 & \beta = 0 \\
2) & \alpha < 1 & \beta \in R
\end{cases}
\begin{cases}
(3) & \beta > 0 & \alpha \in R
\end{cases}
                                                                                            (fit) = K&y+ B&y + My ]
                                                                                                                      \begin{cases} \dot{x}_1 = x_2 \\ \dot{y}_2 = \frac{1}{M} (ftt) - Bx_2 - Kx_1). \end{cases}
x \rightarrow y \left( \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -k & B \\ M & M \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ M \end{bmatrix} f(t).
      X \rightarrow Y
\begin{bmatrix} \dot{y}_1 \\ \dot{y}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -B & 2 \end{bmatrix} \begin{bmatrix} \dot{y}_1 \\ \dot{y}_2 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ \lambda & 2 \end{bmatrix} f(t).
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          \begin{bmatrix} K=10 & \begin{bmatrix} Z \end{bmatrix} = \begin{bmatrix} (0) \begin{bmatrix} Y \\ Y \end{bmatrix} & \begin{bmatrix} Y \\ Y \end{bmatrix} & \begin{bmatrix} X \\
                                                                                                        @ asymptotically { disco => B < 0
                                                                                                @ marginally Bo not suitable B to match it.
                                                                                             3 unstable (1) B > 0 8 B = 0
```

Tutor 6. Q4 sol (i) $0 \times_{k+1} = \begin{bmatrix} 0 & 1 \\ -7 & -1 \end{bmatrix} \times_{k} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} U_{k}$ y = [2 1] x + uk G(Z) = C(ZI-A) B. $= \frac{2}{z^{2} + 2z^{2} - 2} + \frac{2(z + 2)}{z^{2} + 0zz^{2} - 2} = \frac{zz + b}{(z^{2} + zz - 2)}$ $G(z) = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$ = 2s+30 (ii) For 0 | 8 @1 | =0 (=> 22 +28 -2 =0 0 i. RO AU (a) < 1 0 i. asymptotically stable 0 0.382 < 0 0.382 < 0 0.382 < 0i for all Rea) <0 => asymptotically

stable.