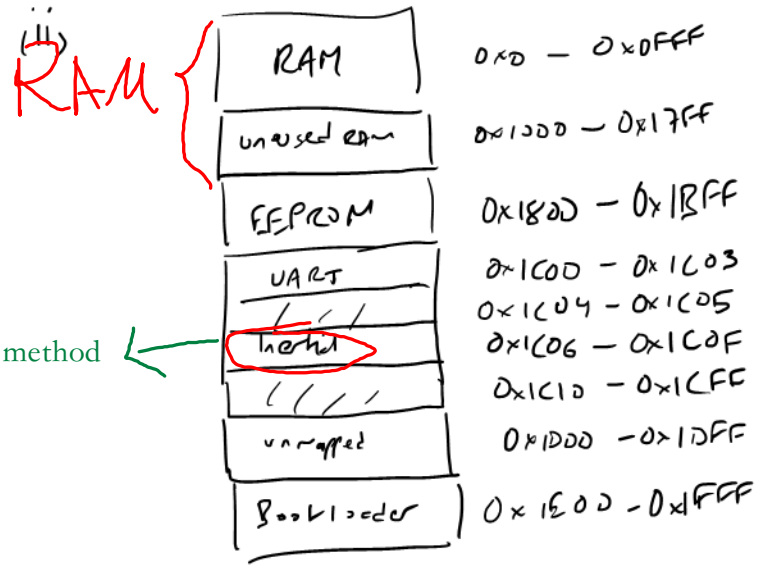
EE302 sem 1 exam 2019-2020

Q1 (c) (i) I/O range is 0x1C00 .. 0x1CFF = 0xFF ⇒ 0xFF + 1 addresses
= 256 addresses

256 ✓

(ii)



(iii) Bootloader 0x1E00 = 1 111 0000 0000 (Basic method)
0x1FFF = 1 1111 1111 1111

$\overline{BL\_ROM\_CS}$ = $(\overline{A_{12} A_{11} A_{10} A_9})$ ✓ $(A_{12} A_{11} A_{10} A_9)$

EEPROM 0x1800 = 1 1000 0000 0000 (basic method)
0x1BFF = 1 1011 1111 1111

$\overline{EEPROM\_CS}$ = $(\overline{A_{12} A_{11} \bar{A}_{10}})$ ✓ $(A_{12} A_{11} \sim A_{10})$

Inertial Sensor : 10 registers not a power of 2 ⇒ Extended Method

分2段

subrange 0x1C06 = 1 1100 0000 0110
0x1C07 = 1 1100 0000 0111

subrange1 = $A_{12} A_{11} A_{10} \bar{A}_9 \bar{A}_8 \bar{A}_7 \bar{A}_6 \bar{A}_5 \bar{A}_4 \bar{A}_3 A_2 A_1$

subrange2 : 0x1C08 = 1 1100 0000 1000
0x1C0F = 1 1100 0000 1111

= $A_{12} A_{11} A_{10} \bar{A}_9 \bar{A}_8 \bar{A}_7 \bar{A}_6 \bar{A}_5 \bar{A}_4 A_3$

$\overline{Inertial\_CS}$ = $(\overline{subrange1 + subrange2})$

~ (S1 + S2)

Assumption: (Active low chip selects)

Q1 (b) (i) 19200 — baud rate

8 — # data bits per async word

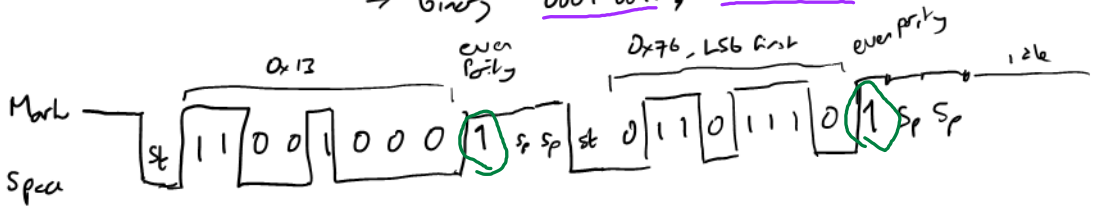
f2 — even parity

2 — # stop bits per async word

(ii) assume order of words transmitted is MS Word first, then least significant word.

Data is 0x1376 ⇒ 2 words 0x13, 0x76 13 76

⇒ binary 0001 0011, 0111 0110



(iii) Max rate for sample values

Each sample is 2 bytes data ⇒ 2 async words

Each async word is 12 bits long

baud rate was 19200 $T_{bit} = \frac{1}{19200}$

$\Rightarrow T_{word} = \frac{12 \times 1}{19200} = 625\,\mu s$

2 words $\Rightarrow T_{sample} = 2 \times 625\,\mu s = 1.25\,ms$

$F_{sample} = \frac{1}{T_{sample}} = 800$ samples/sec

Q2 (a) theory – see notes

(b) (i) bit mask 0b0101 1110 = 0x1E in hex

(ii) mask = 0x1E

oldscale = (VCON & mask) >> 1

```
// VCON      0xEB      0b 1110 1011
// mask      0x1E      0b 0001 1110
// VCON & mask         0b 0000 1010
//      >> 1           0b 0000 0101 = 0x05
// => oldscale is 0x05
```

(iii) $1.375V = scale \times V_{DD}/24 = scale \times 3.3/24$

$\Rightarrow scale = \frac{1.375 \times 24}{3.3} = 10$

$\Rightarrow$ newscale = 10 = 0xA = 0b 0000 1010

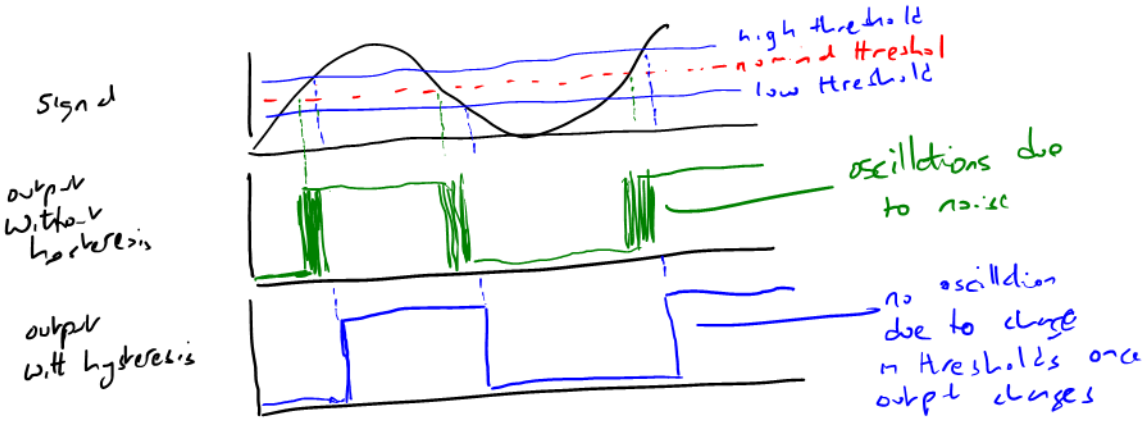
VCON = (VCON & ~mask) | (newscale << 1)

(VCON & ~mask) = tmp1 ; (newscale << 1) = tmp2

```
// VCON = 0xEB          0b1110 1011
// ~mask                0b1110 0001
// tmp1                 0b 1110 0001
// newscale  0xA        0b 0000 1010
// << 1                 0b 0001 0100
// tmp2                 0b 0001 0100
// tmp1 | tmp2 = VCON   0b 1111 0101
                        = 0x F5
```

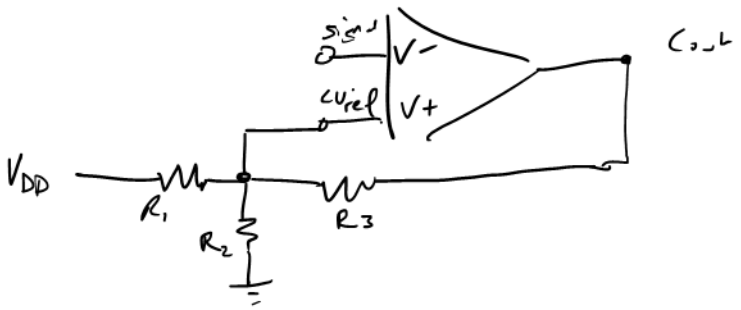
tmp1 | tmp2 bitwise OR

Q2 (c) (i)



More explanation needed – see notes

Q2 (c) (ii)



R_1 and R_2 form a basic resistor divider

R_3 acts in parallel with R_1 if Cout is high or R_2 if Cout is low.

For additional detail required, see notes

(iii) $V_{DD} = 3.3V$, $V_{SS} = 0V$, nominal threshold is 1.1V

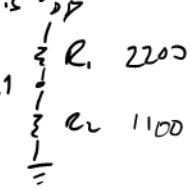
Noise is $< \pm 0.2V$ $\Rightarrow$ $V_{LOW} = 1.1 - 0.2 = 0.9V$

$V_{HIGH} = 1.1 + 0.2 = 1.3V$

Ref circuit should not use much current (eg 1mA),

so choose $R_1 + R_2 \simeq 3300\,\Omega$

$\Rightarrow R_1 \simeq 2200\,\Omega$



From notes

$$\frac{R_2}{R_1} = \frac{V_{LOW}}{V_{DD} - V_{HIGH}} = \frac{0.9}{(3.3 - 1.3)} = 0.45 \Rightarrow R_2 = 0.45 \times 2200 = 990\,\Omega$$

$$\frac{R_3}{R_1} = \frac{V_{LOW}}{V_{HIGH} - V_{LOW}} = \frac{0.9}{1.3 - 0.9} = 2.25 \Rightarrow R_3 = 2.25 \times 2200 = 4950\,\Omega$$

Q3 (a)

```
updateLED():
    const FLASH_DURATION_TICKS = 6
    static ledOnCounter = 0

    if gFlashNeeded is TRUE
        set ledOnCounter = FLASH_DURATION_TICKS

    if ledOnCounter > 0
        set LED to HIGH  // ON
        decrement ledOnCounter
    else
        set LED to LOW   // off
```

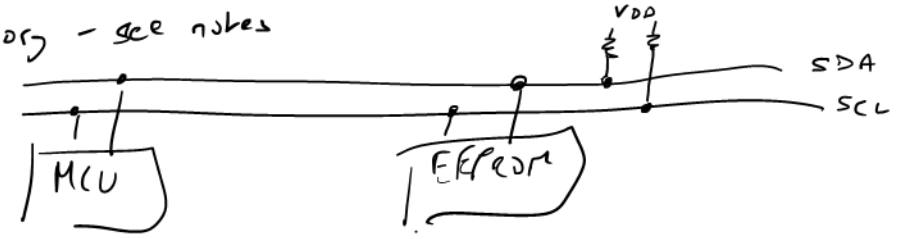
(b) (i) Theory - see notes

(ii) When the ISR runs

- it first checks ADCIF and finds ADC interrupt is present so it would handle ADC interrupt and clear the flag to show we've finished with this interrupt. At this point the ISR returns.
- since there is still an active interrupt (the USART transmit) the ISR would be called again. We would check ADCIF (not active) PORTIF (not active) and finally TXIF which is active. We would handle USART Tx interrupt and clear it and ISR returns

(c) (i) Theory - see notes

(ii)



(iii) Assuming addr at location 0x470 and 0x471

// set the starting location

Start | I2C Addr | W | ACK

0x4 ACK

0x70 ACK

Stop

// read the addr

Start | I2C Addr | R | ACK

0x81 ACK

0x82 NACK

Stop

——— = controller

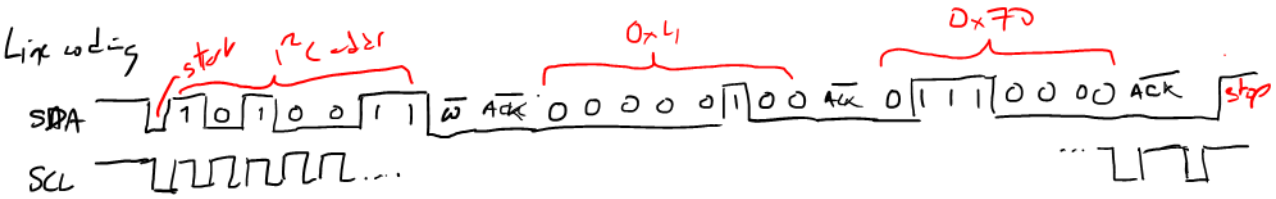
no red line = peripheral

Q3 (c) (iv)

I2C addr = 0x53 = 0b 101 0011 (7 bit addr)

0x470 = 0b 0000 0100 0b 0111 0000 (2 byte addr)

Line coding



Q4 (a) Mainly theory - see notes

(b) (i) Theory - see notes

(ii) $f_{osc} = 10\,MHz$, $f_{src} = \frac{f_{osc}}{4} \Rightarrow T_{src} = \frac{4}{10\,MHz} = 0.4\,\mu s$

1:1 Timeout $T_{src} \times pre \times 2^{16} \times post$

$0.4\,\mu s \times 1 \times 2^{16} \times 1 = 26.2144\,ms$

Resolution $T_{src} \times pre = 0.4\,\mu s$

1:8 Timeout $0.4 \times 8 \times 2^{16} \times 1 = 209.7152\,ms$

resolution $0.4 \times 8 = 3.2\,ms$

(iii) Fc 18 Hz rate $\Rightarrow T = \frac{1}{18} = 55.555\dot{5}\,ms$

Allow 3μs for interrupt and reset $\Rightarrow T_{intr} = 55.552\,ms$

$$\text{desired prescale} = \frac{T_{intr}}{(T_{src} \times 2^{16})} = \frac{55\,552\,\mu s}{0.4\,\mu s \times 65536} = 2.119$$

$\Rightarrow$ required prescale is 1:4

$$N_{intr} = round\left(\frac{T_{intr}}{T_{src} \times pre}\right) = round\left(\frac{55552}{0.4 \times 4}\right) = 34720$$

$\Rightarrow$ Timer1 reg must be set to $2^{16} - 34720 = 30816$

(iv) Timeout will occur in $8 + (4720 \times 0.4 \times 4) = 55555\ \mu s$

Desired period was really $55555.5\dot{5}\ \mu s$

Percentage error is $100 \times \left(\frac{55555.5\dot{5} - 55555}{55555.5\dot{5}}\right) \simeq 0.00099\ \%$

Precise timing is not possible due to the limited resolution of the clock after prescaling. ($1.6\mu s > 0.5\dot{5}\mu s$ we need).