

# Gadgetless Lifting Beats Round Elimination: Improved Lower Bounds for Pointer Chasing

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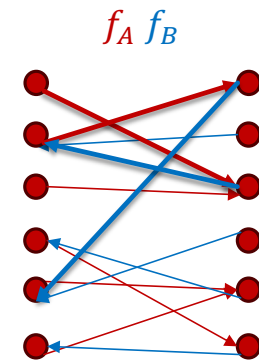
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# The pointer chasing problem

# The pointer chasing problem

Pointer chasing is a natural problem where many rounds of communication is useful.

- ▶ Alice holds  $f_A \in [n]^n$ , Bob hold  $f_B \in [n]^n$ .
- ▶ The  $k$  step pointer chasing function  $PC_k: [n]^n \times [n]^n \rightarrow \{0,1\}$ 
  - ▶  $pt_0 := 1$
  - ▶ for odd  $r$ 's,  $pt_r := f_A(pt_{r-1})$
  - ▶ for even  $r$ 's,  $pt_r := f_B(pt_{r-1})$
  - ▶  $PC_k(f_A, f_B) := pt_k \bmod 2$ .



There is a  $k$ -round protocol for  $PC_k$  with  $O(k \log n)$  communication bits.

# The pointer chasing problem

**Theorem** (Yehudayoff 2016). Any randomized  $(k - 1)$ -round protocol for  $PC_k$  that is correct with probability 0.9 requires  $\Omega\left(\frac{n}{k} - k \log n\right)$  bits of communication. **Round Elimination**

The  $(k \log n)$  loss is associated with many round elimination- based analysis [NW91, Kla00, KNTSZ07, FKM+09, Yeh20].

In this paper, we avoid the  $k \log n$  loss via the gadgetless lifting.

**This work**  $\Omega\left(\frac{n}{k} + k\right)$  lower bound via a completely different proof

Pointer chasing has wide applications in circuit lower bounds [NW91, KPPY84] , distributed computation [NDSP11]

streaming algorithms [FKM+09, GO16, ACK19] property testing [CG18] differential privacy [JMR20] learning [CPP22]

transformer architecture [PNP24].

# Gadgetless Lifting

# Query to communication lifting theorems

- ▶ Let  $g: \{0, 1\}^q \times \{0, 1\}^q \rightarrow \{0, 1\}$  be a **gadget** function with low discrepancy
- ▶ Consider functions of the form  $f \circ g^n$  for some outer function  $f: \{0, 1\}^n \rightarrow \{0, 1\}$ ,  
 $(f \circ g^n)((x_1, y_1), \dots, (x_n, y_n)) := f(g(x_1, y_1), \dots, g(x_n, y_n))$ .

$CC(f \circ g^n) = \Omega(Q(f) \cdot q)$ , where  $Q(f)$  denotes the query complexity of  $f$ .

Lifting theorems show that the query type protocols are optimal for  $f \circ g^n$  !

- ▶ Not all functions can be written as  $f \circ g^n$ . **Pointer chasing is not a composed function**
- ▶ Often need  $q = \Omega(n)$  : Proving lift theorems for constant gadget size  $q$  is very hard and has many implications [RM97, WYY17, CKLM19, GPW18, CFK+19, LMM+20]

# A simple class of $k - 1$ rounds protocols for pointer chasing

- ▶ Alice choose a subset  $I \subseteq [n]$  of size  $S := 10 \frac{n}{k}$  uniformly at random, and then send  $f_A(I)$  to Bob.
- ▶ Alice and Bob run the naïve ( $k$  rounds) protocol, but they can skip one round if the pointer falls into  $I$ .
- ▶ If the skip round never happens, Alice and Bob simply abort at the last round.
- ▶ The skip round event happen **with high probability**.

This is a  $(k - 1)$ –rounds randomized protocol for  $PC_k$  with  $\tilde{\Theta}\left(\frac{n}{k} + k\right)$  communication bits.

This protocol is not a query type protocol but Alice and Bob only send values of some coordinate to each other ! **How to prove this protocol is optimal ?**

# Gadgetless lifting

- ▶ Identify a simple class of protocols  $\mathcal{K}$ .
- ▶ Prove lower bound for these simple protocols.
- ▶ Prove that every protocol can be “simulated” by a combination of simple protocols.

$$CC(f) := \min_{\Pi: \Pi \text{ computes } f} CC(\Pi) \approx \min_{\Pi \in \mathcal{K}} CC(\Pi) =: CC_{\mathcal{K}}(\Pi).$$

- ▶ For pointer chasing,  $\mathcal{K}$  is the set of protocols where Alice and Bob only send values of some coordinate to each other.



# Decomposition and Sampling Process

# Density restoring partition

**Def.** For a random variable  $X$ , its min-entropy is defined as  $\mathbf{H}_\infty(X) := \log \frac{1}{\max_x \Pr[X=x]}$ .

**Def.** We say a random variable  $X$  over  $[n]^J$  is  $\gamma$ -dense if  $\mathbf{H}_\infty(X(I)) \geq \gamma \log n |I|$  for all  $I \subseteq J$ .

For a set  $X$ ,  $\mathbf{X} :=$  uniform distribution over  $X$ .

**Lemma 1** ([GPW17]). For any  $X \subseteq [n]^J$ , there is a partition  $X = X^1 \cup \dots \cup X^r$  and each  $X^i$  is associated with a set  $I_i$  with the following properties.

- $X^i$  is fixed on  $I_i$ : there exists some  $\alpha_i \in [n]^{I_i}$  such that  $x(I_i) = \alpha_i$  for all  $x \in X^i$ .
- $X^i(J \setminus I_i)$  is  $\gamma$ -dense.
- $\mathbf{D}_\infty(X^i(J \setminus I_i)) \leq \mathbf{D}_\infty(X) - (1 - \gamma) \log n |I_i| + \delta_i$  where  $\delta_i = \log \frac{|X|}{|\cup_{j \geq i} X^j|}$ .

►  $\mathbf{D}_\infty(X) := |J| \log n - \mathbf{H}_\infty(X)$  if  $X$  is supported on  $[n]^J$ .



# Decomposition and sampling process $DS(\Pi)$

Input: A protocol tree  $\Pi$  under uniform input distribution

Output: A rectangle  $R = X \times Y \subseteq [n]^n \times [n]^n$ ,  $J_A, J_B \subseteq [n]$ .

Initialization:  $X := Y := [n]^n, J_A := J_B := [n], \text{skip} := \text{false}, r := 0, v := \text{root}$ .

1. Partition  $X$  into  $X = X^0 \cup X^1$  according to node  $v$  in the protocol tree
2. Sample  $\mathbf{b} \in \{0,1\}$  such that  $\Pr[\mathbf{b} = b] = \frac{|X^b|}{|X|}$ .
3. Update  $X := X^b, v := u_b$ .
4. If  $u_b$  is owned by Bob:
  - ▶ Further partition  $X$  into  $X = X^0 \cup X^1$  where  $X^b := \{f_A \in X : f_A(z_{r-1}) \bmod 2 = b\}$ .
  - ▶ Sample  $\mathbf{b} \in \{0,1\}$  such that  $\Pr[\mathbf{b} = b] = \frac{|X^b|}{|X|}$ .
  - ▶ Update  $X := X^b, r := r + 1$ .
5. Let  $X = X^1 \cup \dots \cup X^m$  be **density restoring partition** of  $X$  with associated  $I_1, \dots, I_m$ .
6. Sample a random element  $\mathbf{j} \in [m]$  such that  $\Pr[\mathbf{j} = j] = \frac{|X^j|}{|X|}$  for  $j \in [m]$ .
7. Update  $X := X^j, J_A := J_A \setminus I_j$ .
8. If  $u_b$  is owned by Bob  $z_{r-1} \notin J_B$ , **skip** := true.

Suppose Alice owns node  $v$  and  $u_0, u_1$  be the children of  $v$  in the protocol tree.

As a new round begins, we do an extra partition to fix the parity of  $pt_r$ .

 1|1|4|5|1|4|1|

$\gamma$ -dense

$X_{I_j}$  is fixed;  
 $X_{J_A}$  is dense.

# Loop invariant

Input: A protocol  $\Pi$

Output: A rectangle  $R = X \times Y \subseteq [n]^n \times [n]^n$ ,  $J_A, J_B \subseteq [n]$ .

Initialization:  $X := Y := [n]^n, J_A := J_B := [n], \text{skip} := \text{false}, r := 0, v := \text{root}$ .

**Lemma 2.** Set  $\gamma := 1 - \frac{0.1}{\log n}$ . Then in the running of  $DS(\Pi)$ , we have the following loop invariants:

After each iteration,

- ▶  $X \times Y \subseteq \Pi_v$ .
- ▶  $X(J_A), Y(J_B)$  are  $\gamma$ -dense.
- ▶ There exists some  $\alpha_A \in [n]^{\bar{J}_A}, \alpha_B \in [n]^{\bar{J}_B}$  such that  $x(\bar{J}_A) = \alpha_A, y(\bar{J}_B) = \alpha_B$  for all  $x \in X, y \in Y$ .
- ▶ There exists some  $z_r \in [n]$  such that  $pt_r(f_A, f_B) = z_r$  for all  $f_A \in X, f_B \in Y$ .

In the **round elimination** method, it should fix  $pt_r$  in each round,  
but we only fix the parity of  $pt_r$  and use the density restoring partition helps to fix  $pt_r$ .  
This is why we save the  **$k \log n$**  factor

## Relating accuracy and *average fixed size*

**Lemma.** If  $DS(\Pi)$  outputs  $(R = X \times Y, J_A, J_B)$  then

$$\Pr_{(f_A, f_B)} [\Pi(f_A, f_B) = PC_k(f_A, f_B)] \leq \frac{2^{0.1}}{2} + \frac{2^{0.1}}{n} \cdot k \cdot \mathbf{E}[|\bar{J}_A| + |\bar{J}_B|]$$

$$\mathbf{E}[|\bar{J}_A| + |\bar{J}_B|] \geq \Omega(n/k)$$

Based on the loop invariant, the proof is similar to the analysis of simple protocols. **We omitted the proof in this talk.**

# Average fixed size is bounded by communication: A density increment argument

- ▶ In the running of  $DS(\Pi)$ , our density function is :

$$D_{\infty}(R) := D_{\infty}(X(J_A)) + D_{\infty}(Y(J_B)).$$

$$D_{\infty}(X) := |J| \log n - H_{\infty}(X)$$

- ▶ In the beginning,  $D_{\infty}([n]^n \times [n]^n) = 0$ .

- ▶ In expectation (over the choice of  $\mathbf{b}$ ), each communication bit/new round (assume Alice speaks) **increase**  $D_{\infty}(R)$  by at most 1:

$$\frac{|X^0|}{|X|} \log \frac{|X^0|}{|X|} + \frac{|X^1|}{|X|} \log \frac{|X^1|}{|X|} \leq 1.$$

- ▶ In expectation (over the choice of  $\mathbf{j}$ ),  $D_{\infty}(R)$  **decreases** by at least  $0.1 \mathbf{E}_j[|I_j|] - 1$ .

- ▶  $D_{\infty}(X^i(J \setminus I_i)) \leq D_{\infty}(X) - 0.1 |I_i| + \delta_i$  where  $\delta_i = \log \frac{|X|}{|\cup_{j \geq i} X^j|}$ .

- ▶  $\mathbf{E}_j[\delta_j] = \sum_j p_j \delta_j = \sum_j p_j \log \frac{1}{\sum_{t \geq j} p_t} \leq \int_0^1 \frac{1}{1-x} dx \leq 1$ . where  $p_j := \frac{|X^j|}{|X|}$

- ▶  $D_{\infty}(R) \geq 0 \rightarrow \mathbf{E}[|J_A| + |J_B|] = \mathbf{E}[|I_1| + |I_2| + \dots] \leq O(C)$ .

# Proof outline

- ▶ **The decomposition and sampling process:**

Use **density restoring partition** to decompose the behavior of  $\Pi$  into the combination of simple protocols (i.e., fixing some coordinates).

- ▶ Relating accuracy and **average fixed size** .  $\mathbf{E}[|I|] \geq \Omega(n/k)$  .

By **the analysis of simple protocols**.

- ▶ **Average fixed size** is bounded by communication .  $\mathbf{CC} \geq \mathbf{E}[|I|]$ .

By a density increment argument.

Thank you for listening 😊