# Structurale properties of decomposable digraphs

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# Part I

Primitive graphs and gabbigubbi

#### 0.1 Introduction

Why we need graphs.

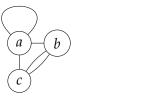
#### Chapter 1

## Graphs and digraphs

Before going deep into structural properties of decomposable digraphs we first need to establish what a graph is. For some graph G(V,E) where V and E are two sets contaning the vertices (also commonly called nodes) and egdes of the graph respectively. We define the **size** of the graph to be the number of vertices |V| this is also known as **cardinality** of V. An **edge**  $e \in E$  where  $e \equiv (a,b)$  and  $\{a,b\} \subseteq V$  then e is an edge in G, e is said to be **incedent** to e and e. We call e and e a

In a graph we have something called a **walk** which is a alternately ordering of vertices an edges in the graph G where the edge in between the two vertices in the ordering is an edge between the vertices in G (for  $(a, e_1, b)$  to be a walk the edge  $e_1$  has to be between a and b). We call a walk closed if the first vertex in the walk is the same as the last.

A path in a graph is a walk where each vertex in the ordering can only apear one time. A cycle is a closed walk where the only vertex pressent more then one time is the first vertex(for the walk to be closed the first vertex has to apear last to also called a closed path).



(a) graph G(V, E) is an example of a graphs, the red edge is a loop, and all pair of vertices in this graph which makes this a digraph graph is adjacent

Before delving more specific into graphs and digraphs we must establish some important prerequisite and properties. A graph is called **simple** if there is no loops and no multiple edges. With multiple edges it means multiple edges between the same pair of vertices like in Figure 1.1a between b and c.

A graph is **connected** if there exists a path between all pair of vertices in the graph and **disconnected** otherwise. A graph is called **complete** if there for all pair of vertices in the graph is an edge between them see Figure 1.2.

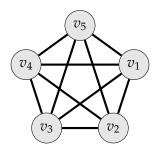


Figure 1.2: Complete graph with 5 vertices.

If we instead of edges have **arcs** between the vertices we call it a **digraph**. An arc is describe just like an egde with two adjecent vertices (a, b) the first vertex mentioned in an arc is the vertex **from** where the arc starts also called the **tail**, the second vertex is where the arc is pointing **to** also called **head**. The set of arcs is normaly denoted A like the set of edges is denoted E. So the arc (a, b) goes from a to b, if you wanted it the other way around the arc is (b, a). These graph containing only arcs and no edges is called a digraph G(V, A) which is what we in this project are focusing on see Figure 1.1b.

In a digraph we have something called the **underlying graph**. An underlying graph of a digraph is where all arcs are replaced by edges (edge is used every time we talk about undirected edges between vertices, when using directions it is called an arc). A digraph is **connected** if the underlying graph is connected, (also called weakly connected), a digraph can be **strongly connected** and **semi connected** too. A digraph is called **semi connected** if there for each pair u and v exists a path from either u to v or v to u. It is said to be **strongly connected** if for each pair of vertices u and v there exists a path from both v to v and v to v. We can use these to describe som specific collection of graphs as the graph **tournaments**. **Tournaments** is a digraph where the underlying graph is complete. So a complete graph of order 5 any orientation of the edges concludes in a tournament. If instead of replacing the one edge by one arc in either direction, but instead replace it by two arcs the digraph is called **semicomplete**.

The reason for grouping the digraphs into smaller collections of digraphs (like tournaments is a smaller collection of semicomplete digraphs) is because of problems that is hard to solve on general graph but is easy/polynomial solvable on specific graphs.

A group of these problems is called NP-hard problems which sometimes sound easy solvable for graphs but only for some specific graphs we know how to solve it in polynomial time.

#### **Definition 1.0.1.** *define NP-hard problems*

In this paper we focusing on the specific digraphs that are **decomposable**. A **decomposable** digraph is a digraph  $D = H[G_1, G_2, ..., G_|H|]$  where each  $G_i$  is sconnected graphs replacing each vertex of the digraph H. ...