

# Automatic Hybrid MPI+OpenMP Code Generation

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05/17/2011

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# Disclaimer

There is actually **no** Boost.Proto  
in this presentation

# The March of Hybrid Parallelism

## What's up on the HPC planet ?

- Machines are becoming more and more hybrids
- HPC Top500 : 80% of clusters of multicores
- HPC Top10 : multicores + GPGPUs or Cell Processors
- Most modern desktop computer are small HPC nodes

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## So is the free lunch free again ?

- Difficulties scale changed
- Combining all these new toys become increasingly complex
- Does having more mean it obviously goes faster ?

# What's left to do so ?

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## Hybrid programming is a complex problem

- Architecture: network bandwidth, number of cores, type of accelerators ...
- Application: Communication computation ratio, problem size ...
- Programming model: MPI, MPI+OpenMP, MPI+CUDA, OpenMP+CUDA, MPI+OpenMP+CUDA, oh my ...



# Purpose of this talk

## Our Objectives

- Find a way to simplify this mess
- Can we find a decent programming model for this ?

## Our Work

- A library for hybrid programming
- A tool to help in configuration exploration
- All using Boost of course

# Talk Layout

- 1 Introduction
- 2 High Level Programming Models**
- 3 BSP++
- 4 Applications
- 5 Conclusion

# Programming Tools and Models

## Message Passing Interface (MPI)

- Run multiple process across distributed nodes
- Process use **Message** to communicate
- Provides a set of ready-to-use communications primitives

## OpenMP

- Standard language extension for shared memory system
- Parallelism is expressed as **parallel sections** using `#pragma`
- Provides functions for threads handling and synchronization

# Higher Level Models

## What do we need

- Architecture asbtraction
- Performances estimation
- Easy to use for the end user

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## What's available ?

- Stream processing
- Parallel Skeletons
- Bulk Synchronous Parallelism

# Higher Level Models

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- Stream processing
- Parallel Skeletons
- Bulk Synchronous Parallelism

# Bulk Synchronous Parallelism

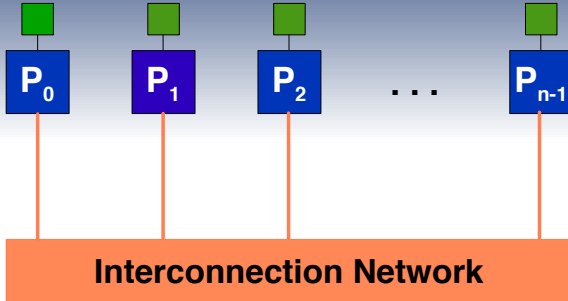
## Origin

- Proposed by L. Valiant in 1990
- Present a constrained form of parallelism
- Bridge the gap between machine and programs

## Principles

- A Machine Model
- A Cost Model
- A Programming Model

# BSP Machine Model

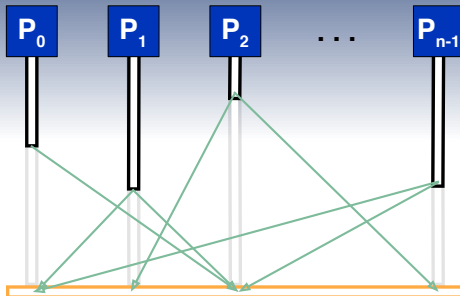


## Definition

- Multiple Computing units : local memory + processor
- One all-to-all interconnection network
- A global barrier mechanism



# BSP Programming Model



## Definition of a Super-Step

- An asynchronous computation step
- A all-to-all communication step
- A global barrier

# BSP Cost Model

## Definition

- $W_i$  : computation time on processor  $i$
- $h$  : amount of bytes to transfer
- $g$  : network throughput
- $L$  : Time for performing a barrier

## Cost of one super-step

$$\Omega = \max W_i + h \times g + L$$

# Existing BSP Library

## Oxford BSPLib [Hill:96]

- C based
- Rely on low-level shared memory runtime
- Provides 20+ primitives for communications over different medium

## BSML [Gava:09]

- Functionnal implementation of BSP in Caml
- Notion of parallel 'vector'
- Two communications + one synchronization primitives
- Provides an extended syntax for BSP construct in ML

# Why BSP ?

## BSP Pros and Cons

- Straightforward `Seq of Par` programming model
- Hybrid programming support with a black-box approach
- Limited support for task parallelism
- Barrier costs impact programm structure

## Our Plans

- Provide a BSP like library for parallel programming
- Provide a tool for BSP application description
- Use BSP cost Model to explore configuration space

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# BSML primitives

## Distributed Vector

A BSP distributed vector is a vector where each element lives on a different BSP node

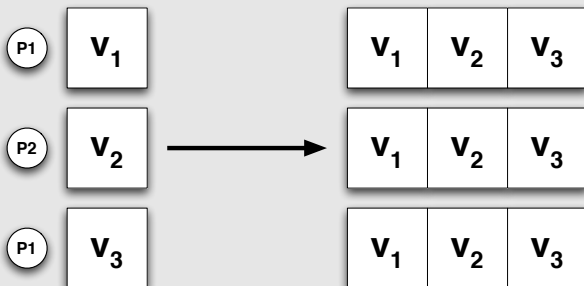
- $\ll v \gg$  : build a vector from value or a function  $v$
- $\$v\$$  : access to the local vector element
- A parallel vector of type  $'a$  has type  $par'a$

# BSML primitives

## The `proj` function

- Replicates a parallel vector around all BSP nodes
- Prototype: `proj : par 'a -> par (int -> 'a)`

## Semantic of `proj v`



# BSML primitives

## The put function

- Generic all-to-all communications function
- Prototype:  $put : par (int \rightarrow 'a) \rightarrow par (int \rightarrow 'a)$

## Semantic of *put vf*





# A sample BSML Code

## BSML Inner Product

```
let inner_product v =  
  let local = << Array.fold_left (+.) (Array.map2 (*.) $v$ $v$) >>  
  in let gathered = proj local  
  in Array.fold_left (+.) (Array.make gathered nprocs) ;;
```

# A sample BSML Code

## BSML Inner Product

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let inner_product v =  
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```

## How does it works

- Build a distributed vector from  $v[i]^2$  in parallel
- Exchange partial results with all nodes
- Perform a final reduction

# From BSML to BSP++

## Why looking at BSML

- Provides a compact and abstract interface
- BSML likes playing with lambda and so do we

## The Plan

- Implement BSML interface and abstraction in C++
- Try to work on the functional side to limit errors
- Try to play nice with C++ functional idioms

# BSP++ 101

## Main Program Structure

- Managed main handles parallel runtime
- Everything in a BSP program is parallel

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## Main Program Structure

- Managed main handles parallel runtime
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## Example

```
#include <bsppp/bsppp.hpp>

int bsp_main( int argc, char const* argv[] )
{
    // Starting from here, everything is parallel
}
```

# BSP++ primitives

## Parallel vector : `par<T>`

- `par<T>` is a BSP distributed `T`
- Constructible from values, functions and ranges

# BSP++ primitives

## Parallel vector : `par<T>`

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- Constructible from values, functions and ranges

## `par<T>` Interface

```
// distributed default construction
par<T> p;

// distributed replication
T v;
par<T> p = v;

// distributed initialization from a Callable Object
T foo(std::size_t pid);
par<T> p = foo;
```

# BSP++ primitives

## Parallel vector : `par<T>`

- `par<T>` is a BSP distributed `T`
- Constructible from values, functions and ranges

## `par<T>` Interface

```
// Access to local value
par<T> p;

T x = *p;

// Envelope behavior
par< vector<T> > p;
p->resize(n);
```



# BSP++ primitives

## The `proj` and `put` function

- BSML returns function **value**
- Let's return **Callable Object** embedding the result
- Make them Range for easier interoperability

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## Examples

```
par< float > r = 1.f / _1;  
result_of::proj<float> exch = proj (r);  
  
// Value at machine 1  
cout << exch(1) << endl;  
  
// Iterate over value receive from all machines  
std::for_each( exch.begin(), exch.end(), ref(cout) << _1 );
```

# BSP++ primitives

## The `proj` and `put` function

- BSMML returns function **value**
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## Examples

```
par< float > r = 1.f / _1;  
  
auto inv = put( [&r](int dst) { if(dst % 2) return *r; else return -*r; } );  
  
// Value at machine 1  
cout << (*inv)(1) << endl;
```

# A sample BSP++ code

## BSP++ Inner Product

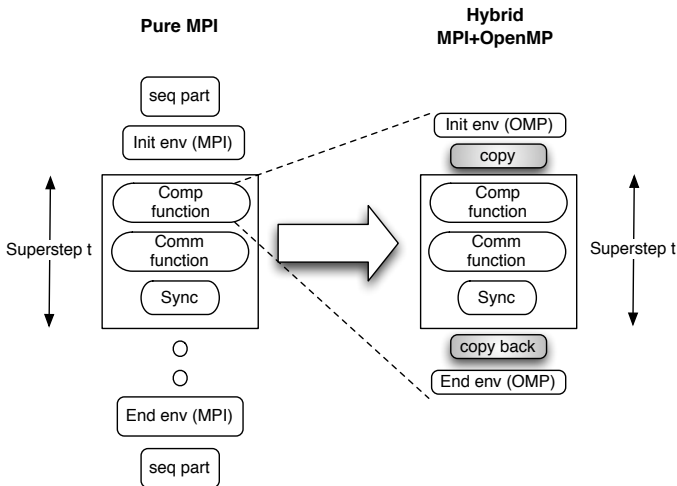
```
template<class Range>
typename iterator_value<typename Range::const_iterator>::type
inner_product( Range const& input )
{
    typedef typename
        iterator_value<typename Range::const_iterator>::type value_type;

    par<Range> v = slice( input );
    par< value_type > r;

    *r = std::inner_product( v->begin(), v->end(), v->begin(), value_type() );

    result_of::proj<value_type> exch = proj( r);
    *r = std::accumulate(exch.begin(), exch.end() );
}
```

# Support for Hybrid programming



# Support for Hybrid programming

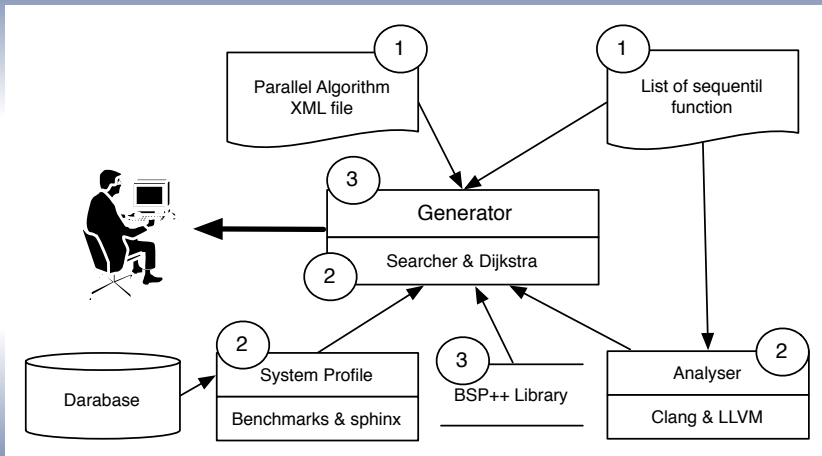
## BSP++ Hybrid Inner Product

```
template<class Range>
typename iterator_value<typename Range::const_iterator>::type
inner_product_omp( Range const& input )
{
    typedef typename
        iterator_value<typename Range::const_iterator>::type value_type;
    BSP_HYB_START(argc, argv)
    {
        par<Range> v = slice( input );
        par< value_type > r;
        *r = std::inner_product( v->begin(), v->end(), v->begin(), value_type() );
        result_of::proj<value_type> exch = proj( r );
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    }
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```

# The BSPGen Framework



# Analysis and Exploration

## Analysis

- Compile each sequential function using LLVM/Clang
- Parse results to find out an estimation of runtime costs
- Estimate communication from offline benchmarks

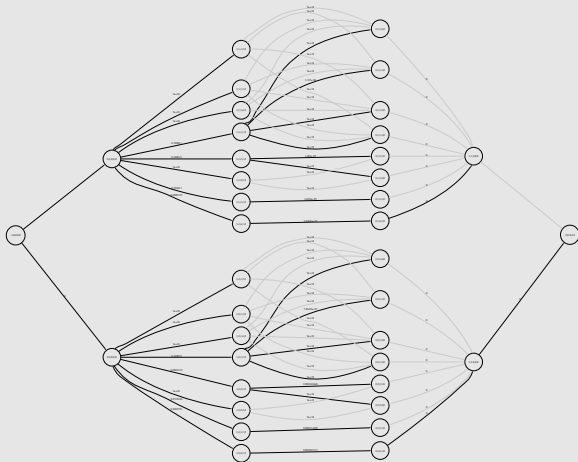
## Configuration exploration

- Buy a directed graph of the sequence of super-steps
- Compute all combination of node/core configurations
- Weights edge with estimated runtime cost
- Run a simple Shortest Path algorithm



# Analysis and Exploration

## Configuration exploration



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# Objectives

## Coverage

- Simple kernels
- Three applications

## Test machines

- a 4x4 cores NUMA machine using AMD processors
- 256 nodes from the French GRID'5000 infra-structure
- a 3 Cell processors cluster

# Simple Kernels

## Chosen Kernels

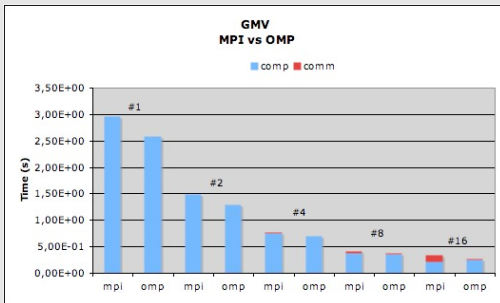
- Matrix-Vector product (GEMV)
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## Results

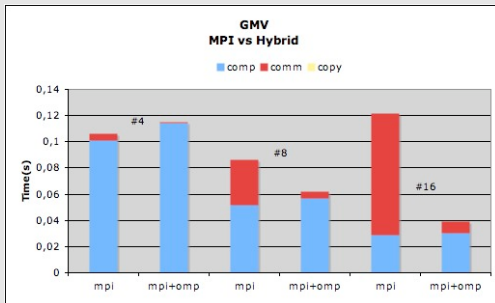


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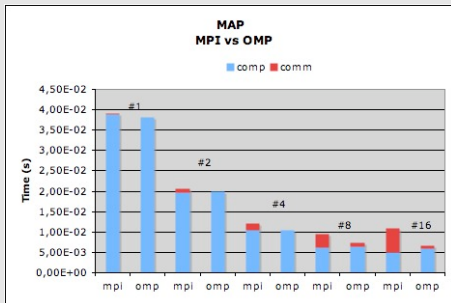


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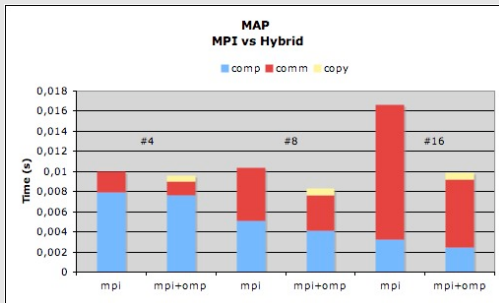


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# Model Checking

## Parallel Approximate Model Checking [Peyronnet:08]

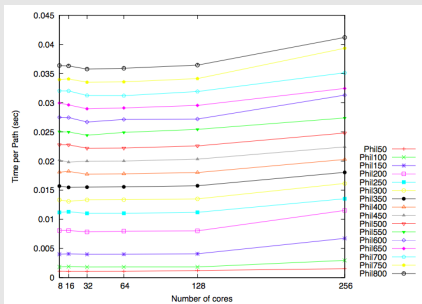
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- Turn system into a set of condition driven states
- Try to solve time-logic predicates over the model
- Large problem, can be solved approximately (APMC)

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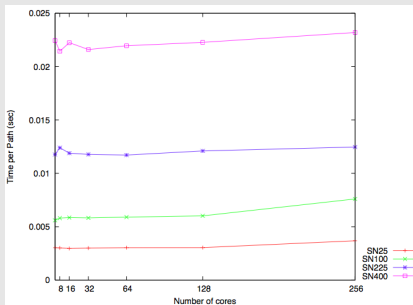


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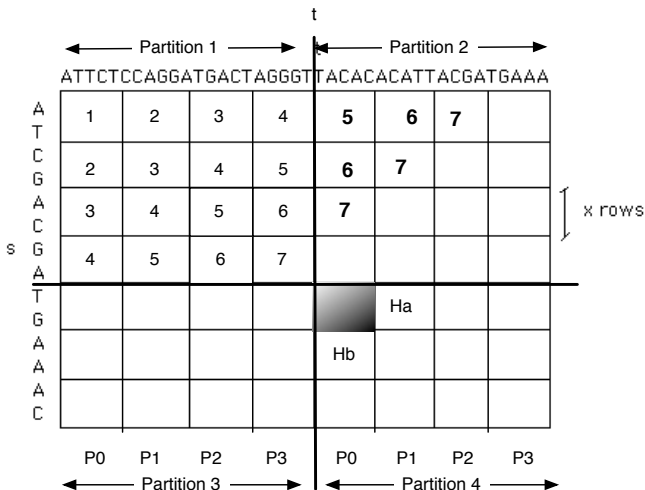
- Great scalability over more than 200 cores
- Parallel APMC allows for larger problem to be verified
- See [Hamidouche PDMC 2010] for more

# Swith and Waterman DNA Comparisons

## Principles

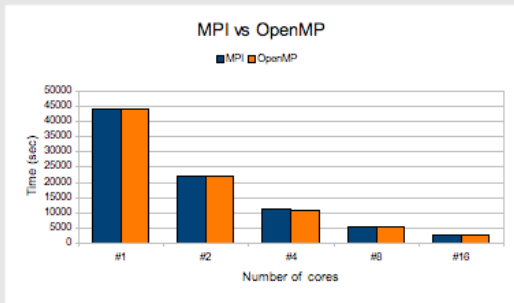
- Compute distance between two DNA sequences
- Heuristic method : BLAST fast but not accurate
- Direct method : S&W accurate but slow

# Swith and Waterman DNA Comparisons



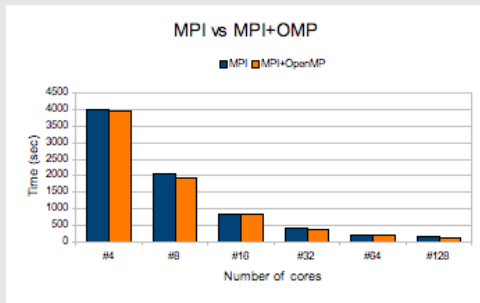
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# Contributions

## BSP++

- Implement BSP in an efficient, C++ way
- Supports black-box hybridation
- Show scalability and usability
- Play with it: <https://github.com/jfalcou/bsppp>

## BSPGen

- Ease the configuration exploration of BSP programs
- Interoperability between Boost and clang
- To be extended

# Future Works

## New Architectures

- Cell Processor : done with Cell-MPI
- GPGPU: require multistage programming

## More BSP with Phoenix 3

- Functionnal version of BSP
- Allow for automatic merging of super-step
- Solve the multistage problem
- Can we force people to write lambda everywhere ?

Thanks for your attention