

# PhyPiDAQ

## Data Acquisition and analysis for Physics education with Raspberry Pi

This is the **English** version of the documentation.

For German readers:

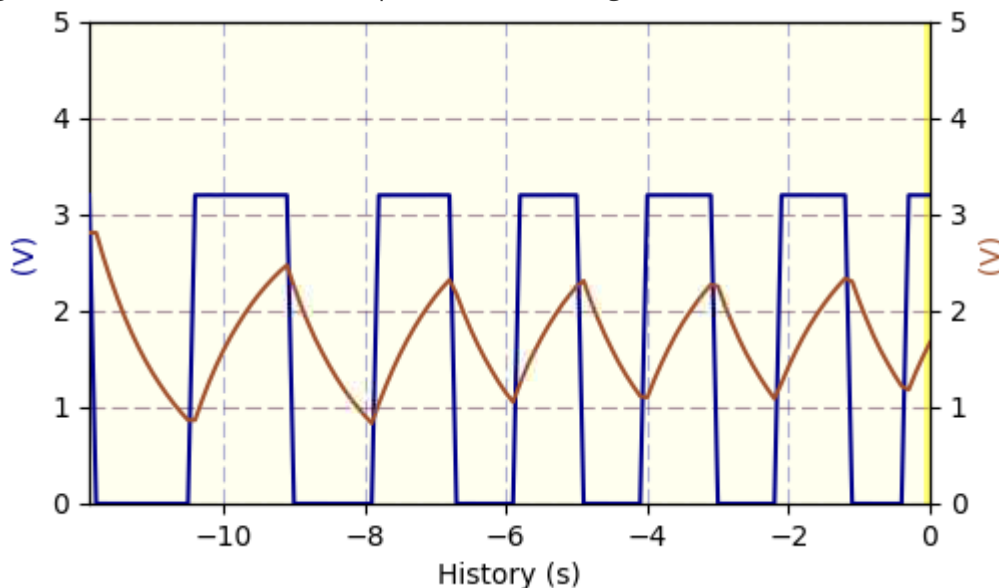
Die **deutsche Version** dieses Dokuments findet sich unter dem Link [README\\_de.md](#) bzw. [README\\_de.pdf](#).

This *python3* code provides some basic functionality for data acquisition and visualisation like data logger, bar-chart, XY- or oscilloscope display and data recording on disk.

In addition to the GPIO inputs/outputs of the Raspberry Pi, the analogue-to-digital converters ADS1115 and MCP3008 and PicoScope USB-oscilloscopes are supported as input devices for analogue data, as well as a number of digital sensors using protocols like I<sup>2</sup>C or SPI.

The package provides an abstraction layer for measurement devices and sensors connected to a Raspberry Pi. Dedicated classes for each device provide a simple, unified interface, containing only the methods `init(<config_dictionary>)`, `acquireData(buffer)` and `closeDevice()`. Simple examples with minimalist code illustrate the usage. The graphical user interface `phypi.py` and the script `run_phypi.py` provide a configurable environment for more complex measurements.

Fig. 1: Visualisation of the time dependence of two signals connected to an ADC



## Quick-start guide

After installation - see below - a number of unified classes for data acquisition, visualisation and recording is available from the sub-directory `./phypidaq`. Each supported device needs a specific configuration, which is read from configuration files in sub-directory `./config`. The overall configuration is given in files of type `.daq`, specifying which devices and display modules to use, the readout rate, calibrations or analytical formulae to be applied to recorded data, or ranges and axis labels of the graphical output.

The graphical user interface `phypi.py` aids in the administration of the configuration options and can be used to start data acquisition. In this case, configurations and produced data files are stored in a dedicated sub-directory in `$HOME/PhyPi`. The sub-directory name is derived from a user-defined tag and the current date and time.

Data acquisition may also be started via the command line:

```
run_phypi.py <config_file_name>.daq
```

If no configuration file is given, the default `PhyPiConf.daq` is used.

The sub-directory `./examples` contains a number of simple *python* scripts illustrating the usage of data acquisition and display modules with minimalist code.

## Configuration files for PhyPiDAQ

The script `run_phypi.py` allows users to perform very general measurement tasks without the need to write custom code. The options for configuration of input devices and their channels as well as for the display and data storage modules are specified in a global configuration file of type `.daq` (in `yaml` markup language), which contains references to device configuration files of type `.yaml`.

### Main configuration file

A typical, commented example of the main configuration file is shown below. Note that text following a `"#"`-sign is ignored and contains descriptive comments or alternatives.

**file `PhyPiConf.daq`**

```
# -- Configuration Options for PhyPiDAQ
# -----

#
# -- configuration files for hardware devices
#
DeviceFile: config/ADS1115Config.yaml    # 16 bit ADC, I2C bus
## optional:
#DeviceFile: config/MCP3008Config.yaml  # 10 bit ADC, SPI bus
#DeviceFile: config/MCP3208Config.yaml  # 12 bit ADC, SPI bus
#DeviceFile: config/PSConfig.yaml       # PicoTechnology USB scope
#DeviceFile: config/MAX31865Config.yaml  # Pt 100 sensor
#DeviceFile: config/GPIOCCount.yaml     # frequency count
#DeviceFile: config/DS18B20Config.yaml   # digital temperature sensor
#DeviceFile: config/MAX31855Config.yaml  # thermo element
#DeviceFile: config/BMP180Config.yaml    # pressure/temperature sensor
#DeviceFile: config/INA219Config.yaml    # Voltage/Current sensor
#DeviceFile: config/MMA8451Config.yaml   # accelerometer
#DeviceFile: ToyData.yaml               # simulated data

## an example of multiple devices
#DeviceFile: [config/ADS1115Config.yaml, config/GPIOCCount.yaml]

#
```

```

# -- configuration options for Channels
#
ChanLabels: [U, U]           # names for channels
ChanUnits: [V, V]           # units for channels
ChanColors: [darkblue, sienna] # channel colours in display

## eventually overwrite Channel Limits obtained from device config
#ChanLimits:
# - [0., 1.]   # chan 0
# - [0., 1.]   # chan 1
# - [0., 1.]   # chan 2

## calibration of raw channel values
##   - null      or - <factor> or - [ [ <true values> ], [ <raw values> ] ]
#ChanCalib:
# - 1.           # chan0: simple calibration factor
# - [ [0.,1.], [0., 1.] ] # chan1: interpolation: [true]([<raw>] )
# - null         # chan2: no calibration

## apply formulae to (calibrated) channel values
#ChanFormula:
# - c0 + c1 # chan0
# - c1      # chan1
# - null    # chan2 : no formula

#
# -- configuration options for graphical display
#
Interval: 0.1           # logging interval
NHHistoryPoints: 120     # number of points used in history buffer
DisplayModule: DataLogger # history of channel signals
#DisplayModule: DataGraphs # text, bar-graph, history and xy-view
#Title: Demo             # display title
#XYmode: false           # enable/disable XY-display
## if more than two channels active:
#Chan2Axes: [0, 1, 0]    # assign channels to axes
#xyPlots:                # define which axes to show
# - [0, 1]                # in xy-plot
# - [0, 2]
# - [1, 2]

#
# -- configuration options for output to file
#
#DataFile: testfile.csv   # file name for output file,
DataFile: null            # null to disable
#CSVseparator: ';'        # field separator, set to ';' for German Excel

# enable buffering of latest data (depth NHHistoryPoints from above)
#bufferData: PhyPiData    # file name to track latest data and eventually
#bufferData: null         # store them, or null to switch off

```

# Device configuration files

Typical, commented examples of device configurations are shown below. The device configuration file for the analogue-to-digital converter **ADS1115** specifies the active channels, their ranges and single or differential operation modes.

## file ADS1115Config.yaml

```
# example of a configuration file for ADC ADS1115

DAQModule: ADS1115Config      # phypidaq module to be loaded

ADCChannels: [0, 3]           # active ADC-Channels
                                # possible values: 0, 1, 2, 3
                                # when using differential mode:
                                #   - 0 = ADCCChannel 0
                                #       minus ADCCChannel 1
                                #   - 1 = ADCCChannel 0
                                #       minus ADCCChannel 3
                                #   - 2 = ADCCChannel 1
                                #       minus ADCCChannel 3
                                #   - 3 = ADCCChannel 2
                                #       minus ADCCChannel 3

DifModeChan: [true, true]     # enable differential mode for Channels

Gain: [2/3, 2/3]              # programmable gain of ADC-Channel
                                # possible values for Gain:
                                #   - 2/3 = +/-6.144V
                                #   - 1 = +/-4.096V
                                #   - 2 = +/-2.048V
                                #   - 4 = +/-1.024V
                                #   - 8 = +/-0.512V
                                #   - 16 = +/-0.256V

sampleRate: 860               # programmable Sample Rate of ADS1115
                                # possible values for SampleRate:
                                #   8, 16, 32, 64, 128, 250, 475, 860
```

The **USB-oscilloscope** PicoScope can also be used as data logger. In this case the average of a large number of measurements at high rate is taken. Choosing a measurement time of 20 ms very effectively eliminates 50 Hz noise.

## file PSconfig.yaml

```
# example of a configuration file for PicoScope 2000 Series

DAQModule: PSConfig

PSmodel: 2000a
```

```
# channel configuration
picoChannels: [A, B]
ChanRanges: [2., 2.]
ChanOffsets: [-1.95, -1.95]
ChanModes: [DC, DC]
sampleTime: 2.0E-02
Nsamples: 100

# oscilloscope trigger
trgActive: false # true to activate
trgChan: A
#trgThr: 0.1
#pretrig: 0.05
#trgTyp: Rising
#trgTO: 1000 # time-out

# internal signal generator
# frqSG: 100.E+3 # put 0. do disable
frqSG: 0.
```

Examples of other devices like the analog-to-digital converter MCP3008, of rate measurements via the GPIO pins of the Raspberry Pi or temperature measurements with the 1-wire digital thermometer DS18B20, PT100 sensors and the resistance-to-digital converter MAX31865 or thermocouples and the thermocouple-to-digital converter MAX31855 are also contained in the configuration directory, see files

MCP3008Config.yaml, GPIOcount.yaml, DS18B20Config.yaml, MAX31865Config.yaml or MAX31855Config.yaml, respectively.

# Installation of PhyPiDAQ on a Raspberry Pi

## Get PhyPiDAQ code and dependencies

After setting up your Raspberry pi with the most recent version of the Debian Release *stretch*, enter the following commands in the console window:

```
mkdir git
cd git
git clone https://github.com/GuenterQuast/PhyPiDAQ
```

For your convenience, the script *installlibs.sh* installs all components needed for PhyPiDAQ. Simply execute the script *installlibs.sh* once on the command line (without text after `#`):

```
cd ~/git/PhyPiDAQ # change to installation directory
git pull          # eventually update to latest version of PhyPiDAQ
./installlibs.sh
```

The installation is now done and *PhyPiDAQ* is ready to be used.

The last part of the installation procedure is also valid to update an existing version of `PhyPiDAQ`.

To test the installation without connected hardware or on a system other than the Raspberry Pi, PhyPiDAQ may be started in demo-mode:

```
cd ~/git/PhyPiDAQ # change to installation directory
./run_phypi.py    # execute run_phypi.py with configuration PhyPiDemo.daq
```

## Anmerkung

### Remark

*PhyPiDAQ* is meant to be an educational tool. Confronting students with the full contents of this package is therefore not appropriate. Instead, it is recommended to create a working directory and copy examples from there to the student's working directory. This is achieved via the following commands:

```
# create PhyPi working directory and make examples and config files available
cd ~/git/PhyPiDAQ
./install_user.sh

# provide icon to graphical user interface
cp ~/git/PhyPiDAQ/phypi.desktop ~/Desktop
```

You might also consider moving the *PhyPiDAQ* package to system space, e.g. `/usr/local`:

```
sudo mv ~/git/PhyPiDAQ /usr/local/
```

Please note that the paths in the example above must be adjusted in this case, e.g. `~/git/` -> /usr/local/`. The paths in `~/Desktop/phyPi.desktop` must also be changed appropriately. This is most easily achieved by right-clicking the icon and use the dialog "Properties".

## Dependencies on external packages

The PhyPiDAQ package relies on code from other packages providing the drivers for the supported devices and libraries for data visualisation:

- the Adafruit Python MCP3008 library  
[https://github.com/adafruit/Adafruit\\_Python\\_MCP3008](https://github.com/adafruit/Adafruit_Python_MCP3008)
- the Adafruit Python ADX1x15 library  
[https://github.com/adafruit/Adafruit\\_Python\\_ADS1x15](https://github.com/adafruit/Adafruit_Python_ADS1x15)
- the Adafruit Python MAX31855 library  
[https://github.com/adafruit/Adafruit\\_Python\\_MAX31855](https://github.com/adafruit/Adafruit_Python_MAX31855)
- the w1thermsensor library by Timo Furrer  
<https://github.com/timofurrer/w1thermsensor>
- components from the picoDAQ project  
<https://github.com/GuenterQuast/picoDAQ>
- the *python* bindings of the *pico-python* project by Colin O'Flynn  
<https://github.com/colinoflynn/pico-python>
- the low-level drivers contained in the Pico Technology Software Development Kit  
<https://labs.picotech.com/raspbian>

For convenience, installation files for external packages and for modules of this package in pip wheel format are provided in sub-directory `./installlibs`.

The visualization modules depend on *matplotlib.pyplot*, *Tkinter* and *pyQt5*, which must also be installed.

For completeness, the steps performed by the script `installlibs.sh` are documented here:

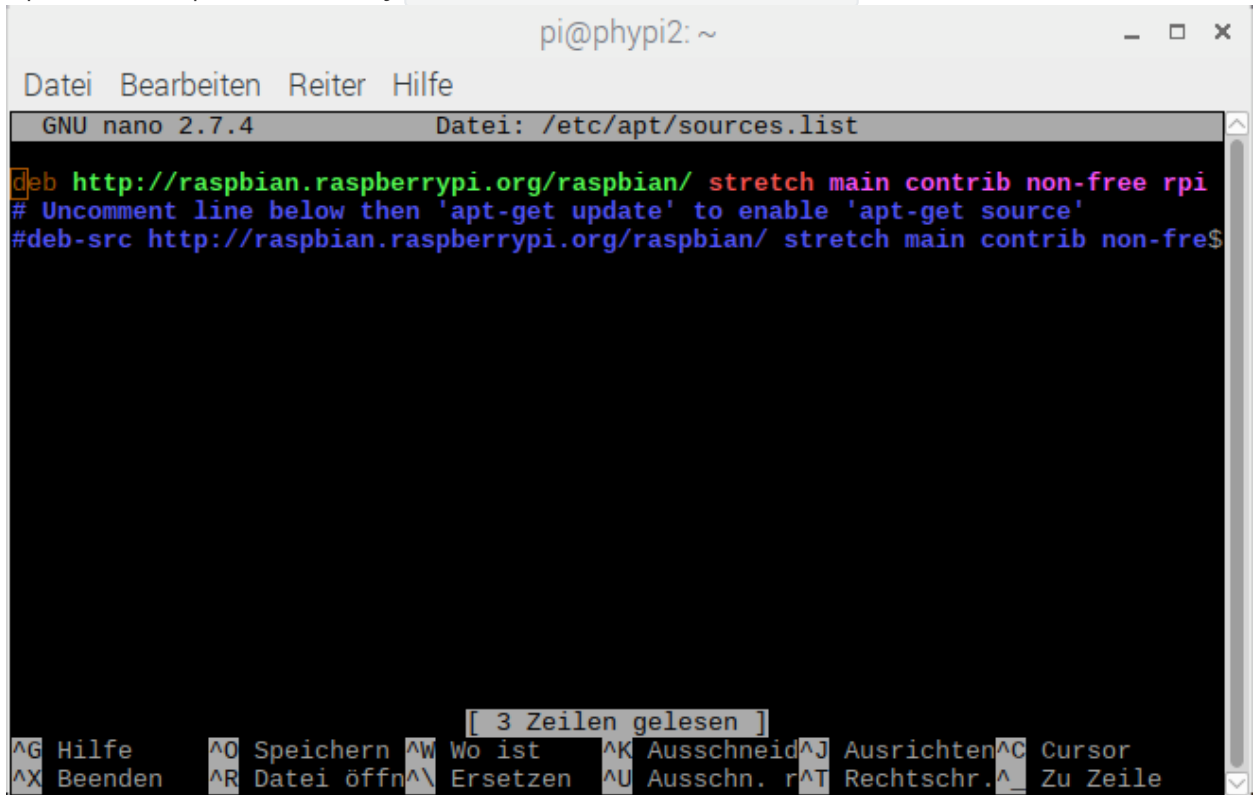
```
# script installlibs.sh

sudo apt-get update
sudo apt-get upgrade
sudo apt-get install python3-scipy
sudo apt-get install python3-matplotlib
sudo apt-get install python3-pyqt5
sudo apt-get install libatlas-base-dev # needed by latest version of numpy
sudo pip3 install pyyaml
# python drivers for sensors and devices
sudo pip3 install installlibs/whl/*.whl
# install drivers for PicoScope 2000 and 2000B
sudo dpkg -i installlibs/picoscopelibs/*.deb

sudo usermod -a -G tty pi # USB access for user pi
```

The drivers for PicoScope oscilloscopes may also be installed from the repository of the vendor, which is included as follows:

1. Open file /etc/apt/sources.list by `sudo nano /etc/apt/sources.list`.



```
pi@phypi2: ~  
Datei Bearbeiten Reiter Hilfe  
GNU nano 2.7.4 Datei: /etc/apt/sources.list  
deb http://raspbian.raspberrypi.org/raspbian/ stretch main contrib non-free rpi  
# Uncomment line below then 'apt-get update' to enable 'apt-get source'  
#deb-src http://raspbian.raspberrypi.org/raspbian/ stretch main contrib non-free$  
[ 3 Zeilen gelesen ]  
^G Hilfe ^O Speichern ^W Wo ist ^K Ausschneid ^J Ausrichten ^C Cursor  
^X Beenden ^R Datei öffn ^\ Ersetzen ^U Ausschn. r ^T Rechtschr. ^_ Zu Zeile
```

2. Use arrow keys to navigate to the next free line and add entry `deb http://labs.picotech.com/raspbian/ picoscope main` to /etc/apt/sources.list.



```
pi@phypi2: ~  
Datei Bearbeiten Reiter Hilfe  
GNU nano 2.7.4 Datei: /etc/apt/sources.list Verändert  
deb http://raspbian.raspberrypi.org/raspbian/ stretch main contrib non-free rpi  
# Uncomment line below then 'apt-get update' to enable 'apt-get source'  
#deb-src http://raspbian.raspberrypi.org/raspbian/ stretch main contrib non-free$  
deb http://labs.picotech.com/raspbian/ picoscope main  
^G Hilfe ^O Speichern ^W Wo ist ^K Ausschneid ^J Ausrichten ^C Cursor  
^X Beenden ^R Datei öffn ^\ Ersetzen ^U Ausschn. r ^T Rechtschr. ^_ Zu Zeile
```

3. Save file /etc/apt/sources.list by `Ctrl + O` and `Enter`.
4. Close /etc/apt/sources.list by `Ctrl + X`.



Now the drivers for drivers for the various PicoScope devices can be included and eventually updated with *apt-get*:

```
wget -O - http://labs.picotech.com/debian/dists/picoscope/Release.gpg.key | sudo apt-  
key add -  
sudo apt-get update  
sudo apt-get install libps2000  
sudo apt-get install libps2000a  
  
# allow access of user pi to usb port  
sudo usermod -a -G tty pi
```

## Overview of files contained in PhyPiDAQ

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### Programs

- `run_phypi.py`  
run data acquisition and display modules as specified in configuration files (default `PhyPiConf.daq` and `.yaml` files in subdirectory `config/`)
- `phypi.py`  
graphical user interface to edit configuration files and start the script `run_phypi.py`

### Modules

- `phypidaq/__init__.py`  
initialisation for package *phypidaq*
- `phypidaq/_version_info.py`  
version info for package *phypidaq*
- `phypidaq/ADS1115Config.py`  
class for handling of analog-to-digital converter ADS1115
- `phypidaq/MCP3008Config.py`  
class analog-to-digital converter MCP3008
- `phypidaq/MCP3008Config.py`  
class for current and voltage sensor INA219
- `phypidaq/DS18B20Config.py`  
class for handling of digital thermometer DS18B20
- `phypidaq/BMPx80Config.py`  
class for the digital temperature and pressure sensors BMP180/280 or BME280
- `phypidaq/MMA8451Config.py`  
class for the digital accelerometer MMA8451
- `phypidaq/GPIOCCount.py`  
class for reading rates from GPIO pins
- `phypidaq/MAX31855Config.py`  
class for MAX31855 thermocouple-to-digital converter

- `phypidaq/MAX31865Config.py`  
class for MAX31865 resistance-to-digital converter
- `phypidaq/PSConfig.py`  
class for PicoScope USB oscilloscopes
- `phypidaq/TCS34725Config` class for TCS34725 RGB color sensor
- `phypidaq/AS7262Config` class for AS7262 six channel color sensor
- `phypidaq/VL53LxConfig`  
class for VL53L1X distance sensor
- `phypidaq/ToyDataConfig.py`  
class to generate simulated data (for test, debugging or exercises)
- `phypidaq/ReplayConfig`  
class to replay data from file
- `phypidaq/Display.py`  
interface and background-process handling data visualisation
- `phypidaq/DataLogger.py`  
class for display of data histories and xy diagrams
- `phypidaq/DataGraphs.py`  
general display module for data as bar graphs, history plots and xy-graphs
- `phypidaq/DataRecorder.py`  
store data in CSV format
- `runPhyPiDAQ.py`  
class containing the implementation of script `run_phypi.py`
- `runPhyPiUI.py` class implementing the graphical user interface `phypi.py`, uses `phypiUI` as base class
- `phypyUI`  
base class for `runPhyPyUI`, generated from `phypi.ui` with `pyuic5`
- `phypi.ui` output of `designer-qt5`, describes the graphical user interface

## Configuration files

- `PhyPiConf.daq`  
main configuration file, depends on device configurations in sub-directory *config/*
- `config/ADS1115Config.yaml` 16 bit ADC
- `config/MCP3008Config.yaml` 10 bit ADC
- `config/MCP3208Config.yaml` 12 bit ADC
- `config/INA219Config.yaml` current and voltage sensore
- `config/DS18B20Config.yaml` digital temperature sensor
- `config/BMP280Config.yaml` temperature and pressure sensor
- `config/BMP180Config.yaml` temperature and pressure sensor
- `config/GPIOCCount.yaml` frequency measruement via GPIO pin
- `config/MAX31855Config.yaml` converter for thermocouple
- `config/MAX31865Config.yaml` converter for PT-100
- `config/INA219Config.yaml` current-voltage sensor
- `config/TCS34752Config.yaml` RGB sensor

- `config/AS7262Config.yaml` 6 channel color sensor
- `config/VL53L1XConfig.yaml` distance sensor
- `config/PSConfig.yaml` PicoScope usb oscilloscope

## Examples

- `examples/read_analog.py`  
very minimalist example to read one channel from an analog-to-digital converter
- `examples/display_analog.py`  
very minimalist example to read one channel from an analog-to-digital converter and display data as a history graph
- `examples/display_analog2.py`  
read two channels from an analog-to-digital converter and display data as a history graph
- `examples/read_INA219.py`  
read data from INA219 current and voltage sensor
- `examples/read_DS18B20.py` simple example to read the temperature sensor DS18B20
- `examples/readBMPx80.py` simple example to read the digital temperature and pressure sensor BMP180/280
- `examples/readMMA8451.py` simple example to read the digital accelerometer MMA8451
- `examples/runOsci.py`  
run an oscilloscope display, configuration as specified in `.yaml` file (default is `PSOsci.yaml`)
- `examples/GPIO-In-Out.py`  
example to control GPIO pins: generate square signal on output pin from variable voltage on input pin
- `examples/poissonLED.py`  
generate a random signal following Poisson statistics on a GPIO pin
- `examples/FreqGen.py`  
generate a fixed frequency signal on a GPIO pin

## Configuration files for *run\_phypi.py*

- `examples/Amperemeter.daq`  
display current and eventually voltage read from INA219 sensor
- `examples/Barometer.daq`  
uses BMP180 or BMP280 sensors to display temperature and air pressure
- `examples/Accelerometer.daq`  
uses MMA8451 to display x-, y- and z-acceleration
- `examples/NoiseMeter.daq`  
measure noise with a microphone connected to PicoScope USB oscilloscope; displays the *rms* of 200 samples taken over a time periods of 20 ms. Can also be used with geophone SM-24
- `examples/RGBsensor.daq` RGB color sensor
- `examples/ColorSpectrum.daq` six channel color sensor
- `examples/ToyData.daq` generation and display of simulated data
- `examples/ReplayData.daq`  
data from file (for demo mode)

## Documentation

- `doc/Kurs_digitale_Messwerterfassung_mit_PhyPiDAQ.md` (.pdf)  
German only: Introductory course to measuring with the Raspberry Pi

- `doc/Einrichten_des_Raspberry_Pi.md (.pdf)`

German only: setting up the Raspberry Pi for this project

- `doc/Komponenten_fuer_PhyPi.md (.pdf)`

recommended components for this project

- `doc/Bauanleitung_Kraftsensor.md (.pdf)`

building instructions for a force sensor