kafe Documentation

Release 1.0.1

D. Savoiu, G. Quast

March 15, 2016

kafe is a data fitting framework designed for use in undergraduate physics lab courses. It provides a basic *Python* toolkit for fitting models to data as well as visualisation of the data and the model function. It relies on *Python* packages such as `numpy` and `matplotlib`, and uses the *Python* interface to the minimizer *Minuit* contained in the data analysis framework *ROOT*.

CHAPTER

ONE

KAFE OVERVIEW

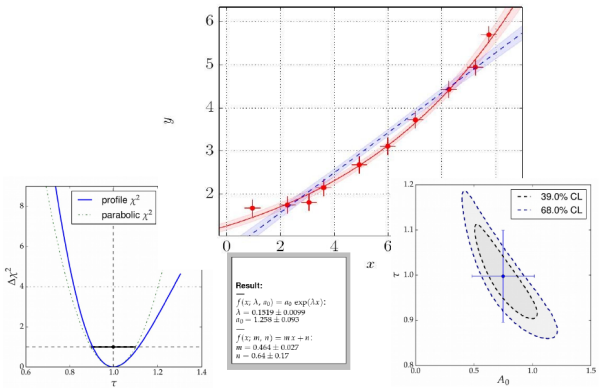

Fig. 1.1: *Graphical output generated with kafe*.

The `kafe` package provides a rather general approach to fitting of a model function to two-dimensional data points with correlated uncertainties in both dimensions. The *Python* API guarantees full flexibility for data input. Helper functions for file-based input and some examples are available for own applications.

Applications range from performing a simple average of measurements to complex situations with both correlated (systematic) and uncorrelated (statistical) uncertainties on the measurements of the x and y values described by a non-linear model function depending on a large number of parameters.

The model function describes the y values as a function of the x-values and a set of model parameters {p}, *y=f(x; {p})*. Full flexibility exists as model functions are implemented as *Python* code. Again, examples are provided, but user implementations are supported as well.

Fitting is based on the χ^2-method, assuming Gaussian errors and correlations described by covariance matrices. The level of agreement between data points and the fit model is expressed in terms of the χ^2 *probability*, i. e. the probability to find less agreement between data and model than actually observed. Full access to the covariance matrix of the - typically correlated - model parameters is provided.

The graphical output visualises the data and the fit model at the best-fit-point of the parameters and also shows the uncertainty of the fit model as a light band surrounding the line representing the model function. Plotting of confidence level contours for pairs of parameters or profiling of the χ^2 curves for each of the fit parameters are also provided.

1.1 Code Structure

The code of `kafe` is centred around very few classes to handle Data input, fitting and plotting, as illustrated in the figure on the right-hand side.

Data, their uncertainties, and, optionally, the correlations of the uncertainties - are passed through the interface of the `kafe` class `Dataset` (page 26). Input can be included in the *Python* code or is read from files in standardised or user-defined formats. The representation of the data within the `Dataset` (page 26) class is minimalistic,

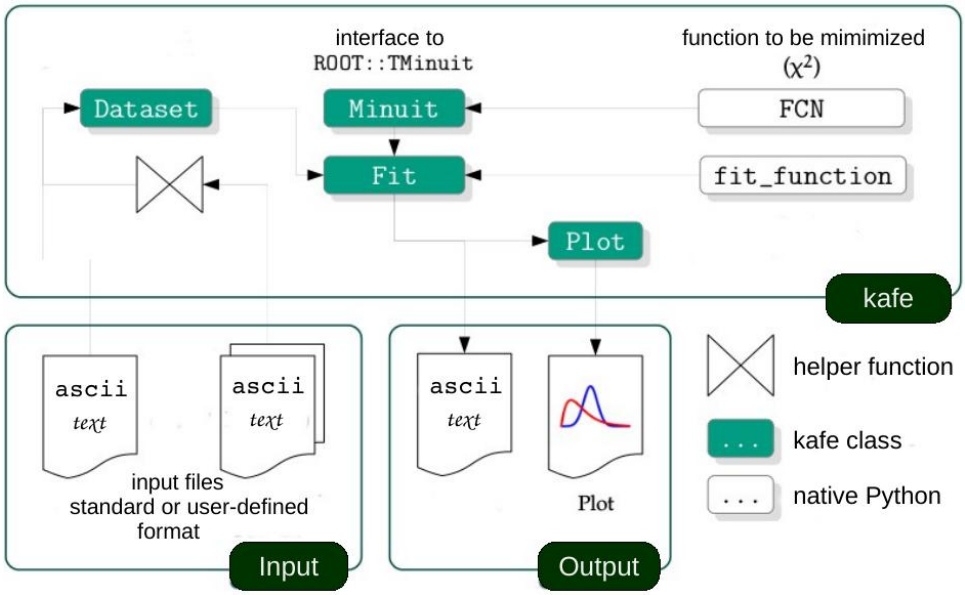

Fig. 1.2: *Code structure of the kafe package*

consisting of the x and y values and the full covariance matrices of their uncertainties. Correlated errors between x and y values are not supported yet, as such use cases are rare.

A helper function, *build_dataset()* (page 31), is available to transform various error models, like a combination of independent and correlated errors or common absolute or relative errors, to this basic format.

Adding a model function, taken either from a prepared set of fit functions within kafe or from a user's own *Python* implementation, results in a *Fit* (page 36) object, which controls the minimizer *Minuit* (page 43). Access to the final results of the fitting procedure is provided by data members of the *Fit* class.

One or multiple fit objects, i. e. the input data and model functions(s) at the best-fit point in parameter-space, are visualised by the class *Plot* (page 49) with the help of `matplotlib` functionality. The *plot* (page 49) module also contains functionality to display the model uncertainty by surrounding the model function at the best-fit values of the parameters by a light band, the one-σ uncertainty band, which is obtained by propagation of the uncertainties of the fit parameters taking into account their correlations.

Two-dimensional contour lines of pairs of parameters are obtained with the method *plot_contour()* (page 39) of the `Fit` class, which internally relies on the *mncont* method of the *Minuit* package. Contour curves are obtained from a scan of the χ^2-function around a fixed value, where each point on the curve represents the minimum with respect to all other free parameters in the fit, thus taking into account the correlation of a pair of parameters with all other parameters of the model.

In a similar way, the method *plot_profile()* (page 39) provides profiled χ^2 curves, i. e. the value of the minimal χ^2 as a function of one parameter while all other parameters are allowed to vary.

1.2 Fitting in a Nutshell

Fitting with **kafe** in a nutshell goes like this:

1. create a *Dataset* (page 26) object from your measurement data:

```
>>> my_d = kafe.Dataset(data=[[0., 1., 2.], [1.23, 3.45, 5.62]])
```

2. add errors (uncertainties) to your *Dataset* (page 26):

```
>>> my_d.add_error_source('y', 'simple', 0.5)  # y errors, all +/- 0.5
```

3. import a model function from *kafe.function_library* (page 41) (or define one yourself):

```
>>> from kafe.function_library import linear_2par
```

4. create a *Fit* (page 36) object from your *Dataset* (page 26) and your model function:

```
>>> my_f = kafe.Fit(my_d, linear_2par)
```

5. do the fit:

```
>>> my_f.do_fit()
```

6. *(optional)* if you want to see a plot of the result, use the *Plot* (page 49) object:

```
>>> my_p = kafe.Plot(my_f)
>>> my_p.plot_all()
>>> my_p.show()
```

1.3 Example

Only very few lines of Python code are needed to perform fits with kafe. The snippet of code shown below performs a fit of a quadratic function to some data points with uncertainties:

```
from kafe import *
from kafe.function_library import quadratic_3par

#### build a Dataset instance:
myDataset = build_dataset(
    [0.05,0.36,0.68,0.80,1.09,1.46,1.71,1.83,2.44,2.09,3.72,4.36,4.60],
    [0.35,0.26,0.52,0.44,0.48,0.55,0.66,0.48,0.75,0.70,0.75,0.80,0.90],
    yabserr=[0.06,0.07,0.05,0.05,0.07,0.07,0.09,0.1,0.11,0.1,0.11,0.12,0.1],
    title='some data',
    axis_labels=['$x$', '$y=f(x)$'])

#### Create the Fit object
myFit = Fit(myDataset, quadratic_3par)
# Set initial values and error estimates
myFit.set_parameters((0., 1., 0.2), (0.5, 0.5, 0.5))
# Do the Fit
myFit.do_fit()

#### Create result plots and output them
myPlot = Plot(myFit)
myPlot.plot_all()
myPlot.save('kafe_example0.pdf') # to file

myPlot.show()                    # to screen
```

The output in text form (also available via various `get_...()` methods of the *Fit* (page 36) class) contains the values of the parameters at the best-fit point, their correlation matrix and the fit probability. The example produces the following graphical output:

The parametrisation chosen in this example leads to a strong correlation of the fit parameters. This can be graphically visualised by adding the following lines at the end of the example:

```
### Create and save contour plots
contour1 = myFit.plot_contour(0, 1, dchi2=[1.,2.3])
contour2 = myFit.plot_contour(0, 2, dchi2=[1.,2.3])
contour3 = myFit.plot_contour(1, 2, dchi2=[1.,2.3])
contour1.savefig('kafe_example0_contour1.pdf')
contour2.savefig('kafe_example0_contour2.pdf')
contour3.savefig('kafe_example0_contour3.pdf')
```

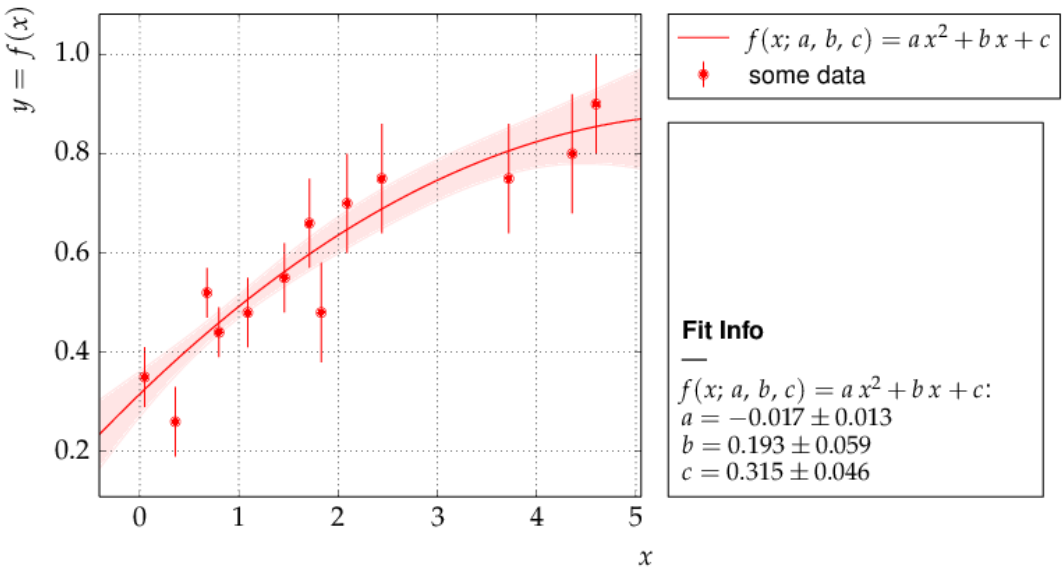

Fig. 1.3: Example: *Data points with one-dimensional error bars compared to a quadratic model function with* **kafe**.

The example code produces two confidence-level contours for each pair of parameters (with *id=0*, *id=1* and *id=2*), corresponding to an increase of the χ^2-function with respect to the minimum by the values given in the list passed as the third parameter to the method `myFit.plot_contour()`. The resulting graphical representation, as shown below, displays the 39% contours, corresponding to the one-sigma errors, and the 68% contours. The uncertainties on each parameter, indicated by the error bars, are also shown. They correspond to the projections of the one-sigma contours on the axes.

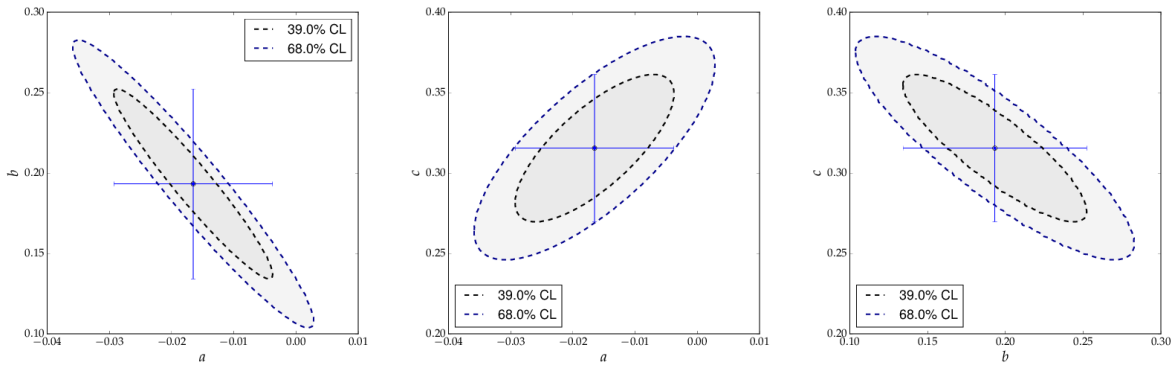

Fig. 1.4: *Contour curves of a pairs of paramters a, b and c of the example above, calculated with* **kafe**.

More and advanced examples - like fitting different models to one data set, comparison of different data sets with model functions, averaging of correlated measurements or fits with a large number of parameters - are provided as part of the `kafe` distribution and are described in the section *Examples* below. They may serve as a starting point for own applications.

1.4 Installation

To install *kafe*, unpack the archive *kafe-<version>.tgz* , change to the directory *kafe-<version>* and follow the installation instructions below.

1.) Install using *pip*:

To install kafe using the *Pip* installer (http://www.pip-installer.org/), simply run the helper script as root:

```
./install.sh
```

If you don't have Pip installed, use:

```
easy_install pip
```

To remove kafe using pip, just run the helper script:

```
./uninstall.sh
```

2. Install using *setuptools*:

Installing using Python's *setup* tools works, but does not provide a clean uninstall. Use this method if installing with *Pip* is not possible:

```
python setup.py install
```

`kafe` needs a working version of the CERN data analysis framework `root`, freely available at http://root.cern.ch

1.4.1 Dependencies

The recommended versions of external packages for `kafe` are as follows, the version numbers in parentheses refer to the minimum requirements:

```
Python packages:
  * SciPy >= 0.12.0 (0.9.0), which includes
      - NumPy >= 1.7.1 (1.6.1) and
      - matplotlib >= 1.2.0 (1.1.1)

Other dependencies:
  * ROOT >= 5.34 (http://root.cern.ch)
  * Qt4 >= 4.8.5 `(could work with other versions)`
  * PyQt >= 3.18.1 `(could work with other versions)`
  * A LaTeX distribution `(tested with texlive)`
```

Be sure that the version of *ROOT* you use is compiled with *PyROOT* support. For *Python* to see the *PyROOT* bindings, the following environment variables must be set correctly:

```
export ROOTSYS=<directory where ROOT is installed>
export LD_LIBRARY_PATH=${LD_LIBRARY_PATH}:$ROOTSYS/lib
export PYTHONPATH=$ROOTSYS/lib:$PYTHONPATH
```

For more info, refer to [http://root.cern.ch/drupal/content/pyroot].

Qt is needed because it is the supported interactive front-end for `matplotlib`. Other front-ends are not supported and can cause weird behaviour.

LaTeX is used by `matplotlib` for displaying labels and mathematical expressions on graphs.

CHAPTER

TWO

FIT EXAMPLES, UTILITIES, TIPS AND TRICKS

A wide range of applications of the `kafe` core and the usage of the helper functions is exemplified here. All of them are contained in the sub-directory `examples/` of the `kafe` distribution and are intended to serve as a basis for user projects.

2.1 Example 1 - model comparison

To decide whether a model is adequate to describe a given set of data, typically several models have to be fit to the same data. Here is the code for a comparison of a data set to two models, namely a linear and an exponential function:

```
# import everything we need from kafe
from kafe import *
# additionally, import the two model functions we want to fit:
from kafe.function_library import linear_2par, exp_2par

#############
# Load the Dataset from the file
my_dataset = Dataset(input_file='dataset.dat', title="Example Dataset")
### Create the Fits
my_fits = [Fit(my_dataset, exp_2par),
           Fit(my_dataset, linear_2par)]
### Do the Fits
for fit in my_fits:
fit.do_fit()
### Create the plots, save and show output
my_plot = Plot(my_fits[0], my_fits[1])
my_plot.plot_all(show_data_for=0) # show data only once (it's the same data)
my_plot.save('plot.pdf')
my_plot.show()
```

The file *dataset.dat* contains x and y data in the standard `kafe` data format, where values and errors (and optionally also correlation coefficients) are given for each axis separately. # indicates a comment line, which is ignored when reading the data:

```
# axis 0: x
# datapoints  uncor. err.
0.957426  3.0e-01
2.262212  3.0e-01
3.061167  3.0e-01
3.607280  3.0e-01
4.933100  3.0e-01
5.992332  3.0e-01
7.021234  3.0e-01
8.272489  3.0e-01
9.250817  3.0e-01
9.757758  3.0e-01
```

```
# axis 1: y
# datapoints  uncor. err.
1.672481  2.0e-01
1.743410  2.0e-01
1.805217  2.0e-01
2.147802  2.0e-01
2.679615  2.0e-01
3.110055  2.0e-01
3.723173  2.0e-01
4.430122  2.0e-01
4.944116  2.0e-01
5.698063  2.0e-01
```

The resulting output is shown below. As can be seen already from the graph, the exponential model better describes the data. The χ^2 probability in the printed output shows, however, that the linear model would be marginally acceptable as well:

```
linear_2par
chi2prob 0.052
HYPTEST  accepted (CL 5%)

exp_2par
chi2prob 0.96
HYPTEST  accepted (CL 5%)
```

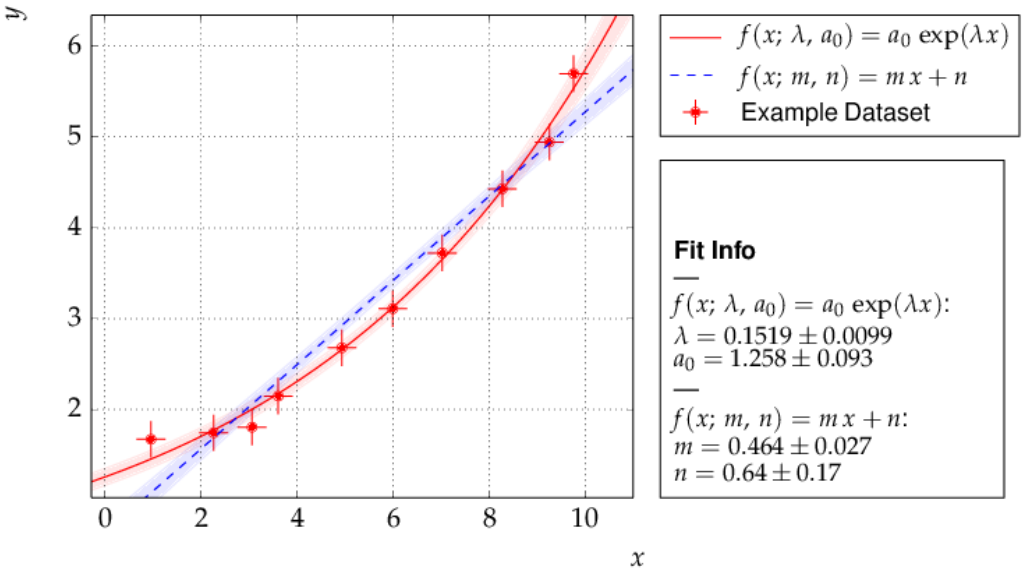

Fig. 2.1: *Output of example1 - compare two models*

The contour curves of the two fits are shown below and reflect the large correlations between the fit parameters. The right plot of the profile χ^2 curve shows that there is a slight deviation from the parabolic curve in the fist fit of a non-linear (exponential) function. For more details on the profiled χ^2 curve see the discussion of example 3, where the difference is more prominent.

2.2 Example 2 - two fits and models

Another typical use case consists of comparing two sets of measurements and the models derived from them. This is very similar to the previous example with minor modifications:

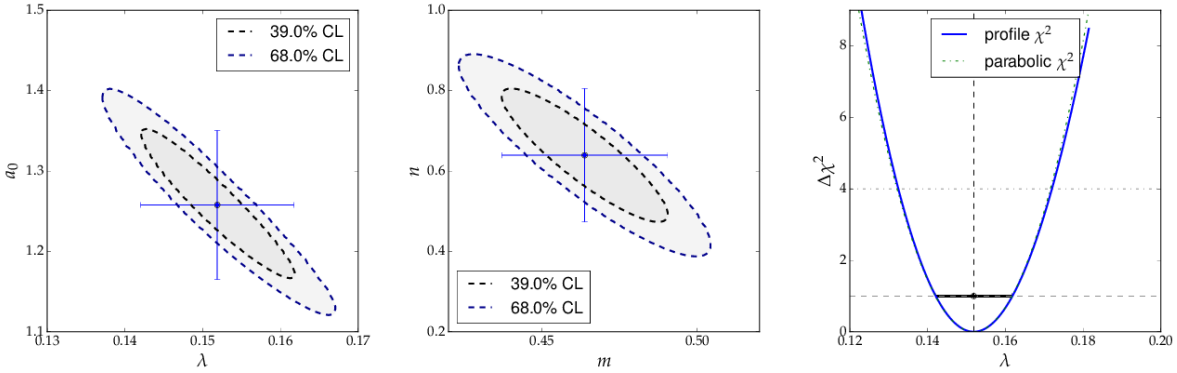

Fig. 2.2: *Contour curves and a profile χ^2 curve for the fits in example 1*

```
...

############
# Workflow #
############
# Load two Datasets from files
my_datasets = [Dataset(input_file='dataset1.dat', title="Example Dataset 1"),
               Dataset(input_file='dataset2.dat', title="Example Dataset 2")]
# Create the Fits
...
# Do the Fits
...
# Create the plots
my_plot.plot_all()  # this time without any arguments, i.e. show everything
...
```

This results in the following output:

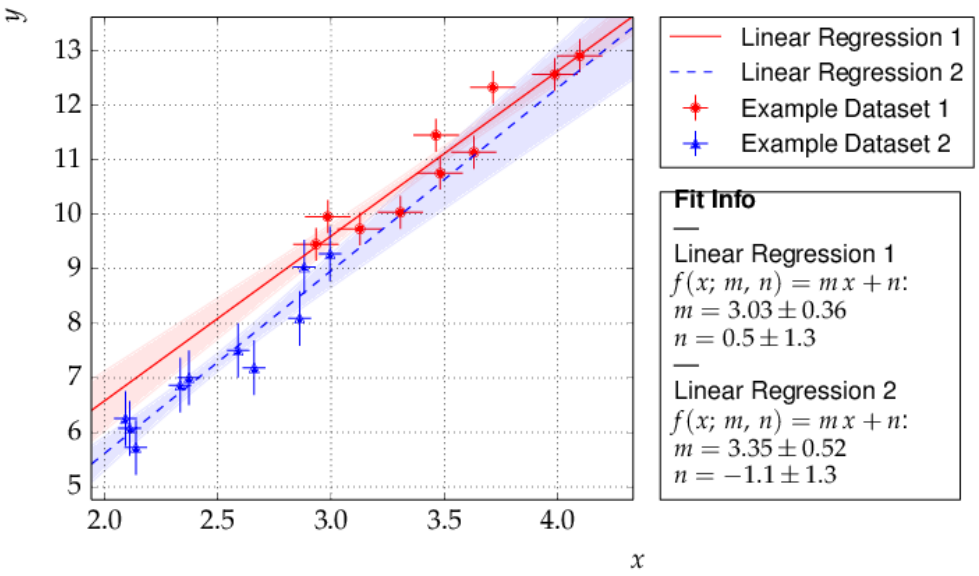

Fig. 2.3: *Output of example2 - comparison of two linear fits.*

Although the parameters extracted from the two data sets agree within errors, the uncertainty bands of the two functions do not overlap in the region where the data of Dataset 2 are located, so the data are most probably

incompatible with the assumption of an underlying single linear model.

2.3 Example 3 - non-linear fit with non-parabolic errors

Very often, when the fit model is a non-linear function of the parameters, the χ^2 function is not parabolic around the minimum. A very common example of such a case is an exponential function prarametrised as shown in the code fragment below. *Minuit* contains a spacial algorithm, *Minos*, which returns correct errors also in this case. Instead of using the curvature the minimum, *Minos* follows the χ^2 function from the minimum to the point where it crosses the the value *minimum+up*, where *up=1* corresponds to one standard deviation in χ^2 fits. During the scan of the χ^2 function at different values of each parameter the minimum with respect to all other parameters in the fit is determined, thus making sure that all correlations among the parameters are taken into account. In case of a parabolic χ^2 function, the *Minos* errors are identical to those obtained by the *Hesse* algorithm, but are typically larger or asymmetric in other cases.

The method `kafe.do_fit()` executes the *Minos* algorithm after completion of a fit and prints the *Minos* errors if the deviation from the parabolic result are larger than 5% .

A graphical visualisation is provided by the method `plot_profile()` , which displays the profile χ^2 curve for the parameter with name or index passed as an argument to the method.

The relevant code fragments and the usage of the method `kafe.fit.plot_profile()` are illustrated here:

```
...
# definition of the fit function
@ASCII(x_name="t", expression="A0*exp(-t/tau)")
# Set some LaTeX-related parameters for this function
@LaTeX(name='A', x_name="t",
   parameter_names=('A_0', '\\tau{}'),
   expression="A_0\\,\\exp(\\frac{-t}{\\tau})")
@FitFunction
def exponential(t, A0=1, tau=1):
   return A0 * exp(-t/tau)
...
# Load the data, perform fit and plot
my_dataset = Dataset(input_file='dataset.dat', title="Example Dataset")
my_fit = Fit(my_dataset, exponential)
my_fit.do_fit()
my_plot = Plot(my_fit)
my_plot.plot_all()
# --> display contours and profile
contour = my_fit.plot_contour(0, 1, dchi2=[1.,2.3])
profile1=my_fit.plot_profile(0)
profile2=my_fit.plot_profile(1)
# Show the plots
my_plot.show()
```

The data points were generated using a normalisation factor of *A0=1.* and a lifetime τ*=1.*. The resulting fit output below demonstrates that this is well reproduced within uncertainties:

The contour A_0 *vs* τ, however, is not an ellipse, as shown in the figure below. The profiled χ^2 curves are also shown; they deviate significantly from parabolas. The proper one-sigma uncertainty in the sense of a 68% confidence interval is read from these curves by determining the parameter values where the χ^2 curves cross the horizontal lines at a value of $\Delta\chi^2$=1 above the minimum. The two-sigma uncertainties correspond to the intersections with the horizontal line at $\Delta\chi^2$=4.

Note: a more parabolic behaviour is achieved by using the width parameter $\lambda=1/\tau$ in the parametrisation of the exponential function.

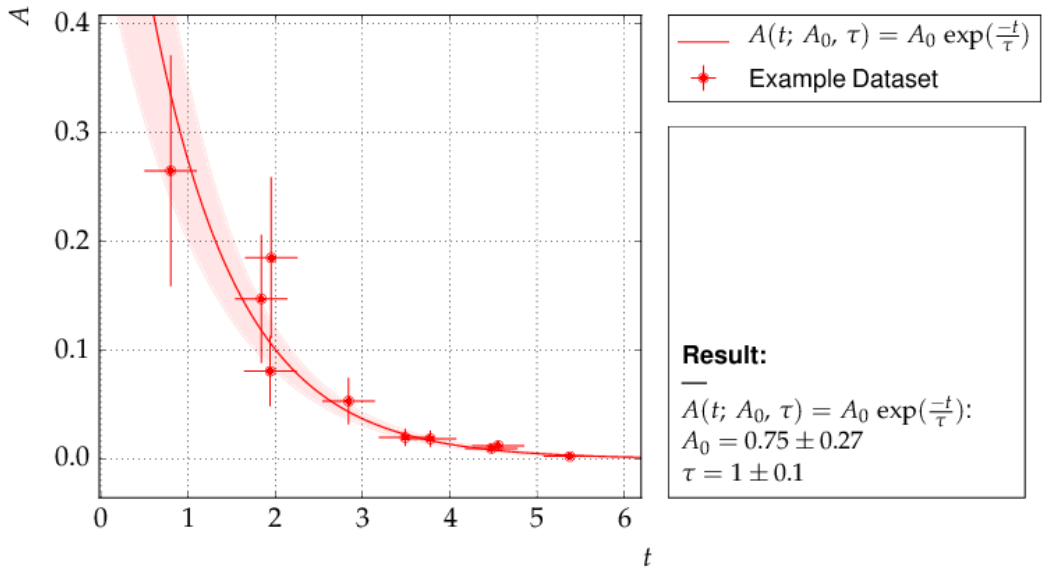

Fig. 2.4: *Output of example 3 - Fit of an exponential*

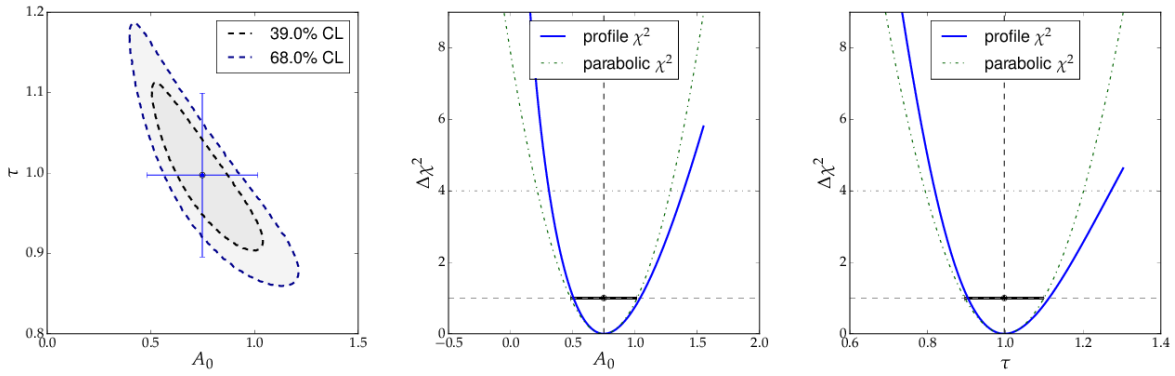

Fig. 2.5: *Contour and profile χ^2 curves of example 3*

2.4 Example 4 - average of correlated measurements

The average of a set of measurements can be considered as a fit of a constant to a set of input data. This example illustrates how correlated errors are handled in `kafe`. Measurements can have a common error, which may be absolute or relative, i. e. depend on the input value. In more complicated cases the full covariance matrix must be constructed.

`kafe` has a helper function, `build_dataset()` in module *fit* (page 36), which aids in setting up the covariance matrix and transforming the input to the default format used by the *Dataset* (page 26) and *Fit* (page 36) classes. Two further helper functions in module *file_tools* (page 32) aid in reading the appropriate information from data files.

1. The function *parse_column_data()* (page 33) reads the input values and their independent errors from one file, and optionally covariance matrices for the x and y axes from additional files. The field ordering is defined by a control string.
2. Another helper function, *buildDataset_fromFile()* (page 32), specifies input values or blocks of input data from a single file with keywords.

The second version needs only very minimal additional user code, as illustrated here:

```
from kafe import *
from kafe.function_library import constant_1par
from kafe.file_tools import buildDataset_fromFile
#
# ------------------------------------------------------
fname = 'WData.dat'
curDataset = buildDataset_fromFile(fname) # Dataset from input file
curFit = Fit(curDataset, constant_1par)   # set up the fit object
curFit.do_fit()

myPlot = Plot(curFit)
myPlot.plot_all()
myPlot.save("plot.pdf")
myPlot.show()
```

The input file is necessarily more complicated, but holds the full information on the data set in one place. Refer to the documentation of the function *parse_general_inputfile()* (page 34) in module *file_tools* (page 32) for a full description of the currently implemented keywords. The input file for the averaging example is here:

```
# Measurements of W boson mass (combined LEP2, 2013)
# ------------------------------------------------
# example to use parse_general_inputfile from kafe;
#  covariance matrix build from common errors
# --
#  Meta data for plotting
*TITLE measurements of the W boson mass
*xLabel number of measurement
*yLabel $m_\matrhm{W}$
*yUnit GeV/$c^2$

# x data need not be given for averaging

# ------------------------------------------------------------
#  Measurements of W mass by ALEPH, DELPI, L3 and OPAL
#                               from from LEP2 Report Feb. 2013
#  common errors within channels
#                     2q2l: 0.021 GeV,
#                       4q: 0.044 GeV,
#     and between channels: 0.025 GeV
# ------------------------------------------------------------
```

```
*yData_SCOV
# W_mass  err     syst    sqrt of the off-diagonal
# 2q2l channel                          elements of the
80.429  0.055   0.021          #         covariance matrix
80.339  0.073   0.021   0.021
80.217  0.068   0.021   0.021 0.021
80.449  0.058   0.021   0.021 0.021 0.021
# 4q  channel
80.477  0.069   0.044   0.025 0.025 0.025 0.025 0.044
80.310  0.091   0.044   0.025 0.025 0.025 0.025 0.044 0.044
80.324  0.078   0.044   0.025 0.025 0.025 0.025 0.044 0.044 0.044
80.353  0.068   0.044   0.025 0.025 0.025 0.025 0.044 0.044 0.044 0.044
```

2.5 Example 5 - non-linear multi-parameter fit (damped oscillation)

This example shows the fitting of a more complicated model function to data collected from a damped harmonic oscillator. In such non-linear fits, stetting the initial values is sometimes crucial to let the fit converge at the global minimum. The *Fit* (page 36) object provides the method *set_parameters()* (page 40) for this purpose. As the fit function for this problem is not a standard one, it is defined explicitly making use of the decorator functions available in `kafe` to provide nice type setting of the parameters. This time, the function *parse_column_data()* (page 33) is used to read the input, which is given as separate columns with the fields

```
<time> <Amplitude> <error on time> <error on Amplitude>
```

Here is the example code:

```
...
from kafe import *
from numpy import exp, cos
# Model function definition #
# --------------------------
# Set an ASCII expression for this function
@ASCII(x_name="t", expression="A0*exp(-t/tau)*cos(omega*t+phi)")
# Set some LaTeX-related parameters for this function
@LaTeX(name='A', x_name="t",
       parameter_names=('a_0', '\\tau{}', '\\omega{}', '\\varphi{}'),
       expression="a_0\\,\\exp(-\\frac{t}{\\tau})\,"
                  "\cos(\\omega{}\\,t+\\varphi{})")
@FitFunction
def damped_oscillator(t, a0=1, tau=1, omega=1, phi=0):
    return a0 * exp(-t/tau) * cos(omega*t + phi)

# ---- Workflow #
# load the experimental data from a file
my_dataset = parse_column_data('damped_oscillation.dat',
    field_order="x,y,xabserr,yabserr", title="Damped Oscillator",
    axis_labels=['Time t', 'Amplitude'])
# --- Create the Fit
my_fit = Fit(my_dataset, damped_oscillator)
# Set the initial values for the fit:
#                      a_0 tau omega phi
my_fit.set_parameters((1., 2., 6.28, 0.8))
my_fit.do_fit()
# --- Create and output the plots
my_plot = Plot(my_fit)
my_plot.plot_all()
#my_plot.save('plot.pdf')
my_fit.plot_correlations() # all contours and profiles
my_plot.show()
```

This is the resulting output:

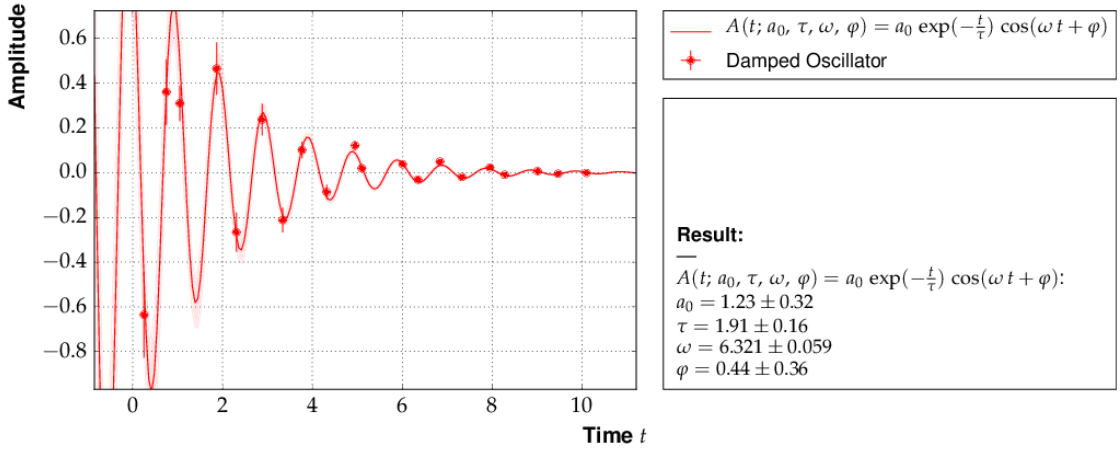

Fig. 2.6: *Example 5 - fit of the time dependence of the amplitude of a damped harmonic oscillator.*

The fit function is non-linear, and, furthermore, there ist not a single local minimum - e.g. a shift in phase of 180° corresonds to a change in sign of the amplitude, and valid solutions are also obtained for multiples of the base frequency. Checking of the validity of the fit result is threfore important. The method `plot_correlations()` (page 39) provides the contours of all pairs of parameters and the profiles for each of the parameters and displays them in a matrix-like arrangement. Distorted contour-ellipses show wether the result is affected by near-by minima, and the profiles allow to correctly assign the parameter uncertainties in cases where the parabolic approximation is not precise enough.

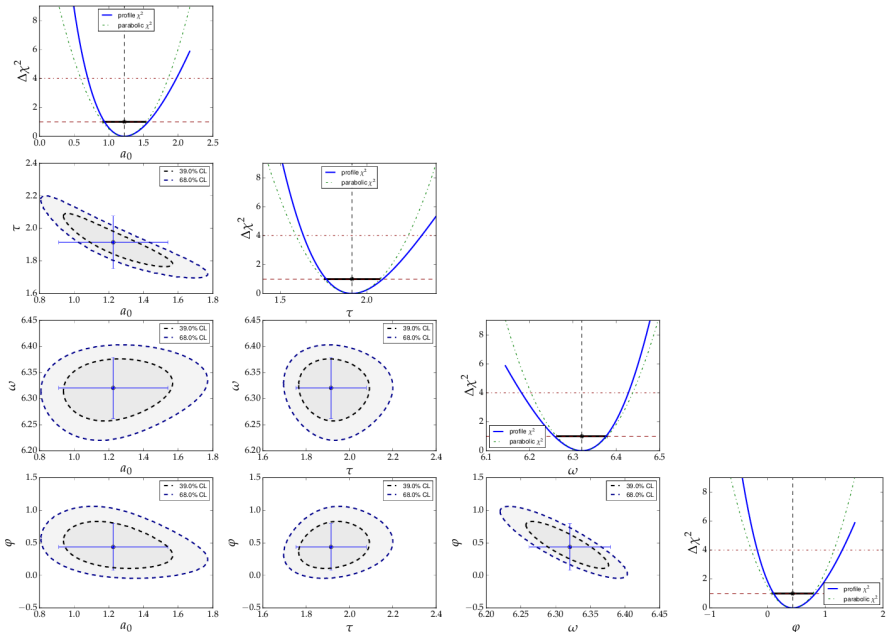

Fig. 2.7: *Confidence contours and profiles for example 5.*

2.6 Example 6 - linear multi-parameter fit

This example is not much different from the previous one, except that the fit function, a standard fourth-degree polynomial from the module `function_library` (page 41), is modified to reflect the names of the problem given, and `matplotlib` functionality is used to influence the output of the plot, e.g. axis names and linear or

logarithmic scale.

It is also shown how to circumvent a problem that often arises when errors depend on the measured values. For a counting rate, the (statistical) error is typically estimated as the square root of the (observed) number of entries in each bin. For large numbers of entries, this is not a problem, but for small numbers, the correlation between the observed number of entries and the error derived from it leads to a bias when fitting functions to the data. This problem can be avoided by iterating the fit procedure:

In a pre-fit, a first approximation of the model function is determined, which is then used to calculate the expected errors, and the original errors are replaced before performing the final fit. Note that the numbers of entries in the bins must be sufficiently large to justify a replacement of the (asymmetric) Poisson uncertainties by the symmetric uncertainties implied by the χ^2-method.

The implementation of this procedure needs accesses some more fundamental methods of the *Dataset*, *Fit* and *FitFunction* classes. The code shown below demonstrates how this can be done with `kafe`, using some of its lower-level, internal interfaces:

```
from kafe.function_library import poly4
# modify function's independent variable name to reflect its nature:
poly4.x_name = 'x=cos(t)'
poly4.latex_x_name = 'x=\\cos(\\theta)'
...

# Set the axis labels appropriately
my_plot.axis_labels = ['$\\cos(\\theta)$', 'counting rate']
...
# load the experimental data from a file
my_dataset = parse_column_data(
  'counting_rate.dat',
  field_order="x,y,yabserr",
  title="Counting Rate per Angle")

### pre-fit
# error for bins with zero contents is set to 1.
covmat = my_dataset.get_cov_mat('y')
for i in range(0, len(covmat)):
    if covmat[i, i] == 0.:
        covmat[i, i] = 1.
my_dataset.set_cov_mat('y', covmat) # write it back

# Create the Fit
my_fit = Fit(my_dataset, poly4)
#            fit_label="Linear Regression " + dataset.data_label[-1])

# perform an initial fit with temporary errors (minimal output)
my_fit.call_minimizer(final_fit=False, verbose=False)

# set errors using model at pre-fit parameter values:
#       sigma_i^2=cov[i, i]=n(x_i)
fdata = my_fit.fit_function.evaluate(my_fit.xdata,
                                     my_fit.current_parameter_values)
np.fill_diagonal(covmat, fdata)
my_fit.current_cov_mat = covmat  # write new covariance matrix
### end pre-fit - rest is as usual
my_fit.do_fit()
# Create the plots and --
my_plot = Plot(my_fit)
# -- set the axis labels
my_plot.axis_labels = ['$\\cos(\\theta)$', 'counting rate']
# -- set scale linear / log
my_plot.axes.set_yscale('linear')
...
```

This is the resulting output:

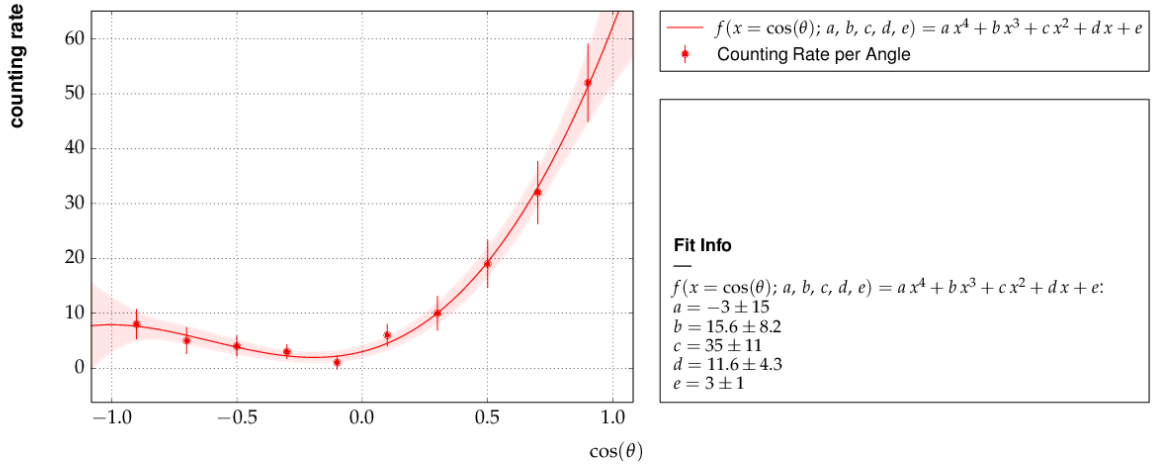

Fig. 2.8: *Output of example 6 - counting rate.*

2.7 Example 7 - another non-linear multi-parameter fit (double-slit spectrum)

Again, not much new in this example, except that the model is now very non-linear, the intensity distribution of light after passing through a double-slit. The non-standard model definition again makes use of the decorator mechanism to provide nice output - the decorators (expressions beginning with '@') can safely be omitted if *LaTeX* output is not needed. Setting of appropriate initial conditions is absolutely mandatory for this example, because there exist many local minima of the χ^2 function.

Another problem becomes obvious when carefully inspecting the fit function definition: only two of the three parameters g, b or k can be determined, and therefore one must be kept fixed, or an external constraint must be applied. Failing to do so will result in large, correlated errors on the parameters g, b and k as an indication of the problem.

Fixing parameters of a model function is achieved by the method *fix_parameters()* (page 37), and a constraint within a given uncertainty is achieved by the method *constrain_parameters()* (page 37) of the *Fit* (page 36) class.

Here are the interesting pieces of code:

```
...
# Model function definition #
# Set an ASCII expression for this function
@ASCII(x_name="x", expression="I0*(sin(k/2*b*sin(x))/(k/2*b*sin(x))"
                              "*cos(k/2*g*sin(x)))^2")
# Set some LaTeX-related parameters for this function
@LaTeX(name='I', x_name="\\alpha{}",
       parameter_names=('I_0', 'b', 'g', 'k'),
       expression="I_0\\,\\left(\\frac{\\sin(\\frac{k}{2}\\,b\\,\\sin{\\alpha})}"
                  "{\\frac{k}{2}\\,b\\,\\sin{\\alpha}}"
                  "\\cos(\\frac{k}{2}\\,g\\,\\sin{\\alpha})\\right)^2")
@FitFunction
def double_slit(alpha, I0=1, b=10e-6, g=20e-6, k=1.e7):
    k_half_sine_alpha = k/2*sin(alpha)  # helper variable
    k_b = k_half_sine_alpha * b
    k_g = k_half_sine_alpha * g
    return I0 * (sin(k_b)/(k_b) * cos(k_g))**2

...

# Set the initial values for the fit
```

```
#                        I    b       g         k
my_fit.set_parameters((1., 20e-6, 50e-6, 9.67e6))
# fix one of the (redundant) parameters, here 'k'
my_fit.fix_parameters('k')

...
```

If the parameter k in the example above has a (known) uncertainty, is is more appropriate to constrain it within its uncertainty (which may be known from an independent measurement or from the specifications of the laser used in the experiment). To take into account a wave number k known with a precision of 10‘000 the last line in the example above should be replaced by:

```
...
my_fit.constrain_parameters(['k'], [9.67e6], [1.e4])
...
```

This is the resulting output:

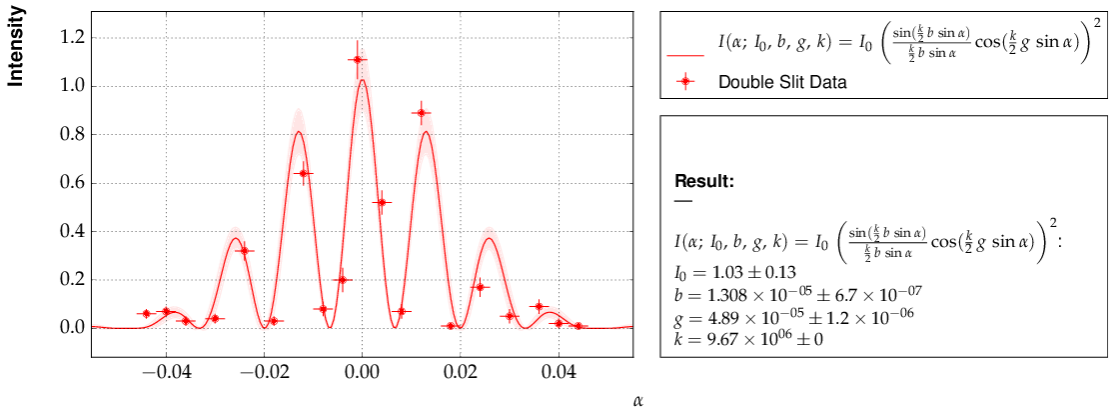

Fig. 2.9: *Example 7 - fit of the intensity distribution of light behind a double slit with fixed or constrained wave length.*

2.8 Example 8 - fit of a Breit-Wigner Resonance to data with correlated errors

This example illustrates how to define the data and the fit function in a single file - provided by the helper function *buildFit_fromFile()* (page 33) in module *file_tools* (page 32). Parsing of the input file is done by the function *parse_general_inputfile()* (page 34), which had already been introduced in Example 4. The definition of the fit function as *Python* code including the `kafe` decorators in the input file, however, is new. Note: because spaces are used to to separate data fields in the input file, spaces needed for proper *Python* indentation have to be replaced by ‘~’. The last key in the file defines the start values of the parameters and their initial ranges.

The advantage of this approach is the location of all data and the fit model in one place, which is strictly separated from the *Python* code. The *Python* code below is thus very general and can handle a large large variety of problems without modification (except for the file name, which could easily be passed on the command line):

```
from kafe import *
from kafe.file_tools import buildFit_fromFile
# ------------------------------------------------------------
fname = 'LEP-Data.dat'
# initialize fit object from file
BWfit = buildFit_fromFile(fname)
BWfit.do_fit()
```

```
#
BWplot = Plot(BWfit)
BWplot.plot_all()
BWplot.save("plot.pdf")
BWplot.show()
```

The magic happens in the input file, which now has to provide all the information needed to perform the fit:

```
# Fit of a Breit-Wigner function to
#      measurements of hadronic Z cross sections at LEP
# - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - -
#  Meta-data for plotting
*TITLE  LEP Hadronic Cross Section ($\sigma^0_\mathrm{had}$)
*xLabel $E_CM$
*xUnit  $\mathrm{GeV}$
*yLabel $\sigma^0_{\mathrm{had}}$
*yUnit  $\mathrm{nb}$

#-----------------------------------------------------------------------
# DATA: average of hadronic cross sections measured by
#  ALEPH, DELPHI, L3 and OPAL around 7 energy points at the Z resonance
#-----------------------------------------------------------------------

# CMenergy E err
*xData
 88.387  0.005
 89.437  0.0015
 90.223  0.005
 91.238  0.003
 92.059  0.005
 93.004  0.0015
 93.916  0.005
# Centre-of-mass energy has a common uncertainty
*xAbsCor 0.0017

# sig^0_h  sig err     #  rad.cor  sig_h measured
*yData
 6.803   0.036      #  1.7915    5.0114
 13.965  0.013      #  4.0213    9.9442
 26.113  0.075      #  7.867    18.2460
 41.364  0.010      #  10.8617  30.5022
 27.535  0.088      #  3.9164   23.6187
 13.362  0.015      # -0.6933   14.0552
  7.302  0.045      # -1.8181    9.1196
# cross-sections have a common relative error
*yRelCor 0.0007

*FITLABEL Breit-Wigner-Fit {\large{( with s-dependent width )}}
*FitFunction
# Breit-Wigner with s-dependent width
@ASCII(expression='s0*E^2*G^2/[(E^2-M^2)^2+(E^4*G^2/M^2)]')
@LaTeX(name='f', parameter_names=('\\sigma^0', 'M_Z', '\\Gamma_Z'),
expression='\\frac{\\sigma^0\\, M_Z^2\\Gamma^2}'
               '{((E^2-M_Z^2)^2+(E^4\\Gamma^2 / M_Z^2))}')
@FitFunction
def fitf(E, M=91.2, G=2.5, s0=41.0):
~~~~return s0*E*E*G*G/((E*E-M*M)**2+(E**4*G*G/(M*M)))

*InitialParameters    # set initial values and ranges
91.2 0.1
2.5  0.1
41.  0.5
```

Here is the output:

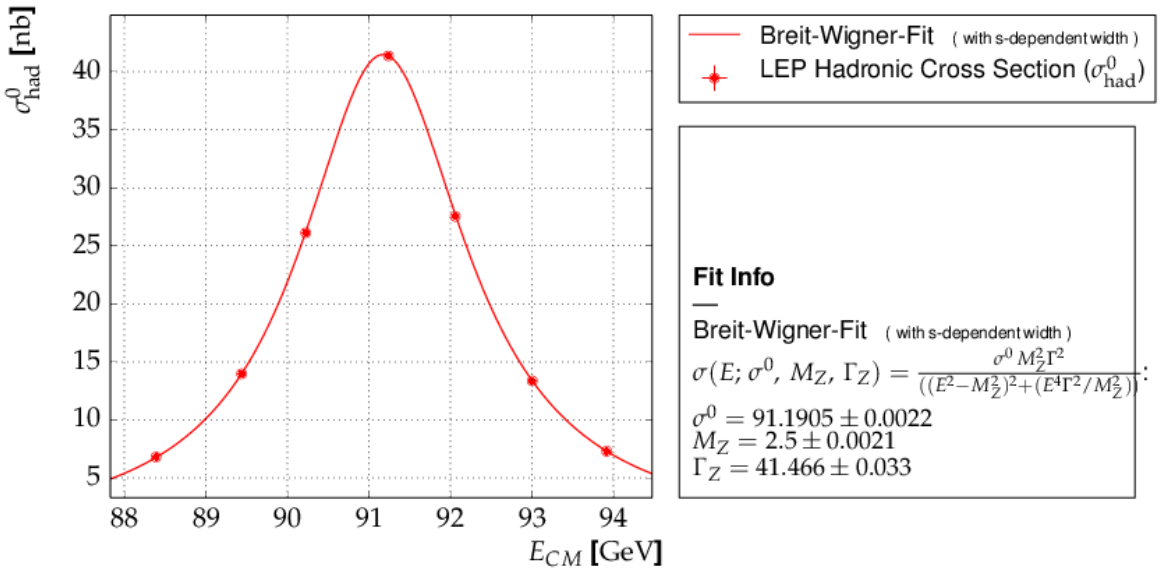

Fig. 2.10: *Output of example 8 - Fit of a Breit-Wigner function.*

This example also contains a code snippet demonstrating how to plot contours by calling the `Fit` (page 36) object's `plot_contour()` (page 39) method. This is the code:

```
# plot pairs of contours at 1 sigma, 68%, 2 sigma and 95%
cont_fig1 = BWfit.plot_contour(0, 1, dchi2=[1.,2.3,4.,5.99])
cont_fig2 = BWfit.plot_contour(0, 2, dchi2=[1.,2.3,4.,5.99])
cont_fig3 = BWfit.plot_contour(1, 2, dchi2=[1.,2.3,4.,5.99])
# save to files
cont_fig1.savefig("kafe_BreitWignerFit_contour12.pdf")
cont_fig2.savefig("kafe_BreitWignerFit_contour13.pdf")
cont_fig3.savefig("kafe_BreitWignerFit_contour23.pdf")
```

The resulting pictures show that parameter correlations are relatively small:

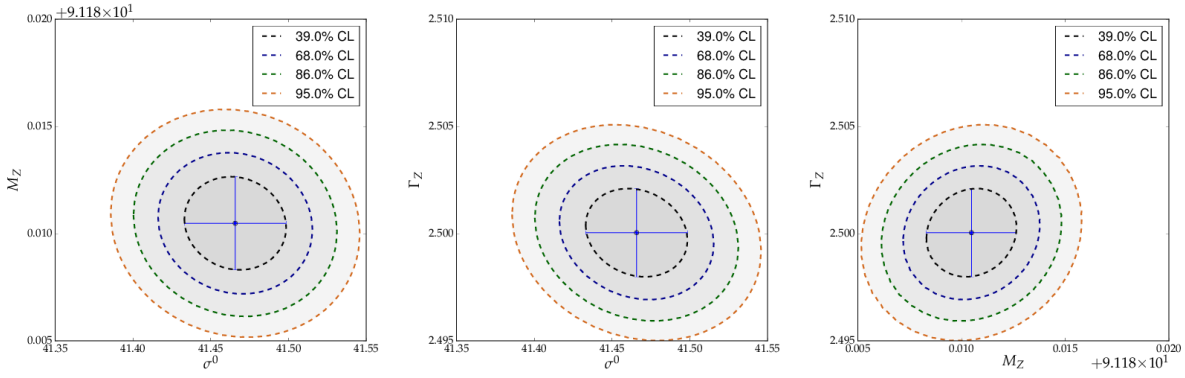

Fig. 2.11: *Contours generated in example 8 - Fit of a Breit-Wigner function.*

2.9 Example 9 - fit of a function to histogram data

This example brings us to the limit of what is currently possible with `kafe`. Here, the data represent the center of a histogram bins ad the number of entries, n_i, in each bin. The (statistical) error is typically estimated as the square root of the (observed) number of entries in each bin. For large numbers of entries, this is not a problem, but for small numbers, especially for bins with 0 entries, the correlation between the observed number of entries and the error derived from it leads to a bias when fitting functions to the histogram data. In particular, bins with zero entries cannot be handled in the χ^2-function, and are typically omitted to cure the problem. However, a bias remains, as bins with downward fluctuations of the observed numbers of events get assigned smaller errors and hence larger weights in the fitting procedure - leading to the aforementioned bias.

These problems are avoided by using a likelihood method for such use cases, where the Poisson distribution of the uncertainties and their dependence on the values of the fit model is properly taken into account. However, the χ^2-method can be saved to some extend if the fitting procedure is iterated. In a pre-fit, a first approximation of the model function is determined, where the error in bins with zero entries is set to one. The model function determined from the pre-fit is then used to calculate the expected errors for each bin, and the original errors are replaced before performing the final fit. Note that the numbers of entries in the bins must be sufficiently large to justify a replacement of the (asymmetric) Poisson uncertainties by the symmetric uncertainties implied by the χ^2-method.

The code shown below demonstrates how to get a grip on such more complex procedures with more fundamental methods of the *Dataset*, *Fit* and *FitFunction* classes:

```
...
# Load Dataset from file
hdataset = Dataset(input_file='hdataset.dat', title="Data for example 9")

# error for bins with zero contents is set to 1.
covmat = hdataset.get_cov_mat('y')
for i in range(0, len(covmat)):
    if covmat[i, i] == 0.:
        covmat[i, i] = 1.
hdataset.set_cov_mat('y', covmat) # write it back

# Create the Fit instance
hfit = Fit(hdataset, gauss, fit_label="Fit of a Gaussian to histogram data")
#
# perform an initial fit with temporary errors (minimal output)
hfit.call_minimizer(final_fit=False, verbose=False)
#
#re-set errors using model at pre-fit parameter values:
#        sigma_i^2=cov[i, i]=n(x_i)
fdata=hfit.fit_function.evaluate(hfit.xdata, hfit.current_parameter_values)
np.fill_diagonal(covmat, fdata)
hfit.current_cov_mat = covmat # write back new covariance matrix
#
# now do final fit with full output
hfit.do_fit()
# and create, draw, save and show plot
...
```

Here is the output, which shows that the parameters of the standard normal distribution, from which the data were generated, are reproduced well by the fit result:

2.10 Example 10 - Plotting with `kafe`: properties of a Gauss curve

This example shows how to access the `kafe` plot objects to annotate plots with `matplotlib` functionality.

A dummy object *Dataset* (page 26) is created with points lying exactly on a Gaussian curve. The *Fit* (page 36) will then converge toward that very same Gaussian. When plotting, the data points used to "support" the curve can be omitted.

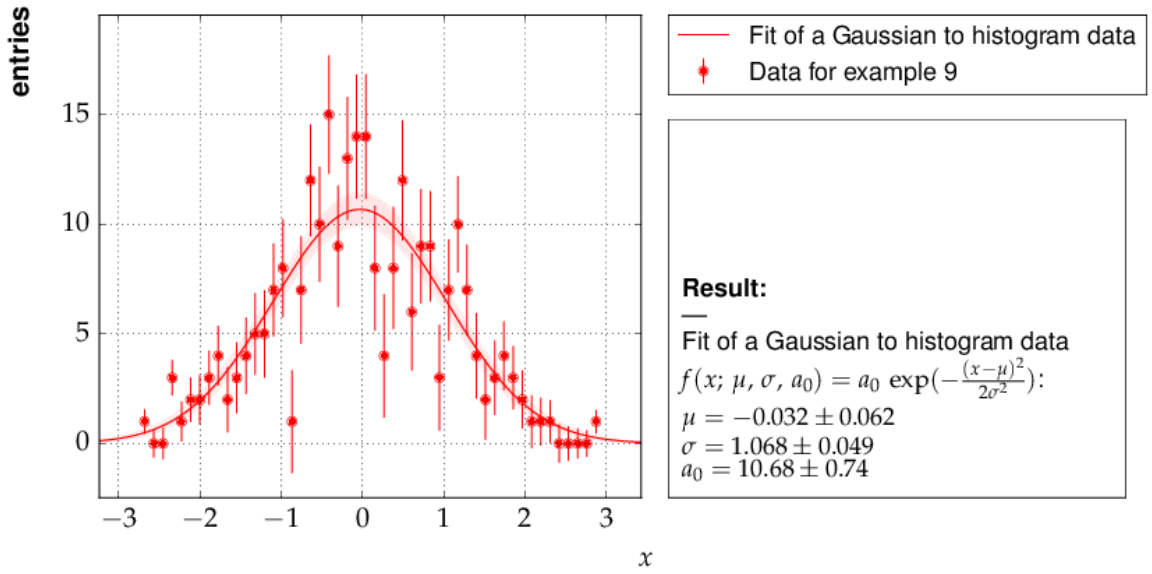

Fig. 2.12: *Output of example 9 - Fit of a Gaussian distribution to histogram data*

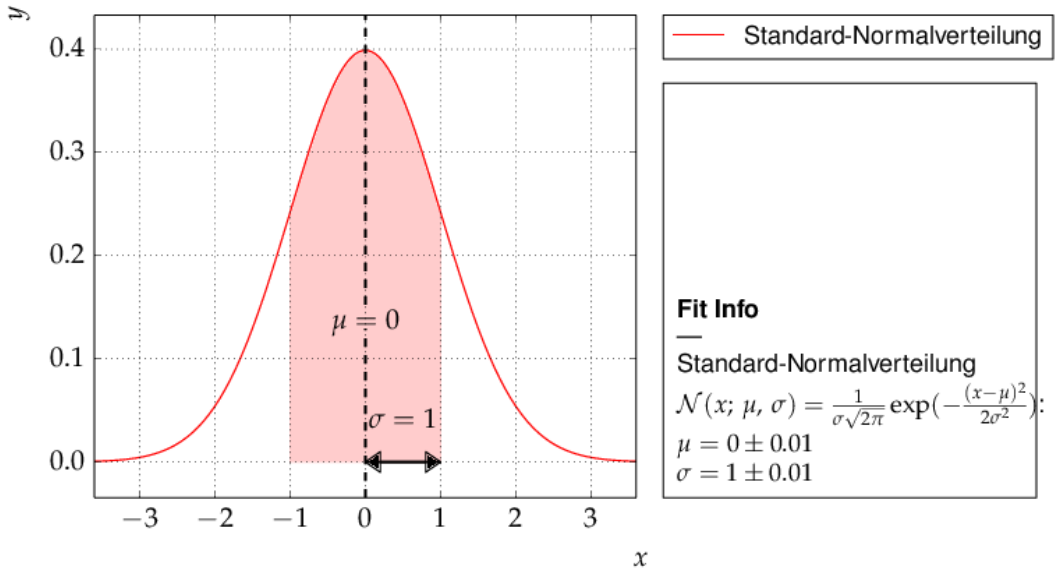

Fig. 2.13: *Output of example 10 - properties of a Gauss curve.*

CHAPTER

THREE

KAFE DOCUMENTATION – MODULE DESCRIPTIONS

The following documentation of functions and methods of relevance to the user interface was generated from the *DocStrings* contained in the *Python* code of the `kafe` package. For further information or if in doubt about the exact functionality, users are invited to consult the source code.

3.1 `__init__` Module

kafe – *a Python package for fitting and plotting for use in physics lab courses.*

This Python package allows fitting of user-defined functions to data. A dataset is represented by a *Dataset* object which stores measurement data as *NumPy* arrays. The uncertainties (errors) of the data are also stored in the *Dataset* as a list of one or more *ErrorSource* objects, each of which stores a part of the uncertainty information as a so-called *covariance matrix* (also called an *error matrix*). This allows **kafe** to work with uncertainties of different kinds for a *Dataset*, particularly when there is a degree of correlation between the uncertainties of the datapoints.

Fitting with **kafe** in a nutshell goes like this:

1. create a *Dataset* object from your measurement data

```
>>> my_d = kafe.Dataset(data=[[0., 1., 2.], [1.23, 3.45, 5.62]])
```

2. add errors (uncertainties) to your *Dataset*

```
>>> my_d.add_error_source('y', 'simple', 0.5)  # y errors, all +/- 0.5
```

3. import a model function from *kafe.function_library* (or define one yourself)

```
>>> from kafe.function_library import linear_2par
```

4. create a *Fit* object from your *Dataset* and your model function

```
>>> my_f = kafe.Fit(my_d, linear_2par)
```

5. do the fit

```
>>> my_f.do_fit()
```

6. *(optional)* if you want to see a plot of the result, use the *Plot* object

```
>>> my_p = kafe.Plot(my_f)
>>> my_p.plot_all()
>>> my_p.show()
```

For more in-depth information on **kafe**'s features, feel free to consult the documentation.

3.2 `_version_info` Module

3.3 `dataset` Module

class `kafe.dataset.`**`Dataset`**(*data=None, title='Untitled Dataset', axis_labels=['x', 'y'], axis_units=['', ''], **kwargs*)

Bases: `object`

The *Dataset* object is a data structure for storing measurement and error data.

It contains the measurement *data* as *NumPy* arrays and the error information as a list of *ErrorSource* (page 31) objects for each axis, each of which represents a separate contribution to the uncertainty of the measurement data, expressed as a *covariance matrix*.

The *Dataset* object calculates a *total covariance matrix* by adding up all the individual *ErrorSource* covariance matrices. This *total covariance matrix* is the one used for fitting.

A *Dataset* can be constructed directly from the measurement data, and can optionally be given a *title*, *axis labels* and *axis units*, as well as a *base name* for log or output files:

```
>>> my_d = kafe.Dataset(data=[[0., 1., 2.], [1.23, 3.45, 5.62]])
```

After constructing the *Dataset*, an error model may be added using *add_error_source()* (page 26) (here, an absolute *y*-uncertainty of 0.5):

```
>>> my_d.add_error_source('y', 'simple', 0.5)  # y errors, all +/- 0.5
```

The *Dataset* may then be used for fitting. For more information, see the *Fit* (page 36) object documentation.

Keyword Arguments

- **data** (*iterable, optional*) – the measurement data. Either of the form (xdata, ydata) or [(x1, y1), (x2, y2),... (xn, yn)]
- **title** (*string, optional*) – the name of the *Dataset*. If omitted, the *Dataset* will be given the generic name 'Untitled Dataset'.
- **axis_labels** (*list of strings, optional*) –

  labels for the *x* and *y* axes. If omitted, these will be set to `'x'` and `'y'`, respectively.
- **axis_units** (*list of strings, optional*) –

  units for the *x* and *y* axes. If omitted, these will be assumed to be dimensionless, i.e. the unit will be an empty string.
- **basename** (*string*) –

  base name of files generated by this Dataset/subsequent Fits...

`add_error_source`(*axis, err_type, err_val, relative=False, correlated=False, recompute_cov_mat=True*)

Add an error source for the data. A *Dataset* can have many error sources for each axis, each corresponding to a covariance matrix. The total error model for the axis is represented by the sum of these matrices.

Note: whenever an ErrorSource is added, the total covariance matrix is (re-)calculated, unless *recompute_cov_mat* is `False`.

Parameters

- **`axis`** (`'x'` or `'y'`) – axis for which to add error source.
- **`err_type`** (`'simple'` or `'matrix'`) – a `'simple'` error source is constructed from a single float or a list of *N* floats (*N* being the size of the *Dataset*), representing the uncertainty of the corresponding data points.

A `'matrix'` error source is a user-constructed covariance matrix.

- **err_val** (float/list of floats *or* numpy.matrix) – for a `'simple'` error source, a float of a list of *N* floats (*N* being the size of the *Dataset*). The float/each float in the list represents the uncertainty of the corresponding data point.

  For a `'matrix'` error source, the user-constructed covariance matrix (type: *numpy.matrix*).

Keyword Arguments

- **relative** (boolean, optional, default `False`) – errors relative to the data (`True`) or absolute (`False`).
- **correlated** (boolean, optional, default `False`) – errors fully correlated (`True`) or totally uncorrelated (`False`).
- **recompute_cov_mat** (boolean, optional, default `True`) – recalculate the total covariance matrix after adding the error source

Returnsthis integer may later be used to remove or disable/enable the error source using *remove_error_source()* (page 30), *disable_error_source()* (page 27) or *enable_error_source()* (page 27).

Return typeint

calc_cov_mats(*axis='all'*)
(Re-)Calculate the covariance matrix from the enabled error sources.

Keyword Arguments**axis** (`'x'` or `'y'` or `'all'`) – axis/axes for which to (re-)calcuate covariance matrix.

cov_mat_is_regular(*axis*)
Returns *True* if the covariance matrix for an axis is regular and `False` if it is singular.

Parameters**axis** (`'x'` or `'y'`) – Axis for which to check for regularity of the covariance matrix.

Returns`True` if covariance matrix is regular

Return typeboolean

cov_mats = None
covariance matrices for axes

disable_error_source(*axis*, *err_src_id*)
Disables an ErrorSource by excluding it from the calculation of the total covariance matrix.

Parameters

- **axis** (`'x'` or `'y'`) – axis for which to add error source.
- **err_src_id** (*int*) – error source ID, as returned by *add_error_source()* (page 26).

enable_error_source(*axis*, *err_src_id*)
Enables an ErrorSource by excluding it from the calculation of the total covariance matrix.

Parameters

- **axis** (`'x'` or `'y'`) – axis for which to add error source.
- **err_src_id** (*int*) – error source ID, as returned by *add_error_source()* (page 26).

err_src = None
lists of ErrorSource objects

error_source_is_enabled(*axis*, *err_src_id*)
Returns `True` if an ErrorSource is enabled, that is if it is included in the total covariance matrix.

Parameters

- **axis** (`'x'` or `'y'`) – Axis for which to load the error matrix.
- **err_src_id** (*int*) – error source ID, as returned by *add_error_source()* (page 26).

Returns

- *bool* – *True* if the specified error source is enables
- **TODO** (*##DocString##*)

get_axis(*axis_alias*)
Get axis id from an alias.

Parameters **axis_alias** (*string or int*) – Alias of the axis whose id should be returned. This is for example either `'0'` or `'x'` for the *x*-axis (id 0).

Returns the axis ID

Return type int

get_cov_mat(*axis*, *fallback_on_singular=None*)
Get the error matrix for an axis.

Parameters **axis** (`'x'` or `'y'`) – Axis for which to load the error matrix.

Keyword Arguments **fallback_on_singular** (*numpy.matrix* or string, optional) – What to return if the matrix is singular. If this is `None` (default), the matrix is returned anyway. If this is a *numpy.matrix* object or similar, that is returned istead. Alternatively, the shortcuts `'identity'` or `1` and `'zero'` or `0` can be used to return the identity and zero matrix respectively.

Returns the current covariance matrix

Return type *numpy.matrix*

get_data(*axis*)
Get the measurement data for an axis.

Parameters **axis** (*string*) – Axis for which to get the measurement data. Can be `'x'` or `'y'`.

Returns the measurement data for the axis

Return type *numpy.array*

get_data_span(*axis*, *include_error_bars=False*)
Get the data span for an axis. The data span is a tuple (*min*, *max*) containing the smallest and highest coordinates for an axis.

Parameters **axis** (`'x'` or `'y'`) – Axis for which to get the data span.

Keyword Arguments **include_error_bars** (*boolean, optional*) – `True` if the returned span should be enlarged to contain the error bars of the smallest and largest datapoints (default: `False`)

Returns the data span for the axis

Return type a tuple (*min*, *max*)

get_formatted(*format_string='.06e'*, *delimiter='\t'*)
Returns the dataset in a plain-text format which is human-readable and can later be used as an input file for the creation of a new *Dataset*.

The format is as follows:

```
# x data
x_1  sigma_x_1
x_2  sigma_x_2  cor_x_12
...  ...        ...       ...
x_N  sigma_x_N  cor_x_1N  ...  cor_x_NN

# y data
y_1  sigma_y_1
y_2  sigma_y_2  cor_y_12
...  ...        ...       ...
y_N  sigma_y_N  cor_y_1N  ...  cor_y_NN
```

Here, the `x_i` and `y_i` represent the measurement data, the `sigma_?_i` are the statistical uncertainties of each data point, and the `cor_?_ij` are the correlation coefficients between the *i*-th and *j*-th data point.

If the `x` or `y` errors are not correlated, then the entire correlation coefficient matrix can be omitted. If there are no statistical uncertainties for an axis, the second column can also be omitted. A blank line is required at the end of each data block!

Keyword Arguments

- **format_string** (*string, optional*) – A format string with which each entry will be rendered. Default is `'.06e'`, which means the numbers are represented in scientific notation with six significant digits.
- **delimiter** (*string, optional*) – A delimiter used to separate columns in the output.

Returns a plain-text representation of the *Dataset*

Return type str

get_size()
Get the size of the *Dataset*. This is equivalent to the length of the *x*-axis data.

Returns the number of datapoints in the *Dataset*.

Return type int

has_correlations(*axis=None*)
Returns *True* if the specified axis has correlation data, `False` if not.

Parameters **axis** (`'x'` or `'y'` or `None`, optional) – Axis for which to check for correlations. If `None`, returns true if there are correlations for at least one axis.

Returns *True* if the specified axis has correlation data

Return type bool

has_errors(*axis=None*)
Returns *True* if the specified axis has any kind of error data.

Parameters **axis** (`'x'` or `'y'` or `None`, optional) – Axis for which to check for error data. If `None`, returns true if there are errors for at least one axis.

Returns *True* if the specified axis has any kind of error data.

Return type bool

n_datapoints = None
number of data points in the *Dataset*

read_from_file(*input_file*)
Reads the *Dataset* object from a file.

One way to construct a Dataset is to specify an input file containing a plain-text representation of the dataset:

```
>>> my_dataset.read_from_file('/path/to/file')
```

or

```
>>> my_dataset.read_from_file(my_file_object)
```

For details on the format, see *get_formatted()* (page 28)

Parameters **input_file** (*str*) – path to the file

Returns `True` if the read succeeded, `False` if not.

Return type boolean

remove_error_source(*axis*, *err_src_id*, *recompute_cov_mat=True*)
Remove the error source from the *Dataset*.

Parameters

- **axis** (`'x'` or `'y'`) – axis for which to add error source.
- **err_src_id** (*int*) – error source ID, as returned by *add_error_source()* (page 26).

Keyword Arguments **recompute_cov_mat** (boolean, optional, default `True`) – recalculate the total covariance matrix after removing the error source

set_axis_data(*axis*, *data*)
Set the measurement data for a single axis.

Parameters

- **axis** (`'x'` or `'y'`) – Axis for which to set the measurement data.
- **data** (*iterable*) – Measurement data for axis.

set_cov_mat(*axis*, *mat*)
Forcibly set the error matrix for an axis, ignoring *ErrorSource* (page 31) objects. This is useful for adjusting the covariance matrix during the fit process.

Parameters

- **axis** (`'x'` or `'y'`) – Axis for which to load the error matrix.
- **mat** (*numpy.matrix* or `None`) – Error matrix for the axis. Passing `None` unsets the error matrix.

set_data(*data*)
Set the measurement data for both axes.

Each element of **data** must be iterable and be of the same length. The first element of the **data** tuple/list is assumed to be the *x* data, and the second to be the *y* data:

```
>>> my_dataset.set_data(([0., 1., 2.], [1.23, 3.45, 5.62]))
```

Alternatively, *x*-*y* value pairs can also be passed as **data**. The following is equivalent to the above:

```
>>> my_dataset.set_data(([0.0, 1.23], [1.0, 3.45], [2.0, 5.62]))
```

In case the *Dataset* contains two data points, the ordering is ambiguous. In this case, the first ordering (*x* data first, then *y* data) is assumed.

Parameters **data** (*iterable*) – the measurement data. Either of the form (xdata, ydata) or [(x1, y1), (x2, y2),... (xn, yn)]

write_formatted(*file_path*, *format_string='.06e'*, *delimiter='\t'*)
Writes the dataset to a plain-text file. For details on the format, see *read_from_file()* (page 29).

Parameters **file_path** (*string*) – Path of the file object to write. **WARNING**: *overwrites existing files*!

Keyword Arguments

- **format_string** (*string, optional*) – A format string with which each entry will be rendered. Default is `'.06e'`, which means the numbers are represented in scientific notation with six significant digits.
- **delimiter** (*string, optional*) – A delimiter used to separate columns in the output.

class `kafe.dataset.`**ErrorSource**

Bases: `object`

This object stores the error information for a `Dataset` as a *covariance matrix* C (sometimes also referred to as the *error matrix*). This has several advantages: it allows calculating the function to minimize (e.g. the chi-square) for a fit as a matrix product, and it allows specifying multiple error sources for a *Dataset* by simply adding up the corresponding matrices.

The object contains methods to generate a covariance matrix for some simple cases, such as when all points have the same relative or absolute errors and the errors are either not correlated or fully correlated. For more complicated error models, a covariance matrix can be specified directly.

get_matrix(*size=None*)

Returns/Generates the covariance matrix for this ErrorSource.

If the user specified the matrix using *make_from_matrix()* (page 31), returns that matrix. If a simple error model is specified, a matrix is constructed as follows:

For *uncorrelated* errors, the covariance matrix is always diagonal.

If a single float σ is given as the error, the diagonal entries will be equal to σ^2. In this case, the matrix size needs to be specified via the `size` parameter.

If a list of floats σ_i is given as the error, the *i*-th entry will be equal to ${\sigma_i}^2$. In this case, the size of the matrix is inferred from the size of the list.

For *fully correlated* errors, the covariance matrix is the outer product of the error array σ_i with itself, i.e. the (i, j)-th matrix entry will be equal to $\sigma_i \sigma_j$.

Keyword Argumentssize (*int (sometimes required)*) – Size of the matrix to return. Only relevant if the error value is a single float, since in that case there is no way to deduce the matrix size.

make_from_matrix(*cov_mat*, *check_singular=False*)

Sets the covariance matrix manually.

Parameterscov_mat (*numpy.matrix*) – A *square*, *symmetric* (and usually *regular*) matrix.

Keyword Argumentscheck_singular (*boolean, optional*) – Whether to force singularity check. Defaults to `False`.

make_from_val(*err_val*, *fully_correlated=False*)

Sets information required to construct the covariance matrix.

Parameterserr_val (*float or sequence of floats*) – If all data points have the same uncertainty

Keyword Argumentsfully_correlated (*boolean, optional*) – Whether the errors are fully correlated. Defaults to `False`.

3.4 `dataset_tools` Module

`kafe.dataset_tools.`**build_dataset**(*xdata*, *ydata*, *cov_mats=None*, *xabserr=0.0*, *xrelerr=0.0*, *xabscor=0.0*, *xrelcor=0.0*, *yabserr=0.0*, *yrelerr=0.0*, *yabscor=0.0*, *yrelcor=0.0*, *title=None*, *axis_labels=None*, *axis_units=None*, ***kwargs*)

This helper function creates a *Dataset* from a series of keyword arguments.

Parameters

- **xdata** (list/tuple/*np.array* of floats) – This keyword argument is mandatory and should be an iterable containing *x*-axis the measurement data.
- **ydata** (list/tuple/*np.array* of floats) – This keyword argument is mandatory and should be an iterable containing *y*-axis the measurement data.
- **cov_mats** (`None` or 2-tuple, optional) – This argument defaults to `None`, which means no covariance matrices are used. If covariance matrices are needed, a tuple with two entries (the first for *x* covariance matrices, the second for *y*) must be passed.

  Each element of this tuple may be either `None` or a NumPy matrix object containing a covariance matrix for the respective axis.

Keyword Arguments

- **error specification keywords** (*iterable or numeric (see below)*) – In addition to covariance matrices, errors can be specified for each axis (*x* or *y*) according to a simplified error model.

  In this respect, a valid keyword is composed of an axis, an error relativity specification (*abs* or *rel*) and error correlation type (*err* or *cor*). The errors are then set as follows:

  1. **For totally uncorrelated errors (*err*):**
     - if keyword argument is iterable, the error list is set to that
     - if keyword argument is a number, an error list with identical entries is generated
  2. **For fully correlated errors (*cor*):**
     - keyword argument *must* be a single number. The global correlated error for the axis is then set to that.

  So, for example:

```
>>> my_dataset = build_dataset(..., yabserr=0.3, yrelcor=0.1)
```

  creates a Dataset with an uncorrelated error of 0.3 for each *y* coordinate and a fully correlated (systematic) error of *y* of 0.1.

- **title** (*string, optional*) – The title of the *Dataset*.
- **axis_labels** (*2-tuple of strings, optional*) – a 2-tuple containing the axis labels for the *Dataset*. This is relevant when plotting *Fits* of the *Dataset*, but is ignored when plotting more than one *Fit* in the same *Plot*.
- **axis_units** (*2-tuple of strings, optional*) – a 2-tuple containing the axis units for the *Dataset*. This is relevant when plotting *Fits* of the *Dataset*, but is ignored when plotting more than one *Fit* in the same *Plot*.

Returns *Dataset* object constructed from data and error information

Return type *Dataset* (page 26)

3.5 file_tools Module

kafe.file_tools.**buildDataset_fromFile**(*file_to_parse*)

Build a kafe *Dataset* (page 26) object from input file with key words and file format defined in *parse_general_inputfile()* (page 34)

Parameters

- **file_to_parse** (*file-like object or string containing a file path*) – The file to parse.

- **returns** (an instance of the *Dataset* (page 26) class,) – constructed with the help of the method `kafe.dataset.Dataset.build_dataset()`

`kafe.file_tools.`**`buildFit_fromFile`**(*file_to_parse*)

Build a kafe *Fit* (page 36) object from input file with keywords and file format defined in *parse_general_inputfile()* (page 34)

Parameters

- **file_to_parse** (*file-like object or string containing a file path*) – The file to parse.
- **returns** (an instance of the *Fit* (page 36) class,) – constructed with the help of the methods `build_dataset()` and `build_fit()`

`kafe.file_tools.`**`parse_column_data`**(*file_to_parse, field_order='x,y', delimiter=' ', cov_mat_files=None, title='Untitled Dataset', basename=None, axis_labels=['x', 'y'], axis_units=['', '']*)

Parses a file which contains measurement data in a one-measurement-per-row format. The field (column) order can be specified. It defaults to `"x,y"`. Valid field names are *x*, *y*, *xabserr*, *yabserr*, *xrelerr*, *yrelerr*. Another valid field name is *ignore* which can be used to skip a field.

A certain type of field can appear several times. If this is the case, all specified errors are added in quadrature:

$$\sigma_{\text{tot}} = \sqrt{{\sigma_1}^2 + {\sigma_2}^2 + \dots}$$

Every valid measurement data file *must* have an *x* and a *y* field.

For more complex error models, errors and correlations may be specified as covariance matrices. If this is desired, then any number of covariance matrices (stored in separate files) may be specified for an axis by using the *cov_mat_files* argument.

Additionally, a delimiter can be specified. If this is a whitespace character or omitted, any sequence of whitespace characters is assumed to separate the data.

Parameters

- **file_to_parse** (*file-like object or string containing a file path*) – The file to parse.
- **field_order** (*string (optional)*) – A string of comma-separated field names giving the order of the columns in the file. Defaults to `'x,y'`.
- **delimiter** (*string (optional)*) – The field delimiter used in the file. Defaults to any whitespace.
- **cov_mat_files** (*several* (see below, optional)) – This argument defaults to `None`, which means no covariance matrices are used. If covariance matrices are needed, a tuple with two entries (the first for *x* covariance matrices, the second for *y*) must be passed.

  Each element of this tuple may be either `None`, a file or file-like object, or an iterable containing files and file-like objects. Each file should contain a covariance matrix for the respective axis.

  When creating the `Dataset`, all given matrices are summed over.
- **title** (*string (optional)*) – The title of the `Dataset`.
- **basename** (string or `None` (optional)) – A basename for the `Dataset`. All output files related to this dataset will use this as a basename. If this is `None` (default), the basename will be inferred from the filename.
- **axis_labels** (*2-tuple of strings (optional)*) – a 2-tuple containing the axis labels for the `Dataset`. This is relevant when plotting `Fits` of the `Dataset`, but is ignored when plotting more than one `Fit` in the same `Plot`.
- **axis_units** (*2-tuple of strings (optional)*) – a 2-tuple containing the axis units for the `Dataset`. This is relevant when plotting `Fits` of the `Dataset`, but is ignored when plotting more than one `Fit` in the same `Plot`.

Returns A *Dataset* built from the parsed file.

Return type py:class:*~kafe.dataset.Dataset*

kafe.file_tools.**parse_general_inputfile**(*file_to_parse*)

This function can be used to specify *kafe* `Dataset` (page 26) or `Fit` (page 36) objects in a single input file, thus requiring minimal Python code. Keywords as specified in a dictionary `tokens` specify all objects and parameters needed by the functions `build_dataset()` (page 31) in module `dataset` (page 26) and `build_fit()` (page 40) in module `fit`.

Parameters

- **file_to_parse** (*file-like object or string containing a file path*) – The file to parse.
- **return** (*dataset_kwargs, fit_kwargs*) – keyword lists to build a kafe `Dataset` (page 26) or `Fit` (page 36) object with the helper functions *build_dataset* or *build_fit*

Description of the format of the input file

The interpretation of the input data is driven by keywords. All data following a key must be of the same kind, a block of data ends when a new key is specified.

Some keys only expect a single float or string-tpye value, given on the same line, separated by a space (`' '`):

```
<key> <value>
```

For multiple input, i.e. data, uncertainties and covariance or correlation matrices, the format is:

```
<key>
<xval>  <xerr>  [<xsyst>  <elements of cov/cor matrix>]

...

<xval>  <xerr>  [<xsyst>  <elements of cov/cor matrix>]
```

The field separator is space (`' '`). Note that the number of input values in each line must correspond to the specified format of the (correlated) uncertainties.

The currently implemented keys are:

- for metadata:
  - `*TITLE` <name of the data set>
  - `*BASENAME` <name from which output file names are derived>
  - `*xLabel` <x axis label>
  - `*yLabel` <y axis label>
  - `xUnit` <x axis unit>
  - `yUnit` <y axis unit>
- for input data:
  - **`*xData`** ***x data and, optionally, uncertainties***

    <xval> [<x-uncert.>]...
  - **`*yData`** ***y data and uncertainties***

    <yval> <y uncert.>...
- *x* or *y* data, independent and correlated uncertainties and elements of correlation matrix, given as as a lower triangular matrix with no diagonal:
  - `*xData_COR`
  - **`*yData_COR`**

<x/y val> <indep. x/y uncert.> <x/y syst> <elements of cor matrix>...

- *x* or *y* data, independent and correlated uncertainties and sqrt of elements of covariance matrix, given as as a lower triangular matrix with no diagonal:

  –`*xData_SCOV`

  –*yData_SCOV

  <x/y val> <idep. x/y uncert.> <x/y syst> <sqrt of elements of cov matrix>...

- *x* or *y* data, independent uncertainties and full covariance matrix (note that the correlated uncertainties are contained in the diagonal of the matrix in this case, i.e. the field <xsyst> is to be omitted):

  –`*xData_COV`

  –*yData_COV

  <x/y val> <indep. x/y ucert.> <elements of cov matrix>...

- Additional keys allow to specify correlated absolute or relative uncertainties:

  –`*xAbsCor <common abs.  x uncert.>`

  –`*yAbsCor <common abs.  y uncert.>`

  –`*xRelCor <common rel.  x uncert.>`

  –`*yRelCor <common rel.  y uncert.>`

- To specify the fit function, the defined keywords are:

  –`*FitFunction` followed by python code (note: blanks for line indent must be replaced by '~'):

```
def fitf(x, ...):
~~~~...
~~~~return ...
```

  The name *fitf* is mandatory. The kafe decorator functions `@ASCII`, `@LATEX` and `@FitFunction` are suppoted.

  –`*FITLABEL` <the name for the fit>

  –`*InitialParameters` - followed by two columns of float values for the initial values of the parameters and their range, one line per fit parameter is mandatory

  <initial value> <range>

- Model parameters can be constrained within their uncertainties, if prior knowledge on the value(s) and uncertainty(ies) of parameters are to be accounted for in the fit. This option is specified via the keyword:

  –`*ConstrainedParameters` followed by one or more lines with the fields:

```
<parameter name>  <parameter value>  <parameter uncert.>,
```

  where *parameter name* is the name of the parameter in the fit function specification.

Here is an example of an input file to calculate the average of correlated measurements:

```
#  Meta data for plotting
*TITLE Higgs-mass measurements
*xLabel number of measurement
*yLabel $m_\mathrm{H}$
*yUnit GeV/$c^2$

#*xData  # commented out, as not needed for simple average

*yData_SCOV  # assume that minimum of syst. errors is a common error
# mH      err     syst as sqrt(cov)
```

```
    124.51   0.52    0.06
    125.60   0.40    0.20  0.06
    125.98   0.42    0.28  0.   0.
    124.70   0.31    0.15  0.   0.  0.15

    # set Python code of fit function
    ### there are some restrictions:
    ##     function name must be 'fitf'
    ##     blanks must be replaced by '~'
    #  kafe fit function decorators are supported
    *FitFunction
    @ASCII(expression='av')
    @LaTeX(name='f', parameter_names=('av'), expression='av')
    @FitFunction
    def fitf(x,av=1.): # fit an average
    ~~~~return av
    *FITLABEL Average
    *InitialParameters
    120. 1.
```

3.6 `fit` Module

class kafe.fit.**Fit**(*dataset*, *fit_function*, *external_fcn=<function chi2>*, *fit_label=None*, *minimizer_to_use='root'*)

Bases: object

Object representing a fit. This object references the fitted *Dataset*, the fit function and the resulting fit parameters.

Necessary arguments are a *Dataset* object and a fit function (which should be fitted to the *Dataset*). Optionally, an external function *FCN* (the minimum of which should be located to find the best fit) can be specified. If not given, the *FCN* function defaults to χ^2.

Parameters

- **dataset** (*Dataset*) – A *Dataset* object containing all information about the data
- **fit_function** (*function*) – A user-defined Python function to fit to the data. This function's first argument must be the independent variable *x*. All other arguments *must* be named and have default values given. These defaults are used as a starting point for the actual minimization. For example, a simple linear function would be defined like:

```
>>> def linear_2par(x, slope=1., y_intercept=0.):
...     return slope * x + y_intercept
```

Be aware that choosing sensible initial values for the parameters is often crucial for a succesful fit, particularly for functions of many parameters.

Keyword Arguments

- **external_fcn** (*function, optional*) – An external *FCN* (function to minimize). This function must have the following call signature:

```
>>> FCN(xdata, ydata, cov_mat, fit_function, parameter_values)
```

It should return a float. If not specified, the default χ^2 *FCN* is used. This should be sufficient for most fits.

- **fit_label** ($LaTeX$-formatted string, optional) – A name/label/short description of the fit function. This appears in the legend describing the fitter curve. If omitted, this defaults to the fit function's $LaTeX$ expression.

- **minimizer_to_use** (*'ROOT' or 'minuit', optional*) – Which minimizer to use. This defaults to whatever is set in the config file, but can be specifically overridden for some fits using this keyword argument.

call_external_fcn (**parameter_values*)
Wrapper for the external *FCN*. Since the actual fit process depends on finding the right parameter values and keeping everything else constant we can use the *Dataset* object to pass known, fixed information to the external *FCN*, varying only the parameter values.

Parameters **parameter_values** (*sequence of values*) – the parameter values at which *FCN* is to be evaluated

call_minimizer (*final_fit=True*, *verbose=False*)
Instructs the minimizer to do a minimization.

constrain_parameters (*parameters*, *parvals*, *parerrs*)
Constrain the parameter with the given name to $c \pm \sigma$.

This is achieved by adding an appropriate *penalty term* to the χ^2 function, see function `chi2()` (page 41).

Parameters

- **parameters** (*list of int*) – list of paramter id's or names to constrain
- **parvals** (*list of float*) – list of parameter values
- **parerrs** (*list of float*) – list of errors on parameters

contours = None
Parameter Contours [id1, id2, dchi2, [xc], [yc]]

current_cov_mat = None
the current covariance matrix used for the *Fit*

dataset = None
this Fit instance's child *Dataset*

do_fit (*quiet=False*, *verbose=False*)
Runs the fit algorithm for this *Fit* object.

First, the `Dataset` is fitted considering only uncertainties in the *y* direction. If the *Dataset* has no uncertainties in the *y* direction, they are assumed to be equal to 1.0 for this preliminary fit, as there is no better information available.

Next, the fit errors in the *x* direction (if they exist) are taken into account by projecting the covariance matrix for the *x* errors onto the *y* covariance matrix. This is done by taking the first derivative of the fit function in each point and "projecting" the *x* error onto the resulting tangent to the curve.

This last step is repeated until the change in the error matrix caused by the projection becomes negligible.

Keyword Arguments

- **quiet** (*boolean, optional*) – Set to `True` if no output should be printed.
- **verbose** (*boolean, optional*) – Set to `True` if more output should be printed.

external_fcn = None
the (external) function to be minimized for this *Fit*

final_parameter_errors = None
Final parameter errors

final_parameter_values = None
Final parameter values

fit_function = None
the fit function used for this *Fit*

fix_parameters(**parameters_to_fix*)
Fix the given parameters so that the minimizer works without them when *do_fit()* (page 37) is called next. Parameters can be given by their names or by their IDs.

get_current_fit_function()
This method returns a function object corresponding to the fit function for the current parameter values. The returned function is a function of a single variable.

ReturnsA function of a single variable corresponding to the fit function at the current parameter values.

Return typefunction handle

get_error_matrix()
This method returns the covariance matrix of the fit parameters which is obtained by querying the minimizer object for this *Fit*

ReturnsThe covariance matrix of the parameters.

Return type*numpy.matrix*

get_function_error(*x*)
This method uses the parameter error matrix of the fit to calculate a symmetric (parabolic) error on the function value itself. Note that this method takes the entire parameter error matrix into account, so that it also accounts for correlations.

The method is useful if, e.g., you want to draw a confidence band around the function in your plot routine.

Parameters**x** (*float* or sequence of *float*) – the values at which the function error is to be estimated

Returnsthe estimated error at the given point(s)

Return typefloat or sequence of float

get_parameter_errors(*rounding=False*)
Get the current parameter uncertainties from the minimizer.

Keyword Arguments**rounding** (*boolean, optional*) – Whether or not to round the returned values to significance.

ReturnsA tuple of the parameter uncertainties

Return typetuple

get_parameter_values(*rounding=False*)
Get the current parameter values from the minimizer.

Keyword Arguments**rounding** (*boolean, optional*) – Whether or not to round the returned values to significance.

ReturnsA tuple of the parameter values

Return typetuple

latex_parameter_names = None
$LaTeX$ parameter names

minos_errors = None
MINOS Errors [err, err+, err-, gcor]

number_of_parameters = None
the total number of parameters

par_cov_mat = None
Parameter covariance matrix (*numpy.matrix*)

parabolic_errors = None
`True` if χ^2 is approx. parabolic (boolean)

parameter_is_fixed(*parameter*)
Check whether a parameter is fixed. Accepts a parameter's name or ID and returns a boolean value.

parameter_names = None
the names of the parameters

plot_contour(*parameter1*, *parameter2*, *dchi2=2.3*, *n_points=100*, *color='gray'*, *alpha=0.1*, *show=False*, *axes=None*)
Plots one or more two-dimensional contours for this fit into a separate figure and returns the figure object.

Parameters

- **parameter1** (*int or string*) – ID or name of the parameter to appear on the *x*-axis.
- **parameter2** (*int or string*) – ID or name of the parameter to appear on the *y*-axis.

Keyword Arguments

- **dchi2** (*float or list of floats (otpional)*) – delta-chi^2 value(s) used to evaluate contour(s) 1. = 1 sigma 2.3 = 68.0% (default) 4. = 2 sigma 5.99 = 95.0%
- **n_points** (*int, optional*) – Number of plot points to use for the contour. Higher values yield smoother contours but take longer to render. Default is 100.
- **color** (*string, optional*) – A `matplotlib` color identifier specifying the fill color of the contour. Default is 'gray'.
- **alpha** (*float, optional*) – Transparency of the contour fill color ranging from 0. (fully transparent) to 1. (fully opaque). Default is 0.25
- **show** (*boolean, optional*) – Specify whether to show the figure before returning it. Defaults to `False`.
- **axes** (*maplotlib.pyplot.axes*) – Sub-plot axes to add plot to

ReturnsA figure object containing the contour plot.

Return type`matplotlib` figure object if no axes given

plot_correlations()
Plots two-dimensional contours for all pairs of parameters and profile for all parameters, arranges as a matrix.

ReturnsA figure object containing the matrix of plots.

Return type`matplotlib` figure object

plot_profile(*parid*, *n_points=21*, *color='blue'*, *alpha=0.5*, *show=False*, *axes=None*)
Plots a profile
chi^2 for this fit into a separate figure and returns the figure object.

Parameters **parid** (*int or string*) – ID or name of parameter

Keyword Arguments

- **n_points** (*int, optional*) – Number of plot points to use for the profile curve.
- **color** (*string, optional*) – A `matplotlib` color identifier specifying the line color. Default is 'blue'.
- **alpha** (*float, optional*) – Transparency of the contour fill color ranging from 0. (fully transparent) to 1. (fully opaque). Default is 0.25
- **show** (*boolean, optional*) – Specify whether to show the figure before returning it. Defaults to `False`.
- **axes** (*sub-plot axes to put plot*)

ReturnsA figure object containing the profile plot.

Return type`matplotlib` figure object if axes is None

print_fit_details()
prints some fit goodness details

print_fit_results()
prints fit results

print_raw_results()
unformatted print-out of all fit results in

print_rounded_fit_parameters()
prints the fit parameters

profiles = None
Parameter Profiles [id1, [xp], [dchi1(xp)]]

project_x_covariance_matrix()
Project elements of the *x* covariance matrix onto the total matrix.

This is done element-wise, according to the formula:

$$C_{\mathrm{tot},ij} = C_{y,ij} + C_{x,ij} \frac{\partial f}{\partial x_i} \frac{\partial f}{\partial x_j}$$

release_parameters(**parameters_to_release*)
Release the given parameters so that the minimizer begins to work with them when `do_fit()` is called next. Parameters can be given by their names or by their IDs. If no arguments are provied, then release all parameters.

set_parameters(**args*, ***kwargs*)
Sets the parameter values (and optionally errors) for this fit. This is usually called just before the fit is done, to establish the initial parameters. If a parameter error is omitted, it is set to 1/10th of the parameter values themselves. If the default value of the parameter is 0, it is set, by exception, to 0.1.

This method accepts up to two positional arguments and several keyword arguments.

Parameters

- **args[0]** (*tuple/list of floats, optional*) – The first positional argument is expected to be a tuple/list containing the parameter values.
- **args[1]** (*tuple/list of floats, optional*) – The second positional argument is expected to be a tuple/list of parameter errors, which can also be set as an approximate estimate of the problem's uncertainty.

Keyword Arguments

- **no_warning** (*boolean, optional*) – Whether to issue warnings (`False`) or not (`True`) when communicating with the minimizer fails. Defaults to `False`.
- **Valid keyword argument names are parameter names. The keyword arguments**
- **themselves may be floats (parameter values) or 2-tuples containing the**
- **parameter values and the parameter error in that order**
- ***<parameter_name>*** (*float or 2-tuple of floats, optional*) – Set the parameter with the name <'parameter_name'> to the value given. If a 2-tuple is given, the first element is understood to be the value and the second to be the parameter error.

xdata = None
the *x* coordinates of the data points used for this *Fit*

ydata = None
the *y* coordinates of the data points used for this *Fit*

kafe.fit.**build_fit**(*dataset*, *fitfunc*, *fitlabel='untitled'*, *initial_fit_parameters=None*, *constrained_parameters=None*)
This helper fuction creates a *Fit* (page 36) from a series of keyword arguments.

Parameters

- **dataset** (a `kafe` *Dataset* (page 26)) –
- **fitfunc** (*a python function, optionally with*) – `@FitFunction`, `@LATEX` and `@FitFunction` decorators

Keyword Arguments

- **fitlabel** (*name for this fit, optional*) – Defaults to "untitled".
- **initial_fit_parameters** (`None` or 2-tuple of list, sequence of floats) – specifying initial parameter values and errors
- **constrained_parameters** (`None` or 3-tuple of list, tuple/*np.array*) – of one string and 2 floats specifiying the names, values and uncertainties of constraints to apply to model parameters

Returns

Return type*Fit* (page 36) object

`kafe.fit.`**chi2**(*xdata*, *ydata*, *cov_mat*, *fit_function*, *parameter_values*, *constrained_parameters=None*)

The χ^2 implementation. Calculates χ^2 according to the formula:

$$\chi^2 = \lambda^T C^{-1} \lambda$$

Here, λ is the residual vector $\lambda = \vec{y} - \vec{f}(\vec{x})$ and C is the covariance matrix.

If a constraint $c_i \pm \sigma_i$ is applied to a parameter p_i, a *penalty term* is added for each constrained parameter:

$$\chi^2_{\text{cons}} = \chi^2 + \sum_i \left(\frac{p_i - c_i}{\sigma_i} \right)^2$$

Parameters

- **xdata** (*iterable*) – The *x* measurement data
- **ydata** (*iterable*) – The *y* measurement data
- **cov_mat** (*numpy.matrix*) – The total covariance matrix
- **fit_function** (*function*) – The fit function $f(x)$
- **parameter_values** (*list/tuple*) – The values of the parameters at which $f(x)$ should be evaluated.

Keyword Argumentsconstrained_parameters (`None` or list of two iterables, optional) – The first iterable (c_i) contains the constrained parameters' expected values and the second iterable (σ_i) contains the constraint uncertainties. A parameter with constraint uncertainty set to 0 remains unconstrained.

`kafe.fit.`**round_to_significance**(*value*, *error*, *significance=2*)

Rounds the error to the established number of significant digits, then rounds the value to the same order of magnitude as the error.

Parameters

- **value** (*float*) – value to round to significance
- **error** (*float*) – uncertainty of the value

Keyword Argumentssignificance (*int, optional*) – number of significant digits of the error to consider

3.7 `function_library` Module

Collection of model functions

3.8 `function_tools` Module

`kafe.function_tools.`**`ASCII`**(***kwargs*)

Optional decorator for fit functions. This overrides a FitFunction's plain-text (ASCII) attributes. The new values for these attributes must be passed as keyword arguments to the decorator. Possible arguments:

name[string] Plain-text representation of the function name.

parameter_names[list of strings] List of plain-text representations of the function's arguments. The length of this list must be equal to the function's argument number. The argument names should be in the same order as in the function definition.

x_name[string] Plain-text representation of the independent variable's name.

expression[string] Plain-text-formatted expression representing the function's formula.

class `kafe.function_tools.`**`FitFunction`**(*f*)

Decorator class for fit functions. If a function definition is decorated using this class, some information is collected about the function which is relevant to the fitting process, such as the number of parameters, their names and default values. Some details pertaining to display and representation are also set, such as $LaTeX$ representations of the parameter names and the function name. Other decorators can be applied to a function object to specify things such as a $LaTeX$ or plain-text expression for the fit function.

`derive_by_parameters`(*x_0*, *precision_spec*, *parameter_list*)

Returns the gradient of *func* with respect to its parameters, i.e. with respect to every variable of *func* except the first one.

precision_spec[`float` or iterable of `floats`] An array of floats indicating the initial point spacing for numerically evaluating the derivative. Can be a single float value to use the same spacing for every derivation.

`derive_by_x`(*x_0*, *precision_list*, *parameter_list*)

If *x_0* is iterable, gives the array of derivatives of a function $f(x, par_1, par_2, \ldots)$ around $x = x_i$ at every x_i in $\vec{x}$. If *x_0* is not iterable, gives the derivative of a function $f(x, par_1, par_2, \ldots)$ around $x =$ `x_0`.

`evaluate`(*x_0*, *parameter_list*)

Evaluate the fit function at an x-value or at an array of x-values for the parameter values in *prarameter_list*.

x_0 float or array of floats

parameter_list values of function parameters

returns function value(s)

`expression` = None

a math expression (string) representing the function's result

`get_function_equation`(*equation_format='latex'*, *equation_type='full'*, *ensuremath=True*)

Returns a string representing the function equation. Supported formats are $LaTeX$ and ASCII inline math. Note that $LaTeX$ math is wrapped by default in an `\ensuremath{}` expression. If this is not desired behaviour, the flag `ensuremath` can be set to `False`.

equation_format[string (optional)] Can be either "latex" (default) or "ascii".

equation_type[string (optional)] Can be either "full" (default), "short" or "name". A "name"-type equation returns a representation of the function name:

```
f
```

A "short"-type equation limits itself to the function name and variables:

```
f(x, par1, par2)
```

A "full"-type equation includes the expression which the function calculates:

```
f(x, par1, par2) = par1 * x + par2
```

ensuremath[boolean (optional)] If a $LaTeX$ math equation is requested, `True` (default) will wrap the resulting expression in an `\ensuremath{}` tag. Otherwise, no wrapping is done.

`latex_expression` = None
a $LaTeX$ math expression, the function's result

`latex_name` = None
The function's name in $LaTeX$

`latex_parameter_names` = None
A list of parameter names in $LaTeX$

`latex_x_name` = None
A $LaTeX$ symbol for the independent variable.

`name` = None
The name of the function

`number_of_parameters` = None
The number of parameters

`parameter_defaults` = None
The default values of the parameters

`parameter_names` = None
The names of the parameters

`x_name` = None
The name given to the independent variable

`kafe.function_tools.`**`LaTeX`**(***kwargs*)
Optional decorator for fit functions. This overrides a FitFunction's *latex_* attributes. The new values for the *latex_* attributes must be passed as keyword arguments to the decorator. Possible arguments:

name[string] $LaTeX$ representation of the function name.

parameter_names[list of strings] List of $LaTeX$ representations of the function's arguments. The length of this list must be equal to the function's argument number. The argument names should be in the same order as in the function definition.

x_name[string] $LaTeX$ representation of the independent variable's name.

expression[string] $LaTeX$-formatted expression representing the function's formula.

`kafe.function_tools.`**`derivative`**(*func*, *derive_by_index*, *variables_tuple*, *derivative_spacing*)
Gives $\frac{\partial f}{\partial x_k}$ for $f = f(x_0, x_1, \ldots)$. *func* is f, *variables_tuple* is $\{x_i\}$ and *derive_by_index* is k.

`kafe.function_tools.`**`outer_product`**(*input_array*)
Takes a *NumPy* array and returns the outer (dyadic, Kronecker) product with itself. If *input_array* is a vector $\mathbf{x}$, this returns $\mathbf{x}\mathbf{x}^T$.

3.9 `minuit` Module

`kafe.minuit.`**`D_MATRIX_ERROR` = {0: 'Error matrix not calculated', 1: 'Error matrix approximate!', 2: 'Error matrix**
Error matrix status codes

class `kafe.minuit.`**`Minuit`**(*number_of_parameters*, *function_to_minimize*, *parameter_names*, *start_parameters*, *parameter_errors*, *quiet=True*, *verbose=False*)
A class for communicating with ROOT's function minimizer tool Minuit.

FCN_wrapper(*number_of_parameters*, *derivatives*, *f*, *parameters*, *internal_flag*)
This is actually a function called in *ROOT* and acting as a C wrapper for our *FCN*, which is implemented in Python.

This function is called by *Minuit* several times during a fit. It doesn't return anything but modifies one of its arguments (*f*). This is *ugly*, but it's how *ROOT*'s `TMinuit` works. Its argument structure is fixed and determined by *Minuit*:

number_of_parameters[int] The number of parameters of the current fit

derivatives[C array] If the user chooses to calculate the first derivative of the function inside the *FCN*, this value should be written here. This interface to *Minuit* ignores this derivative, however, so calculating this inside the *FCN* has no effect (yet).

f[C array] The desired function value is in f[0] after execution.

parameters[C array] A C array of parameters. Is cast to a Python list

internal_flag[int] A flag allowing for different behaviour of the function. Can be any integer from 1 (initial run) to 4(normal run). See *Minuit*'s specification.

fix_parameter(*parameter_number*)
Fix parameter number <*parameter_number*>.

parameter_number[int] Number of the parameter to fix.

function_to_minimize = None
the actual *FCN* called in `FCN_wrapper`

get_chi2_probability(*n_deg_of_freedom*)
Returns the probability that an observed χ^2 exceeds the calculated value of χ^2 for this fit by chance, even for a correct model. In other words, returns the probability that a worse fit of the model to the data exists. If this is a small value (typically <5%), this means the fit is pretty bad. For values below this threshold, the model very probably does not fit the data.

n_def_of_freedom[int] The number of degrees of freedom. This is typically $n_extdatapoints - n_extparameters$.

get_contour(*parameter1*, *parameter2*, *n_points=21*)
Returns a list of points (2-tuples) representing a sampling of the 1σ contour of the TMinuit fit. The `FCN` has to be minimized before calling this.

parameter1[int] ID of the parameter to be displayed on the *x*-axis.

parameter2[int] ID of the parameter to be displayed on the *y*-axis.

n_points[int (optional)] number of points used to draw the contour. Default is 21.

returns[2-tuple of tuples] a 2-tuple (x, y) containing `n_points+1` points sampled along the contour. The first point is repeated at the end of the list to generate a closed contour.

get_error_matrix()
Retrieves the parameter error matrix from TMinuit.

return : *numpy.matrix*

get_fit_info(*info*)
Retrieves other info from *Minuit*.

info[string] Information about the fit to retrieve. This can be any of the following:

- `'fcn'`: *FCN* value at minimum,
- `'edm'`: estimated distance to minimum
- `'err_def'`: *Minuit* error matrix status code
- `'status_code'`: *Minuit* general status code

get_parameter_errors()
Retrieves the parameter errors from TMinuit.

return[tuple] Current *Minuit* parameter errors

get_parameter_info()
Retrieves parameter information from TMinuit.

return[list of tuples] `(parameter_name, parameter_val, parameter_error)`

get_parameter_name(*parameter_nr*)
Gets the name of parameter number `parameter_nr`

parameter_nr[int] Number of the parameter whose name to get.

get_parameter_values()
Retrieves the parameter values from TMinuit.

return[tuple] Current *Minuit* parameter values

get_profile(*parid*, *n_points=21*)
Returns a list of points (2-tuples) the profile the χ^2 of the TMinuit fit.

parid[int] ID of the parameter to be displayed on the *x*-axis.

n_points[int (optional)] number of points used for profile. Default is 21.

returns[two arrays, par. values and corresp. χ^2] containing `n_points` sampled profile points.

max_iterations = None
maximum number of iterations until `TMinuit` gives up

minimize(*final_fit=True*, *log_print_level=2*)
Do the minimization. This calls *Minuit*'s algorithms `MIGRAD` for minimization and, if *final_fit* is *True*, also `HESSE` for computing/checking the parameter error matrix.

minos_errors()
Get (asymmetric) parameter uncertainties from MINOS algorithm. This calls *Minuit*'s algorithms `MINOS`, which determines parameter uncertainties using profiling of the chi2 function.

returns[tuple] A tuple of [err+, err-, parabolic error, global correlation]

name = None
the name of this minimizer type

number_of_parameters = None
number of parameters to minimize for

release_parameter(*parameter_number*)
Release parameter number <*parameter_number*>.

parameter_number[int] Number of the parameter to release.

reset()
Execute TMinuit's *mnrset* method.

set_err(*up_value=1.0*)
Sets the `UP` value for Minuit.

up_value[float (optional, default: 1.0)] This is the value by which *FCN* is expected to change.

set_parameter_errors(*parameter_errors=None*)
Sets the fit parameter errors. If parameter_values='None', sets the error to 10% of the parameter value.

set_parameter_names(*parameter_names*)
Sets the fit parameters. If parameter_values='None', tries to infer defaults from the function_to_minimize.

set_parameter_values(*parameter_values*)

Sets the fit parameters. If parameter_values='None', tries to inferdefaults from the function_to_minimize.

set_print_level (*print_level=1*)
Sets the print level for Minuit.

print_level[int (optional, default: 1 (frugal output))] Tells `TMinuit` how much output to generate. The higher this value, the more output it generates.

set_strategy (*strategy_id=1*)
Sets the strategy Minuit.

strategy_id[int (optional, default: 1 (optimized))] Tells `TMinuit` to use a certain strategy. Refer to `TMinuit`'s documentation for available strategies.

tolerance = None
`TMinuit` tolerance

update_parameter_data (*show_warnings=False*)
(Re-)Sets the parameter names, values and step size on the C++ side of Minuit.

`kafe.minuit.`**P_DETAIL_LEVEL = 1**
default level of detail for TMinuit's output (typical range: -1 to 3, default: 1)

3.10 `iminuit_wrapper` Module

`kafe.iminuit_wrapper.`**D_MATRIX_ERROR = {0: 'Error matrix not calculated', 1: 'Error matrix approximate!', 2: 'E**
Error matrix status codes

class `kafe.iminuit_wrapper.`**IMinuit** (*number_of_parameters*, *function_to_minimize*, *parameter_names*, *start_parameters*, *parameter_errors*, *quiet=True*, *verbose=False*)
A wrapper class for iminuit.

FCN_wrapper (***kw_parameters*)
This wrapper converts from the "keyword argument" way of calling the function to a "positional argument" way, taking into account the order of the parameters as they appear in *self.parameter_names*.

This mapping is done for each call, so it's quite resource intensive, but this is unavoidable, since external FCNs to minimize expect positional arguments.

kw_parameters[dict] Map of parameter name to parameter value.

errordef = None
`iminuit` errordef

fix_parameter (*parameter*)
Fix parameter <*parameter*>.

parameter[string] Name of the parameter to fix.

function_to_minimize = None
the actual *FCN* called in `FCN_wrapper`

get_chi2_probability (*n_deg_of_freedom*)
Returns the probability that an observed χ^2 exceeds the calculated value of χ^2 for this fit by chance, even for a correct model. In other words, returns the probability that a worse fit of the model to the data exists. If this is a small value (typically <5%), this means the fit is pretty bad. For values below this threshold, the model very probably does not fit the data.

n_def_of_freedom[int] The number of degrees of freedom. This is typically $n_extdatapoints - n_extparameters$.

get_contour (*parameter1*, *parameter2*, *n_points=21*)
Returns a list of points (2-tuples) representing a sampling of the 1σ contour of the iminuit fit. The `FCN` has to be minimized before calling this.

parameter1[int] ID of the parameter to be displayed on the *x*-axis.

parameter2[int] ID of the parameter to be displayed on the *y*-axis.

n_points[int (optional)] number of points used to draw the contour. Default is 21.

returns[2-tuple of tuples] a 2-tuple (x, y) containing `n_points+1` points sampled along the contour. The first point is repeated at the end of the list to generate a closed contour.

get_error_matrix(*correlation=False*)
Retrieves the parameter error matrix from iminuit.

correlation[boolean (optional, default `False`)] If `True`, return correlation matrix, else return covariance matrix.

return : *numpy.matrix*

get_fit_info(*info*)
Retrieves other info from *Minuit*.

info[string] Information about the fit to retrieve. This can be any of the following:

- `'fcn'`: *FCN* value at minimum,
- `'edm'`: estimated distance to minimum
- `'err_def'`: *Minuit* error matrix status code
- `'status_code'`: *Minuit* general status code

get_parameter_errors()
Retrieves the parameter errors from iminuit.

return[tuple] Current *Minuit* parameter errors

get_parameter_info()
Retrieves parameter information from iminuit.

return[list of tuples] `(parameter_name, parameter_val, parameter_error)`

get_parameter_name(*parameter_nr*)
Gets the name of parameter number `parameter_nr`

parameter_nr[int] Number of the parameter whose name to get.

get_parameter_values()
Retrieves the parameter values from iminuit.

return[tuple] Current *Minuit* parameter values

get_profile(*parameter*, *n_points=21*)
Returns a list of points (2-tuples) the profile the χ^2 of the iminuit fit.

parid[int] ID of the parameter to be displayed on the *x*-axis.

n_points[int (optional)] number of points used for profile. Default is 21.

returns[two arrays, par. values and corresp. χ^2] containing `n_points` sampled profile points.

max_iterations = None
maximum number of iterations until `iminuit` gives up

minimize(*final_fit=True*, *log_print_level=2*)
Do the minimization. This calls *Minuit*'s algorithms `MIGRAD` for minimization and, if *final_fit* is *True*, also `HESSE` for computing/checking the parameter error matrix.

minos_errors()
Get (asymmetric) parameter uncertainties from MINOS algorithm. This calls *Minuit*'s algorithms `MINOS`, which determines parameter uncertainties using profiling of the chi2 function.

returns[tuple] A tuple of (err+, err-, parabolic error, global correlation)

name = None
the name of this minimizer type

number_of_parameters = None
number of parameters to minimize for

release_parameter(*parameter*)
Release parameter <*parameter*>.

parameter[string] Name of the parameter to release.

reset()
Resets iminuit by re-creating the minimizer.

set_err(*up_value=1.0*)
Sets the `UP` value for Minuit.

up_value[float (optional, default: 1.0)] This is the value by which *FCN* is expected to change.

set_parameter_errors(*parameter_errors=None*, *update_iminuit=True*)
Sets the fit parameter errors. If parameter_values='None', sets the error to 10% of the parameter value.

set_parameter_names(*parameter_names*, *update_iminuit=True*)
Sets the fit parameter names.

set_parameter_values(*parameter_values*, *update_iminuit=True*)

Sets the fit parameters. If parameter_values='None', tries to inferdefaults from the function_to_minimize.

set_print_level(*print_level=1*)
Sets the print level for Minuit.

print_level[int (optional, default: 1 (frugal output))] Tells `iminuit` how much output to generate. The higher this value, the more output it generates.

set_strategy(*strategy_id=1*)
Sets the strategy Minuit.

strategy_id[int (optional, default: 1 (optimized))] Tells `iminuit` to use a certain strategy. Refer to `iminuit`'s documentation for available strategies.

set_tolerance(*tol*)
Sets the tolerance value for Minuit.

tol[float] The tolerance

update_parameter_data(*show_warnings=False*)
(Re-)Sets the parameter names, values and step size in iminuit.

kafe.iminuit_wrapper.**P_DETAIL_LEVEL = 1**
default level of detail for iminuit's output (typical range: -1 to 3, default: 1)

3.11 `config` Module

kafe.config.**create_config_file**(*config_type*, *force=False*)
Create a kafe config file.

config_type['user' or 'local'] Create a 'user' config file in '~/.config/kafe' or a 'local' one in the current directory.

force[boolean (optional)] If true, overwrites existing files.

kafe.config.**log_file**(*file_relative_path*)
Returns correct location for placing log files.

3.12 `plot` Module

class `kafe.plot.`**`Plot`**(**fits*, ***kwargs*)
Bases: `object`

The constuctor accepts a series of *Fit* objects as positional arguments. Some keyword arguments can be provided to override the defaults.

`axis_labels` = **None**
axis labels

`compute_plot_range`(*include_error_bars=True*)
Compute the span of all child datasets and sets the plot range to that

`draw_fit_parameters_box`(*plot_spec=0*, *force_show_uncertainties=False*)
Draw the parameter box to the canvas

Parameters

- **`plot_spec`** (*int, list of ints, string or None (optional, default: 0)*) – Specify the plot id of the plot for which to draw the parameters. Passing 0 will only draw the parameter box for the first plot, and so on. Passing a list of ints will only draw the parameters for plot ids inside the list. Passing `'all'` will print parameters for all plots. Passing `None` will return immediately doing nothing.
- **`force_show_uncertainties`** (*boolean (optional, default: False)*) – If `True`, shows uncertainties even for Datasets without error data. Note that in that case these values are meaningless!

`draw_legend`()
Draw the plot legend to the canvas

`extend_span`(*axis*, *new_span*)
Expand the span of the current plot.

This method extends the current plot span to include *new_span*

`fits` = **None**
list of `Fit` objects to plot

`init_plots`(***kwargs*)
Initialize the plots for each fit.

`on_draw`(*event*)
Function to call when a draw event occurs.

`plot`(*p_id*, *show_data=True*, *show_function=True*, *show_band=True*)
Plot the *Fit* object with the number *p_id* to its figure.

`plot_all`(*show_info_for='all'*, *show_data_for='all'*, *show_function_for='all'*, *show_band_for='meaningful'*)
Plot every *Fit* object to its figure.

`plot_range` = **None**
plot range

`plot_style` = **None**
plot style

`save`(*output_file*)
Save the *Plot* to a file.

`set_axis_scale`(*axis*, *scale_type*, ***kwargs*)
Set the scale for an axis.

Parameters

- **`axis`** (*''x'' or ''y''*) – Axis for which to set the scale.

•**scale_type** (*''linear" or ''log''*) – Type of scale to set for the axis.

Keyword Arguments

•****basex**** (*int*) – Base of the ''x" axis scale logarithm. Only relevant for log scales.

•****basey**** (*int*) – Base of the ''y" axis scale logarithm. Only relevant for log scales.

show()
Show graphics in one or more matplotlib interactive windows.

Note: This shows all figures/plots generated before it is called. Because of the way `matplotlib` handles some plotting parameters (`matplotlib.rcParams`) these cannot be set individually for each figure before it is displayed. This means that all figures will be shown with the same plot style: that of the *Plot* object from which show() is called.

---

show_legend = None
whether to show the plot legend (`True`) or not (`False`)

class `kafe.plot.`**PlotStyle**
Class for specifying a style for a specific plot. This object stores a progression of marker and line types and colors, as well as preferences relating to point size and label size. These can be overriden by overwriting the instance variables directly. A series of *get_...* methods are provided which go through these lists cyclically.

get_line(*idm*)
Get a specific line type. This runs cyclically through the defined defaults.

get_linecolor(*idm*)
Get a specific line color. This runs cyclically through the defined defaults.

get_marker(*idm*)
Get a specific marker type. This runs cyclically through the defined defaults.

get_markercolor(*idm*)
Get a specific marker color. This runs cyclically through the defined defaults.

get_pointsize(*idm*)
Get a specific point size. This runs cyclically through the defined defaults.

`kafe.plot.`**label_to_latex**(*label*)
Generates a simple LaTeX-formatted label from a plain-text label. This treats isolated characters and words beginning with a backslash as mathematical expressions and surround them with $ signs accordingly.

Parameters**label** (*string*) – Plain-text string to convert to LaTeX.

`kafe.plot.`**pad_span**(*span*, *pad_coeff=1*, *additional_pad=None*)
Enlarges the interval *span* (list of two floats) symmetrically around its center to length *pad_coeff*. Optionally, an *additional_pad* argument can be specified. The returned span is then additionally enlarged by that amount.

additional_pad can also be a list of two floats which specifies an asymmetric amount by which to enlarge the span. Note that in this case, positive entries in *additional_pad* will enlarge the span (move the interval end away from the interval center) and negative amounts will shorten it (move the interval end towards the interval center).

`kafe.plot.`**pad_span_log**(*span*, *pad_coeff=1*, *additional_pad=None*, *base=10*)

3.13 `latex_tools` Module

`kafe.latex_tools.`**ascii_to_latex_math**(*str_ascii*, *monospace=True*, *ensuremath=True*)
Escapes certain characters in an ASCII input string so that the result can be included in math mode without error.

str_ascii[string] A plain-text string containing characters to be escaped for $LaTeX$ math mode.

monospace[boolean (optional)] Whether to render the whole expression as monospace. Defaults to `True`.

ensuremath[boolean (optional)] If this is `True`, the resulting formula is wrapped in an `\ensuremath{}` tag. Defaults to `True`.

3.14 `numeric_tools` Module

`kafe.numeric_tools.`**`MinuitCov_to_cor`**(*cov_mat*)
Converts a covariance matrix as returned by Minuit to the corresponding correlation matrix; note that the Minuit covariance matrix may contain lines/rows with zeroes if parameters are fixed

cov_mat[*numpy.matrix*] The Minuit covariance matrix to convert.

`kafe.numeric_tools.`**`cor_to_cov`**(*cor_mat*, *error_list*)
Converts a correlation matrix to a covariance matrix according to the formula

$$\mathrm{Cov}_{ij} = \mathrm{Cor}_{ij}\,\sigma_i\,\sigma_j$$

cor_mat[*numpy.matrix*] The correlation matrix to convert.

error_list[sequence of floats] A sequence of statistical errors. Must be of the same length as the diagonal of *cor_mat*.

`kafe.numeric_tools.`**`cov_to_cor`**(*cov_mat*)
Converts a covariance matrix to a correlation matrix according to the formula

$$\mathrm{Cor}_{ij} = \frac{\mathrm{Cov}_{ij}}{\sqrt{\mathrm{Cov}_{ii}\,\mathrm{Cov}_{jj}}}$$

cov_mat[*numpy.matrix*] The covariance matrix to convert.

`kafe.numeric_tools.`**`extract_statistical_errors`**(*cov_mat*)
Extracts the statistical errors from a covariance matrix. This means it returns the (elementwise) square root of the diagonal entries

cov_mat The covariance matrix to extract errors from. Type: *numpy.matrix*

`kafe.numeric_tools.`**`make_symmetric_lower`**(*mat*)
Copies the matrix entries below the main diagonal to the upper triangle half of the matrix. Leaves the diagonal unchanged. Returns a *NumPy* matrix object.

mat[*numpy.matrix*] A lower diagonal matrix.

returns[*numpy.matrix*] The lower triangle matrix.

`kafe.numeric_tools.`**`zero_pad_lower_triangle`**(*triangle_list*)
Converts a list of lists into a lower triangle matrix. The list members should be lists of increasing length from 1 to N, N being the dimension of the resulting lower triangle matrix. Returns a *NumPy* matrix object.

For example:

```
>>> zero_pad_lower_triangle([ [1.0], [0.2, 1.0], [0.01, 0.4, 3.0] ])
matrix([[ 1.  ,  0.  ,  0.  ],
        [ 0.2 ,  1.  ,  0.  ],
        [ 0.01,  0.4 ,  3.  ]])
```

triangle_list[list] A list containing lists of increasing length.

returns[*numpy.matrix*] The lower triangle matrix.

3.15 `stream` Module

class `kafe.stream.`**`StreamDup`**(*out_file*, *suppress_stdout=False*)
Bases: `object`

Object for simultaneous logging to stdout and files. This object provides a file/like object for the outout to be written to. Writing to this object will write to stdout (usually the console) and to a file.

out_file[file path or file-like object or list of file paths ...] File(s) to which to log the output, along with stdout. If a file exists on disk, it will be appended to.

suppress_stdout[boolean] Whether to log to stdout simultaneously (`False`) or suppress output to stdout (`True`). Default to `False`.

`fileno`()
Returns the file handler id of the main (first) output file.

`flush`()

`write`(*message*)

`write_timestamp`(*prefix*)

`write_to_file`(*message*)

`write_to_stdout`(*message*, *check_if_suppressed=False*)
Explicitly write to stdout. This method will not check by default whether `suppress_stdout` is set for this *StreamDup*. If `check_if_suppressed` is explicitly set to `True`, then this check occurs.

Symbols

A

B

C

D

E

F

G

H

I

K

L

M

N

Y

Z