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# **mimoCoRB**

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## MIMOCORB - MULTIPLE-IN MULTILE-OUT CONFIGURABLE RING BUFFER: OVERVIEW

**mimoCoRB**: multiple-in multiple-out Configurable Ring Buffer

The package **mimoCoRB** provides a central component of each data acquisition system needed to record and pre-analyze data from randomly occurring processes. Typical examples are waveform data as provided by single-photon counters or typical detectors common in quantum mechanical measurements or in nuclear, particle physics and astro particle physics, e. g. photo tubes, Geiger counters, avalanche photo-diodes or modern SiPMs.

The random nature of such processes and the need to keep read-out dead times low requires an input buffer and a buffer manager running as a background process. While a data source feeds data into the buffer, consumer processes are fed with an almost constant stream of data to filter, reduce, analyze or simply visualize data and on-line analysis results. Such consumers may be obligatory ones, i. e. data acquisition pauses if all input buffers are full and an obligatory consumer is still busy processing. A second type of random consumers or “observers” receives an event copy from the buffer manager upon request, without pausing the data acquisition process. Typical examples of random consumers are displays of a subset of the wave forms or of intermediate analysis results.

This project originated from an effort to structure and generalize data acquisition for several experiments in advanced physics laboratory courses at Karlsruhe Institute of Technology (KIT).

As a simple demonstration, we provide data from simulated signals as would be recorded by a detector for cosmic muons with three detection layers. Occasionally, such muons stop in an absorber between the 2nd and 3rd layer, where they decay at rest and emit a high-energetic electron recorded as a 2nd pulse in one or two of the detection layers. After data acquisition, a search for typical pulses is performed, data with detected double pulses are selected and fed into a second buffer. A third buffer receives data in a reduced format which only contains the parameters of found pulses. These data and the wave forms of all double-pulses are finally stored on disk. This application is a very typical example of the general process of on-line data processing in modern physics experiments and may serve as a starting point for own applications.

### 1.1 Description of components

In order to decouple the random occurrence of “events” one needs a buffer capable of rapidly storing new incoming data and delivering a constant data stream to subsequent consumer processes of the data. This is typically implemented as a first-in, first out ringbuffer providing storage space in memory for incoming data, which is released and overwritten by new data when all consuming processes have finished. As digital filtering of incoming data may be very CPU intensive, multi-processing and multi-core capable components are needed to ensure sufficient processing power to process and analyze data. *mimoCoRB.mimo\_buffer* implements such a buffer allowing multiple processes to read (“multiple out”) or write (“multiple in”) to the buffer space. Because processing of the data, i.e. digital filtering, selection, compression and storage or real-time visualization of the data may be a complex workflow, buffers may be arranged in chains where one or several reader processes of a buffer write to one or to several output buffer(s).

Memory management and access control is provided by the class **newBuffer**. To control the data flow in such a data acquisition suite, three types of access are needed, implemented as **Writer**, **Reader** and **Observer** classes. Readers of the same type are grouped together for multi-processing of compute-intense tasks and form a Reader-group. Observers receive only a sub-set of the data and are mainly intended to be used for visual inspection or graphical representation of samples of the recorded or processed data.

Processes for data provisioning from front-end hardware or from other sources, like disk files, web streams or simulation, rely on these basic classes. Any Writer-process blocks if no free buffer slot is available. Reader processes block if no slot is left that has not yet been processed by any process belonging to the same group of readers. Note that the buffer manager ensures that every slot assigned to a Reader (or a group of Readers) is actually processed; therefore, the whole chain blocks if no Reader or member of a Reader-group processes the data in the buffer it is assigned to.

The data format is based on structured *numpy* arrays with field names. Each buffer entry is also associated with a unique number and a time stamp in microseconds (*time.time\_ns()//1000*) of type *longlong* (64 bit integer) and a deadtime fraction provided by the initial data producer. The deadtime accounts for inefficiencies of the data acquisition due to processing in mimoCoRB. These metadata are set by the initial producer and must not be changed at a later stage in the processing chain.

## 1.2 Simple application example (also provided as a unit test)

An application example of *mimo\_buffer* is shown below. This code may serve as a starting point for own projects. The set-up is as follows:

2 ring buffers are defined:

- input Buffer RB\_1: 10 ch x 1024 slots (int32)
- output Buffer RB\_2: 10 ch x 2 slots/ch (float64)

Simple data is filled into RB\_1, copied and extended by a process writing data into RB\_2, and finally a reader process to check integrity and completeness of the data. The most complex part of the code is in function *run\_control()*, which demonstrates how to set up the buffers, define Reader and Writer instances and start the parallel processes for generating, processing and reading the data.

The example including comment lines for explanation is shown here:

```
import time
import unittest
import numpy as np
from multiprocessing import Process, Value
from mimocorb import mimo_buffer as bm

# global variables
N_requested = 1000 # number of data injections ("events")
Time_tick = 0.001 # time between events
Ncpul = 2         # number of parallel analyzer processes

def data_generator(sink_dict):
    """writes continuously rising integers to buffer specified in sink_dict
    """
    sink = bm.Writer(sink_dict)
    n=0
    # inject data
    for x in range(N_requested):
```

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```

    buffer = sink.get_new_buffer() # get new buffer and pass last item
    # random wait for next data item
    time.sleep(-Time_tick*np.log(np.random.rand() ))
    # fill "data"
    n += 1
    buffer[:] = n
# process last data item
sink.process_buffer()

def analyzer(source_dict, sink_dict):
    """read from source and write first element and a time difference to sink
    """
    source = bm.Reader(source_dict)
    sink = bm.Writer(sink_dict)
    start_time = time.time()

    while True:
        input_data = source.get()
        output_data = sink.get_new_buffer()
        # process data
        output_data[0] = input_data[0]
        # mimick processing time
        time.sleep(2*Time_tick)
        output_data[1] = time.time() - start_time

        #
        sink.process_buffer()

def check_result(source_dict, res):
    """reads RB_2 and sum up the integer content (value should be sum(1 -35) = 630);

    sum is returned as shared memory Value-object
    """
    source = bm.Reader(source_dict)
    sum_rb = 0
    while True:
        input_data = source.get()
        res.value +=int(input_data[0])

def run_control():
    """Setup buffers, start processes and shut_down when 1st writer done
    """

    # Create ring buffers: #2: 10 channel, 2 value per channel
    # (1: buffer content; 2: time difference as int)
    # d_type = [('chA', np.float)] #not necessary: always the same type
    generator_buffer = bm.NewBuffer(10, 1, np.int32)
    eval_buffer = bm.NewBuffer(10, 2, np.float32)

    # create readers first

```

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```

source_dic_gen = generator_buffer.new_reader_group()
source_dic_eval = eval_buffer.new_reader_group()

# Create worker processes (correct sequence: first action as last)
process_list = []
# evaluation to test ring buffer behavior
result = Value('i', 0) # int variable in shared meomry
process_list.append(Process(target=check_result,
                           args=(source_dic_eval, result)))
# data transfer between the 2 buffers: generator_buffer -> eval_buffer
sink_dic_eval = eval_buffer.new_writer()
# work with all cpu's requested
number_of_workers = Ncpu1
for i in range(number_of_workers):
    process_list.append(Process(target=analyzer,
                              args=(source_dic_gen, sink_dic_eval)))

# fill buffer (generator_buffer) with data first
sink_dic_gen = generator_buffer.new_writer()
process_list.append(Process(target=data_generator,
                           args=(sink_dic_gen,)))

for p in process_list:
    p.start()

run_active = True
while run_active:
    run_active = False if process_list[-1].exitcode==0 else True
    time.sleep(0.1) # wait

time.sleep(0.1) # some grace-time for readers to finish

generator_buffer.shutdown()
eval_buffer.shutdown()
del generator_buffer, eval_buffer

for p in process_list:
    p.join()

return result.value

class RPTest(unittest.TestCase):

    def test_process(self):
        # start python test module and check result
        a = run_control()
        expected_result = N_requested*(N_requested+1)//2
        self.assertEqual(a, expected_result) # expected result: sum(i); i = 1, N_requested

if __name__ == "__main__":

```

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```
unittest.main(verbosity=2)
#     print(process_buffer())
```



## ACCESS CLASSES IN THE MODULE *BUFFER\_CONTROL*

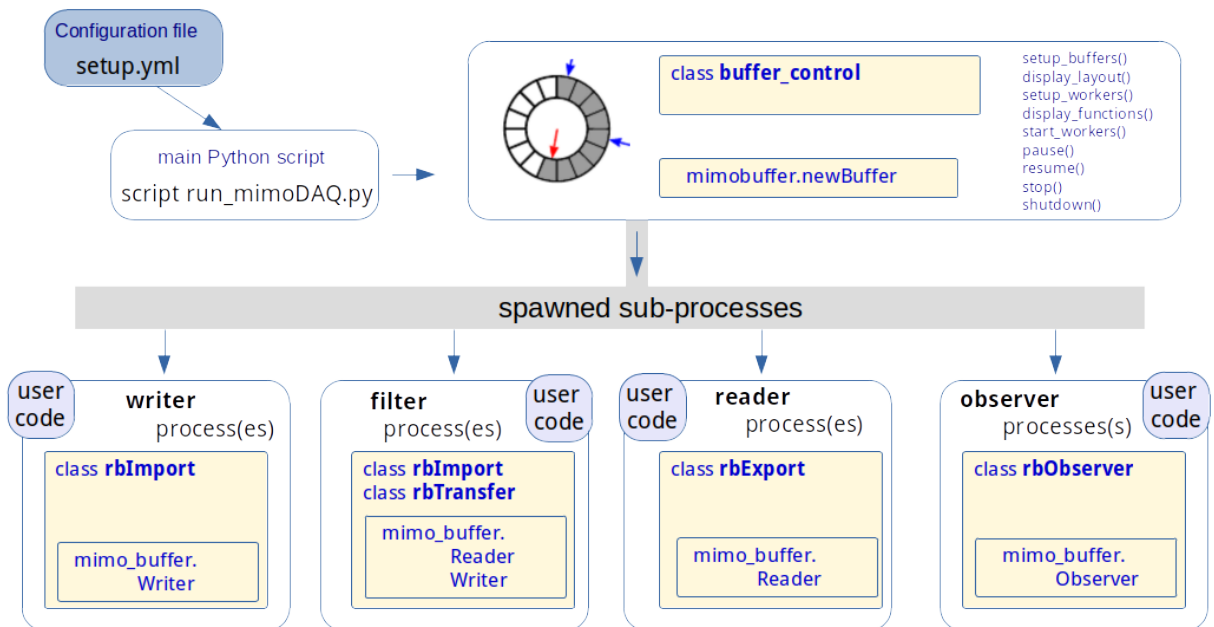
To ease user interaction with the buffer manager, a set of additional classes is provided in the module *buffer\_control* to set-up and manage cascades of ringbuffers and the associated functions for filling, filtering and extracting data. These classes are also interesting for developers wanting to help improving the package.

The classes are:

- **class *buffer\_control***  
Set-up and management of ringbuffers and associated sub-processes. This is the overarching class with access to all created buffers and sub-processes.
- **class *rbImport***  
Read data from source (front-end like a PicoScope USB oscilloscope, or from file or simulation) and put data in a *mimo\_buffer*. Data is input is handled by a call of a user-supplied generator function for data and metadata.
- **class *rbTransfer***  
Read data from a *mimo\_buffer*, filter and/or reformat data and write to output *mimo\_buffer(s)*. Data is provided as the argument to a user-defined filter function returning *None* if data is to be discarded, a number if data is to be copied to another buffer, or - optionally - a list of data records produced from processed input data. If such data are provided, a respective number of ringbuffers as destination must be configured.
- **class *rbExport***  
Read data from *mimo\_buffer* and analyze (with user-supplied code), without writing to another ringbuffer. Data is provided by a generator function in the `__call__()` method of the class yielding a tuple of data and metadata.
- **class *rbObserver***  
Deliver data from a buffer to an observer process. A tuple (data, metadata) is provided by a generator function ( i.e. via `yield()`) implemented in the `__call__()` method of the class.
- **class *rb\_toTxtfile*:**  
Save *mimo\_buffer* data to a file in csv-format. The header line of this file contains the keys of the respective columns, which are derived from the datatype of the structured ringbuffer array. Aliases for improved clarity can be provided in the configuration file.
- **class *rb\_toParquetfile*:**  
Save *mimo\_buffer* data to an archive in *tar* format; each data record is packed in Parquet format.
- **class *run\_mimoDAQ***  
Setup and run Data Acquisition suite with *mimoCoRB* buffer manager. The layout of ringbuffers and associated functions are defined in a configuration file in *yaml* format. All configured functions are executed as worker processes in separate sub-processes and therefore optimal use is made of multi-core architectures.
- **class *bufferinfoGUI*:**  
A graphical interface showing buffer rates and status information and providing some control buttons interacting with the *runDAQ* class

These classes shield much of the complexity from the user, who can thus concentrate on writing the pieces of code need to acquire and process the data. The access classes expect as input lists of dictionaries with the parameters of buffers to read from (**source\_list**), to write to (**sink\_list**) or to observe (**observe\_list**). An additional dictionary (**config\_dict**) provides the additional parameters needed for the specific functionality, for example names of functions to read data, filter or manipulate data or the names of target files. The interface for passing data between the user-defined functions and ringbuffers relies on Python generators (i.e. the `yield` instruction).

The overarching class **buffer\_control** provides methods to setup buffers and worker processes and to control the data acquisition process. The methods collected in the class `run_mimoDAQ`, in particular the function `run_mimoDAQ`, contains the code needed to run a real example of a data-acquisition suite defined in a configuration file specifying the associated, user-defined functions for data provisioning, filtering and storage. `run_mimoDAQ` is controlled either by keyboard commands or from a graphical user interface; pre-defined conditions on the total number of events processed, the duration of the data taking run or finishing of the writer process to the first buffer due to source exhaustion can also be defined to end data taking. The class structure and dependencies are shown in the figure below.



For complex setups and longer data-taking periods it is important to gain a quick overview of the status of all buffers and to monitor long-term stability. Therefore, a graphical display with the processing rate of all buffers is provided by the class **bufferinfoGUI**. A text window receives frequent updates of the number of events processed by each buffer and of the buffer fill-levels. Klick-buttons send information via a dedicated command queue to the calling process `run_mimoDAQ` and allow pausing, resuming and ending the data acquisition.

The suggested structure of the project work-space for mimiCoRB applications is as follows:

```
|--> <user working directory>      # the main configuration script resides here
|
| --> modules      # project-specific, user-supplied python code
| --> config       # configuration files in yaml format
| --> target       # output of data-acquisition run(s)
```

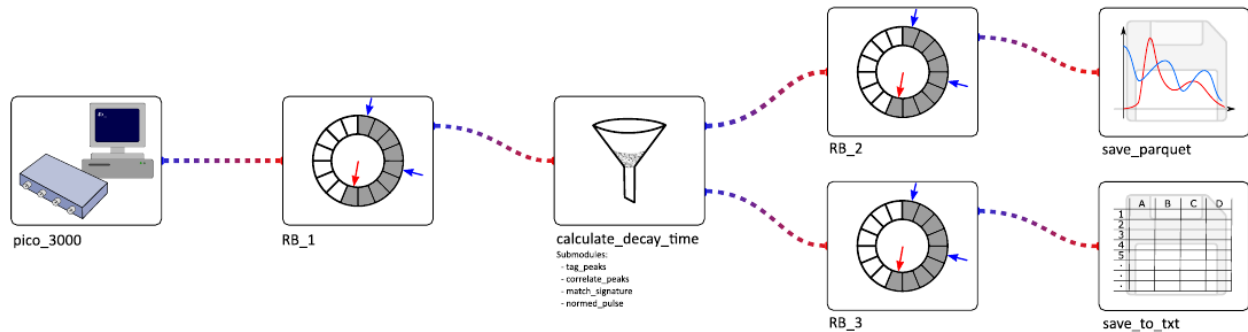
For illustration and as a starting point for own applications, a stand-alone example is provided as part of the package, as described in the following section.

## 2.1 Application example

The subdirectory *examples/* contains a rather complete application use case. It runs stand-alone and uses as input simulated waveform data of short pulses in a scintillator detector. The simulated physics process corresponds to signatures produced by cosmic muons. Of particular interest in this case are (rare) signatures with a double-pulse structure, where the first pulse originates from a detected muon and the second one from a decay electron of a muon that is stopped in or near a detection layer.

Examples of code snippets and configuration data are provided in the subdirectories *examples/modules/* and *examples/config/*, respectively. Waveform data, as provided by, for example, a multi-channel digital oscilloscope, are generated and filled into the first one of a cascaded set of three ringbuffers. The raw data are analyzed, and accepted data with a double-pulse signature are selected and directly passed on to a second ringbuffer. A third buffer contains only the information on found signal pulses; a result file in *csv* format contains the data extracted from this buffer. Configuration files and the recorded data files are stored in the subdirectory *examples/target/<projectname>\_<date\_and\_time>*.

A graphical representation of the set-up is shown in the figure below [source: Master's Thesis Christoph Mayer, ETP 2022]. Note that the oscilloscope is replaced by a signal simulation in the provided example.



The buffer layout and the associated functions are defined in the main configuration file *simulsource\_setup.py*, which serves as the input to the execution script *run\_daq.py* in the top-level directory of the package. The *python* files *simulation\_source.py*, *lifetime\_filter.py* and *save\_files.py* contain the user code for data generation, analysis and filtering and extraction of the final data to disk files. The *.yaml* files *simulation\_config.yaml* and *save\_lifetimes.yaml* contain configurable parameters provided to these functions.

An observer process receives a sub-set of the data in the second buffer and shows them as an oscilloscope display on screen while data are generated and propagated through the buffers.

This example is executed from the directory *examples/* by entering:

```
../run_daq.py simulsource_setup.yaml
```

The code needed to run a data acquisition based on the package *mimocorb.buffer\_control.run\_mimoDAQ* is shown here:

```
# script run_daq.py

from mimocorb.buffer_control import run_mimoDAQ
daq = run_mimoDAQ()
daq.setup()
daq.run()
```

The input *yaml* file for the example provided as part of the package looks as follows:

```
# Application example for mimoCoRB
# -----
```

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```

RingBuffer:
    # define ring buffers
    - RB_1:
        # raw input data buffer (waveforms from PicoScope, filele_source or simulation_
        ↪source)
        number_of_slots: 128
        channel_per_slot: 4250
        data_type:
            1: ['chA', "float64"]
            2: ['chB', "float64"]
            3: ['chC', "float64"]
            4: ['chD', "float64"]
    - RB_2:
        # buffer with accepted signatures (here double-pulses)
        number_of_slots: 128
        channel_per_slot: 4250
        data_type:
            1: ['chA', "float64"]
            2: ['chB', "float64"]
            3: ['chC', "float64"]
            4: ['chD', "float64"]
    - RB_3:
        # buffer with pulse parameters (derived from waveforms)
        number_of_slots: 32
        channel_per_slot: 1
        data_type:
            1: ['decay_time', "int32"]
            3: ['1st_chA_h', "float64"]
            4: ['1st_chB_h', "float64"]
            5: ['1st_chC_h', "float64"]
            6: ['1st_chA_p', "int32"]
            7: ['1st_chB_p', "int32"]
            8: ['1st_chC_p', "int32"]
            9: ['1st_chA_int', "float64"]
            10: ['1st_chB_int', "float64"]
            11: ['1st_chC_int', "float64"]
            12: ['2nd_chA_h', "float64"]
            13: ['2nd_chB_h', "float64"]
            14: ['2nd_chC_h', "float64"]
            15: ['2nd_chA_p', "int32"]
            16: ['2nd_chB_p', "int32"]
            17: ['2nd_chC_p', "int32"]
            18: ['2nd_chA_int', "float64"]
            19: ['2nd_chB_int', "float64"]
            20: ['2nd_chC_int', "float64"]
            21: ['1st_chD_h', "float64"]
            22: ['1st_chD_p', "int32"]
            23: ['1st_chD_int', "float64"]
            24: ['2nd_chD_h', "float64"]
            25: ['2nd_chD_p', "int32"]
            26: ['2nd_chD_int', "float64"]

```

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**Functions:**

```

# define functions and assignments
- Fkt_main:
  config_file: "config/simulation_config.yaml"
- Fkt_1:
  file_name: "modules/simulation_source"
  kt_name: "simulation_source"
  num_process: 1
  RB_assign:
    RB_1: "write"
- Fkt_2:
  file_name: "modules/lifetime_filter"
  fkt_name: "calculate_decay_time"
  num_process: 2
  RB_assign:
    RB_1: "read"      # input
    RB_2: "write"     # waveform to save (if double pulse was found)
    RB_3: "write"     # pulse data
- Fkt_3:
  file_name: "modules/save_files"
  fkt_name: "save_to_txt"
  num_process: 1
  RB_assign:
    RB_3: "read"      # pulse data
- Fkt_4:
  file_name: "modules/save_files"
  fkt_name: "save_parquet"
  num_process: 1
  RB_assign:
    RB_2: "read"      # waveform to save
- Fkt_5:
  file_name: "mimocorb/plot"
  fkt_name: "plot_graph"
  num_process: 1
  RB_assign:
    RB_2: "observe"   # double pulse waveform

```

The configuration file referenced in the line `config_file: "config/simulation_config.yaml"` provides the information needed by the user-supplied functions.

### 2.1.1 Indices and tables

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## MODULE DOCUMENTATION

### **mimo-ringbuffer:**

Module implementing a multiple-in multiple-out ringbuffer appropriate for multi-core multiprocessing.

The ringbuffer creation and management is handled by the class `NewBuffer`. Buffer access is managed by the `Reader`, `Writer` and `Observer` classes.

classes:

- `NewBuffer`: create a new ringbuffer, assign writer(s) and reader(s) or observer(s)

methods:

- `new_writer`
  - `new_reader_group`
  - `new_observer`
  - `buffer_status`
- `Writer`: write elements into a ringbuffer
  - `Reader`: read all elements from a ringbuffer
  - `Observer`: read selected elements from a ringbuffer.

**class** `mimocorb.mimo_buffer.NewBuffer`(*number\_of\_slots, values\_per\_slot, dtype, debug=False*)

Class to create a new ringbuffer object according to the 'FIFO' principle (first-in first-out).

Memory shares, IPC queues, lock and event objects as well as background threads are defined for the multi-processing ringbuffer management. Methods are provided to build the setup dictionaries (necessary parameter objects) for the `Reader`, `Writer` or `Observer` instances, respectively. Further, methods are provided to allow an index processing (e.g. listeners) and to pause data processing.

important methods:

- `__init__()` constructor to create a new 'FIFO' ringbuffer
- `new_writer()` create new writer
- `new_reader_group()` create reader group
- `new_observer()` create observer
- `buffer_status()` display status: event count, processing rate, occupied slots
- `pause()` disable writer(s) to ringbuffer
- `resume()` (re-)enable writers
- `set_ending()` stop data-taking (gives processes time to finish before shutdown)

- `close()` release shared memory
- `shutdown()` end connected processes, delete ringbuffer

**buffer\_status()**

Processing Rate and approximate number of free slots in this ringbuffer. This method is meant for user information purposes only, as the result may not be completely accurate due to race conditions.

**Returns**

Number of free slots in this ringbuffer

**Return type**

int

**new\_WSobserver()**

Method to create a new (web-socket based) observer. It's possible to create multiple observers and simply share the setup dictionary between different `Observer`-instances (analogues to the behavior of the `new_reader_group`). It might be possible that data seen by an `Observer` instance are corrupted (especially with a not ideal ringbuffer configuration and/or a heavily loaded PC system).

**``Observer``-instances MUST NOT rely on data integrity!!**

**Returns**

The `setup_dict` object passed to an `Observer`-instance to grant access to this ringbuffer.

**Return type**

dict

**new\_observer()**

Method to create a new (Queue based) observer.

Method: a copy of the most recent data is transferred via a Queue whenever the Queue (of size 1) becomes empty. Sending data to the Queue is handled in a separate thread

**Returns**

The `setup_dict` object passed to an `Observer`-instance to give access to the `dataQueue` defined for this ringbuffer.

**Return type**

dict

**new\_reader\_group()**

Method to create a new reader group. The processing workload of a group can be distributed to multiple processes by using the same setup dictionary (`setup_dict`) defined for a `Reader`-object. Each ringbuffer element is processed by one reader group process. It's possible to create multiple reader groups per ringbuffer, where each reader group gets every element written to the ringbuffer. If a reader group is created, at least one `Reader`-class instance MUST steadily call its `get()` method to prevent the ringbuffer from blocking and to allow a safe shutdown.

**Returns**

The `setup_dict` object passed to a `Reader`-instance to grant read access to this ringbuffer.

**Return type**

dict

**new\_writer()**

Method to create a new writer. It is possible to create multiple writers and simply share a setup dictionary definition between different `Writer`-instances (analogues to the behavior of the `new_reader_group`).

**Returns**

The `setup_dict` object passed to a `Writer`-instance to grant write access to this ringbuffer.

**Return type**

dict

**pause()**

Disable writing to ringbuffer (paused)

**resume()**

(Re)enable writing to ringbuffer (resume)

**set\_ending()**

Stop data flow (before shut-down)

**shutdown()**

Shut down the ringbuffer(s): close background threads, terminate associated processes and release the shared memory definitions.

Affect processes using a `Reader`, `Writer` or `Observer` instance to a ringbuffer.

A ‘trickle down’ approach is used to have as few ringbuffer elements as possible unprocessed. This may not work correctly with more complex signal analysis chains. So always make sure to shut down the ringbuffers in data flow order (start with first element of the chain, the ringbuffer closest to the signal source).

**CAUTION!** If there are loops in the signal analysis chain, this method may end in an infinite loop!

**class** mimocorb.mimo\_buffer.**Observer**(*setup\_dict*)

Class for reading selected elements from a ringbuffer via q multiprocessing Queue

The data transfer is implemented via a multiprocessing Queue and interfaces with the ringbuffer manager (`NewBuffer`-class).

**get()**

Get latest element from buffer: metadata and data

As new data is provided and transferred as soon as data is read from the Queue, the `get()` method must not be called too frequently

**class** mimocorb.mimo\_buffer.**Reader**(*setup\_dict*)

Class to read elements from a ringbuffer (multiple-out part).

Ringbuffer elements are structured NumPy arrays and strictly **read-only**. The returned array won’t change until the next `Reader.get()` call is performed, blocking the ringbuffer element for the time being. A program design processing the ringbuffer content has to call the `Reader.get()`-method in a way that minimizes the ringbuffer lock time.

methods:

- `get()`
- `get_metadata()`:

**data\_available()**

Method to check for new data and avoid blocking of consumers

**get()**

Get a new element from the ringbuffer. The last element obtained by calling this function is marked as “processing is done”. No memory views of old elements may be accessed after calling this function (memory might change, be corrupted or be inconsistent). This function blocks if there are no new elements in the ringbuffer.

**Raises**

**SystemExit** – When the `shutdown()`-method of the `NewBuffer` object has been called, a `SystemExit` is raised which terminates the process.

**Returns**

One element (structured numpy.ndarray) of the ringbuffer as specified in the `NewBuffer()-dtype-object`.

**Return type**

numpy.ndarray

**get\_metadata()**

Get the metadata defined for a ringbuffer element of the `Reader.get()-method`.

**Returns**

Currently a 3-tuple is returned with (counter, timestamp, deadtime) which is assigned to the latest element of the ringbuffer. The content of these variables is filled by the `Writer`-process. The current convention is:

- counter (int): a unique, 0 based, consecutive integer referencing this element
- timestamp (float): the UTC timestamp
- **deadtime (float): In a live-data environment, the dead time of the first** writer in the analyses chain. This is meant to be the fraction of dead time to active data capturing time (so 0.0 = no dead time whatsoever; 0.99 = only 1% of the time between this and the last element was spent with active data capturing)

**Return type**

tuple

**class mimocorb.mimo\_buffer.WSobserver(*setup\_dict*)**

Class for reading selected elements from a ringbuffer via websocket

Ringbuffer elements are structured NumPy arrays. The returned array will not change until the next `Observer.get()`-call, the ringbuffer element is not blocked. The data transfer is implemented via web socket and interfaces with the ringbuffer manager (`NewBuffer`-class).

**async check\_active\_state()** → None

Internal asynchronous function to check if `NewBuffer.shutdown()` was called in the main process

**async establish\_connection()** → None

Internal asynchronous function establishing the websocket connection with the ringbuffer manager in the main process (used for IPC)

**get()**

Get a copy of the latest element added to the ringbuffer by a `Writer` process.

**Returns**

One element (structured numpy.ndarray) from the ringbuffer as specified in the `NewBuffer()-dtype-object`, or None if run ended

**Return type**

numpy.ndarray

**async get\_new\_index()** → None

Internal asynchronous function to query the index of the latest ringbuffer element from the ringbuffer manager

**class mimocorb.mimo\_buffer.Writer(*setup\_dict*)**

Class to write elements into a ringbuffer (multiple-in part).

Ringbuffer elements are structured NumPy arrays. Writing is triggered by a call of `Writer.process_buffer()` or at the next call of `Writer.get_new_buffer()`. The ringbuffer element is blocked while writes to the

NumPy array are permitted. A program design processing the ringbuffer content has to call the `Writer.process_buffer()` or `Writer.get_new_buffer()`-methods in a way that minimizes the ringbuffer lock time.

methods:

- `get_new_buffer()`
- `set_metadata()`
- `process_buffer()`

#### **`get_new_buffer()`**

##### **Get a new free element in the ringbuffer.**

The last element obtained by calling this function is marked as “ready to be processed”. No memory views of old elements may be accessed after calling this function. This function blocks if there are no free elements in the ringbuffer and always returns a valid NumPy array that can be written to.

##### **Raises**

**SystemExit** – When the `shutdown()`-method of the `NewBuffer` object has been called, a `SystemExit` is raised which terminates the process.

##### **Returns**

One free ringbuffer element (structured `numpy.ndarray`) as specified in the `NewBuffer()-dtype`-object. Free elements may contain older data, but they can be safely overwritten.

##### **Return type**

`numpy.ndarray`

#### **`process_buffer()`**

Mark the current ringbuffer element as “ready to be processed”.

The content of the array **MUST NOT** be changed after calling this function. If there is no current element, nothing happens. As the ringbuffer element is blocked while writing to the NumPy array it is recommended to call `Writer.process_buffer()` as soon as possible to minimize the ringbuffer lock time.

#### **`set_metadata(counter, timestamp, deadline)`**

Set the metadata defined for the current ringbuffer element. If there is no current ringbuffer element (e.g. because `process_buffer()` has been called or `get_new_buffer()` has not been called yet), nothing happens. Copying metadata from a `Reader` to a `Writer` object (here called `source` and `sink`) can be done with:

```
sink.set_metadata(*source.get_metadata())
```

##### **Parameters**

- **counter** (*integer* (`np.longlong`)) – a unique, 0 based, consecutive integer referencing this element
- **timestamp** (*float* (`np.float64`)) – the UTC timestamp
- **deadline** (*float* (`np.float64`)) – In a live-data environment, the dead time of the first writer in the analyses chain. This is meant to be the fraction of dead time to active data capturing time (so 0.0 = no dead time whatsoever; 0.99 = only 1% of the time between this and the last element was spent with active data capturing)

Collection of classes to set-up, manage and access ringbuffers and associated functions

**class** mimocorb.buffer\_control.**buffer\_control**(*buffers\_dict, functions\_dict, output\_directory*)

Set-up and management ringbuffers and associated sub-processes

Class methods:

- **setup\_buffers()**
- **setup\_workers()**
- **start\_workers()**
- **pause()**
- **resume()**
- **shutdown()**

**display\_functions()**

Print list of functions and buffer associations

**display\_layout()**

Print list of buffers

**pause()**

Pause data acquisition

**resume()**

Re-enable data acquisition after pause

**setup\_workers()**

Set up all the (parallel) worker functions

**shutdown()**

Delete buffers, stop processes by calling the shutdown()-Method of the buffer manager

**start\_workers()**

start all of the (parallel) worker functions

**stop()**

stop writing and reading data, allow processes to finish

**class** mimocorb.buffer\_control.**rbExport**(*source\_list=None, config\_dict=None, \*\*rb\_info*)

Read data from buffer and send to requesting client (via Python yield()). Data are provided by a generator function yielding data and metadata in the `__call__()` method of the class.

**class** mimocorb.buffer\_control.**rbImport**(*sink\_list=None, config\_dict=None, ufunc=None, \*\*rb\_info*)

Read data from external source (e.g. front-end device, file, simulation, etc.) and put data in mimo\_buffer. Data is read by calling a user-supplied generator function for data and metadata.

**class** mimocorb.buffer\_control.**rbObserver**(*observe\_list=None, config\_dict=None, \*\*rb\_info*)

Deliver data from buffer to an observer process. A tuple (data, metadata) is provided by a generator function ( i.e. via yield()) implemented in the `__call__()` method of the class.

**class** mimocorb.buffer\_control.**rbTransfer**(*source\_list=None, sink\_list=None, config\_dict=None, ufunc=None, \*\*rb\_info*)

Read data from input buffer, filter data and write to output buffer(s) Data is provided as the argument to a user-defined filter function returning None if data is to be rejected, a number if data is to be copied to another buffer, or a list of processed input data write to additional buffers.

Args:

- buffer configurations (only one source and several sinks, no observers!)
- function `ufunc()` must return
  - None if data to be rejected,
  - int if only raw data to be copied to sink[0]
  - list of parameterized data to be copied to sinks[]

Action:

store accepted data in buffers

**class** `mimocorb.buffer_control.rbWSObserver`(*observe\_list=None, config\_dict=None, \*\*rb\_info*)

Deliver data from buffer to an observer process

**class** `mimocorb.buffer_control.rb_toParquetfile`(*source\_list=None, config\_dict=None, \*\*rb\_info*)

Save data a set of parquet-files packed as a tar archive

**class** `mimocorb.buffer_control.rb_toTxtfile`(*source\_list=None, config\_dict=None, \*\*rb\_info*)

Save data to file in csv-format

**class** `mimocorb.buffer_control.run_mimoDAQ`(*verbose=2*)

Setup and run Data Acquisition suite with mimoCoRB buffer manager

The layout of ringbuffers and associated functions is defined in a configuration file in yaml format.

Functions:

- `setup()`
- `run()`
- `end()`

Data acquisition stops when either of the following conditions is met:

- number of requested events processed
- requested run-time reached
- input source exhausted
- end command issued from Keyboard or graphical interface

**end**(*twait=3.0*)

clean shutdown of daq suite

Arg:

twait: waiting time for processes to finish before shutdown

**keyboard\_input**(*cmd\_queue*)

Read keyboard input and send to Queue, running as background-thread to avoid blocking

**class** `tc`

define terminal color codes

*bufferInfoGUI* Graphical display of buffer status

`mimocorb.bufferinfoGUI.bufferinfoGUI`(*Qcmd, Qlog, Qinfo, RBnames=['RB\_1'], maxRate=100.0, interval=1000.0*)

Show Buffer Manager logging messages and rate history and command buttons

**Parameters**

- **Qcmd** – multiprocessing.Queue for command passing to calling process
- **Qlog** – multiprocessing.Queue() for logging-info
- **Qinfo** – multiprocessing.Queue() for status info
- **RBnames** – list, buffer names, used as line labels
- **maxrate** – maximum rate for y-axis
- **interval** – update interval for graphics in ms

**class** mimocorb.bufferinfoGUI.**plot\_bufferinfo**(*Q, RBnames, maxRate=1500.0, interval=1000.0*)

display statistics from Buffer Manager

uses multiprocessing.Queue() to display buffer information: total number of events, data acquisition rate, buffer filling level

#### Parameters

- **Q** – multiprocessing.Queue() for status info
- **RBnames** – list, buffer names, used as line labels
- **maxrate** – maximum rate for y-axis
- **interval** – graphics update interval in ms

**plot\_buffer** Collection of classes with graphics functions to plot buffer data

**class** mimocorb.plot\_buffer.**WaveformPlotter**(*conf\_dict=None, dtypes=None, fig=None*)

Oscilloscope-like display of wave from buffer data

The `__call__` method of this class receives input data and updates and redraws only the new elements of the figure created in `__init__`

**init()**

plot initial line objects to be animated

**class** mimocorb.plot\_buffer.**plotWaveformBuffer**(*source\_list=None, sink\_list=None, observe\_list=None, config\_dict=None, \*\*rb\_info*)

Plot data using a mimiCoRB Observer

**rb\_unittest:** application example for mimo\_buffer

This code may serve as a very basic starting point for own projects

Set-up: 2 ring buffers are defined:

- input Buffer RB\_1: 10 ch x 1024 slots (int32)
- output Buffer RB\_2: 10 ch x 2 slots/ch (float64)

**simulation\_source:** Generate simulated wave form data

**simulation\_source.simulation\_source**(*source\_list=None, sink\_list=None, observe\_list=None, config\_dict=None, \*\*rb\_info*)

Generate simulated data and pass data to buffer

The class `mimocorb.buffer_control/rbImport` is used to interface to the `newBuffer` and `Writer` classes of the package `mimoCoRB.mimo_buffer`

#### Parameters

**config\_dict** – configuration dictionary

- **events\_required:** number of events to be simulated or 0 for infinite



- **sleeptime:** (mean) time between events
- **random:** random time between events according to a Poission process
- **number\_of\_samples, sample\_time\_ns, pretrigger\_samples** and **analogue\_offset** describe the waveform data to be generated (as for oscilloscope setup)

Internal parameters of the simulated physics process (the decay of a muon) are (presently) not exposed to user.

### Module **lifetime\_filter**

This (rather complex) module filters waveform data to search for valid signal pulses in the channel data. The goal is to clearly identify coincidences of signals in different layers (indiating the passage of a cosmic ray particle, a muon) and find double-pulse signatures that a muon was stopped in or near a detection layer where the resulting decay-electron produced a delayed pulse. The time difference between the initial and the delayed pulses is the individual lifetime of the muon.

Wave forms passing this filter-criterion an passed on to a new buffer; the decay time and the properties of the signal pulses (height, integral and postition in time) are written to another buffer.

The relevant configuration parameters can be found in the section *calculate\_decay\_time*: of the configuration file.

**lifetime\_filter.calculate\_decay\_time**(*source\_list=None, sink\_list=None, observe\_list=None, config\_dict=None, \*\*rb\_info*)

Calculate decay time as time between double pulses

#### **Input:**

pulse wave forms

#### **Returns:**

None if failed, int or list of pulse parameters if successful

Note: output produced when filter is passed depends on number of defined sinks:

- one sink: input data
- two sinks: input data and double-pulse parameters
- three sinks: input data and double-pulse parameters separately for upwards and for downwards going decay electrons

**plot:** plotting waveforms from buffer using `mimoCoRB.buffer_control.OberserverData`

**plot\_waveform.plot\_graph**(*source\_list=None, sink\_list=None, observe\_list=None, config\_dict=None, \*\*rb\_info*)

Plot waveform data from mimiCoRB buffer

#### **Parameters**

**input** – configuration dictionary

- **plot\_title:** graphics title to be shown on graph
- **min\_sleeptime:** time between updates
- **sample\_time\_ns, channel\_range, pretrigger\_samples** and **analogue\_offset** describe the waveform data as for oscilloscope setup

**read\_from\_buffer:** example of a module reading and analyzing data from a buffer

Since reading blocks when no new data is available, a 2nd thread is started to collect data at the end

**read\_from\_buffer.read\_from\_buffer**(*source\_list=None, sink\_list=None, observe\_list=None, config\_dict=None, \*\*rb\_info*)

Read data from mimiCoRB buffer using the interface class `mimo_control.rbExport`

**Parameters**

**input** – configuration dictionary

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