1. **ADC\_PWM\_init()**

* This function is done to do the initializations for Tail Motor
* PE4 => PWM Output for Tail Motor
* PE2, PE3 => Direction Control of Tail Motor

1. **Motor\_in\_it()**

* This function is done for initialization of Head Motor
* PE5 => PWM Output for Head Motor
* PC6,PC7 => Direction Control of Head Motor

1. **SERVO\_PWM\_init()**

* This function takes care of initialization of Servo PWM