

main

May 17, 2023

1 Load and View Data

```
[ ]: import numpy as np
import pandas as pd
import matplotlib.pyplot as plt

file = '../data.csv'
data = pd.read_csv(file, header=None, names=['u', 'y'])
N = len(data)

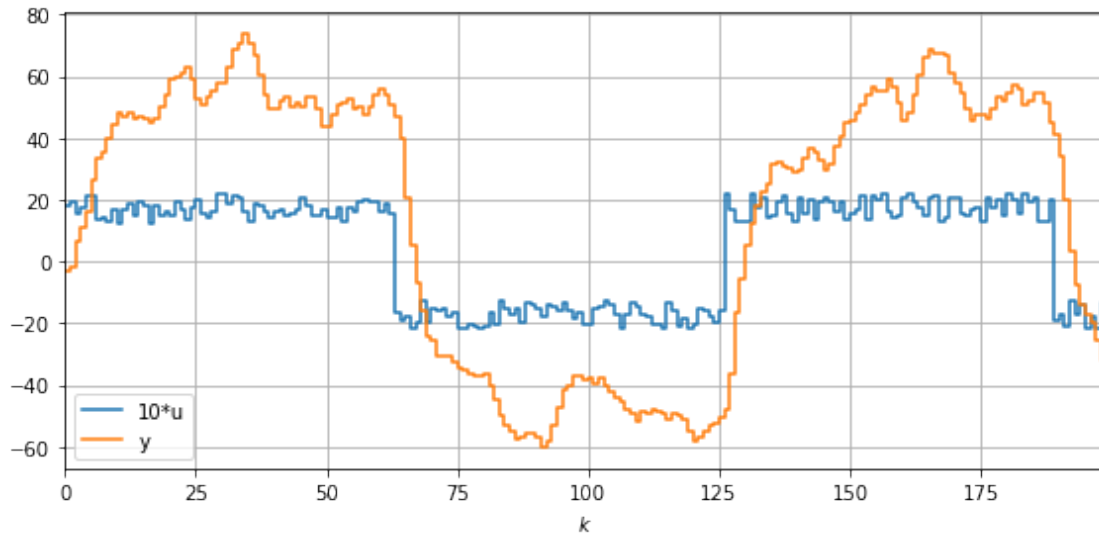
k = data.index.values
u = data.u.values
y = data.y.values

print('Number of data points:', N)
print(f'k in [{k[0]}, {k[-1]}]')

plt.figure(figsize=(8,4))
plt.plot(k, 10*u, label='10*u', drawstyle='steps-post')
plt.plot(k, y, label='y', drawstyle='steps-post')
plt.xlim(k[0], k[-1])
plt.xlabel(r'$k$')
plt.grid()
plt.legend()
plt.tight_layout()
plt.show()
```

Number of data points: 200

k in [0, 199]



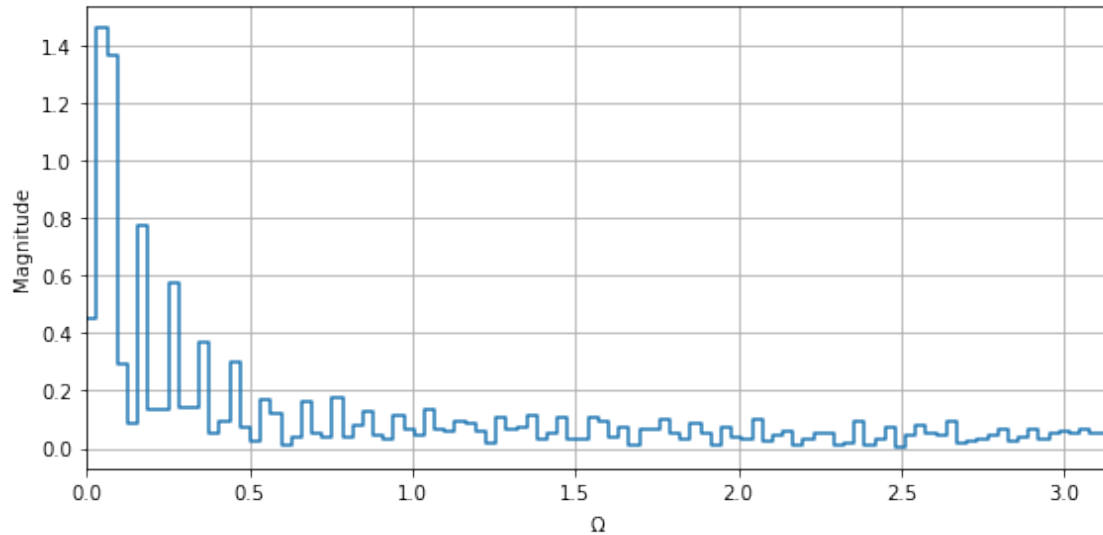
1.1 Input Fourier Transform

```
[ ]: from scipy import fft

u_rfft = fft.rfft(u, norm='forward')
u_rfft[1:-1] = 2*u_rfft[1:-1]

u_rfft_mag = np.abs(u_rfft)
Omega = np.linspace(0, np.pi, len(u_rfft_mag))

plt.figure(figsize=(8,4))
plt.plot(Omega, u_rfft_mag, drawstyle='steps-post')
plt.xlim(Omega[0], Omega[-1])
plt.xlabel(r'$\Omega$')
plt.ylabel('Magnitude')
plt.grid()
plt.tight_layout()
plt.show()
```



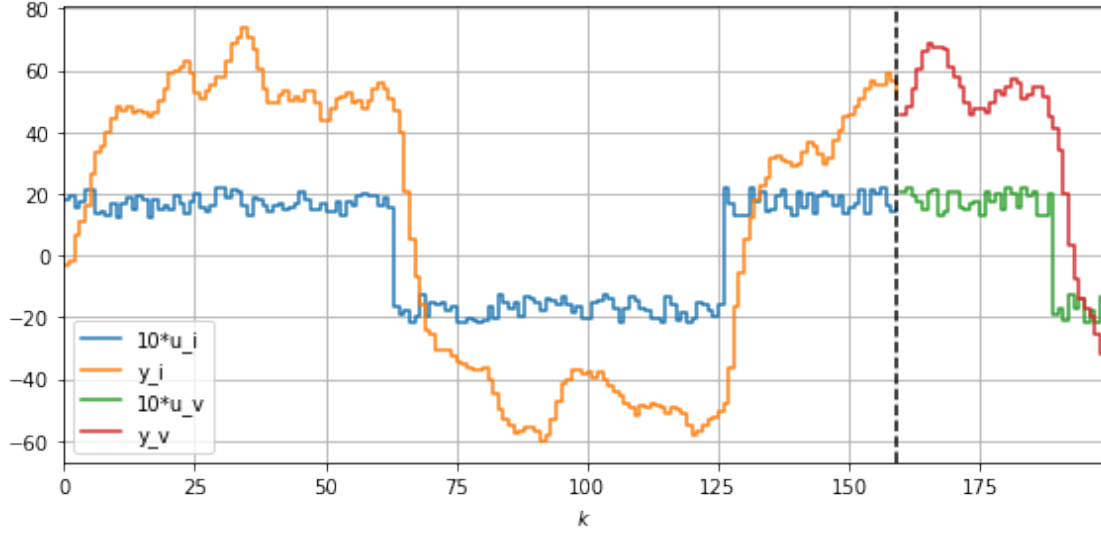
1.2 Separate Identification and Validation Data

```
[ ]: N_fold = 160

k_i = k[:N_fold]
u_i = u[:N_fold]
y_i = y[:N_fold]

k_v = k[N_fold:]
u_v = u[N_fold:]
y_v = y[N_fold:]

plt.figure(figsize=(8,4))
plt.plot(k_i, 10*u_i, label='10*u_i', drawstyle='steps-post')
plt.plot(k_i, y_i, label='y_i', drawstyle='steps-post')
plt.plot(k_v, 10*u_v, label='10*u_v', drawstyle='steps-post')
plt.plot(k_v, y_v, label='y_v', drawstyle='steps-post')
plt.axvline(k[N_fold-1], color='black', linestyle='--')
plt.xlim(k[0], k[-1])
plt.xlabel(r'$k$')
plt.grid()
plt.legend()
plt.tight_layout()
plt.show()
```



2 Generic Model

$$\begin{aligned}
 A(q) y[k] &= \frac{B(q)}{F(q)} u[k - n_k + 1] + \frac{C(q)}{D(q)} e[k] \\
 y[k] &= G(q) u[k - n_k + 1] + H(q) e[k] \\
 G(q) &= \frac{B(q)}{A(q) F(q)} \quad H(q) = \frac{C(q)}{A(q) D(q)} \\
 A(q) &= 1 - a_1 q^{-1} - \dots - a_{n_a} q^{-n_a} \\
 B(q) &= b_1 q^{-1} + \dots + b_{n_b} q^{-n_b} + b_{n_b+1} q^{-n_b-1} \\
 C(q) &= 1 + c_1 q^{-1} + \dots + c_{n_c} q^{-n_c} \\
 D(q) &= 1 + d_1 q^{-1} + \dots + d_{n_d} q^{-n_d} \\
 F(q) &= 1 + f_1 q^{-1} + \dots + f_{n_f} q^{-n_f}
 \end{aligned}$$

```
[ ]: from functions import models_frame
```

```
models = models_frame()
```

3 ARX

$$\begin{aligned}
 y[k] &= G(q) u[k - n_k + 1] + H(q) e[k] \\
 G(q) &= \frac{B(q)}{A(q)} \quad H(q) = \frac{1}{A(q)} \\
 A(q) &= 1 - a_1 q^{-1} - \dots - a_{n_a} q^{-n_a} \\
 B(q) &= b_1 q^{-1} + \dots + b_{n_b} q^{-n_b} + b_{n_b+1} q^{-n_b-1}
 \end{aligned}$$

```
[ ]: from functions import arx

na_range = range(0, 3 + 1)
nb_range = range(0, 2 + 1)
nk_range = range(0, 2 + 1)

models_arx = arx(u_i, y_i, u_v, y_v, na_range, nb_range, nk_range)

models = pd.concat([models, models_arx], ignore_index=True)
```

4 ARMAX

$$y[k] = G(q) u[k - n_k + 1] + H(q) e[k]$$

$$G(q) = \frac{B(q)}{A(q)} \quad H(q) = \frac{C(q)}{A(q)}$$

$$A(q) = 1 - a_1 q^{-1} - \dots - a_{n_a} q^{-n_a}$$

$$B(q) = b_1 q^{-1} + \dots + b_{n_b} q^{-n_b} + b_{n_b+1} q^{-n_b-1}$$

$$C(q) = 1 + c_1 q^{-1} + \dots + c_{n_c} q^{-n_c}$$

```
[ ]: from functions import armax

na_range = range(0, 3 + 1)
nb_range = range(0, 2 + 1)
nc_range = range(0, 3 + 1)
nk_range = range(0, 2 + 1)

models_armax = armax(u_i, y_i, u_v, y_v, na_range, nb_range, nc_range, nk_range)

models = pd.concat([models, models_armax], ignore_index=True)
```

5 Output Error

$$y[k] = G(q) u[k - n_k + 1] + H(q) e[k]$$

$$G(q) = \frac{B(q)}{F(q)} \quad H(q) = 1$$

$$B(q) = b_1 q^{-1} + \dots + b_{n_b} q^{-n_b} + b_{n_b+1} q^{-n_b-1}$$

$$F(q) = 1 + f_1 q^{-1} + \dots + f_{n_f} q^{-n_f}$$

```
[ ]: from functions import oe

nb_range = range(0, 2 + 1)
nf_range = range(1, 3 + 1) # nf = 0 causa erro no pysid!
```

```
nk_range = range(0, 2 + 1)

models_oe = oe(u_i, y_i, u_v, y_v, nb_range, nf_range, nk_range)

models = pd.concat([models, models_oe], ignore_index=True)
```

6 Box-Jenkins

$$y[k] = G(q) u[k - n_k + 1] + H(q) e[k]$$

$$G(q) = \frac{B(q)}{F(q)} \quad H(q) = \frac{C(q)}{D(q)}$$

$$B(q) = b_1 q^{-1} + \dots + b_{n_b} q^{-n_b} + b_{n_b+1} q^{-n_b-1}$$

$$C(q) = 1 + c_1 q^{-1} + \dots + c_{n_c} q^{-n_c}$$

$$D(q) = 1 + d_1 q^{-1} + \dots + d_{n_d} q^{-n_d}$$

$$F(q) = 1 + f_1 q^{-1} + \dots + f_{n_f} q^{-n_f}$$

```
[ ]: from functions import bj

nb_range = range(0, 2 + 1)
nc_range = range(0, 3 + 1)
nd_range = range(0, 3 + 1)
nf_range = range(0, 3 + 1)
nk_range = range(0, 2 + 1)

models_bj = bj(u_i, y_i, u_v, y_v, nb_range, nc_range, nd_range, nf_range,
               ↪nk_range)

models = pd.concat([models, models_bj], ignore_index=True)
```

7 Results

```
[ ]: print('Number of models:', len(models.loc[models.B.notnull()]))
      print('Number of fails: ', len(models.loc[models.B.isnull()]))
```

```
Number of models: 557
Number of fails: 226
```

7.1 Sort by Prediction Cost

```
[ ]: models.sort_values(by=['Jp'], inplace=True)
```

7.2 Display Predictions

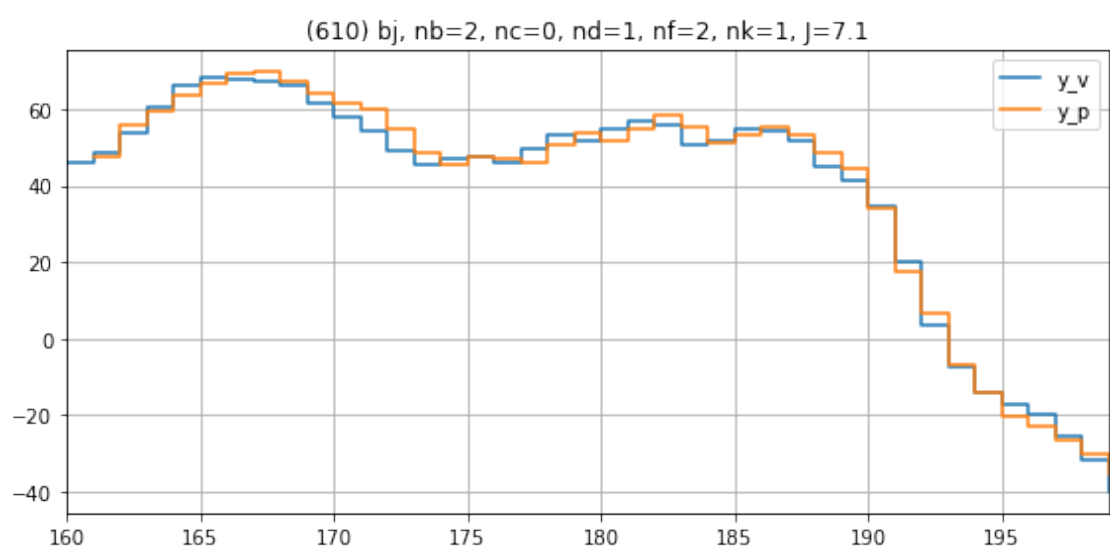
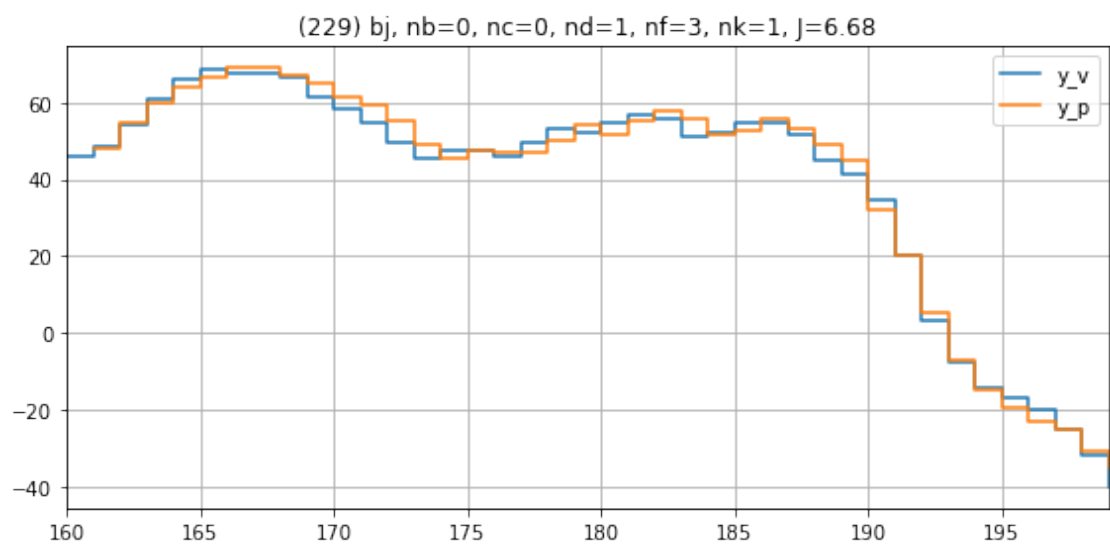
```
[ ]: for i, (index, model) in enumerate(models.iterrows()):
    if i > 10:
        break

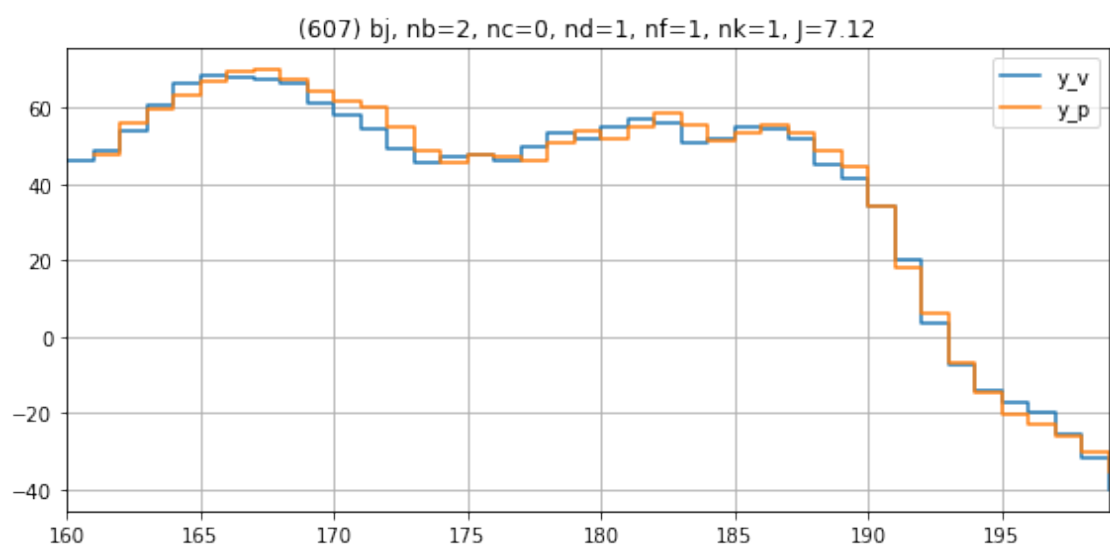
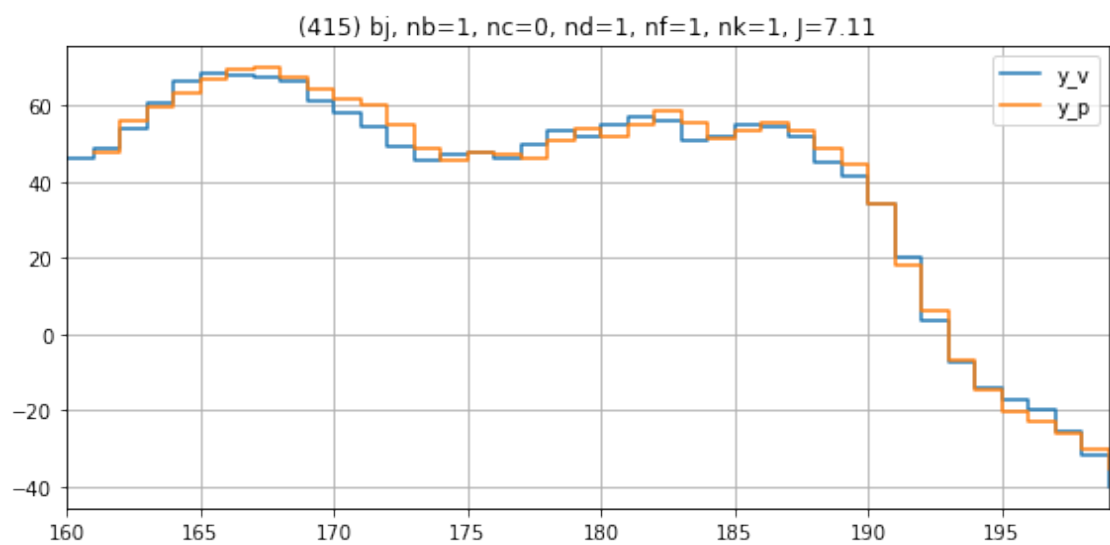
    if np.isnan(model.yp).any():
        continue

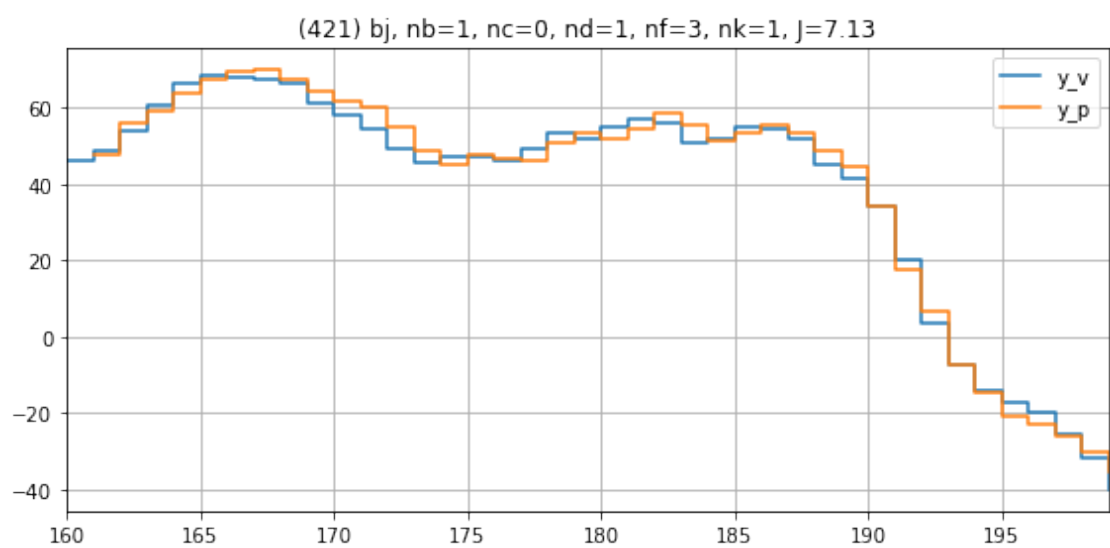
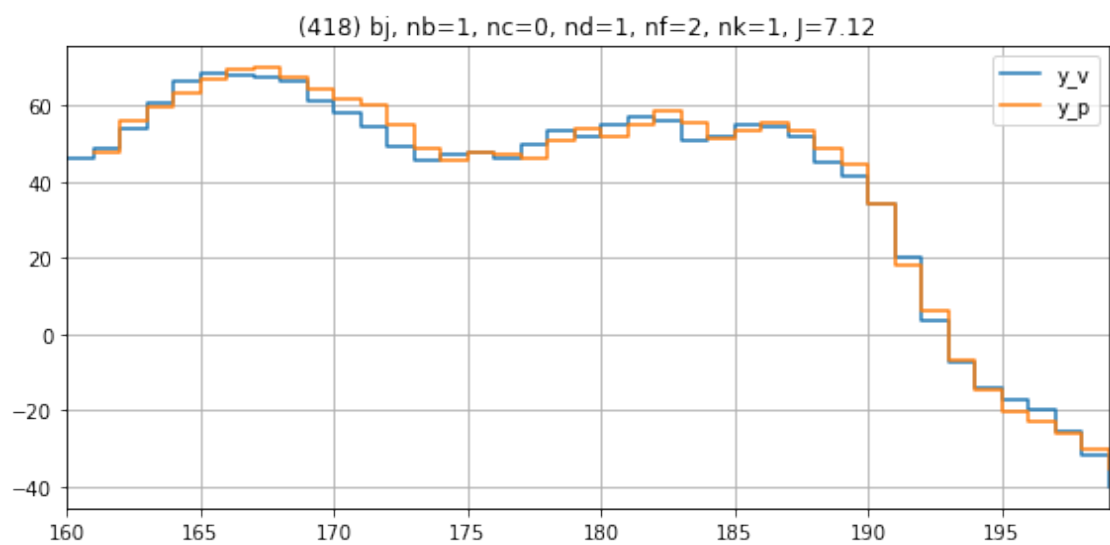
    if model.model == 'arx':
        title = f'({index}) {model.model}, na={model.na}, nb={model.nb}, nk={model.
↵nk}, J={model.Jp:.3g}'
    elif model.model == 'armax':
        title = f'({index}) {model.model}, na={model.na}, nb={model.nb}, nc={model.
↵nc}, nk={model.nk}, J={model.Jp:.3g}'
    elif model.model == 'oe':
        title = f'({index}) {model.model}, nb={model.nb}, nf={model.nf}, nk={model.
↵nk}, J={model.Jp:.3g}'
    elif model.model == 'bj':
        title = f'({index}) {model.model}, nb={model.nb}, nc={model.nc}, nd={model.
↵nd}, nf={model.nf}, nk={model.nk}, J={model.Jp:.3g}'
    else:
        assert(False)

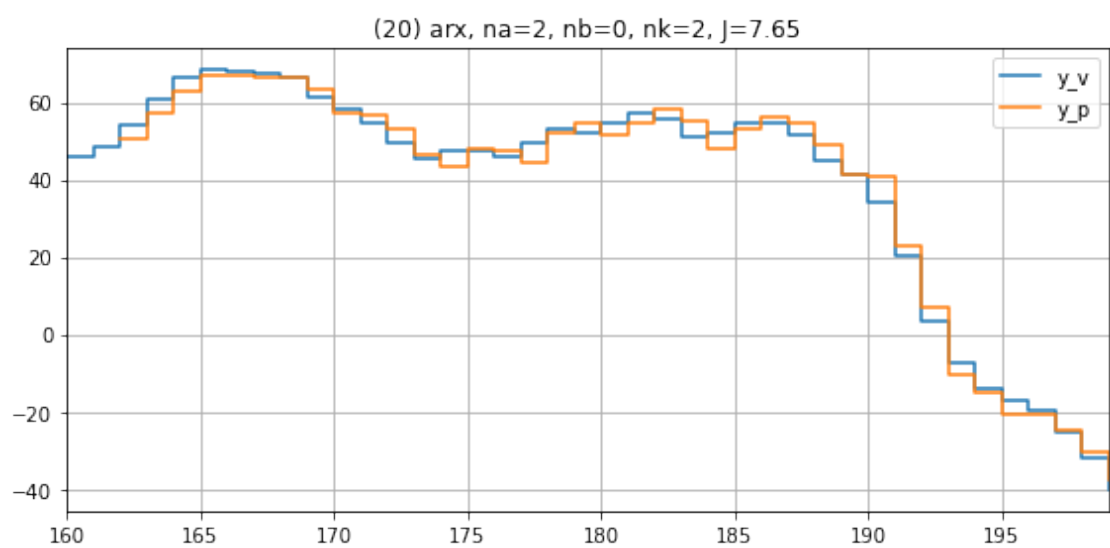
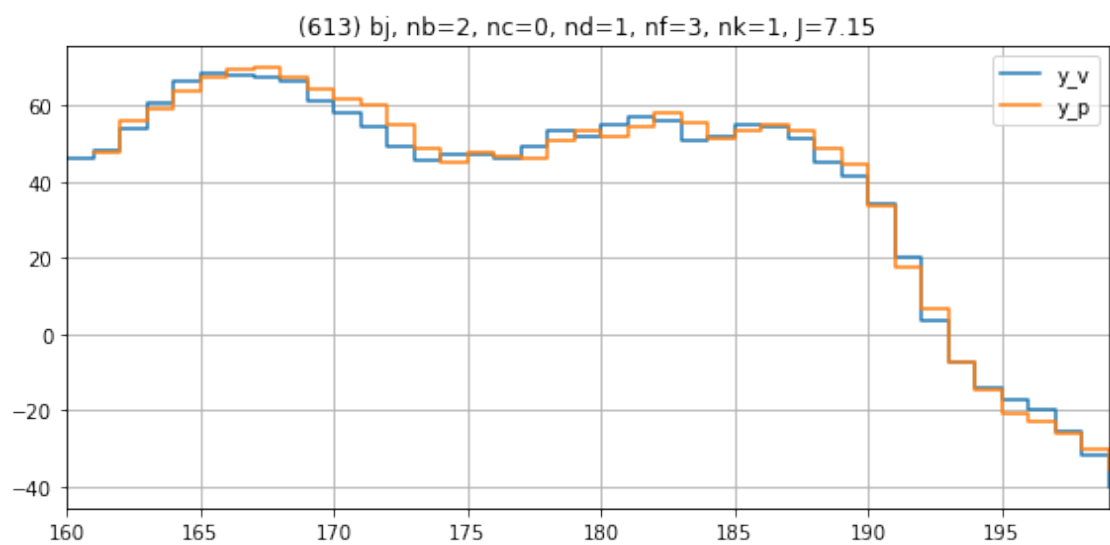
    # display(model.G)

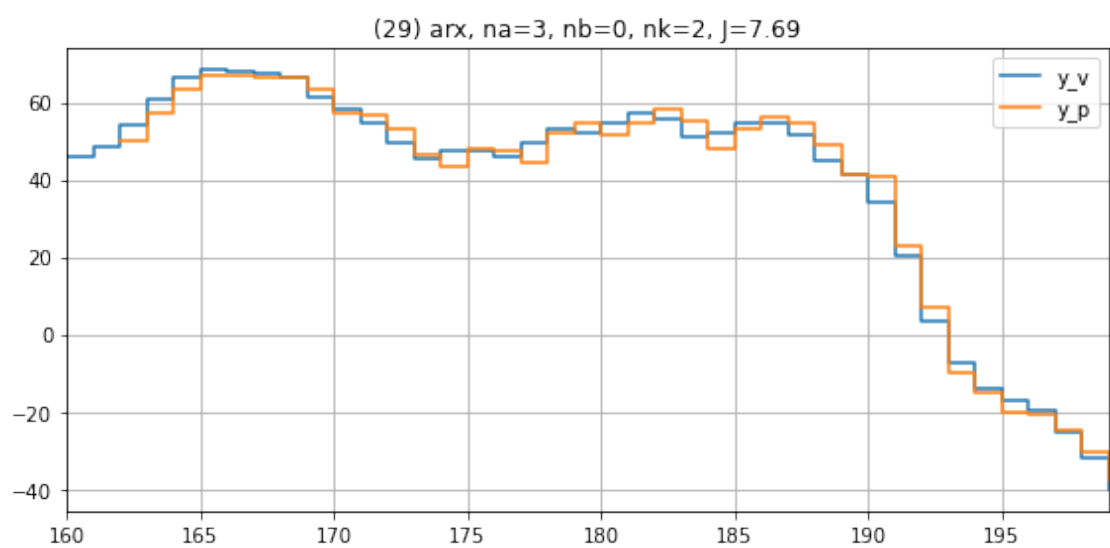
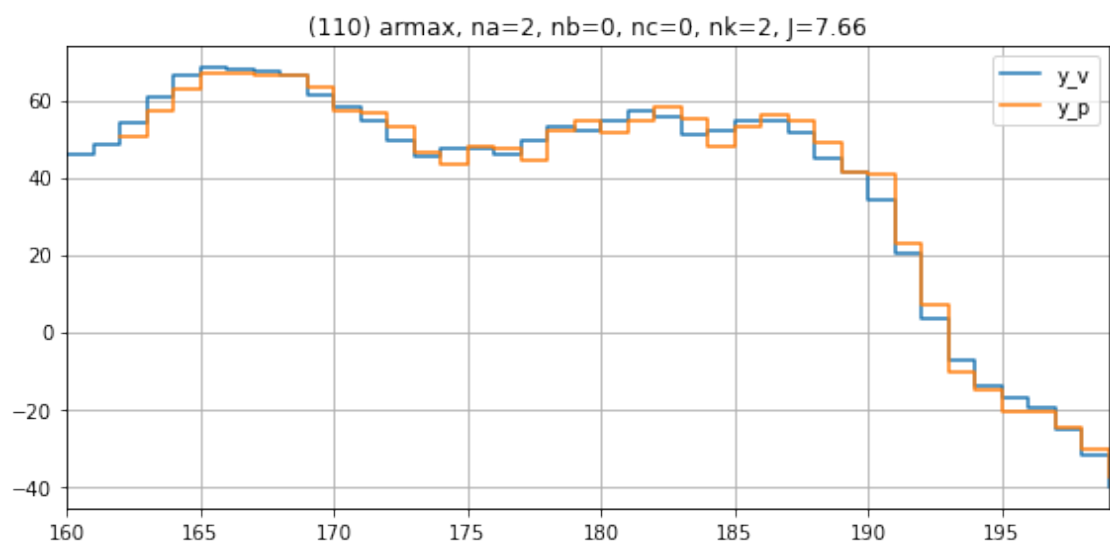
    plt.figure(figsize=(8,4))
    plt.title(title)
    plt.plot(k_v, y_v, label='y_v', drawstyle='steps-post')
    plt.plot(k_v[model.nk:], model.yp, label='y_p', drawstyle='steps-post')
    plt.xlim(k_v[0], k_v[-1])
    plt.grid()
    plt.legend()
    plt.tight_layout()
    plt.show()
```

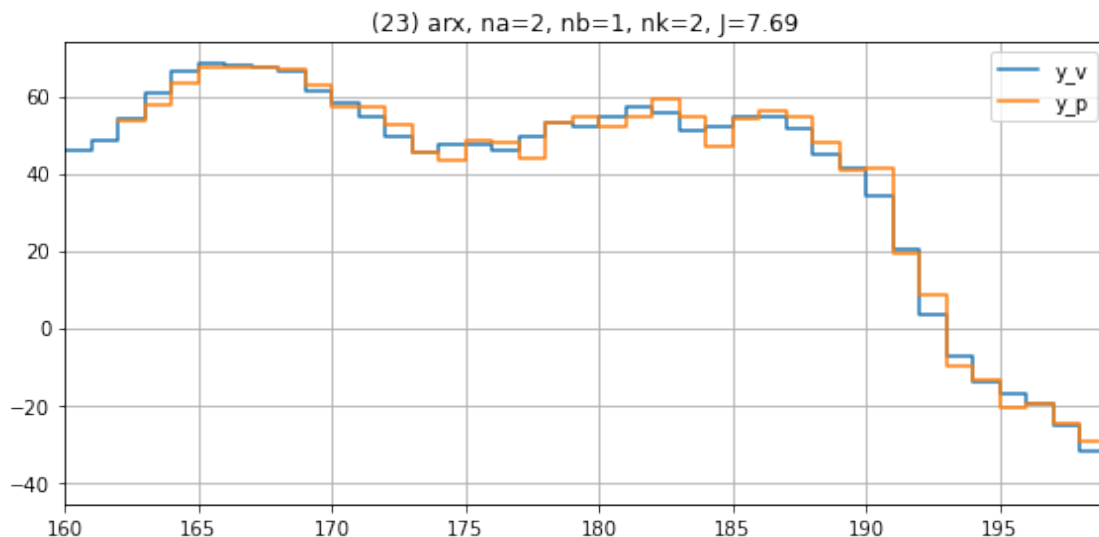












7.3 Display Best ARX

```
[ ]: display(models.loc[models.model == 'arx'][['na','nb','nk','Jp','A','B'],]).  
      ↪head(20))
```

	na	nb	nk	Jp	A \
20	2	0	2	7.645443	[1.0, -1.3660455345977758, 0.46216420283874365]
29	3	0	2	7.689685	[1.0, -1.3873295518220405, 0.48805419928292326...
23	2	1	2	7.689954	[1.0, -1.4641248135410299, 0.5285400201585324]
32	3	1	2	7.892806	[1.0, -1.4338646895641036, 0.4480849301598035,...
35	3	2	2	8.105173	[1.0, -1.4646304544414424, 0.528125287033142, ...
26	2	2	2	8.116282	[1.0, -1.470109560817867, 0.5424885365137805]
13	1	1	1	9.445924	[1.0, -0.8393277799197246]
16	1	2	1	9.446921	[1.0, -0.8475073498920537]
17	1	2	2	12.220939	[1.0, -0.8536344010412926]
10	1	0	1	12.227166	[1.0, -0.8678590885029938]
11	1	0	2	12.263688	[1.0, -0.8463826959667305]
22	2	1	1	12.272655	[1.0, -1.3097104301654667, 0.41739885788678394]
14	1	1	2	12.535729	[1.0, -0.852414481348611]
31	3	1	1	14.254416	[1.0, -1.3524174269820388, 0.5032190693764751,...
34	3	2	1	15.842331	[1.0, -1.3994740241334414, 0.4627146071616107,...
25	2	2	1	16.155434	[1.0, -1.4068341173741103, 0.48261202067241576]
19	2	0	1	16.409968	[1.0, -1.3707902290649023, 0.46379315525848536]
28	3	0	1	18.702151	[1.0, -1.414703381673296, 0.556534746868992, -...
9	1	0	0	53.836422	[1.0, -0.8940577163754525]
15	1	2	0	58.178657	[1.0, -0.8385439305093618]

	B
20	[0.0, 0.0, 2.6625996144096495]

```

29          [0.0, 0.0, 2.5495944772087906]
23 [0.0, 0.0, 3.2667955231622616, -1.512659611800...
32 [0.0, 0.0, 3.2988193484523514, -1.597544061149...
35 [0.0, 0.0, 3.2526649889541677, -1.770506126503...
26 [0.0, 0.0, 3.24561533692063, -1.76727531046355...
13      [0.0, 2.5182279776811285, 2.247524574924342]
16 [0.0, 2.565934481739721, 2.624492279202261, -0...
17 [0.0, 0.0, 4.779090659243092, -0.2522758132522...
10          [0.0, 3.9772885834983422]
11          [0.0, 0.0, 4.478108167722055]
22      [0.0, 2.141831622134629, 0.9412691651247993]
14 [0.0, 0.0, 4.7414599587574, -0.4290815265286632]
31      [0.0, 2.1431634822971874, 0.8728783964686994]
34 [0.0, 2.155788344731435, 1.6239328839062663, -...
25 [0.0, 2.1624655631747225, 1.6108433820602714, ...
19          [0.0, 2.6558802749327906]
28          [0.0, 2.605489877940335]
9          [3.2900528140628835]
15 [0.7506498902905142, 1.89369360076428, 2.17204...

```

7.4 Display Best ARMAX

```
[ ]: display(models.loc[models.model == '
↪ 'armax'] [['na', 'nb', 'nc', 'nk', 'Jp', 'A', 'B', 'C']].head(20))
```

	na	nb	nc	nk	Jp	A	\
110	2	0	0	2	7.655574	[1.0, -1.362122379521981, 0.4587552445700221]	
146	3	0	0	2	7.746983	[1.0, -1.372107576696417, 0.48234394954692567, ...	
125	2	1	1	2	7.758462	[1.0, -1.4600096157027267, 0.5255264002325278]	
122	2	1	0	2	7.768006	[1.0, -1.4527206948581295, 0.5192633529898458]	
158	3	1	0	2	7.981943	[1.0, -1.4226945047469746, 0.43970782319280444...	
170	3	2	0	2	8.308704	[1.0, -1.4503767229272535, 0.5066968102866604, ...	
137	2	2	1	2	8.311072	[1.0, -1.475717281818618, 0.5469116297457893]	
134	2	2	0	2	8.321067	[1.0, -1.4609863882165854, 0.5343165080233506]	
149	3	0	1	2	8.342984	[1.0, -0.9399801899614851, -0.208706173994137, ...	
161	3	1	1	2	8.469429	[1.0, -1.1844387652049873, 0.09576639519608975...	
113	2	0	1	2	8.514107	[1.0, -1.2305922717569349, 0.3405767785078947]	
85	1	1	0	1	9.509086	[1.0, -0.8399456251236832]	
97	1	2	0	1	9.518973	[1.0, -0.8484592491471614]	
128	2	1	2	2	9.551023	[1.0, -1.2809967354890153, 0.36654414556152054]	
173	3	2	1	2	9.832684	[1.0, -0.5378590100399637, -0.8697379520070603...	
131	2	1	3	2	9.932755	[1.0, -1.4900377017683388, 0.5504158109798434]	
116	2	0	2	2	10.852399	[1.0, -0.9940512967773427, 0.11949413417148878]	
89	1	1	1	2	11.407452	[1.0, -0.8486142701479353]	
101	1	2	1	2	11.471396	[1.0, -0.8468051831338753]	
152	3	0	2	2	11.537025	[1.0, -0.8790926145365645, -0.1998558265309171...	

B \

110 [0.0, 0.0, 2.67814901214612]
 146 [0.0, 0.0, 2.6789063216335074]
 125 [0.0, 0.0, 3.375042699009375, -1.5856254449940...
 122 [0.0, 0.0, 3.373178325899714, -1.553870209586459]
 158 [0.0, 0.0, 3.409553051450076, -1.6411466235616...
 170 [0.0, 0.0, 3.339266589052116, -1.8938528860596...
 137 [0.0, 0.0, 3.3336402291030303, -1.967736751034...
 134 [0.0, 0.0, 3.323574570886201, -1.8887521811331...
 149 [0.0, 0.0, 3.249889847820225]
 161 [0.0, 0.0, 3.385492016217483, -1.0482476919565...
 113 [0.0, 0.0, 3.082182901198755]
 85 [0.0, 2.3600625664231103, 2.3834374176082576]
 97 [0.0, 2.390729908024276, 2.711384911721081, -0...
 128 [0.0, 0.0, 3.4399250148001252, -1.080417100133...
 173 [0.0, 0.0, 3.384555801371594, 1.38369530339439...
 131 [0.0, 0.0, 3.40971308278597, -1.7536633125344618]
 116 [0.0, 0.0, 3.52245164538883]
 89 [0.0, 0.0, 3.8067868935708913, 0.5499943801358...
 101 [0.0, 0.0, 3.7855378088305622, 0.5411600759363...
 152 [0.0, 0.0, 3.4578629152037212]

C

110 [1.0]
 146 [1.0]
 125 [1.0, -0.011089805787230764]
 122 [1.0]
 158 [1.0]
 170 [1.0]
 137 [1.0, -0.02244962850440833]
 134 [1.0]
 149 [1.0, 0.4596703082418364]
 161 [1.0, 0.24506116219632135]
 113 [1.0, 0.19672390277132173]
 85 [1.0]
 97 [1.0]
 128 [1.0, 0.1794893731060149, 0.16236729312536188]
 173 [1.0, 0.8964131465447145]
 131 [1.0, -0.038179062820397985, 0.040590637656112...
 116 [1.0, 0.439347639302333, 0.2817830769564706]
 89 [1.0, 0.4384234142947657]
 101 [1.0, 0.4388454181096915]
 152 [1.0, 0.5681759014356293, 0.202204520470848]

7.5 Display Best OE

```
[ ]: display(models.loc[models.model == 'oe'][['nb', 'nf', 'nk', 'Jp', 'B', 'F']]).  
      ↪head(20))
```

	nb	nf	nk	Jp	B \
206	2	3	2	226.888138	[0.0, 0.0, 7.978013556932356, -3.2286730261476...
197	1	3	2	226.967451	[0.0, 0.0, 7.838397199009468, -6.694009875361453]
203	2	2	2	227.08397	[0.0, 0.0, 7.711764588803071, -6.9074618014256...
194	1	2	2	227.262327	[0.0, 0.0, 7.563069203358311, -6.423786171942781]
200	2	1	2	241.402568	[0.0, 0.0, 8.08301108469978, -1.78417565469243...
202	2	2	1	249.64325	[0.0, 3.5064182856277886, -0.07824020826054166...
191	1	1	2	250.846734	[0.0, 0.0, 9.157994362787939, -4.8911579830779...
196	1	3	1	252.373055	[0.0, 3.3507417420103387, -2.7664680983782803]
205	2	3	1	256.792102	[0.0, 4.628640282915869, -8.623214903962165, 4...
188	0	3	2	261.168841	[0.0, 0.0, 7.921348852710581]
185	0	2	2	267.121761	[0.0, 0.0, 7.561901643498672]
199	2	1	1	271.972336	[0.0, 3.781185711341447, 2.8049375221333177, -...
204	2	3	0	274.352316	[3.1280668470184683, -5.340581221648062, 2.580...
182	0	1	2	276.99766	[0.0, 0.0, 5.391554067951758]
187	0	3	1	277.617842	[0.0, 2.988611484449413]
190	1	1	1	278.665287	[0.0, 4.827973256321665, -0.37190745122050206]
184	0	2	1	279.553033	[0.0, 4.698984403191706]
181	0	1	1	280.648584	[0.0, 4.524318877565773]
193	1	2	1	281.122009	[0.0, 4.3337745347488585, 4.2860954942594605]
195	1	3	0	285.269845	[1.5834576171801729, -1.1667113369486124]

	F
206	[1.0, -0.9518156100627038, -0.3203644473814848...
197	[1.0, -1.4544706372946097, 0.4468435158751912, ...
203	[1.0, -1.5244322818192362, 0.56005967515822]
194	[1.0, -1.509661698574922, 0.5468800443643043]
200	[1.0, -0.8709600909127035]
202	[1.0, -1.6007510106966596, 0.627251005434897]
191	[1.0, -0.8573586792852766]
196	[1.0, -2.1777873976684754, 1.625637672754031, ...
205	[1.0, -2.759095117485883, 2.61038161396743, -0...
188	[1.0, -0.4573530409988488, -0.0409717896603812...
185	[1.0, -0.3205139270891644, -0.42269253608061114]
199	[1.0, -0.8640834799035708]
204	[1.0, -2.7253048407638283, 2.578705640429255, ...
182	[1.0, -0.8153866103917702]
187	[1.0, -1.647584086767555, 1.166908619339762, -...
190	[1.0, -0.8514087957661273]
184	[1.0, -0.8030776462543977, -0.04009386383446041]
181	[1.0, -0.8488426199496534]
193	[1.0, 0.04900478959474314, -0.7608467552754207]
195	[1.0, -2.501677402990944, 2.1829670787314317, ...

7.6 Display Best BJ

```
[ ]: display(models.loc[models.model == '
↳ 'bj'][['nb', 'nc', 'nd', 'nf', 'nk', 'Jp', 'B', 'C', 'D', 'F']].head(20))
```

	nb	nc	nd	nf	nk	Jp	\
229	0	0	1	3	1	6.675921	
610	2	0	1	2	1	7.103042	
415	1	0	1	1	1	7.107374	
607	2	0	1	1	1	7.119668	
418	1	0	1	2	1	7.122786	
421	1	0	1	3	1	7.126711	
613	2	0	1	3	1	7.147105	
226	0	0	1	2	1	7.858919	
239	0	0	2	2	2	8.720289	
431	1	0	2	2	2	8.771421	
428	1	0	2	1	2	8.859718	
242	0	0	2	3	2	8.953137	
251	0	0	3	2	2	9.044681	
434	1	0	2	3	2	9.050066	
620	2	0	2	1	2	9.055038	
236	0	0	2	1	2	9.076879	
443	1	0	3	2	2	9.136736	
623	2	0	2	2	2	9.162588	
440	1	0	3	1	2	9.237344	
254	0	0	3	3	2	9.389977	

	B	C	\
229	[0.0, 2.688141278221442]	[1.0]	
610	[0.0, 2.3478282185298474, 5.096527272299687, 2...	[1.0]	
415	[0.0, 2.344296218297878, 2.825520409261619]	[1.0]	
607	[0.0, 2.344447984057369, 2.8318259756191324, -...	[1.0]	
418	[0.0, 2.34448302850676, 2.852622937222137]	[1.0]	
421	[0.0, 2.3310033884478294, 3.0402361290651934]	[1.0]	
613	[0.0, 2.3308263024050233, 2.838620525444865, -...	[1.0]	
226	[0.0, 3.0115919098877106]	[1.0]	
239	[0.0, 0.0, 3.5019507656056597]	[1.0]	
431	[0.0, 0.0, 3.349193072443662, -1.7775884528373...	[1.0]	
428	[0.0, 0.0, 3.5482906571711608, 0.2858822969171...	[1.0]	
242	[0.0, 0.0, 3.3500091640579415]	[1.0]	
251	[0.0, 0.0, 3.565838195878382]	[1.0]	
434	[0.0, 0.0, 3.331503161637364, -0.8551562311690...	[1.0]	
620	[0.0, 0.0, 3.448442221090623, 0.2726044485092...	[1.0]	
236	[0.0, 0.0, 3.567850575202136]	[1.0]	
443	[0.0, 0.0, 3.376921440068028, -2.0993345353713...	[1.0]	
623	[0.0, 0.0, 3.302831622129785, -1.2972424032536...	[1.0]	
440	[0.0, 0.0, 3.6079100194975062, 0.2026999940729...	[1.0]	
254	[0.0, 0.0, 3.429127315563511]	[1.0]	

D \

229 [1.0, -0.9289937416737682]
610 [1.0, -0.9341682155923209]
415 [1.0, -0.9343867522324996]
607 [1.0, -0.9342305307417798]
418 [1.0, -0.934195041218468]
421 [1.0, -0.9369178960361715]
613 [1.0, -0.9372026762173828]
226 [1.0, -0.9438017519648862]
239 [1.0, -1.458155553275884, 0.5483535057734815]
431 [1.0, -1.4769712224894986, 0.5733963064298735]
428 [1.0, -1.4631480553885532, 0.5471891887933172]
242 [1.0, -1.4741934171674256, 0.5726446814107561]
251 [1.0, -1.426960883004859, 0.4619976532321713, ...
434 [1.0, -1.4841070828482519, 0.5811156881875443]
620 [1.0, -1.46540220905493, 0.5601426684864359]
236 [1.0, -1.4740541947694308, 0.5494407044946709]
443 [1.0, -1.4362379085719919, 0.4606296547878398,...
623 [1.0, -1.4861249843985334, 0.5846771788274585]
440 [1.0, -1.427167998101631, 0.4510434895269983, ...
254 [1.0, -1.4241186566755433, 0.44704927930510013...

F

229 [1.0, -1.5632174239302818, 0.8951586489158623,...
610 [1.0, 0.1442903549544611, -0.7839292708223434]
415 [1.0, -0.8153741783712067]
607 [1.0, -0.8159164961511574]
418 [1.0, -0.8078458673576828, -0.0066902219605544...
421 [1.0, -0.7291991947864063, -0.1388407532093586...
613 [1.0, -0.8169448415853702, -0.0695356924726619...
226 [1.0, -1.302072278854778, 0.4140327168562698]
239 [1.0, -0.9960096081270118, 0.11807914388348542]
431 [1.0, -1.5212473292658029, 0.5765638436863573]
428 [1.0, -0.8662343607025677]
242 [1.0, -0.956902992202918, -0.08394568951933881...
251 [1.0, -0.9652667847846519, 0.08910273864935399]
434 [1.0, -1.1854559008583219, 0.13907771190711846...
620 [1.0, -0.8471033232598844]
236 [1.0, -0.875103944965068]
443 [1.0, -1.5916875036198268, 0.6365784594376858]
623 [1.0, -1.3018214862846305, 0.396225129977099]
440 [1.0, -0.867624235105665]
254 [1.0, -0.9264964404877519, -0.1256535074300869...

7.7 Display Model in Class

```
[ ]: model = models.loc[(models.model == 'arx') & (models.na == 2) & (models.nb == 2) & (models.nk == 1)]
      assert(len(model) == 1)
      model = model.iloc[0]

      print('G =')
      display(model.G)
      print('H =')
      display(model.H)
      print('J_p =', model.Jp)

      plt.figure(figsize=(8,4))
      plt.plot(k_v, y_v, label='y_v', drawstyle='steps-post')
      plt.plot(k_v[model.nk:], model.yp, label='y_p', drawstyle='steps-post')
      plt.xlim(k_v[0], k_v[-1])
      plt.grid()
      plt.legend()
      plt.tight_layout()
      plt.show()
```

G =

$$\frac{2.162z^2 + 1.611z - 1.602}{z^3 - 1.407z^2 + 0.4826z}$$

H =

$$\frac{z^2}{z^2 - 1.407z + 0.4826}$$

J_p = 16.155434149353134

