Classroom Exercise 2¹

The files required for this exercise are on the Moodle of the course. For the runs with Fast Downward, set a time limit of 1 minute and a memory limit of 2 GB. Using Linux, such limits can be set with ulimit -t 60 and ulimit -v 2000000, respectively.

Exercise 1

The goal of this exercise is to implement the A* search algorithm in the Fast Downward planner. We have prepared a stub of the class AStarSearch in the files

hands-on-2/fast-downward/src/search/search_engines/astar_search.{cc,h}.

Implement the parts marked as missing with a comment "// insert your code here":

• Add a comparison operator for two objects of type AStarSearchNode. You can find the stub in astar_search.h in the function

bool operator()(const AStarSearchNode *lhs, const AStarSearchNode *rhs) const

of the struct Compare within the AStarSearchNode class. Implement the comparison such that it returns true if the f-value of lhs is larger than the f-value of rhs, or if both f-values are equal and the h-value of lhs is larger than the h-value of rhs.

- The class OpenList internally works with the priority queue std::priority_queue from the C++ standard library. Based on the corresponding functions in std::priority_queue, implement the two functions to insert and remove AStarSearchNodes into and from OpenList in astar_search.h.
- In astar_search.cc, the implementation of the A* search algorithm in the search method of AStarSearch is missing. Implement A* based on the pseudo code that has been presented in the lecture.

Your implementation of A^* based on the provided code stub uses a fixed admissible heuristic (the LM-Cut heuristic). Test the correctness of your implementation (called with --search "planopt_astar()") by comparing to the Fast Downward version of A^* and LM-Cut (called with --search "astar(lmcut())") on all instances in the directory hands-on-2/benchmarks. Discuss the search time and the plan costs.

¹Exercício de Malte Helmert.