### Lecture 4 - Greedy algorithms

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## Greedy algorithms

**Greedy Algorithm**: 1) pull each arm once and then 2) always pull the arm with the best empirical mean reward.

#### Algorithm 1: The greedy algorithm

**Output:** 
$$\pi(t), t \in \{0, 1, ..., T\}$$
 while  $0 < t < m - 1$  do

$$\pi(t) = t + 1$$

while  $m \le t \le T$  do

$$\pi(t) = rg \max_{i \in [m]} \left\{ rac{1}{N_{t-1,i}} \sum_{t'=0}^{t-1} r_{t'} \mathbb{1}\{a_{t'} = i\} 
ight\}$$

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### The Regret of Greedy algorithms

Consider a two-armed bandit instance where r(1) and r(2) follow Bernoulli distributions with mean p and q respectively.

- If the event  $(r_1 = 0, r_2 = 1)$  (with probability q(1-p)) is true, the algorithm will pull arm 2 for the rest of the horizon.
- induce a regret of at least  $q(1-p)\Delta_2 T + o(T)$ .

The worst-case regret of the greedy algorithm is O(T) (Note O(T) is the worst).



### arepsilon Greedy algorithms

 $\varepsilon$ -greedy algorithm: takes a non-deterministic policy that forces exploration on sub-optimal arms. which is built upon the philosophy of being optimistic is good.

#### **Algorithm 2:** The $\varepsilon$ -greedy algorithm

**Input:**  $\varepsilon_t, t \in \{0, 1, \dots, T\}$  the exploration parameters

**Output:**  $\pi(t), t \in \{0, 1, ..., T\}$ 

while  $0 \le t \le m-1$  do

$$\pi(t) = t + 1$$

while  $m \leq t \leq T$  do

$$\pi(t) \sim \left\{ \begin{aligned} & \underset{i \in [m]}{\arg \max} \left\{ \frac{1}{N_{t-1,i}} \sum_{t'=0}^{t-1} r_{t'} \mathbb{1}\{a_{t'} = i\} \right\} & \text{with probability } 1 - \varepsilon_t \\ & i & \text{with probability } \varepsilon_t / m, \text{ for each } i \in [m] \end{aligned} \right.$$

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## The Regret of arepsilon Greedy algorithms

The algorithm amounts to the choice of the exploration parameters  $\varepsilon_t$ .

•  $\varepsilon_t$  does not diminish with t. In fact, if  $\varepsilon_t > \varepsilon$  holds for some constant  $\varepsilon > 0$ , then for T-m rounds, the algorithm has a probability at least  $\varepsilon$  to pull a random arm. As pulling a random arm induces an expected regret of  $\frac{1}{m}(\Delta_2 + \cdots + \Delta_m)$  per step (arm 1 is the best, so  $\Delta_1 = 0$ ), the regret of the algorithm is at least:

$$\overline{R}_t \geq \frac{1}{m}(\Delta_2 + \cdots + \Delta_m)\varepsilon(T - m).$$

The worst-case regret of the greedy algorithm is O(T).



## The Regret of arepsilon Greedy algorithms

The algorithm amounts to the choice of the exploration parameters  $\varepsilon_t$ .

• By carefully choosing  $\varepsilon_t$  as a decreasing function of t, we can obtain an algorithm with its regret at most  $O(\log T)$ .

#### **Theorem**

Assume that r(i) is 1-sub-Gaussian for each i. By choosing  $\varepsilon_t = \min\{1, Ct^{-1}\Delta_{\min}^{-2}m\}$  for some sufficiently large constant C, the regret under the  $\varepsilon$ -greedy algorithm satisfies

$$\overline{R}_T \leq C' \sum_{i \geq 2} \left( \Delta_i + \frac{\Delta_i}{\Delta_{\min}^2} \log \max \left\{ e, \frac{T \Delta_{\min}^2}{m} \right\} \right),$$

where C' is an absolute constant.



#### **Proof Schema**

The proof of the theorem is two-fold.

- The cost of exploration, being  $\overline{R}_t = \frac{1}{m}(\Delta_2 + \dots + \Delta_m)\varepsilon$  for  $\varepsilon_t = O(1)$ , reduces to  $\overline{R}_t = \frac{1}{m}(\Delta_2 + \dots + \Delta_m)O(1 + \frac{1}{2} + \dots + \frac{1}{T}) = \frac{1}{m}(\Delta_2 + \dots + \Delta_m)O(\log T)^1$  with the annealing of  $\varepsilon_t$ .
- Show that the probability of pulling a suboptimal arm in a round after  $\log T$  explorations is very thin (as thin as at most  $O(\log T/T)$ ).

$$H_n = 1 + 1/2 + 1/3 + ... + 1/n$$
, is approximately  $\log(n)$ 



<sup>&</sup>lt;sup>1</sup>The nth partial sum of the harmonic series,

### Some Remarks of arepsilon Greedy algorithms

#### Remarks of the Theorem:

- ε-greedy algorithm is the first algorithm we introduce to obtain a logarithmic regret (this is in fact the best regret).
- The choice for  $\varepsilon$  requires information on the gap of suboptimality.

Without prior knowledge, one has to pull each arm for a few times to get an estimation of this gap and plug in the estimation (known as bootstrap).

# Question and Answering (Q&A)



