

TSIA 202a – Exam

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Documents autorisés: photocopié, notes de cours/TD.

Durée: 1 heure 30.

Authorized Documents : lecture notes, tutorial notes.

Duration: 1 hour and 30 minutes.

EXERCISE 1: REPRESENTATIONS OF AN ARMA(2,1) PROCESS

We consider a random process $(X_t)_{t \in \mathbb{Z}}$ satisfying the following recurrence equation:

$$X_t = 6X_{t-1} - 9X_{t-2} + \varepsilon_t + \frac{1}{2}\varepsilon_{t-1}, \quad (1)$$

where (ε_t) is a zero-mean weak white noise with variance σ^2 .

1. Why does Eq. (1) admit a unique weakly stationary solution ? What is the nature of this solution (X_t) ?
2. Find the expression of the power spectral density $f(\lambda)$ of the process X .
3. Find a canonical representation of X by using a suitable all-pass filter.
4. What is the innovation process of X ? What is its variance?
5. Compute the coefficients $(\phi_k)_{k \geq 1}$ of the AR(∞) representation

$$X_t = \sum_{k \geq 1} \phi_k X_{t-k} + Z_t,$$

where (Z_t) is the innovation process of (X_t) .

Answer of exercise 1

1. We have that $\Phi(z) := 1 - 6z + 9z^2 = (1 - 3z)^2$ does not vanish on the unit circle, which ensures existence and uniqueness of the solution, which is then called an ARMA(2,1) process.
2. The spectral density is given by

$$f(\lambda) = \frac{\sigma^2}{2\pi} \frac{|1 + e^{-i\lambda}/2|^2}{|1 - 3e^{-i\lambda}|^4}.$$

3. Let F_β denote the all-pass filter with coefficients $(\beta_k) \in \ell^1$ defined by the equation

$$\sum_{k \in \mathbb{Z}} \beta_k z^k = \frac{1 - z^{-1}/3}{1 - 3z}, \quad z \in \mathbb{C}, |z| = 1.$$

We apply this filter twice on both sides of (1) and obtain that X is solution of

$$(1 - B/3)^2 X = (1 + B/2) Z, \quad (2)$$

where $Z = F_\beta(\epsilon)$ has spectral density

$$f^Z(\lambda) = \frac{\sigma^2}{2\pi} \left| \frac{1 - e^{i\lambda}/3}{1 - 3e^{-i\lambda}} \right|^4 = \frac{\sigma^2}{3^4 \cdot 2\pi}$$

Hence Z is a white noise with variance $\sigma^2/3^4$. The representation (2) is a canonical representation of X .

4. From the previous question, we deduce that Z is the innovation process of X . It has variance $\sigma^2/3^4$.
5. From (2), we have

$$Z = F_\alpha(X),$$

where $(\alpha)_k$ is the ℓ^1 sequence satisfying

$$\sum_{k \in \mathbb{Z}} \alpha_k z^k = \frac{(1 - z/3)^2}{1 + z/2}, \quad z \in \mathbb{C}, |z| = 1.$$

Now, we have, for all $z \in \mathbb{C}$ with $|z| = 1$,

$$\begin{aligned} \frac{(1 - z/3)^2}{1 + z/2} &= (1 - z/3)^2 \sum_{k \geq 0} (-1/2)^k z^k \\ &= (1 - z/3) \left(1 + \sum_{k \geq 1} ((-1/2)^k - (-1/2)^{k-1}/3) z^k \right) \\ &= (1 - z/3) \left(1 + \frac{5}{3} \sum_{k \geq 1} (-1/2)^k z^k \right) \\ &= 1 - \frac{7}{6}z + \frac{5}{3} \sum_{k \geq 2} ((-1/2)^k - (-1/2)^{k-1}/3) z^k \\ &= 1 - \frac{7}{6}z + \left(\frac{5}{3} \right)^2 \sum_{k \geq 2} (-1/2)^k z^k. \end{aligned}$$

We conclude that $\phi_1 = -\alpha_1 = 7/6$ and, for all $k \geq 2$, $\phi_k = -\alpha_k = -(5/3)^2(-1/2)^k$.

EXERCISE 2: LINEAR PREDICTION

Let $\{X_t, t \in \mathbb{Z}\}$ be a weakly stationary, zero-mean, real random process satisfying the equation

$$X_t = \theta X_{t-1} + Z_t,$$

where $\theta \in]-1, 1[$, and $\{Z_t, t \in \mathbb{Z}\}$ is weak noise with $\text{Var}(Z_t) = \sigma^2$. Let \hat{X}_t be a linear predictor of X_t , that is

$$\hat{X}_t = \sum_{k=1}^P \alpha_k X_{t-k} - p,$$

with $P \in \mathbb{N}$ being the *order* of the predictor. Finally, we define

$$Y_t = X_t - \hat{X}_t,$$

as the prediction error. We want to compare the variance (power) and the autocorrelation function of the prediction error with those of the original process X . In several applications (e.g., signal compression) it is desirable to have a prediction error with a smaller power than the original process. Also, achieving a white prediction error is desirable.

1. The input signal

- (a) Is X a causal filtering of Z ?
- (b) Find the autocorrelation function (ACF) of X , $\gamma_X(h)$
- (c) Find the variance of X_t

2. Simple first-order predictor

- (a) Let us consider the simplest predictor: $\hat{X}_t = X_{t-1}$. Find the variance of the prediction error.
- (b) In which case the variance of Y is smaller than the variance of X ?
- (c) Find the ACF of Y

3. Optimal first-order predictor

- (a) The optimal first-order predictor is: $\hat{X}_t = \alpha X_{t-1}$ with $\alpha \in \mathbb{R}$ such that the variance of Y is minimized. Find the optimal value of α .
Hint: the optimal predictor is such that the prediction error is uncorrelated with the linear past, in particular $\text{Cov}(Y_t, X_{t-1}) = 0$
- (b) Find the variance of Y : is it smaller than that of X ?
- (c) Find the ACF of Y and justify the name “whitening filter”

4. Optimal second-order predictor

- (a) A second-order predictor is in the form $\hat{X}_t = \alpha X_{t-1} - \beta X_{t-2}$. Show that for the optimal second-order predictor, $\beta = 0$, and conclude.

Answer of exercise 2

1. The input signal

- (a) X is a causal filtering of Z because the only root of the polynomial $\Theta(z) = 1 - \theta z$ is $\frac{1}{\theta}$, outside the unit circle. Therefore, one can write $X_t = \sum_{\ell \geq 0} \theta^\ell Z_{t-\ell}$
- (b) For $h \geq 0$, the autocorrelation function (ACF) of X , $\gamma_X(h)$ is

$$\begin{aligned} \gamma_X(h) &= \mathbb{E} \left[\sum_{\ell \geq 0} \theta^\ell Z_{n-\ell} \sum_{k \geq 0} \theta^k Z_{n+h-k} \right] = \sum_{\ell \geq 0} \sum_{k \geq 0} \theta^{\ell+k} \mathbb{E} [Z_{n-\ell} Z_{n+h-k}] \\ &= \sum_{\ell \geq 0} \sum_{k \geq 0} \theta^{\ell+k} \sigma^2 \delta_{k-(\ell+h)} = \sum_{\ell \geq 0} \sigma^2 \theta^{2\ell+h} \\ &= \theta^h \frac{\sigma^2}{1 - \theta^2} \end{aligned}$$

By the symmetry of ACF, we have $\gamma_X(h) = \theta^{|h|} \frac{\sigma^2}{1 - \theta^2}$.

- (c) The variance of X_t is easily found as $\gamma_X(0)$:

$$\sigma_X^2 = \frac{\sigma^2}{1 - \theta^2}$$

2. Simple first order predictor

- (a) The variance of the prediction error is:

$$\begin{aligned} \text{Var}(Y_t) &= \mathbb{E}[Y_t^2] = \mathbb{E}[(X_t - X_{t-1})^2] = \mathbb{E}[X_t^2 + X_{t-1}^2 - 2X_t X_{t-1}] \\ &= 2\gamma_X(0) - 2\gamma_X(1) = \frac{2\sigma^2}{1 - \theta^2}(1 - \theta) \\ &= \sigma_X^2 2(1 - \theta) \end{aligned}$$

- (b) From the previous, the variance of Y is smaller than the variance of X if and only if $2(1 - \theta) < 1$, implying $\theta > \frac{1}{2}$. Also, remember that $\theta < 1$ by hypothesis. In conclusion the simple predictor is effective only if consecutive samples of X are correlated enough.
- (c) The ACF of Y is computed as follows for $h > 0$:

$$\begin{aligned} \gamma_Y(h) &= \mathbb{E}[Y_t Y_{t+h}] = \mathbb{E}[(X_t - X_{t-1})(X_{t+h} - X_{t-1+h})] \\ &= 2\gamma_X(h) - \gamma_X(h-1) - \gamma_X(h+1) = \frac{\sigma^2}{1 - \theta^2} (2\theta^h - \theta^{h-1} - \theta^{h+1}) \\ &= \frac{-\sigma^2}{1 - \theta^2} (1 - \theta)^2 \theta^{h-1} = \frac{-\sigma^2}{1 + \theta} (1 - \theta) \theta^{h-1} = \frac{-(1 - \theta)\theta^{h-1}}{2} \sigma_Y^2 \end{aligned}$$

For $h = 0$, $\gamma_Y(h) = \text{Var}(Y_t)$ and for $h < 0$, $\gamma_Y(h) = \gamma_Y(-h)$.

3. Optimal first order predictor

(a) The optimal first order predictor is found by setting $\text{Cov}(\alpha X_{t-1} - X_t, X_{t-1}) = 0$

$$0 = \text{Cov}(\alpha X_{t-1} - X_t, X_{t-1}) = \alpha \gamma_X(0) - \gamma_X(1)$$

$$\alpha = \frac{\gamma_X(1)}{\gamma_X(0)} = \theta$$

$$\hat{X}_t = \theta X_{t-1}$$

$$Y_t = X_t - \theta X_{t-1} = Z_t$$

(b) Since $Y_t = Z_t$, its variance is σ^2 , which is smaller than $\sigma_X^2 = \frac{\sigma^2}{1-\theta^2}$ for any $\theta \in]-1, 1[$. The variance of Y_t can also be found explicitly as $\mathbb{E}[(X_t - \theta X_{t-1})^2]$.

(c) The ACF of Y is the one of Z : $\gamma_Y(h) = \sigma^2 \delta_h$. Therefore Y is white noise. Again, γ_Y can be found by calculating $\mathbb{E}[(X_t - \theta X_{t-1})(X_{t+h} - \theta X_{t-1+h})]$

4. Optimal second order predictor

(a) The optimal second order predictor is such that:

$$\text{Cov}(\alpha X_{t-1} + \beta X_{t-2} - X_t, X_{t-1}) = 0 \quad \alpha \gamma_X(0) + \beta \gamma_X(1) = \gamma_X(1)$$

$$\text{Cov}(\alpha X_{t-1} + \beta X_{t-2} - X_t, X_{t-2}) = 0 \quad \alpha \gamma_X(1) + \beta \gamma_X(0) = \gamma_X(2)$$

$$\begin{bmatrix} \gamma_X(0) & \gamma_X(1) \\ \gamma_X(1) & \gamma_X(0) \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \begin{bmatrix} \gamma_X(1) \\ \gamma_X(2) \end{bmatrix}$$

$$\begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \frac{1}{\gamma_X^2(0) - \gamma_X^2(1)} \begin{bmatrix} \gamma_X(0) & -\gamma_X(1) \\ -\gamma_X(1) & \gamma_X(0) \end{bmatrix} \begin{bmatrix} \gamma_X(1) \\ \gamma_X(2) \end{bmatrix}$$

$$\beta = \frac{\gamma_X(0)\gamma_X(2) - \gamma_X^2(1)}{\gamma_X^2(0) - \gamma_X^2(1)}$$

But $\gamma_X(0)\gamma_X(2) - \gamma_X^2(1) = \sigma_X^4 \theta^2 - \sigma_X^4 \theta^2 = 0$, thus $\beta = 0$.

Conclusion: since X is an AR(1) process, there is no advantage in considering linear predictors of order greater than 1.