



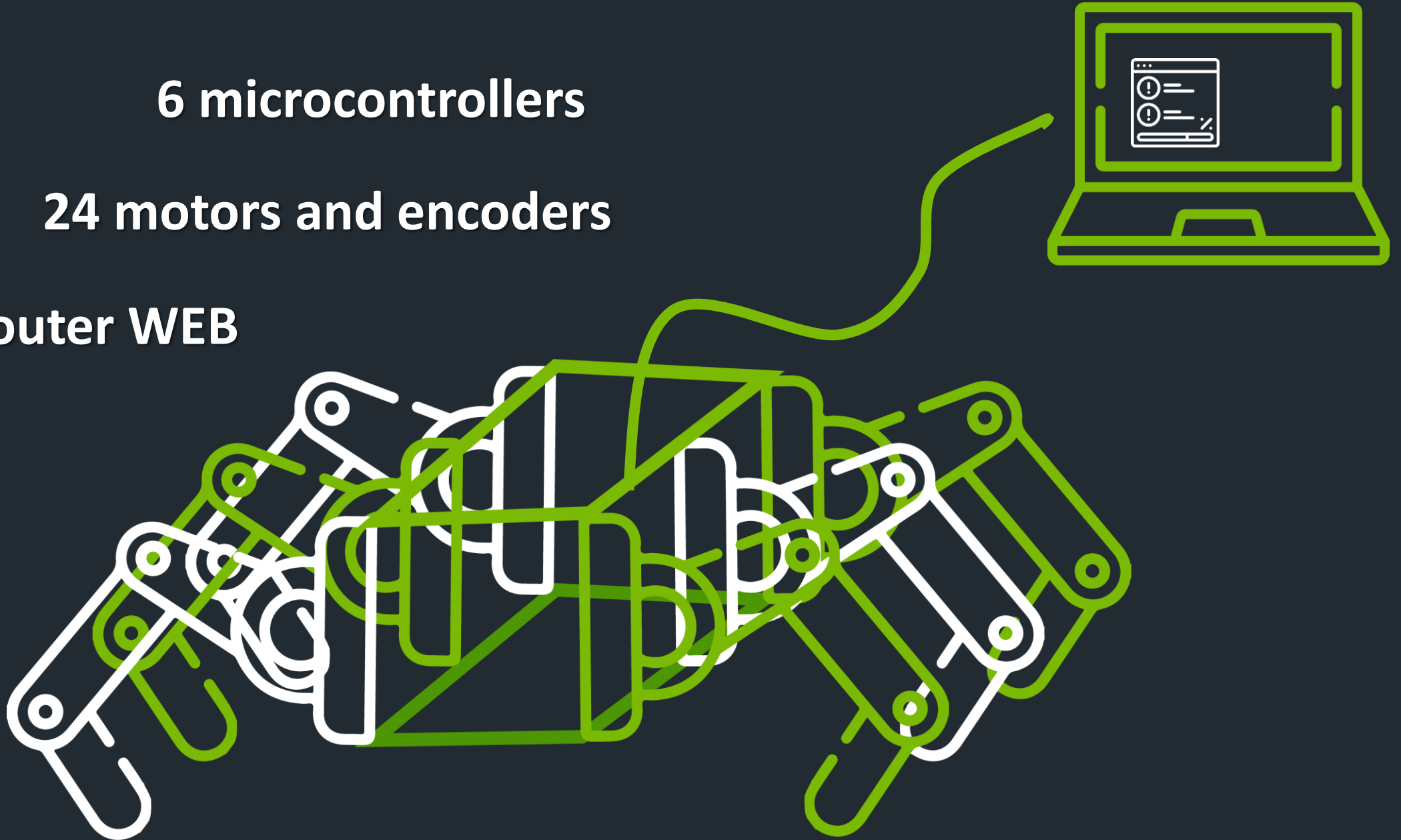
5 minutes presentation

Robot Rhex Project

6 microcontrollers

24 motors and encoders

1 router WEB



Difficulties

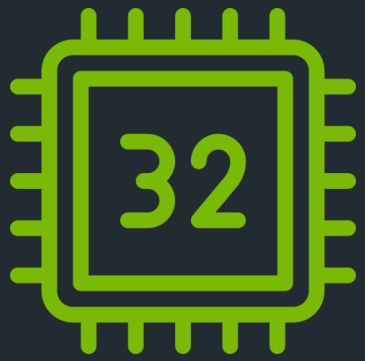


Understand the previous project

Departure of one member

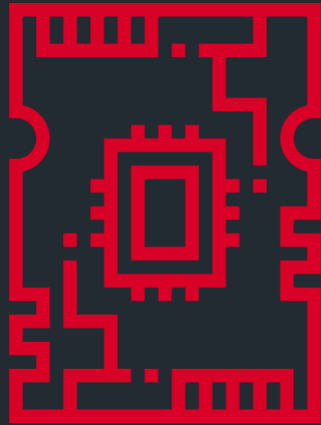
No cards allows for test

The electronic Shield



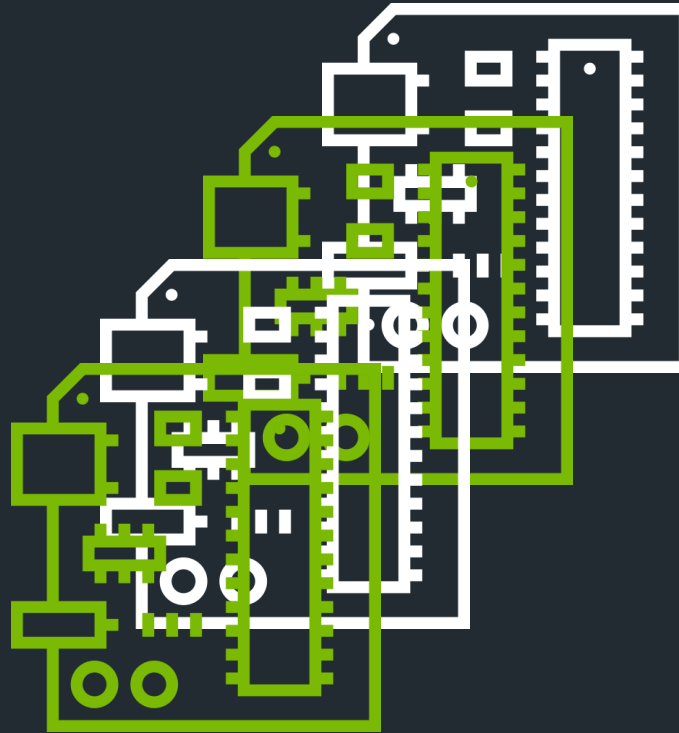
STM32

+



Interface card

+



4 power motors
cards

=



The code

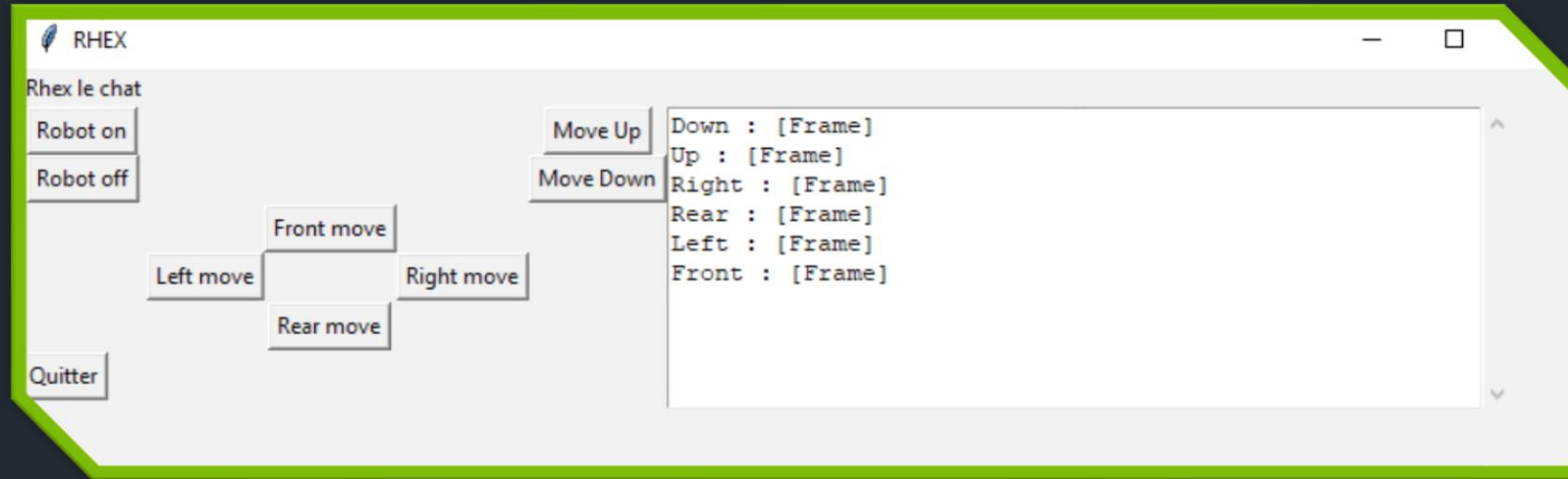
Free RTOS optimizations

CAN Controller

System security



The control interface

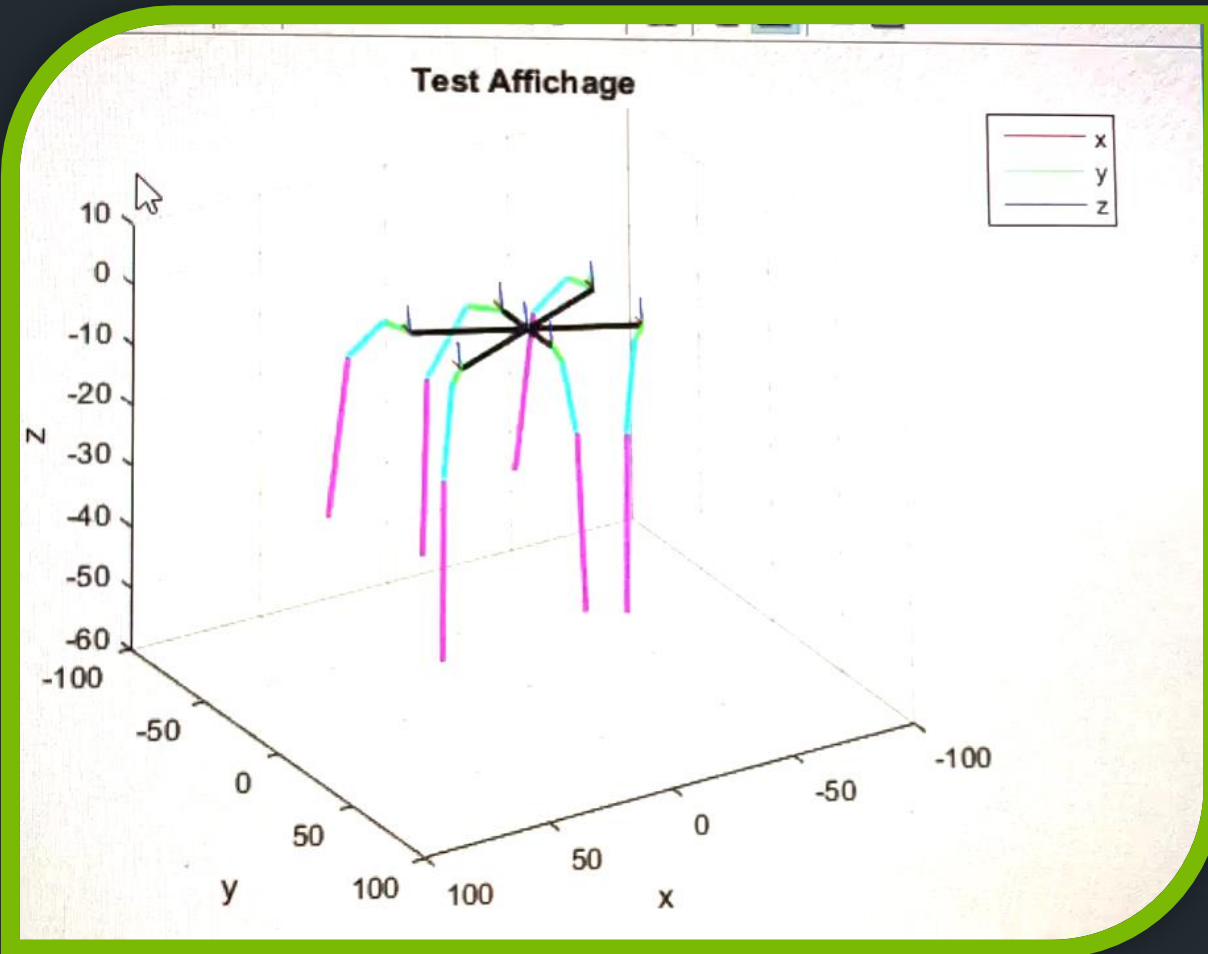


Simplicity

Clarity

Debug possibilities

The movement simulation



How to make Rhex go straight?

Joints 1, 3, 5

Joints 2, 4, 6

How to make Rhex turn?

Joints 1 and 6

Joints 2 and 5

Joints 3 and 4

Conclusion

