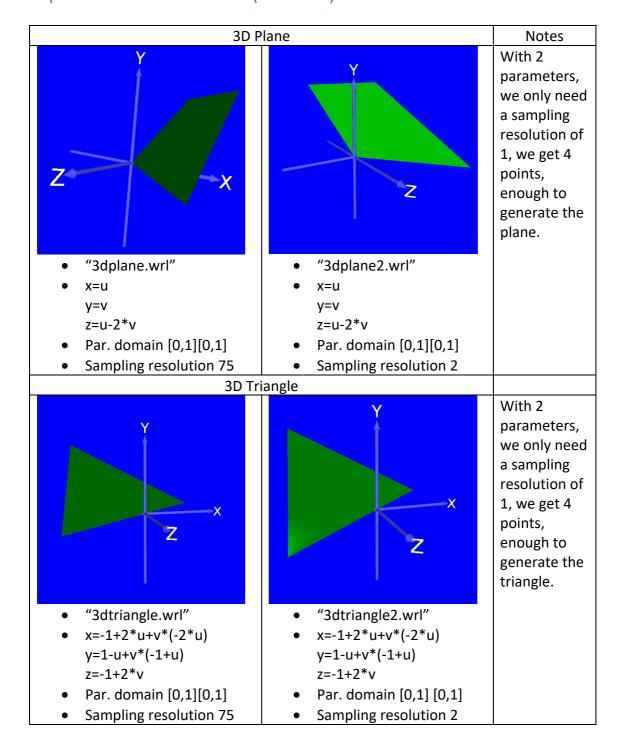
LAB 3 REPORT: PARAMETRIC SURFACES AND SOLIDS

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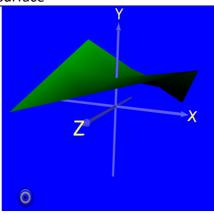
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Experiment on resolution (surfaces)



Bilinear surface

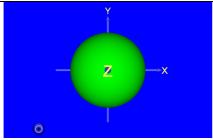
- "bilinearsurface.wrl"
- x=-1+2*uy=1-u+v*(-1+1.5*u)z=-1+2*v
- Par. domain [0,1] [0,1]
- Sampling resolution 75



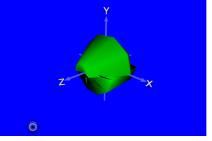
- "bilinearsurface2.wrl"
- x=-1+2*uy=1-u+v*(-1+1.5*u)z=-1+2*v
- Par. domain [0,1] [0,1]
- Sampling resolution 2

With 2 parameters, we only need a sampling resolution of 1, we get 4 points, enough to generate the plane. However, this surface is curved, so we get edges on the surface if the resolution is low.

Sphere



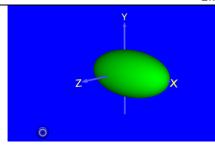
- "sphere.wrl"
- x=0.7*cos(2pi*u)cos(pi*v)
 y=0.7*cos(2pi*u)sin(pi*v)
 z=0.7*sin(2pi*u)
- Par. domain [0,1][0,1]
- Sampling resolution 75



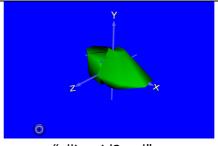
- "sphere2.wrl"
- x=0.7cos(2pi*u)cos(pi*v)
 y=0.7cos(2pi*u)*sin(pi*v)
 z=0.7sin(2pi*u)
- Par. domain [0,1][0,1]
- Sampling resolution 5

With a resolution of 5, we do not get enough polygons to generate a decent sphere.

Ellipsoid

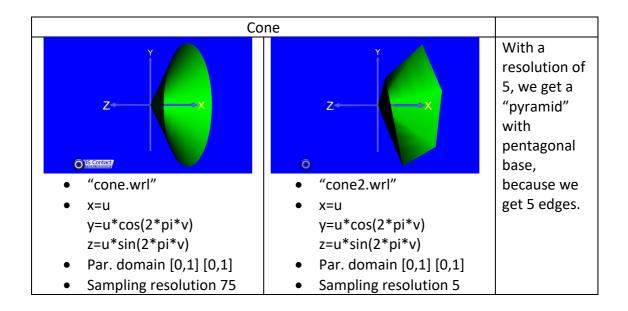


- "ellipsoid.wrl"
- x=1*cos(2pi*u)*sin(pi*v)
 y=0.5*sin(2*pi*u)
 z=0.5*cos(2pi*u)cos(pi*v)
- Parameter domain [0,1]
- Sampling resolution 75

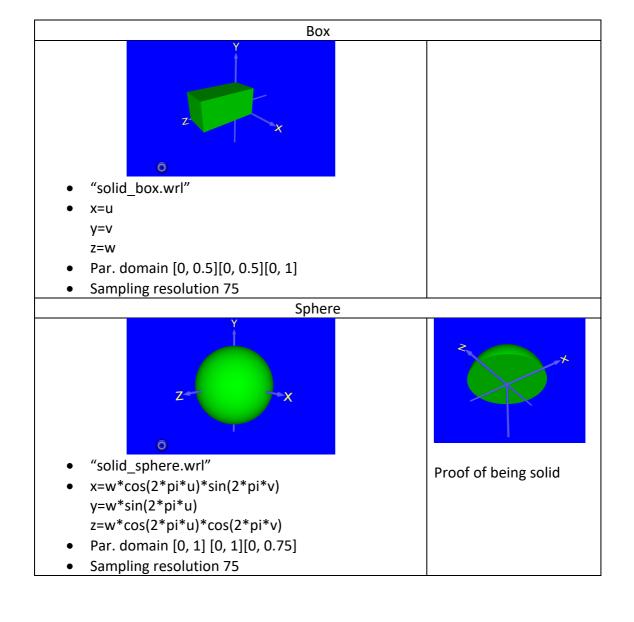


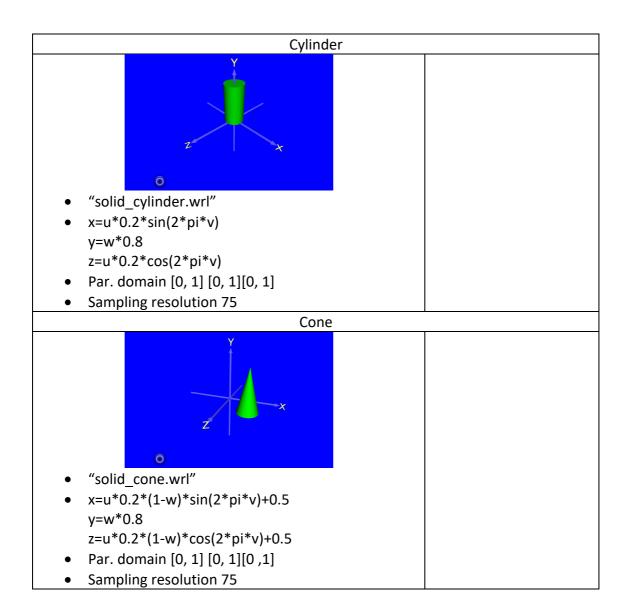
- "ellipsoid2.wrl"
- x=1*cos(2pi*u)*sin(pi*v)
 y=0.5*sin(2*pi*u)
 z=0.5*cos(2pi*u)cos(pi*v)
- Parameter domain [0,1]
- Sampling resolution 5

With a resolution of 5, we do not get enough polygons to generate a decent ellipsoid.



Experiment on solids





Converting a closed surface into a solid object

One simple example is the case of the sphere.

```
    x=1*cos(2*pi*u)*sin(2*pi*v)
    y=1*sin(2*pi*u)
    z=1*cos(2*pi*u)*cos(2*pi*v)
    u,v [0,1]
```

With this parametric equations we will get a sphere, but not a solid one. For this, we need to add a new parameter 'w', this parameter will make the radius variable to 'fill' the sphere. This parameter will have domain [0, R].

```
    x=w*cos(2*pi*u)*sin(2*pi*v)
    y=w*sin(2*pi*u)
    z=w*cos(2*pi*u)*cos(2*pi*v)
    u,v [0,1] w [0, 0.75]
```

Experiment with sine function: rotational and translational sweeping

