## Solución Tarea 5 FISI 6510

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## Exercise 5.7: Consider the integral

$$I = \int_0^1 \sin^2 \sqrt{100x} \, \mathrm{d}x$$

- a) Write a program that uses the adaptive trapezoidal rule method of Section 5.3 and Eq. (5.34) to calculate the value of this integral to an approximate accuracy of  $\epsilon=10^{-6}$  (i.e., correct to six digits after the decimal point). Start with one single integration slice and work up from there to two, four, eight, and so forth. Have your program print out the number of slices, its estimate of the integral, and its estimate of the error on the integral, for each value of the number of slices N, until the target accuracy is reached. (Hint: You should find the result is around I=0.45.)
- b) Now modify your program to evaluate the same integral using the Romberg integration technique described in this section. Have your program print out a triangular table of values, as on page 161, of all the Romberg estimates of the integral. Calculate the error on your estimates using Eq. (5.49) and again continue the calculation until you reach an accuracy of  $\epsilon = 10^{-6}$ . You should find that the Romberg method reaches the required accuracy considerably faster than the trapezoidal rule alone.

```
[1]: import numpy as np
  import matplotlib.pyplot as plt
  def f(x):
     return (np.sin((100*x)**.5))**2

def trapezoid(f,a=0,b=1,h=1,N=1):
     h=(b-a)/N
     s = 0.5*f(a) + 0.5*f(b)
     for k in range(1,N):
        s += f(a+k*h)
     return h*s
```

a)

```
[2]: N = 1 # Número inicial de pasos
a=0
b=1
```

```
h=(b-a)/N
I=[]
k = 0
epsilon,err= 1e-6,1
I.append(trapezoid(f,N=1)) # valor inicial $I_1$
print("N = {:4}\t I = {:.7f}\t error = N/A".format(N,I[0]))
while abs(err) > epsilon:
    N=2*N
   h = h/2
    s=0
    for n in range(1,N,2):
        s+= f(a+n*h)
    i = .5*I[k] + h*s
    I.append(i)
    k+=1
    err = (I[k] - I[k-1])/3
    print("N = {:4}\t I = {:.7f}\t error = {:.7f}\".format(N,i,err))
```

```
N =
                I = 0.1479795
                                error = N/A
                I = 0.3252319
                                error = 0.0590841
N =
                I = 0.5122829
                               error = 0.0623503
                I = 0.4029974
N =
      8
                               error = -0.0364285
     16
                I = 0.4301034
                               error = 0.0090353
N =
                I = 0.4484147
N =
     32
                               error = 0.0061038
     64
                I = 0.4539129
                               error = 0.0018328
N =
    128
                I = 0.4553485
                               error = 0.0004785
N =
N = 256
                I = 0.4557113
                               error = 0.0001209
N = 512
                I = 0.4558022 error = 0.0000303
N = 1024
                I = 0.4558249
                               error = 0.0000076
N = 2048
                I = 0.4558306 error = 0.0000019
N = 4096
                I = 0.4558321
                               error = 0.0000005
```

## **b**)

```
[3]: def romberg(f,a,b,h,N,precision=1e-6):
    R=[]
    I1=trapezoid(f,a,b,h,N)
    R.append([I1])
    ERR=[]
    err=1
    i=1
    while abs(err) > precision:
        N=2*N
```

```
h=h/2
s=0
for n in range(1,N,2):
    s+= f(a+n*h)
I_1m= .5*I1 + h*s
R.append([I_1m])
I1=I_1m

for m in range(1,i+1):
    err= (1/(4**m-1))*(R[i][m-1] - R[i-1][m-1])
    ERR.append(err)
    R_im= R[i][m-1] + err
    R[i].append(R_im)
i+=1

return R,ERR,N
```

```
[4]: N=1
    a=0
    b=1
    h=(b-a)/N

r=romberg(f,a,b,h,N)

for i in r[0]:
    print(i)
    print("\nN = {} steps".format(r[2]))
```

```
[0.147979484546652]
[0.3252319078064746, 0.38431604889308213]
[0.5122828507233315, 0.5746331650289505, 0.5873209727713417]
[0.4029974484782483, 0.3665689810632206, 0.35269803546550527, 0.34897386185747614]
[0.43010336929474696, 0.4391386762335798, 0.4439766559116038, 0.4454255229028117, 0.4458037647108326]
[0.44841466578746997, 0.4545184312850443, 0.45554374828847527, 0.455727352929378, 0.4557677522628155, 0.45577749223109704]
[0.4539129312153758, 0.45574568635801105, 0.4558275033628755, 0.45583200741167545, 0.45583241782140993, 0.45583248103309965, 0.4558324944613785]
```

N = 64 steps

Exercise 5.8: Write a program that uses the adaptive Simpson's rule method of Section 5.3 and Eqs. (5.35) to (5.39) to calculate the same integral as in Exercise 5.7, again to an approximate accuracy of  $\epsilon = 10^{-6}$ . Starting this time with two integration slices, work up from there to four, eight, and so forth, printing out the results at each step until the required accuracy is reached. You should find you reach that accuracy for a significantly smaller number of slices than with the trapezoidal rule calculation in part (a) of Exercise 5.7, but a somewhat larger number than with the Romberg integration of part (b).

```
[5]: def adap_simp(f,a=0,b=1,N=2,h=.5):
    fa=f(a)
    fb=f(b)
    integral=0

    for k in range(2,N-1,2):
        integral=f(a+k*h)+integral

    S=(integral*2 + fa+fb)*(1/3)

    integral=0
    for k in range(1,N,2):
        integral=f(a+k*h)+integral
    T=integral*(2/3)

    integral=h*(S+2*T)
    I=integral
    return I,S,T
```

```
err=(1/15)*(Inew-I)
I=Inew
print("I = {:.7f}\t N= {}\t error is {:.7f}".format(I,N,err))
```

```
I = 0.3843160
                N=2
                       error is 1.0000000
I = 0.5746332
                N=4
                       error is 0.0126878
I = 0.3665690
               N= 8
                       error is -0.0138709
I = 0.4391387
               N=16
                       error is 0.0048380
I = 0.4545184
               N = 32
                       error is 0.0010253
               N= 64
I = 0.4557457
                        error is 0.0000818
I = 0.4558270
              N= 128 error is 0.0000054
I = 0.4558322 N= 256 error is 0.0000003
```