

InsertTask.BreakIntoActions

MoveToNodeTask.BreakInto
Actions

AbstractRobotWorker.Break
IntoActions

```
graph LR; A[InsertTask.BreakIntoActions] --> C[AbstractRobotWorker.BreakIntoActions]; B[MoveToNodeTask.BreakIntoActions] --> C;
```

The diagram illustrates a relationship between three methods. On the left, there are two white rectangular boxes with black borders. The top box contains the text 'InsertTask.BreakIntoActions'. The bottom box contains the text 'MoveToNodeTask.BreakInto' on the first line and 'Actions' on the second line. On the right, there is a gray rectangular box with a black border containing the text 'AbstractRobotWorker.Break' on the first line and 'IntoActions' on the second line. Two blue arrows point from the right side of the two white boxes to the left side of the gray box, indicating that the two concrete methods inherit from or implement the abstract method.