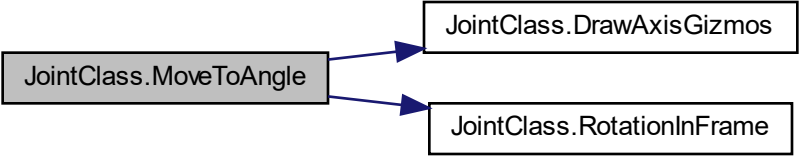


JointClass.MoveToAngle



```
graph LR; A[JointClass.MoveToAngle] --> B[JointClass.DrawAxisGizmos]; A --> C[JointClass.RotationInFrame];
```

The diagram illustrates a branching structure. On the left, a gray rectangular box contains the text 'JointClass.MoveToAngle'. Two blue arrows originate from the right side of this box. The top arrow points to a white rectangular box containing 'JointClass.DrawAxisGizmos'. The bottom arrow points to another white rectangular box containing 'JointClass.RotationInFrame'. All boxes have a thin black border.

JointClass.DrawAxisGizmos

JointClass.RotationInFrame