

ILLAServo.Action

ILLAServo.MoveToJointTarget
Position

Lynxmotion.Robotics.LssServo.
Action

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graph LR; A[ILLAServo.Action] --> C[Lynxmotion.Robotics.LssServo.Action]; B[ILLAServo.MoveToJointTarget Position] --> C;
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The diagram illustrates a relationship between three classes. On the left, there are two white rectangular boxes. The top box contains the text 'ILLAServo.Action'. The bottom box contains the text 'ILLAServo.MoveToJointTarget Position'. On the right, there is a larger grey rectangular box containing the text 'Lynxmotion.Robotics.LssServo.Action'. Two blue arrows point from the right side of the two white boxes to the left side of the grey box, indicating a relationship such as inheritance or association.