

Lynxmotion.Robotics.Channel
Operations.RetrieveSettings.onPacket

Lynxmotion.Robotics.LssServo.
Receive

Lynxmotion.Robotics.LssTelemetry.
Update

```
graph LR; A[Lynxmotion.Robotics.ChannelOperations.RetrieveSettings.onPacket] --> C[Lynxmotion.Robotics.LssTelemetry.Update]; B[Lynxmotion.Robotics.LssServo.Receive] --> C;
```

The diagram illustrates a dependency or call relationship. Two source functions, 'Lynxmotion.Robotics.ChannelOperations.RetrieveSettings.onPacket' and 'Lynxmotion.Robotics.LssServo.Receive', are shown in white boxes on the left. Arrows from both point to a target function, 'Lynxmotion.Robotics.LssTelemetry.Update', which is shown in a grey box on the right.