

Lynxmotion.Robotics.LssChannel.  
ReadAndDistributeServoPackages

Lynxmotion.Robotics.Channel  
Operations.Scan.Run

Lynxmotion.Robotics.LssChannel.  
ReadLine

```
graph LR; A[Lynxmotion.Robotics.LssChannel.  
ReadAndDistributeServoPackages] --> C[Lynxmotion.Robotics.LssChannel.  
ReadLine]; B[Lynxmotion.Robotics.Channel  
Operations.Scan.Run] --> C;
```

The diagram illustrates a dependency or call relationship. Two source methods on the left point via blue arrows to a single target method on the right. The target method is highlighted with a gray background. The first source method is 'Lynxmotion.Robotics.LssChannel.ReadAndDistributeServoPackages' and the second is 'Lynxmotion.Robotics.ChannelOperations.Scan.Run'. Both point to 'Lynxmotion.Robotics.LssChannel.ReadLine'.