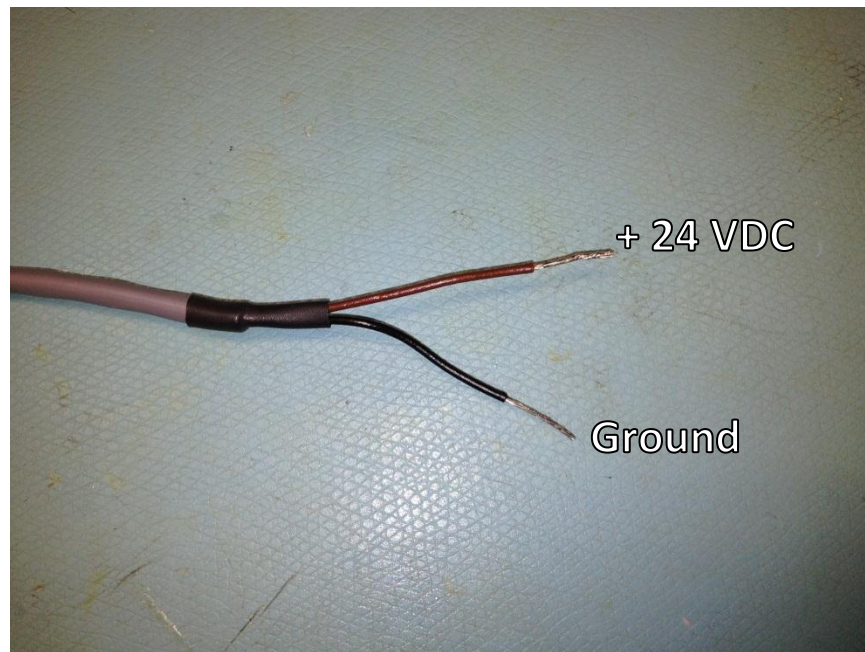# iRobot Dexter Hand Quick Start Guide
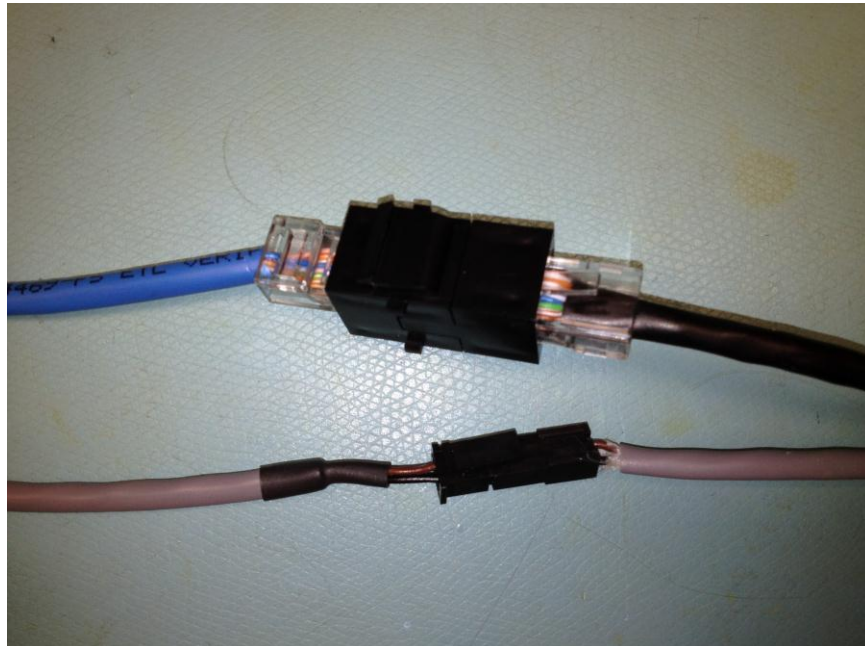
7/23/2013

Power the hand by connecting the **brown wire to +24 VDC** and the **black wire to GROUND** with a 5 A current limit.

Use a male-to-male RJ45 coupler to connect the palm to the computer for communication.

To mount the palm, use 3 M6 X 1.0 bolts at a maximum depth of 5.50 mm into the housing.

28°

155°

120°

Ø74 BCD

3 x Ø 5 ⩛ 6.50
M6x1.0 – 6H ⩛ 5.50