

CS207 Design and Analysis of Algorithms

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Algorithm design techniques

Algorithm design is an art

- ▶ Many are algorithms that generate a sense of wonder with a design that does not fit any paradigm
- ▶ Still very many problems can be solved using well known techniques
- ▶ Some well known tricks of the trade are
 - ▶ Divide and conquer
 - ▶ Dynamic programming
 - ▶ Greedy method
 - ▶ Backtracking
 - ▶ Branch and bound
 - ▶ Local Search

Divide and Conquer

- ▶ Solve a problem recursively
 - ▶ Divide the problem into a number of smaller instances of the same problem
 - ▶ For each of these subproblems, if its size is sufficiently large, then Conquer it recursively, else Conquer it directly
 - ▶ Combine the solutions to the subproblems into the solution for the original problem

Dynamic Programming

- ▶ Particularly useful for optimization problems. Solution space. Constraints. Many feasible solutions, each of which satisfies the constraints, and has a value. We wish to find one feasible solution that minimises (maximizes) value.
- ▶ Steps:
 - ▶ Formulate the structure of an optimal solution
 - ▶ Recursively define the value of an optimal solution
 - ▶ Compute the value of an optimal solution, typically in a bottom-up fashion
 - ▶ Construct an optimal solution from computed information
- ▶ Works particularly when the following properties hold:
 - ▶ Optimal Substructure: an optimal solution to the problem contains within it optimal solutions to subproblems
 - ▶ Overlapping subproblems: recursive algorithm for the problem solves the same subproblems repeatedly

Greedy Method

- ▶ Works for some optimization problems, not all
- ▶ A greedy choice is one that looks best at the moment
- ▶ Steps:
 - ▶ Formulate a solution in which we make a *greedy* choice and are left with one subproblem.
 - ▶ Prove that there is always an optimal solution reachable through the greedy choice; that is, the greedy choice is safe
 - ▶ Devise a way to combine an optimal solution to the subproblem with the greedy choice to obtain an optimal solution to the original problem

Backtracking

- ▶ Useful for constraint satisfaction problems (CSPs)
- ▶ (A CSP has a set of variables, each with a domain of values, and a set of constraints on these variables specified through relations on them. We need to find values for all variables, so that all constraints are satisfied. E.g., Sudoku)
- ▶ Incrementally builds candidates to the solutions
- ▶ Abandons a candidate ("backtracks") as soon as it becomes clear that the candidate cannot be completed into a valid solution

Branch and Bound

- ▶ Branch and bound (BB) is useful for various kinds of optimization problems
- ▶ Applicable when the set S of candidate solutions can be partitioned using a rooted tree
- ▶ The root corresponds to S
- ▶ Subtrees rooted at the root's children represent a partition of S into disjoint subsets
- ▶ Before exploring a branch, we check it against upper and lower estimated bounds on the optimal solution
- ▶ The branch is not explored if it cannot produce a solution better than the best one found so far
- ▶ If estimations are not possible, then the algorithm is an exhaustive search

Local Search

- ▶ A heuristic method for solving computationally hard optimization problems
- ▶ Move from feasible solution to feasible solution by applying local changes, until a locally optimal solution is found or a time bound is exceeded
- ▶ Analogy: A ball rolling down a slope settles at the bottom of the first ditch, take it out on the other side until it starts rolling down again; repeat when it settles at the bottom of another ditch; continue until your time runs out; declare the lowest point found as *the lowest point*