

construction robotics

international M.Sc.programme



- 1 Introduction
- 2 Research methods
- 3 Dataset
- 4 Particle Size Detection Approaches
- 5 Result
- 6 Implementation Plan
- 7 Schedule

- 1 Introduction
  - 1.1 Task description
  - 1.2 Motivation and Problem Statement
  - 1.3 Objectives
- 2 Research methods
- 3 Dataset
- 4 Particle Size Detection Approaches
- 5 Result
- 6 Implementation Plan
- 7 Schedule

# **Task Description**

# Material examination and classification using computer vision













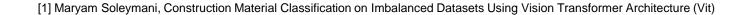


#### **Intelligent Construction Sites**

- Piles of materials are often delivered to the construction site.
- Unmanned intelligent construction management
- Integration of robots with RGB-D cameras
- The biggest challenge of these studies is related to materials with similar shapes and textures.[1]→(Granular materials)
- <u>Granular material recognition and</u> classification

#### **Goals and Applications**

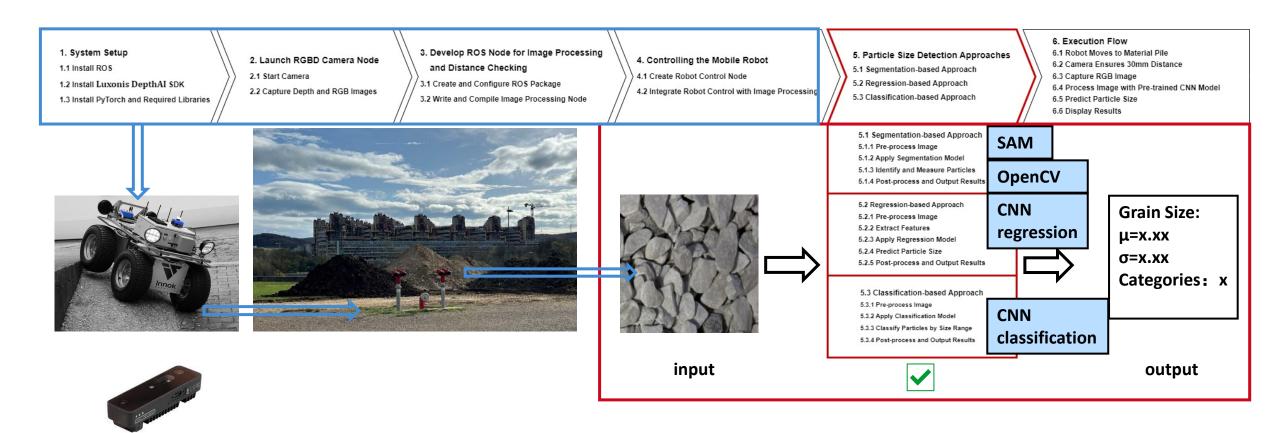
- Particle size and distribution prediction
- Particle shape and type recognition
- Enhancing construction efficiency and accuracy



# **Objectives & Workflow**

## Material examination and classification using computer vision

#### **Automated Particle Size Detection Workflow**

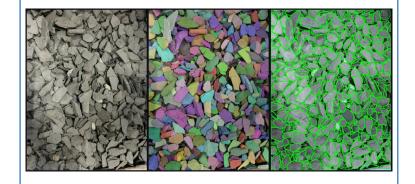


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### Research methods

# Material examination and classification using computer vision

- Segmentation-Based Method
- Segment materials into individual particles using a segmentation model (e.g., SAM).
- Extract features from each particle.



- Regression-Based Method
- Use a CNN model to extract features from each image.
- Map features to numerical values.
- Training set results correlate features with specific numerical outcomes.



**Grain Size:**  $\mu = x.xx$  $\sigma = x.xx$ 

- Classification-Based Method
- Train a CNN model to extract features from each image.
- Map features to corresponding labels.



Categories: x

conducted a custom dataset to evaluate the effectiveness of each method.



The dataset plays a decisive role in the usability of the trained models.

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#### **Dataset**

### Material examination and classification using computer vision

### **Dataset Preparation**

- Image Source: Collected from Aachen Bauhaus and OBI, including 20 types of construction granular materials.
- **Product Diversity:** Ranges from 1-3mm gravel to 40-60mm marble.
- Sampling and Labeling: Products are representing the construction industry. (The most common construction particle size range is 0.075-80mm[1]). These products have <u>small grain size variances</u> and have been labeled. Easier for labeling, feature extraction, and machine learning.



- Image Specifications:
- Manual photography
- Consistent lighting conditions
- Fixed camera distance: 30mm
- Image resolution: 3024x4032 pixels



[1] K.V. Anusree, G.M. Latha, Characterization of sand particle morphology: state of the art, Bull. Eng. Geol. Environ. 82 (2023) 269.

- Introduction
- **Research methods**
- **Dataset**
- **Particle Size Detection Approaches** 
  - **Segmentation-based Approach**
  - **Regression-based Approach**
  - **Classification-based Approach**

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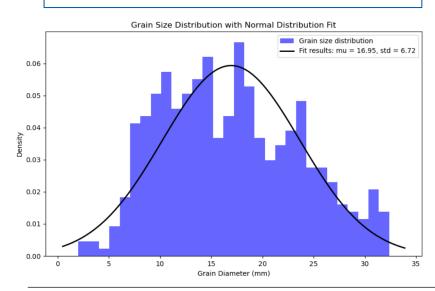
- Result
- **Implementation Plan**
- **Schedule**

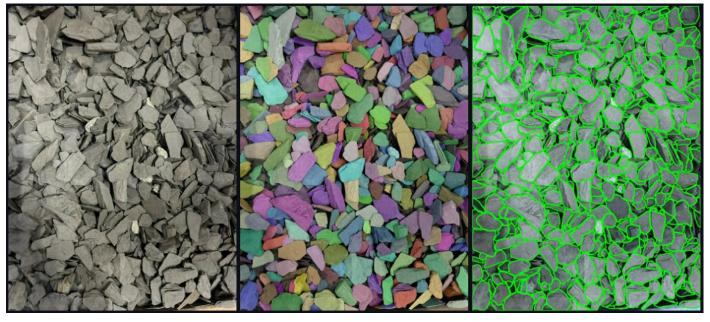
# Particle size detection approachs

### Material examination and classification using computer vision

## Segmentation-Based Method

- Segment materials into individual particles using a segmentation model (e.g., SAM).
- Extract features from each particle using OpenCV.
- Estimate particle size distribution.





#### **Limitations:**

- Accuracy depends on segmentation quality.
- Small particles (<3mm) may appear larger due to image resolution limits.
- Large particles (>30mm) may be over-segmented due to shadows and occlusions.
- Best suited for particles sized 3-30mm.
- Segment Anything Model (SAM) is computationally intensive and time-consuming.

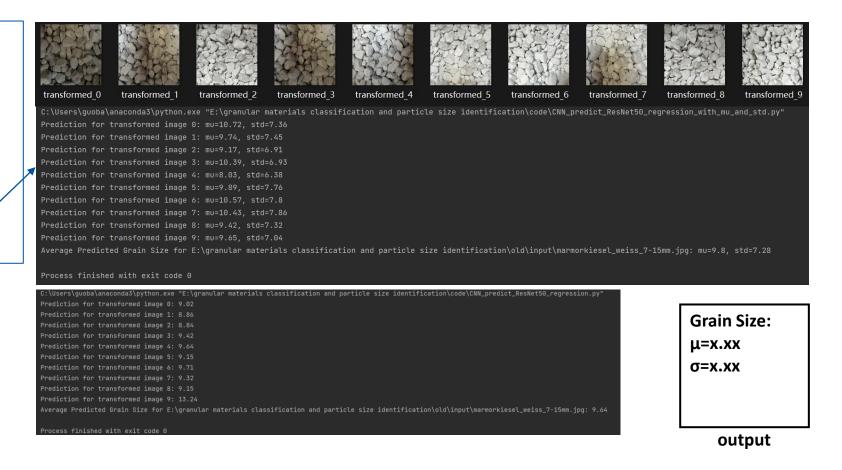
# Particle size detection approachs

## Material examination and classification using computer vision

- Regression-Based Method
- Use a CNN model to extract features from each image.
- Map features to numerical values.
- Training set results correlate features with specific numerical outcomes.



input



# Particle size detection approachs

#### Material examination and classification using computer vision

- Classification-Based Method
- Train a CNN model to extract features from each image.
- Map features to corresponding labels.





Category	Characteristics	Product Names
Fine Pebbles and Gravel	Small size, rounded to semi-rounded, smooth to medium roughness	Marmorkiesel_Weiss_7-15mm, Marmorkiesel_Weiss_15-25mm, Marmorkiesel_Gruen_15-25mm, Quarzkies_Rund_Hell_8-16mm, Kies_2-8mm, Kies_8-16mm, Kies_1-3mm
Medium Pebbles and Gravel	Medium size, rounded to semi- rounded, smooth to medium roughness	Marmorkiesel_Weiss_25-40mm, Marmorkiesel_Weiss_40-60mm, Marmorkiesel_Schwarz_40-60mm, Quarzkies_Rund_Hell_16-32mm, Kies_16-32mm, Marmorsplitt_7-12mm, Splitt_2-5mm
Large Pebbles and Broken Stones	Large size, irregular shape, rough texture	Bruchsteine_Veronarot_30-60mm, Schieferplaettchen_22-40mm, Marmorsplitt_Veronarot_9-12mm, Marmorsplitt_Donaublau_8-12mm, Basaltsplitt_8-12mm, Granitsplitt_8-12mm, Marmorkiesel_Weiss_15-25mm

#### **Classification Criteria:**

Combines particle size, shape, and smoothness.

#### Three categories:

- 1 Small particles
- 2 Medium-sized particles (aesthetic, suitable for decoration and outdoor paving)
- 3 Large and rough particles (suitable for construction, providing higher friction)

Challenges: Overfitting issues during training. Current training paused to explore alternative methods.

# Result

# Material examination and classification using computer vision

Method	Key Characteristics	Advantages	Limitations
Segmentation-Based	Segments images into individual particles, extracts features (e.g., diameter, area)	Detailed particle size distribution (average size, variance)	Dependent on segmentation quality, less effective for very small (<3mm) or large (>30mm) particles
Regression-Based	Uses CNN to extract features, maps to numerical values	High accuracy with consistent conditions, faster than segmentation, adjustable labeling	Dependent on consistent testing conditions, potential overfitting issues
Classification-Based	Combines size, shape, and smoothness into categories	Broad applicability, practical for varied uses	Overfitting during training, further optimization needed



### Research methods

#### Material examination and classification using computer vision

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Categories: x



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# Implementation plan

# Material examination and classification using computer vision



### Step 2

Ensure the camera is positioned at the optimal 30mm distance.



#### Step 4

Utilize a pretrained CNN model to process the images.



### Step 6

Display and analyze the results for construction site management.

#### Step 1:

Deploy the robot to navigate to the material pile.



# Step 3

Capture RGB images under controlled lighting conditions.

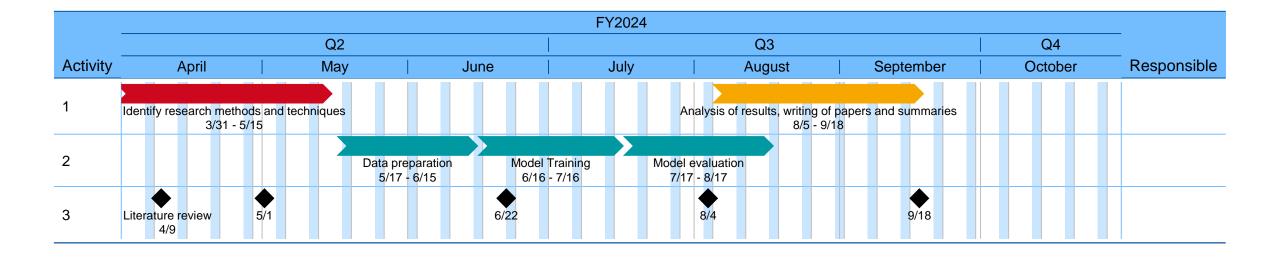


### Step 5

Predict the particle size using the model.



# **Schedule**



#### Sources

https://paperswithcode.com/task/material-recognition/codeless https://www.cs.columbia.edu/CAVE/software/curet/ https://www.csc.kth.se/cvap/databases/kth-tips/index.html https://www.fmdsa.org/research-network/ http://opensurfaces.cs.cornell.edu/ https://en.wikipedia.org/wiki/Convolutional\_neural\_network https://image-net.org/challenges/LSVRC/ https://towardsdatascience.com/r-cnn-fast-r-cnn-faster-r-cnn-yolo-object-detection-algorithms-36d53571365e https://arxiv.org/abs/1312.6229 https://viso.ai/deep-learning/vgg-very-deep-convolutional-networks/ http://yann.lecun.com/exdb/publis/pdf/farabet-pami-13.pdf https://arxiv.org/abs/2304.07193



Thanks for listening. Any Question?

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