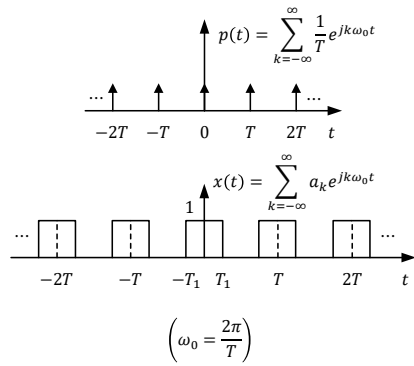


Discussion 3.3: Determine the spectral coefficients of a square wave based on the spectral coefficients of an impulse train.



Solution:

$$p(t) = \sum_{k=-\infty}^{\infty} \frac{1}{T} e^{jk\omega_0 t}$$
$$\frac{d}{dt} x(t) = \sum_{k=-\infty}^{\infty} jk\omega_0 a_k e^{jk\omega_0 t} = p(t + T_1) - p(t - T_1)$$

For $k \neq 0$

$$a_k = \frac{\frac{1}{T} e^{jk\omega_0 T_1} - \frac{1}{T} e^{-jk\omega_0 T_1}}{jk\omega_0} = \frac{2j \operatorname{sinc} \omega_0 T_1}{j2k\pi} = \frac{\operatorname{sinc} \omega_0 T_1}{k\pi}$$

For $k = 0$

$$a_0 = \frac{1 \times 2T_1}{T} = \frac{2T_1}{T}$$

§3.5 Fourier Series Representation of Discrete-time Periodic Signals

1. Linear Combinations of Harmonically Related Complex Exponentials

The set of harmonically related complex exponentials:

$$\phi_k[n] = e^{jk\omega_0 n} = e^{jk\frac{2\pi}{N}n} \quad (k \in \mathbb{Z})$$
$$\phi_k[n] = \phi_{k+rN}[n]$$

Fourier Series:

$$x[n] = \sum_{k=\langle N \rangle} a_k \phi_k[n] = \sum_{k=\langle N \rangle} a_k e^{jk\omega_0 n} = \sum_{k=\langle N \rangle} a_k e^{jk\frac{2\pi}{N}n}$$

a_k is called the **discrete-time Fourier series coefficients**.

2. Determination of the Fourier Series Representation of a Discrete-Time Period Signal

$$\sum_{n=\langle N \rangle} e^{j(k-r)\frac{2\pi}{N}n} = N\delta[k-r] = \begin{cases} N(k-r=0, \pm N, \dots) \\ 0(k-r \neq 0, \pm N, \dots) \end{cases}$$

$$\sum_{n=\langle N \rangle} x[n] e^{-jr\frac{2\pi}{N}n} = \sum_{n=\langle N \rangle} \left(\sum_{k=\langle N \rangle} a_k e^{jk\frac{2\pi}{N}n} \right) e^{-jr\frac{2\pi}{N}n}$$
$$= \sum_{k=\langle N \rangle} a_k \sum_{n=\langle N \rangle} e^{j(k-r)\frac{2\pi}{N}n} = N a_r$$
$$\therefore a_r = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jr\frac{2\pi}{N}n}$$

The discrete-time Fourier Series Pair:

$$\begin{cases} x[n] = \sum_{k=\langle N \rangle} a_k e^{jk\omega_0 n} = \sum_{k=\langle N \rangle} a_k e^{jk\frac{2\pi}{N}n} \\ a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk\omega_0 n} = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk\frac{2\pi}{N}n} \end{cases}$$

a_k is also called the spectral coefficients of $x[n]$.
 $a_k = a_{k+N}$ has the period N .

§3.6 Properties of Discrete-Time Fourier Series

$x[n] \xleftrightarrow{FS} a_k \text{ and } y[n] \xleftrightarrow{FS} b_k \text{ have the same period } T.$

2. Time Shifting

$$x[n - n_0] \xleftrightarrow{FS} e^{-jk\frac{2\pi}{N}n_0} a_k$$

Proof:

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk\omega_0 n}$$

$$\begin{aligned} x[n - n_0] &= \sum_{k=\langle N \rangle} a_k e^{jk\omega_0(n-n_0)} = \sum_{k=\langle N \rangle} a_k e^{-jk\omega_0 n_0} e^{jk\omega_0 n} \\ &= \sum_{k=\langle N \rangle} (e^{-jk\omega_0 n_0} a_k) e^{jk\omega_0 n} \end{aligned}$$

Note that $(\omega_0 = \frac{2\pi}{N})$

1. Multiplication

$$x[n]y[n] \xleftrightarrow{FS} c_k = \sum_{l=\langle N \rangle} a_l b_{k-l}$$

Proof:

$$\begin{aligned} c_k &= \frac{1}{N} \sum_{n=\langle N \rangle} x[n]y[n] e^{-jk\omega_0 n} \\ &= \frac{1}{N} \sum_{n=\langle N \rangle} \left(\sum_{l=\langle N \rangle} a_l e^{jl\omega_0 n} \right) y[n] e^{-jk\omega_0 n} \\ &= \sum_{l=\langle N \rangle} a_l \left\{ \frac{1}{N} \sum_{n=\langle N \rangle} y[n] e^{-j(k-l)\omega_0 n} \right\} \\ &= \sum_{l=\langle N \rangle} a_l b_{k-l} \end{aligned}$$

3. First Difference

$$x[n] - x[n - 1] \xleftrightarrow{FS} (1 - e^{-jk\frac{2\pi}{N}}) a_k$$

Proof:

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk\omega_0 n}$$

$$x[n - 1] = \sum_{k=\langle N \rangle} (e^{-jk\frac{2\pi}{N}} a_k) e^{jk\omega_0 n}$$

$$x[n] - x[n - 1] = \sum_{k=\langle N \rangle} (1 - e^{-jk\frac{2\pi}{N}}) a_k e^{jk\omega_0 n}$$

4. Parseval's Relation for Discrete-Time Period Signals

$$\frac{1}{N} \sum_{n=\langle N \rangle} |x[n]|^2 = \sum_{k=\langle N \rangle} |a_k|^2$$

Proof:

$$\begin{aligned} \frac{1}{N} \sum_{n=\langle N \rangle} |x[n]|^2 &= \frac{1}{N} \sum_{n=\langle N \rangle} x[n]x^*[n] \\ &= \frac{1}{N} \sum_{n=\langle N \rangle} x[n] \left(\sum_{k=\langle N \rangle} a_k e^{jk\omega_0 n} \right)^* \\ &= \sum_{k=\langle N \rangle} a_k^* \left\{ \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk\omega_0 n} \right\} \\ &= \sum_{k=\langle N \rangle} a_k^* a_k = \sum_{k=\langle N \rangle} |a_k|^2 \end{aligned}$$

2. Discrete-Time LTI systems

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk\omega_0 n} \rightarrow \boxed{h[n]} \rightarrow y[n] = \sum_{k=\langle N \rangle} b_k e^{jk\omega_0 n}$$

① System Function:

$$H(z) = \sum_{k=-\infty}^{+\infty} h[k]z^{-k}$$

② Frequency Response:

$$H(e^{j\omega}) = \sum_{n=-\infty}^{+\infty} h[n]e^{-j\omega n}$$

③ Input-output Relation:

$$b_k = a_k H(e^{jk\omega_0})$$

§3.7 Fourier Series and LTI Systems

1. Continuous-Time LTI systems

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} \rightarrow \boxed{h(t)} \rightarrow y(t) = \sum_{k=-\infty}^{\infty} b_k e^{jk\omega_0 t}$$

① System Function:

$$H(s) = \int_{-\infty}^{+\infty} h(\tau) e^{-s\tau} d\tau$$

② Frequency Response:

$$H(j\omega) = \int_{-\infty}^{+\infty} h(t) e^{-j\omega t} dt$$

③ Input-Output Relation:

$$b_k = a_k H(jk\omega_0)$$

§3.8 Filtering

Change the relative amplitudes of the frequency components or eliminate some frequency components in a signal

1. Frequency-Shaping Filters

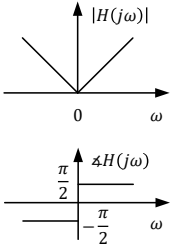
LTI systems that change the shape of the spectrum

$$x(t) \rightarrow \boxed{h(t)} \rightarrow \frac{d}{dt} x(t)$$

$$H(j\omega) = \int_{-\infty}^{+\infty} u_1(t) e^{-j\omega t} dt = j\omega$$

$$|H(j\omega)| = |\omega|$$

$$\angle H(j\omega) = \begin{cases} \frac{\pi}{2} & (\omega > 0) \\ -\frac{\pi}{2} & (\omega < 0) \end{cases} = \frac{\pi}{2} \text{sgn}(\omega)$$



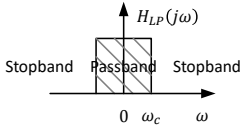
2. Frequency-Selective Filters

LTI systems that are designed to pass some frequencies
Undistorted and attenuate or eliminate others

① Continuous-Time LTI Systems

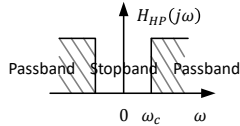
a. Ideal Low-Pass Filter

$$H_{LP}(j\omega) = \begin{cases} 1 & (|\omega| < \omega_c) \\ 0 & (|\omega| > \omega_c) \end{cases}$$



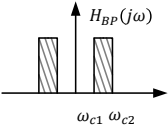
b. Ideal High-Pass Filter

$$H_{HP}(j\omega) = 1 - H_{LP}(j\omega) = \begin{cases} 0 & (|\omega| < \omega_c) \\ 1 & (|\omega| > \omega_c) \end{cases}$$



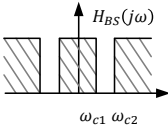
c. Ideal Band-Pass Filter

$$H_{BP}(j\omega) = \begin{cases} 1 & (\omega_{c1} < |\omega| < \omega_{c2}) \\ 0 & (|\omega| < \omega_{c1}) \cup (|\omega| > \omega_{c2}) \end{cases}$$



d. Ideal Band-Stop Filter

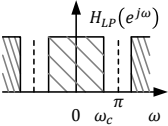
$$H_{BS}(j\omega) = 1 - H_{BP}(j\omega) = \begin{cases} 0 & (\omega_{c1} < |\omega| < \omega_{c2}) \\ 1 & (|\omega| < \omega_{c1}) \cup (|\omega| > \omega_{c2}) \end{cases}$$



② Discrete-Time LTI Systems

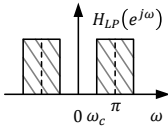
a. Ideal Low-Pass Filter

$$H_{LP}(e^{jk\omega}) = \begin{cases} 1 & (|\omega| < \omega_c) \\ 0 & (\omega_c < |\omega| < \pi) \end{cases}$$



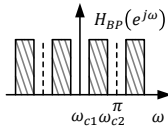
b. Ideal High-Pass Filter

$$H_{LP}(e^{jk\omega}) = \begin{cases} 0 & (|\omega| < \omega_c) \\ 1 & (\omega_c < |\omega| < \pi) \end{cases}$$



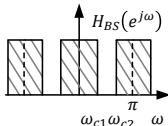
c. Ideal Band-Pass Filter

$$H_{BP}(e^{jk\omega}) = \begin{cases} 1 & (\omega_{c1} < |\omega| < \omega_{c2}) \\ 0 & (|\omega| < \omega_{c1}) \cup (\omega_{c2} < |\omega| < \pi) \end{cases}$$



d. Ideal Band-Stop Filter

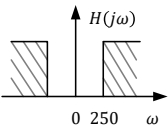
$$H_{BS}(e^{jk\omega}) = \begin{cases} 0 & (\omega_{c1} < |\omega| < \omega_{c2}) \\ 1 & (|\omega| < \omega_{c1}) \cup (\omega_{c2} < |\omega| < \pi) \end{cases}$$



Example 3.4 Consider a continuous-time LTI system of which the frequency response is $H(j\omega) = \begin{cases} 1 & (|\omega| > 250) \\ 0 & (|\omega| < 250) \end{cases}$.

When the input to this system is a signal $x(t)$ with the fundamental period $T = \frac{\pi}{7}$ and Fourier series coefficient a_k , the output $y(t)$ is identical to $x(t)$. Determine the values of k that lead to $a_k = 0$.

Solution:
 $\omega_0 = \frac{2\pi}{T} = 14$



$$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk14t} \qquad y(t) = \sum_{k=-\infty}^{+\infty} H(j14k) a_k e^{j14kt}$$

$\therefore x(t) = y(t)$

$\therefore a_k = a_k H(j14k)$

$$\therefore H(j14k) = \begin{cases} 1 & \left(|k| \geq \left\lceil \frac{250}{14} \right\rceil = 18 \right) \\ 0 & \left(|k| \leq \left\lfloor \frac{250}{14} \right\rfloor = 17 \right) \end{cases}$$

$\therefore a_k = 0 \quad (|k| \leq 17)$

Solution:

$$x(t) = \frac{1}{3} + \frac{1}{2} e^{j\frac{\omega_0}{2}t} - \frac{5}{6} e^{-j3\omega_0 t} + \cos 6\omega_0 t = \sum_{k=-\infty}^{\infty} a_k e^{jk\frac{\omega_0}{2}t}$$

$$a_0 = \frac{1}{3}, \quad a_1 = \frac{1}{2}, \quad a_{-6} = -\frac{5}{6}, \quad a_{\pm 12} = \frac{1}{2}$$

$$y(t) = \sum_{k=-\infty}^{\infty} b_k e^{jk\frac{\omega_0}{2}t}$$

$$b_k = a_k H\left(jk\frac{\omega_0}{2}\right)$$

$$b_0 = \frac{1}{3}, \quad b_1 = \frac{1}{2}, \quad b_{-6} = -\frac{5}{6}, \quad b_{\pm 12} = 0$$

$$y(t) = \frac{1}{3} + \frac{1}{2} e^{j\frac{\omega_0}{2}t} - \frac{5}{6} e^{-j3\omega_0 t} \quad \text{is not a real signal}$$

Discussion 3.4: The frequency response of a system is written as

$$H(j\omega) = \begin{cases} 1, & |\omega| < \omega_0 \\ 2, & 2\omega_0 < |\omega| < 4\omega_0 \\ 0, & \text{otherwise} \end{cases}$$

(a) Compute the output of the system $y(t)$, when the input signal is given by

$$x(t) = \frac{1}{3} + \frac{1}{2} e^{j\frac{\omega_0}{2}t} - \frac{5}{6} e^{-j3\omega_0 t} + \cos 6\omega_0 t$$

(b) Express the output $y(t)$ with the Fourier series. Is the output a real signal?

Homework			
3.13	3.43		
3.1	3.15	3.34	3.35

- ① Do not wait until the last minute
 - ② Express your own idea and original opinion
 - ③ Keep in mind the zero-tolerance policy on plagiarism