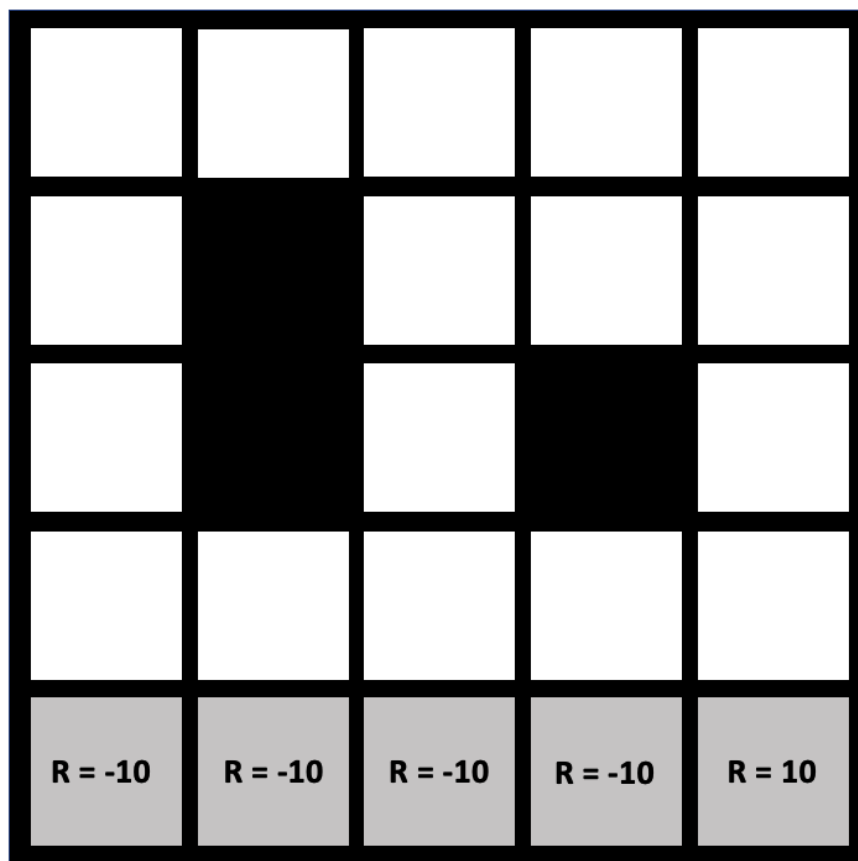


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Lab Assignment 2: Policy evaluation, policy iteration and value iteration

## Grid World

In this lab assignment, we are going to focus on the GridWorld environment illustrated below. On this figure, each white square represents a state with associated reward 0, and each grey square an absorbing state with associated reward indicated on the figure. A black square stands for an obstacle.



An agent is moving on this grid, trying to get the best possible reward. To do so, it can choose at any time-step between four actions:

- $a_0$  = going north of its current state
- $a_1$  = going east of its current state
- $a_2$  = going south of its current state
- $a_3$  = going west of its current state

The chosen action has a probability  $p$  to succeed and lead to the expected direction. If it fails it has equal probability to lead to any other direction. For example, if the agent chooses the action  $a_0$  =

going north, it is going to succeed and go north with probability  $p$ , and it has probability  $\frac{1-p}{3}$  to go east, probability  $\frac{1-p}{3}$  to go south and probability  $\frac{1-p}{3}$  to go west.  $p$  is given as a hyperparameter, defining the environment.

If the outcome of action leads the agent to a wall or an obstacle, its effect is to keep the agent at his current place. For example, if the agent chooses the action  $a_1$  = going east and there is a wall east but no wall in the other directions, it is going to stay in place in his current state with probability  $p$  and to go north, south or west with probability  $\frac{1-p}{3}$ .

## Jupyter Notebook

This lab assignment is based on the provided Jupyter Notebook (you can also find it directly on Google Colab: <https://colab.research.google.com/drive/1kSS1Se2cSbqMM2yP6VtkJDrEYjz0zQBx?usp=sharing>), which already defined most of the GridWorld structure. In the following questions, you will be asked to progressively complete the functions of the GridWorld class indicated with the tag "[Action required]".

The Notebook has the following structure:

1. GraphicsGridWorld class definition: allow all the graphical visualisation of the GridWorld. You DO NOT NEED to read or understand this class, you can simply call its methods when needed.
2. Utility function definition: some functions used across all code, you DO NOT NEED to read or understand them.
3. GridWorld class definition: this class is the main GridWorld class, we encourage you to try to understand it, as you will be asked to complete it in the following questions.
4. Questions sections: each question of this lab assignment corresponds to one code block that will allow you to test your code and visualise your results.

## Question 1: Grid World definition

Using the Grid World presentation above, build the environment by implementing the methods:

- `fill_in_transition`
- `fill_in_reward`

## Question 2: Policy evaluation implementation

Fill in the `policy_evaluation` method of the GridWorld class to perform policy evaluation of a given policy in the Grid World environment. Use the example code provided for Question 2 to test your code and visualise your value function.

### Question 3: Impact of gamma on the policy evaluation

Use the example code provided for Question 3 to visualise the impact of the discount factor `gamma` on the policy evaluation algorithm. You can investigate similarly the impact of the `threshold` value, or the initialisation of the policy in the policy evaluation, and the structure of the grid (obstacle localisation, reward values, etc).

### Question 4: Policy iteration implementation

Fill in the `policy_iteration` method of the `GridWorld` class to perform policy iteration and find the optimal policy in the Grid World environment. Use the example code provided for Question 4 to test your code and visualise your value function.

### Question 5: Impact of gamma on the policy iteration

Use the example code provided for Question 5 to visualise the impact of the discount factor `gamma` on the **policy iteration** algorithm. Try to investigate similarly the impact of the other parameters.

### Question 6: Value iteration implementation

Fill in the `value_iteration` method of the `GridWorld` class to perform value iteration and find the optimal policy in the Grid World environment. Use the example code provided for Question 6 to test your code and visualise your value function.

### Question 7: Impact of gamma on the value iteration

Use the example code provided for Question 7 to visualise the impact of the discount factor `gamma` on the **value iteration** algorithm. Try to investigate similarly the impact of the other parameters.