Singular Value Decomposition and

Principal Component Analysis

What's the deal?

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SVD - what is it?

I have a matrix X:

(centred)

p parameters, pixels, dimensions

I want to write it as $X = U\Sigma V^T$

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X is centred = each row of X has had the average row of X subtracted from it

I want to write it as $X = U\Sigma V^T$

SVD - what is it?

I have a matrix X:

(centred)

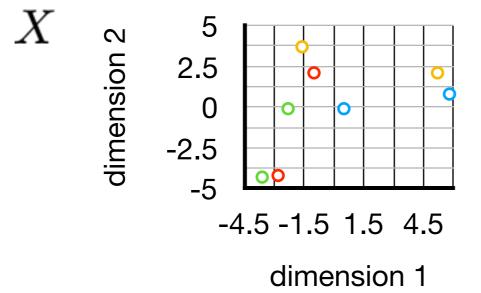
$$p = 2$$
 dimensions

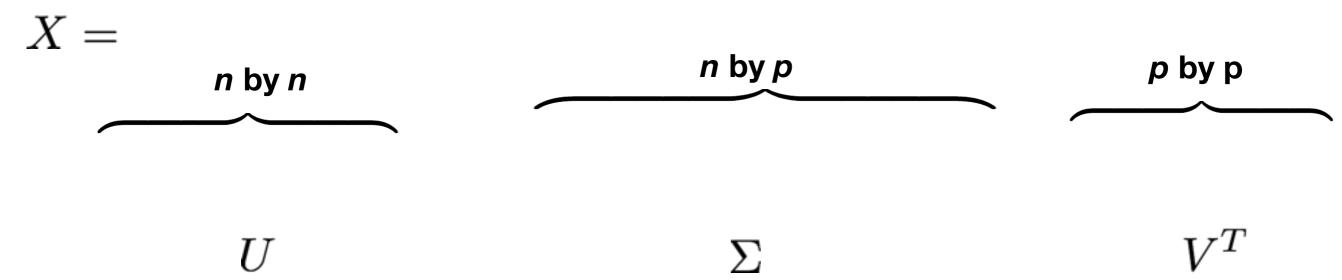
n = 8 pieces of data

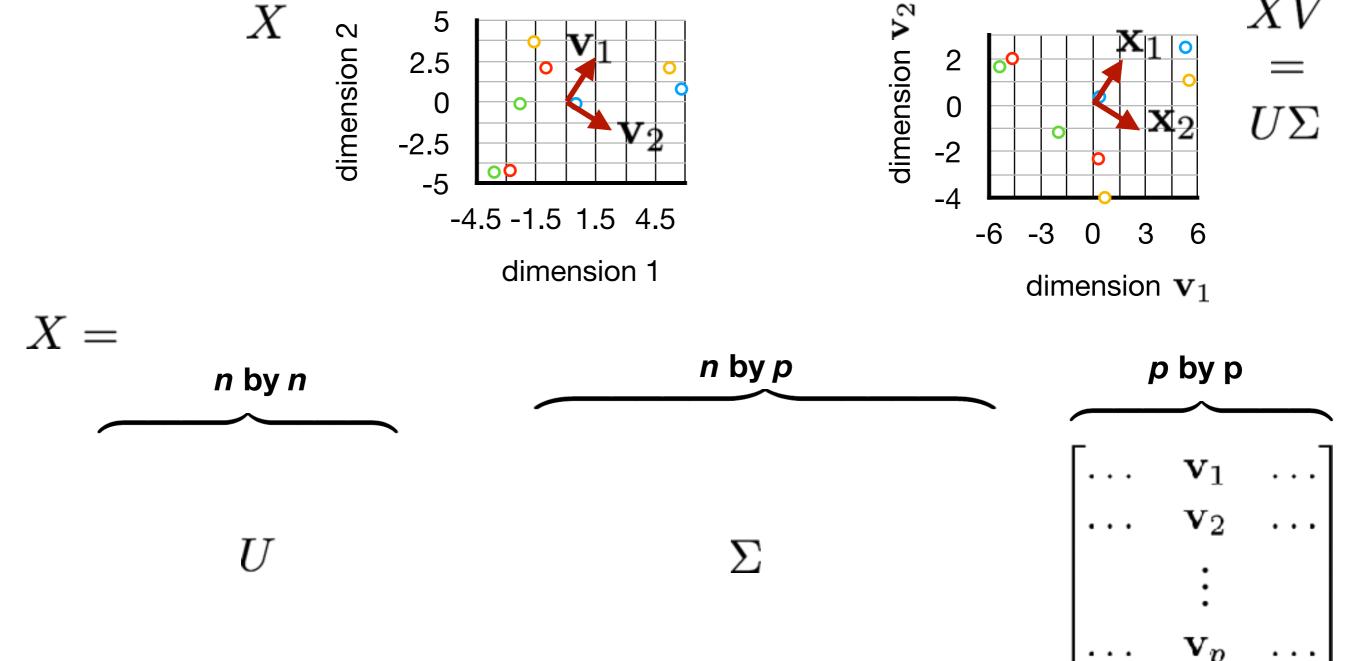
2.5

-4.5 -3 -1.5 0 1.5 3 4.5 6 dimension 1

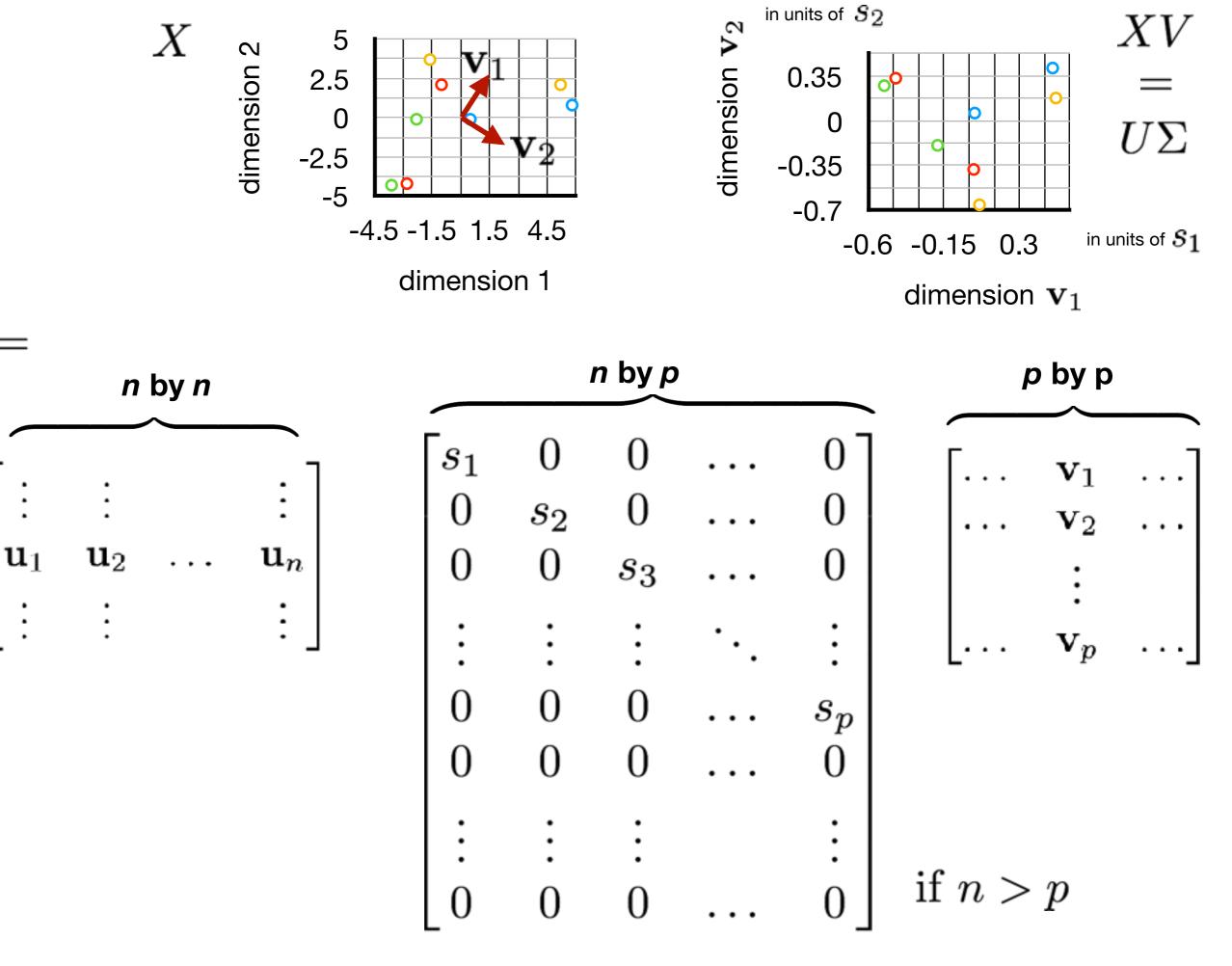
I want to write it as $X = U\Sigma V^T$

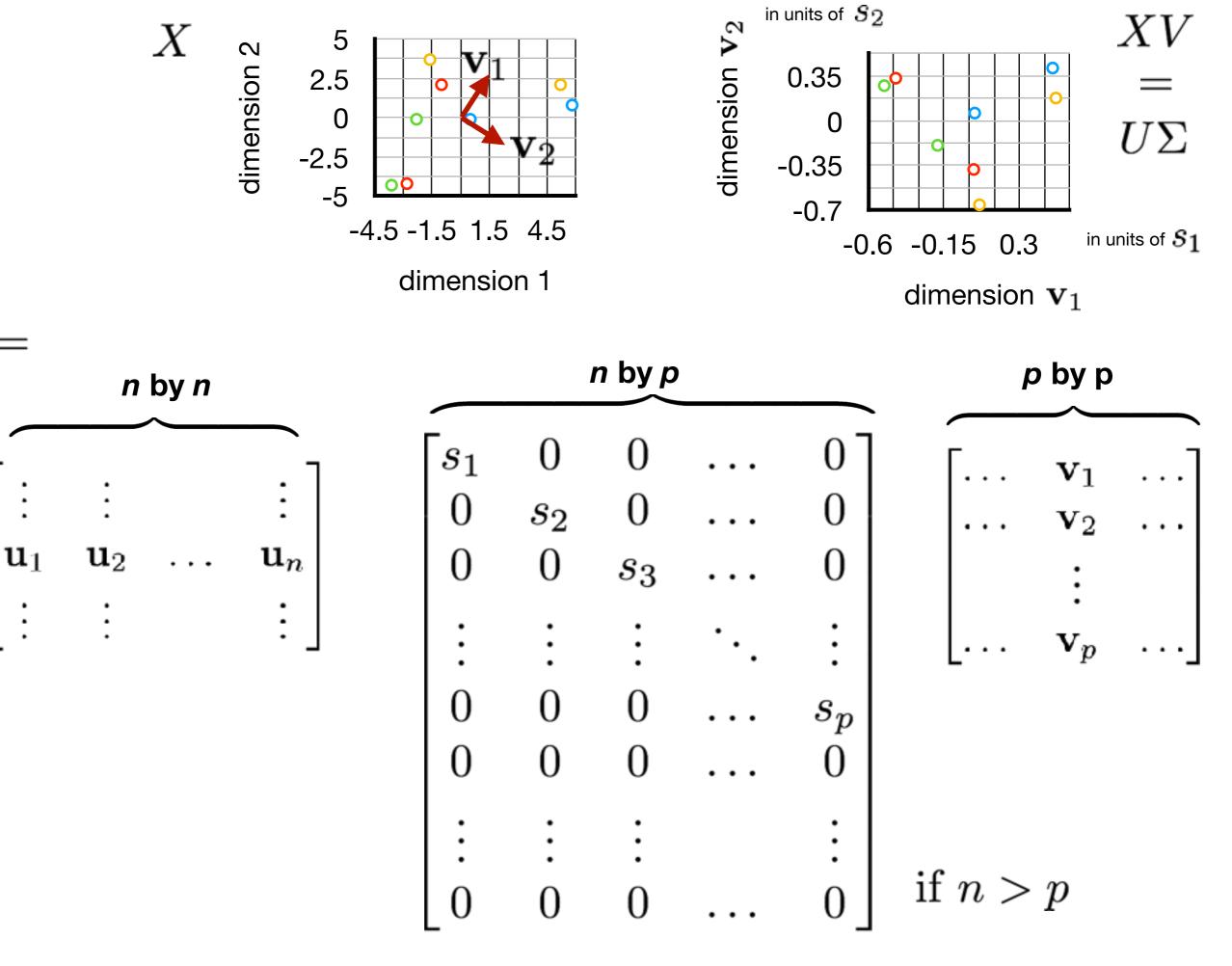


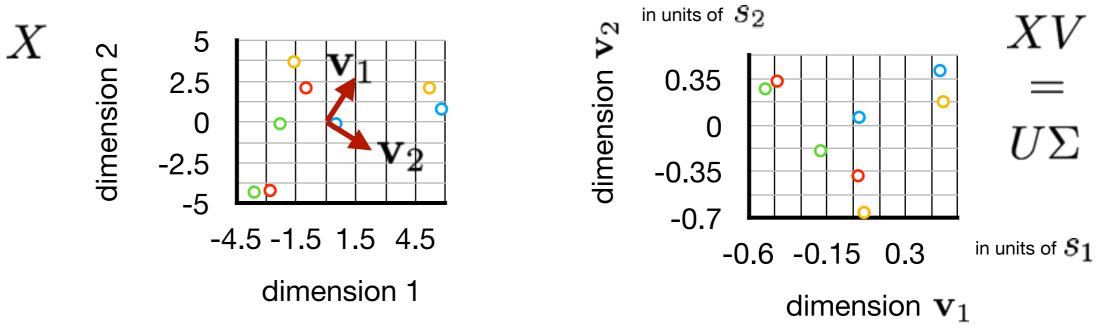




2.5







if
$$p > n$$

I have a matrix X:

(centered)

p parameters, pixels, dimensions

I want to diagonalise its covariance matrix

$$C = \frac{1}{n-1} X^T X$$

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I want to find a new orthonormal coordinate system with

most of the variance along the first axis

•each successive axis having as much as possible of the remaining variance

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I want to find a new orthonormal coordinate system with

most of the data explained along the first axis

•each successive axis explaining as much of the data as possible

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$$C = rac{1}{n-1} X^T X$$
 $p ext{ by p}$
$$= VDV^T$$

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$$\begin{bmatrix} \vdots & \vdots & & & \vdots \\ \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_p \\ \vdots & \vdots & & \vdots \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & 0 & \dots & 0 \\ 0 & \lambda_2 & 0 & \dots & 0 \\ 0 & 0 & \lambda_3 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \lambda_p \end{bmatrix} \begin{bmatrix} \dots & \mathbf{v}_1 & \dots \\ \dots & \mathbf{v}_2 & \dots \\ \vdots & \vdots & \vdots \\ \dots & \mathbf{v}_p & \dots \end{bmatrix}$$

p by p

p by p

$$C = rac{1}{n-1} X^T X$$
 Write X as a singular value decomposition $\mathbf{v} = \mathbf{r}$

$$X = U\Sigma V^T$$

$$C=rac{1}{n-1}X^TX$$
 Write X as a singular value decomposition
$$X=U\Sigma V^T$$

$$C=rac{1}{n-1}(U\Sigma V^T)^T(U\Sigma V^T)$$

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 Write X as a singular value decomposition $X=U$
$$C=rac{1}{n-1}(U\Sigma V^T)^T(U\Sigma V^T)$$

$$=rac{1}{n-1}(V\Sigma^T U^T)(U\Sigma V^T)$$

$$X = U\Sigma V^T$$

$$C=rac{1}{n-1}X^TX$$
 Write X as a singular value decomposition $X=U$ $C=rac{1}{n-1}(U\Sigma V^T)^T(U\Sigma V^T)$

$$X = U\Sigma V^T$$

$$C = \frac{1}{n-1} (U\Sigma V^T)^T (U\Sigma V^T)$$

$$= \frac{1}{n-1} (V \Sigma^T U^T) (U \Sigma V^T)$$

$$= \frac{1}{n-1} V \Sigma^T (U^T U) \Sigma V^T$$

$$U^TU = I$$

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$$=\frac{1}{n-1}V\Sigma^T\Sigma V^T$$

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$$= V\left(\frac{1}{n-1}\Sigma^2\right)V^T$$

$$= VDV^T$$

$$U^T U = I$$

$$C = \frac{1}{n-1} X^T X$$
 Write X as a singular value decomposition

$$X = U\Sigma V^T$$

$$C = \frac{1}{n-1} (U\Sigma V^T)^T (U\Sigma V^T)$$

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So the diagonal matrix D is

$$D = \frac{1}{n-1} \Sigma^2$$

So we can do PCA by SVD

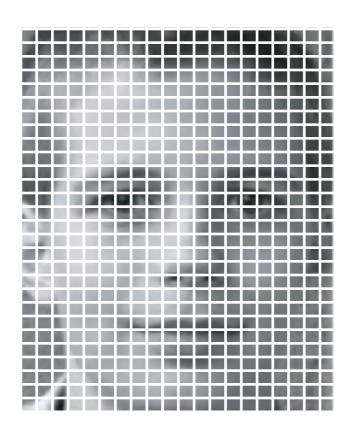
(but we could also do it by directly diagonalising the covariance matrix)

PCA using SVD is more stable against numerical rounding errors

The fastest way to do each on large data sets is probabilistically / stochastically

Example 1: image data compression n= 32 images, p~100,000 pixels





vectorise the image

this becomes row n=1 of X

Example 1: image data compression actual photos



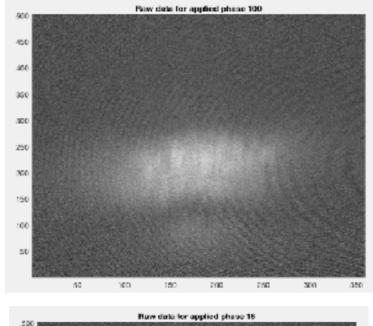
http://people.ciirc.cvut.cz/~hlavac/TeachPresEn/11ImageProc/15PCA.pdf

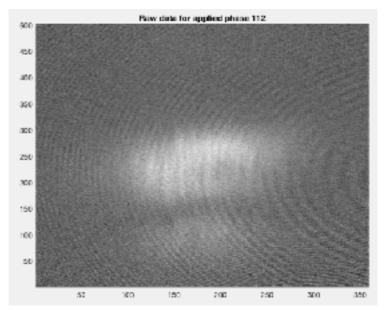
Example 1: image data compression images reconstructed using only first 4 PCs

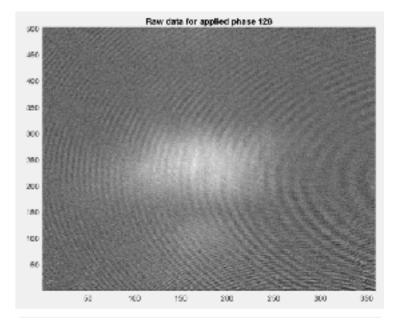


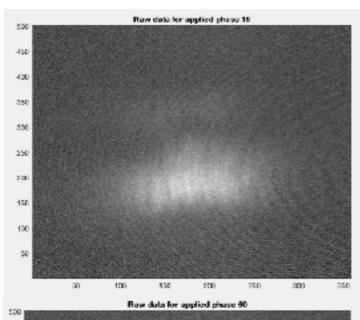
http://people.ciirc.cvut.cz/~hlavac/TeachPresEn/11ImageProc/15PCA.pdf

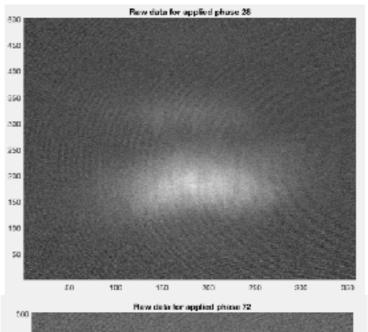
Example 2: images, data extraction

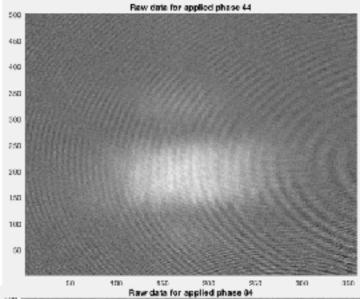


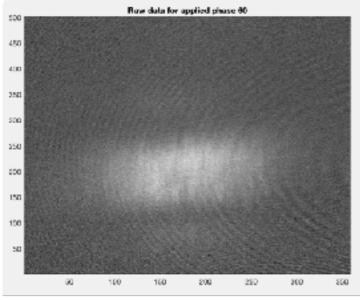


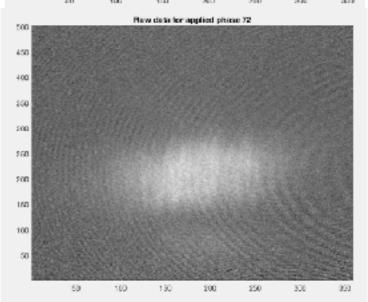


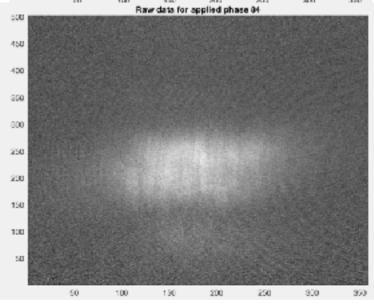


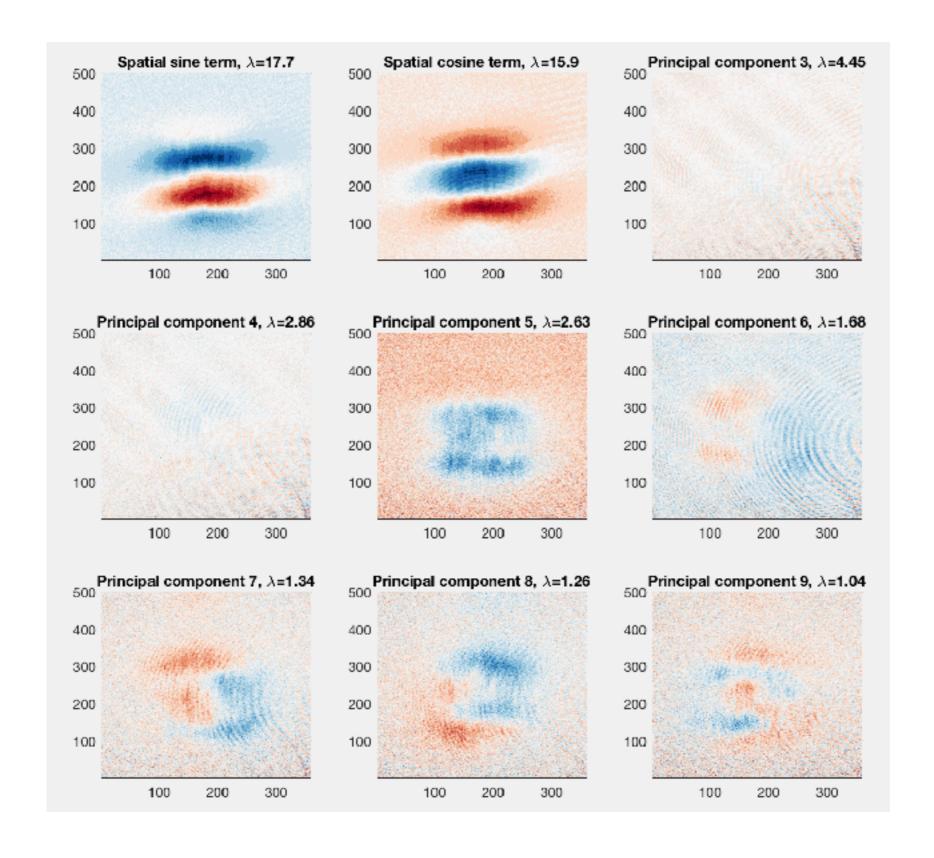


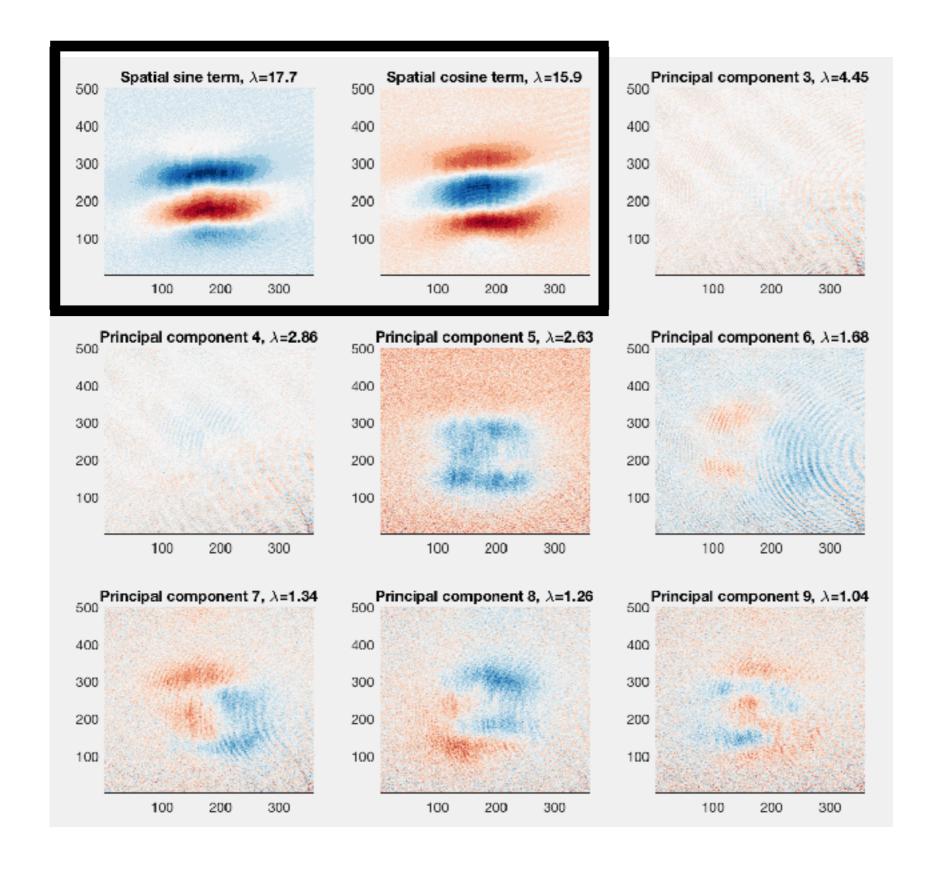




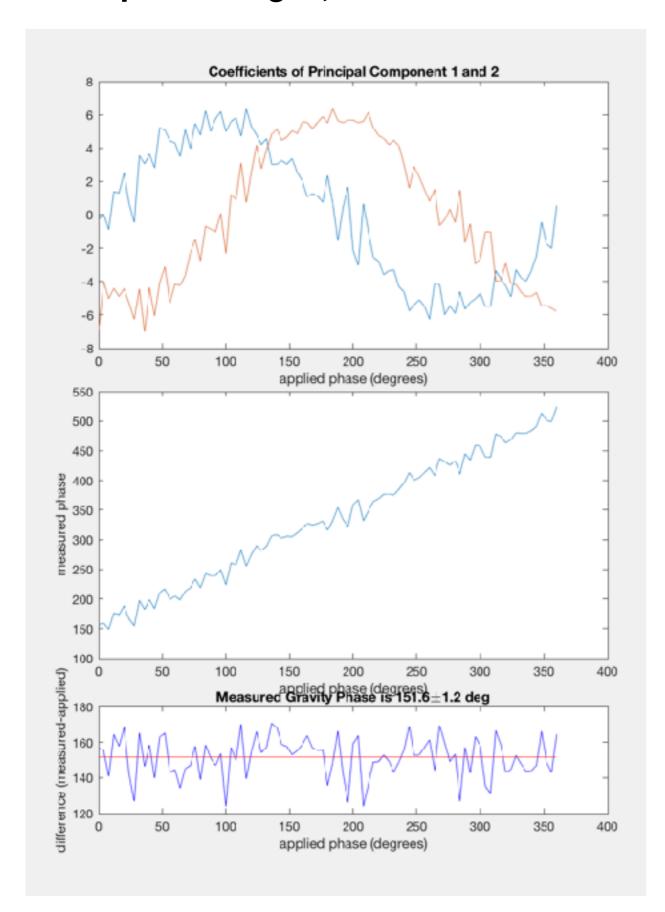




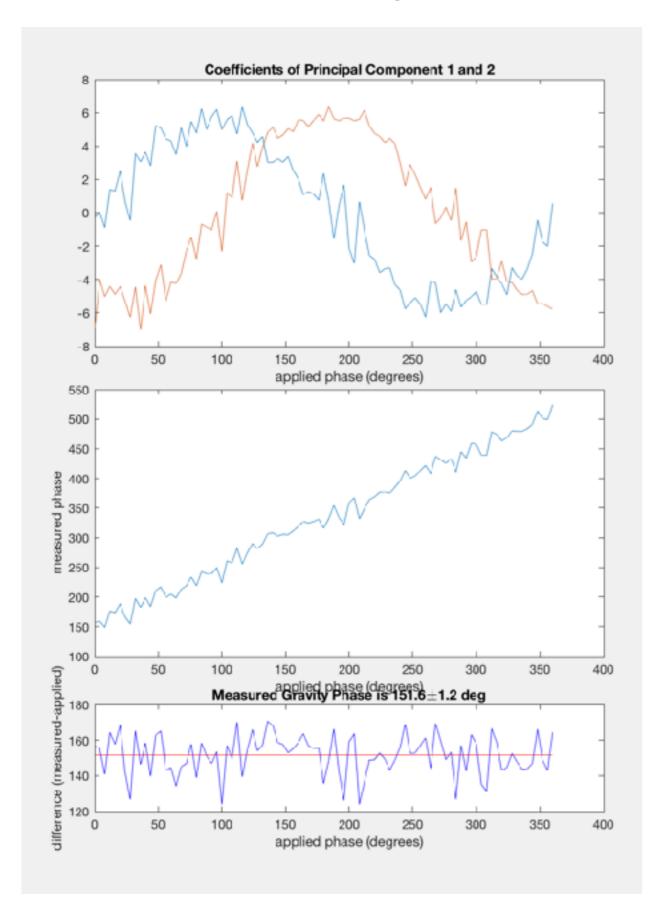


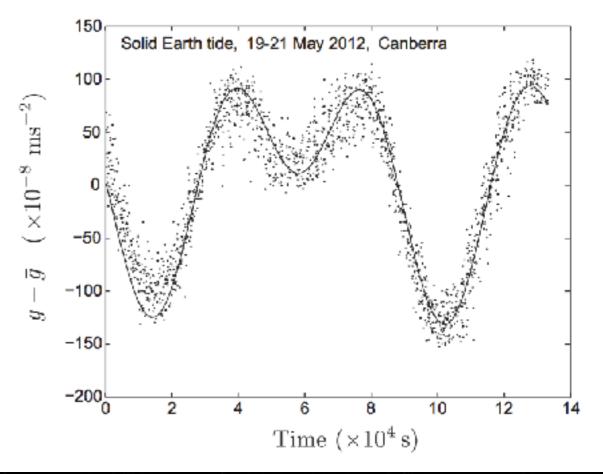


Example 2: images, data extraction



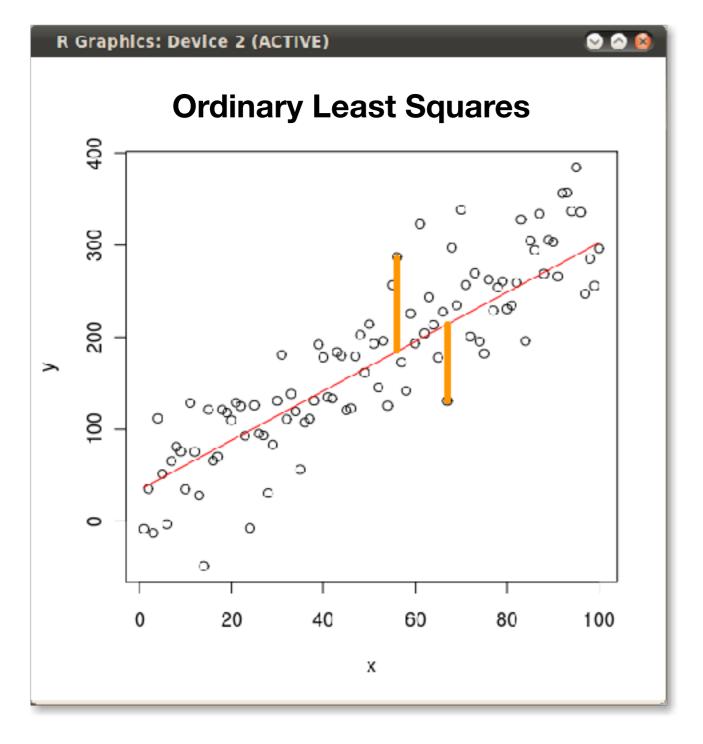
Example 2: images







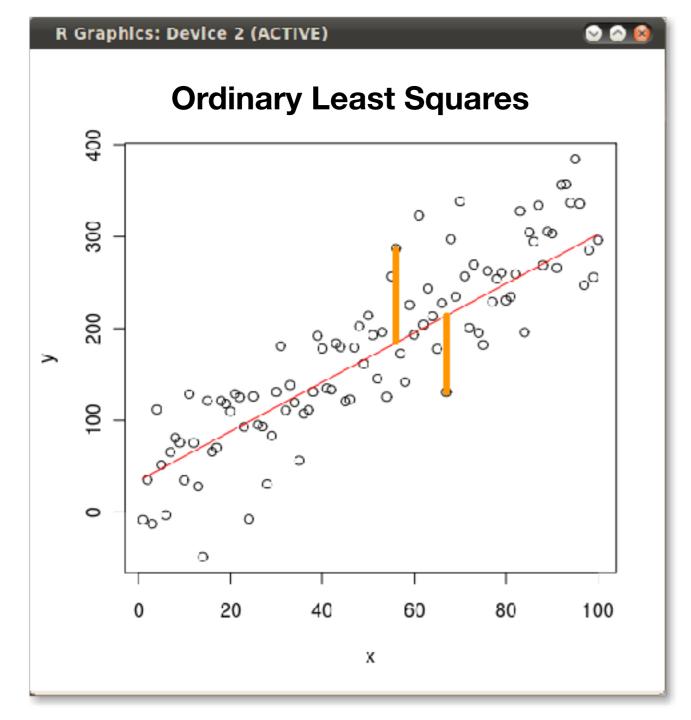
minimize given
$$|y - \hat{y}|^2 \qquad x = \hat{x}$$

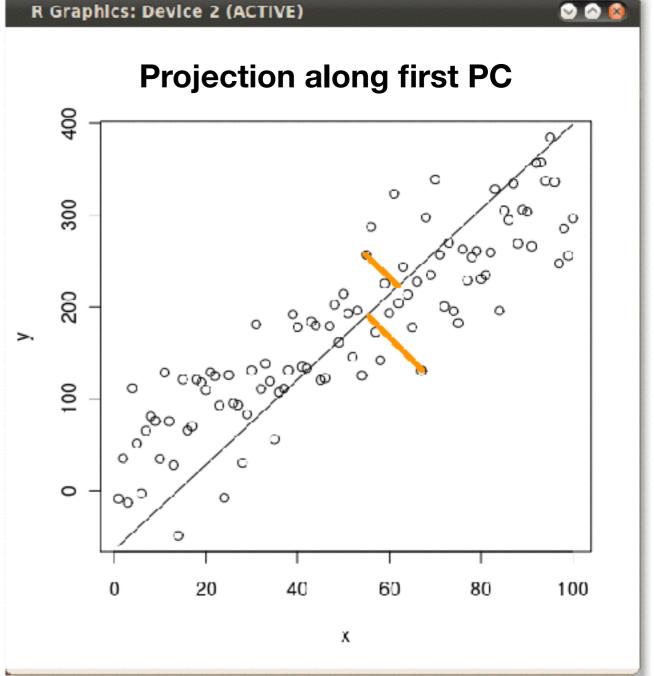


https://www.r-bloggers.com/principal-component-analysis-pca-vs-ordinary-least-squares-ols-a-visual-explanation/

$$\begin{aligned} & \text{minimize} & & \text{given} \\ & \left| y - \hat{y} \right|^2 & & x = \hat{x} \end{aligned}$$

$$\frac{\text{minimize}}{\left|y-\hat{y}\right|^2+\left|x-\hat{x}\right|^2}$$





For more authoritative references, see also:

SVD: D. Lay, Linear Algebra and its Aplications, Chapter 7

PCA: C. Bishop, Pattern Recognition and Machine Learning, Chapter 12

Or for the tl;dr...

https://stats.stackexchange.com/questions/134282/relationship-between-svd-and-pca-how-to-use-svd-to-perform-pca