High-Performance Hardware Implementation of MPCitH and Picnic3

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Abstract. PICNIC is a post-quantum digital signature, the security of which relies solely on symmetric-key primitives such as block ciphers and hash functions instead of number theoretic assumptions. One of the main concerns of Picnic is the large signature size. Although Katz et al.'s protocol (MPCitH-PP) significantly reduces the size of Picnic, the involvement of more parties in MPCitH-PP leads to longer signing/verification times and more hardware resources. This poses new challenges for implementing high-performance Picnic on resource-constrained FPGAs. So far as we know, current works on the hardware implementation of MPCitH-based signatures are compatible with 3 parties only. In this work, we investigate the optimization of the implementation of MPCitH-PP and successfully deploying MPCitH-PP with more than three parties on resource-constrained FPGAs, e.g., Xilinx Artix-7 and Kintex-7, for the first time. In particular, we propose a series of optimizations, which include pipelining and parallel optimization for MPCitH-PP and the optimization of the underlying symmetric primitives. Besides, we make a slight modification to the computation of the offline commitment, which can further reduce the number of computations of Keccak. These optimizations significantly improve the hardware performance of Picnic3. Signing messages on our FPGA takes 0.046 ms for the L1 security level, outperforming PICNIC1 with hardware by a factor of about 5.4, which is the fastest implementation of post-quantum signatures as far as we know. Our FPGA implementation for the L5 security level takes 0.229 ms beating Picnic1 by a factor of 5.4, and outperforming SPHINCS by a factor of 11.

Keywords: FPGA · MPCitH · Picnic · LowMC

1 Introduction

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The emergence of quantum computers presents a potential threat to the security of commonly used cryptographic schemes [Sho94, Gro96]. To address this concern, the US National Institute of Standards and Technology (NIST) is currently undertaking the Standardization Process for Post-Quantum Cryptography (PQC). PICNIC, which has been selected as one of the digital signature candidates in the third round, has attracted significant attention among all the post-quantum candidates of NIST. PICNIC's security does not rely on any number theoretic assumptions but instead solely on symmetric-key primitives, such as block cipher and hash functions. This unique property is made possible by the MPC-in-the-head (MPCitH) paradigm, a novel method for constructing zero-knowledge proofs. MPCitH allows the prover to prove the correctness of a statement without revealing any additional information by simulating the executions of multi-party computation (MPC) protocols. As stated in [Nat20], "NIST also sees PICNIC reliance on only assumptions about symmetric primitives as an advantage in case the need arises for an extremely conservative signature standard in the future".

The early version of Picnic, called Picnic1, suffers from a larger signature size compared to other post-quantum candidates since the proof size of MPCitH is linear with the number of non-linear operations of the underlying block cipher, i.e., LowMC. To overcome this problem, Katz et al. [KKW18] introduced MPCitH with preprocessing

(MPCitH-PP), which reduces the size of Picnic1 dramatically by involving more parties in the MPCitH protocol. The resulting scheme, called Picnic2, allows for a much smaller signature size, but the involvement of more parties leads to longer signing/verification times compared to Picnic1. Moreover, MPCitH-PP in Picnic2 poses new challenges for implementing MPCitH-based digital signatures on hardware, particularly considering the hardware implementation requirements of NIST [AASA+19]. So far as we know, previous works [KRR+20, Wal19] on the hardware implementation of MPCitH-based digital signatures have only implemented signatures with 3 parties. It is challenging to implement high-performance Picnic2 on resource-constrained FPGAs because more parties in Picnic2 increase the running time of signing and verification and significantly impact hardware resources.

Recently, several optimizations [MZ17, MR18, KZ20, KZ22] have been developed for MPCitH-PP, particularly in the case of PICNIC3 [KZ20]. These optimizations improve the linear calculation method in the underlying circuit of MPCitH-PP, resulting in an N-fold increase in linear calculation speed, where N represents the number of parties. While these optimizations provide a promising avenue for implementing digital signatures based on MPCitH-PP for more parties, there is currently a lack of hardware-level implementation of these techniques. It is, therefore, a natural question to ask whether we can deploy MPCitH-PP with more than three parties on a resources-constrained FPGA board, and if so, what the resulting performance of PICNIC would be, as well as any additional limitations that may arise.

1.1 Contributions

In this work, we focus on optimizing the implementation of MPCitH-PP and successfully deploying MPCitH-PP with more than three parties on resource-constrained FPGAs (Xilinx Artix-7 and Kintex-7) for the first time, resulting in significantly improved performance of PICNIC3. We first refine a general gate-level circuit model for MPCitH-PP and apply the linear swapping and optimized mask sampling proposed by Kales et al. [KZ20] to improve the implementation of MPCitH-PP. Building on this, we propose 4 optimizations for the hardware implementation of PICNIC3 so that PICNIC3 can better utilize the resources of the FPGA development board to achieve high-performance implementation.

- Pipelining and parallel optimization. We performed a detailed study of the Picnic3 signature and divided it into three distinct steps. The construction of a Merkel tree is encompassed within the first and third steps, while the second step focuses on the repetitive instantiation of zero-knowledge proofs. To enhance efficiency, we fragmented the second stage into multiple parts and devised a multi-level pipeline structure, resulting in a substantial reduction in time consumption. Furthermore, leveraging the fundamental attributes of FPGA, we orchestrated widespread parallel computing across all three steps.
- Optimization of symmetric primitives. LowMC has a longer critical path, while KECCAK has a shorter critical path. Since the clock cycle of KECCAK is larger than that of LowMC, we investigate the clock cycle and critical path of symmetric primitives. To design an optimized version for a high-performance implementation of digital signatures, we reduce KECCAK's clock cycles so that its critical path does not exceed (or slightly exceed) that of LowMC.
- Extending the pipeline construction covering the first and third steps. The Merkel Tree needs to be stored in the BRAM. We precompute the nodes from the root to the second-to-last layer and store them. For each instance, only the last leaf nodes are needed to compute, which has a similar time interval to that of the pipeline in step 2. For step 3, two independent Keccak components with optimized critical

- paths are incorporated into the pipeline in step 2 to save the running time of $\mathcal{O}(M)$ KECCAK, where M is the number of instances.
- To further reduce the number of computations of KECCAK, we make a slight modification on the computation of the final offline commitment, which does not affect the security of the KKW protocol and Picnic3.

By combining all the above optimizations, our FPGA implementation of PICNIC3 achieves significantly improved performance. Concretely, signing messages on our FPGA takes 0.046 ms for the L1 security level beating PICNIC3 with software by a factor of about 110, and outperforming PICNIC1 with hardware by a factor of about 5.4, which is the fastest implementation of post-quantum signatures seen Table 10. Our FPGA implementation for the L5 security level takes 0.229 ms beating PICNIC1 by a factor of 5.4, and outperforming the NIST selected signature SPHINCS by a factor of 11.

1.2 Related Work

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The MPCitH paradigm has seen significant advancements since Ishai et al.'s work [IKOS07]. Notably, ZKBoo [GMO16] and ZKB++ [CDG⁺17] have significantly advanced the practicality of MPCitH, culminating in the submission of PICNIC1 to Round 1 of the NIST PQC Standardization Process. Katz et al. [KKW18] extended the paradigm to MPCitH-PP, leading to PICNIC2. Furthermore, Kales et al. [KZ20] optimized the structure of LowMC [ARS⁺15] utilized in PICNIC2 and reduced the time required for signature generation and verification, resulting in the development of PICNIC3.

Efficient hardware implementations have become a focal point of extensive research, further accentuated by the NIST post-quantum standardization project [AASA+19]. On the hardware implementations of MPCitH or PICNIC algorithms, only PICNIC1 is currently available in a hardware-enable format [KRR+20]. In the case of PICNIC1, the utilization of FPGA resources is exceedingly substantial. [KRR+20] argues that PICNIC2 allows for shorter signatures, but performing the simulated MPC protocol with a larger number of parties results in longer signing and verification times compared to PICNIC1. [Wal19] proposed an efficient VHDL implementation of PICNIC2, therefore, requires at least 63 LowMC instances which would not fit on any FPGA. Implementing the MPCitH-PP digital signature, involving more parties and requiring pre-computation, becomes challenging to deploy on a resource-constrained FPGA. PICNIC3 introduces optimizations to the LowMC computation of MPCitH-PP, thereby reducing the calculation of the linear layer. To the best of our knowledge, no prior work has investigated the hardware implementations of MPCitH-PP and PICNIC3.

2 Preliminaries

Notation. Let L denote an NP language. The NP relation is defined as $R(\mathbf{x}, \mathbf{w}) = 1$ if $x \in L$ and \mathbf{w} is the corresponding witness. Let [x] denote an N-out-of-N (XOR-based) secret sharing scheme of a bit x, i.e., $x = [x]_1 \oplus \cdots \oplus [x]_i \oplus \cdots \oplus [x]_N$, where $[x]_i$ for $1 \leq i \leq N$ is the secret share. Let [i,j] denote the range from integers i to j.

2.1 Symmetric Primitives

The underlying symmetric primitives of Picnic3 are block cipher and hash function, which are instantiated by LowMC and SHAKE, respectively.

Block cipher. LowMC [ARS+15] is a family of lightweight SPN-based block ciphers.
One of the key advantages of LowMC is its low multiplicative complexity, e.g., small
AND gate/depth. This property makes LowMC well-suited for a range of cryptographic

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applications, including multi-party computation, fully homomorphic encryption, and zero-139 knowledge proofs. LowMC encryption starts with an initial whitening by XORing the 140 first round key to the plaintext, followed by r rounds. As depicted in Figure 1, one round consists of four steps: (i) SBOXLAYER, (ii) LINEARLAYER, (iii) CONSTANTADDITION and 142 (iv) KEYADDITION, i.e., 143

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LowMCRound(i) = KeyAddition
                  • Constant Addition
                  \circ Linear Layer \circ Sbox Layer (i).
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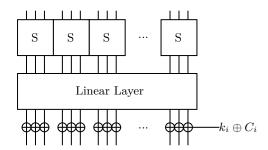


Figure 1: One round of encryption with LowMC in Picnic3.

In the SBOXLAYER, m 3-bit Sboxes are typically applied to the initial $3 \cdot m$ bits of the state. The SBOXLAYER does not modify the remaining bits of the state. Note that in PIC-NIC3, the parameter n is set to $3 \cdot m$ in order to decrease the number of rounds r. The specific parameters [Pic20] are $(n, k, m, r) \in \{(129, 129, 43, 4), (192, 192, 64, 4), (255, 255, 85, 4)\}$, where k denotes the key size. Shox is defined as

$$S(a,b,c) = (a \oplus b \cdot c, a \oplus b \oplus a \cdot c, a \oplus b \oplus c \oplus a \cdot b)$$

with three bits inputs and outputs. In LINEARLAYER, the state is multiplied with a pseudorandomly generated matrix $L_i \in \mathbb{F}_2^{n \times n}$. The matrices are chosen pseudorandomly from the set of all invertible binary $n \times n$ matrices during the instantiation of LowMC. During Constant Addition the vector $C_i \in \mathbb{F}_2^n$ is XORed to the state. During KEYADDITION, the round key of the current round is XORed to the state. All round keys are generated as a result of the multiplication of the master key with the matrix $K_i \in \mathbb{F}_2^{n \times k}$. The matrices are chosen pseudorandomly from the set of all full-rank binary $n \times k$ matrices during the instantiation of LowMC. The full description of the encryption algorithm is given in Algorithm 1.

Algorithm 1: LowMC encryption.

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Input: plaintext p \in \mathbb{F}_2^n and key mk \in \mathbb{F}_2^k
   Output: ciphertext c \in \mathbb{F}_2^n.
1 state \leftarrow K_0 \cdot mk + p
2 foreach i \in [1, r] do
       state \leftarrow SboxLayer(state)
       state \leftarrow L_i \cdot state
4

▷ LINEARLAYER

       state \leftarrow C_i + state
                                                                             state \leftarrow K_i \cdot mk + state
                                                                                     ▶ KEYADDITION
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  end
8 c \leftarrow state
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Hash function. Hash functions in Picnic are used to generate randomness and commitments. In Picnic2, hash functions are employed to expand a random "seed" into additional randomness using a tree construction, and to create a Merkle Tree of the committed values. Picnic3 uses the SHA-3 function SHAKE for all hashing, with specific parameters detailed in Table 1. For more information of SHAKE, we refer the reader to Keccak.

Table 1: Parameters of Keccak. Block length denotes the bit number absorbed or squeezed. Round denotes the number of repeat permutation Keccak-p.

Scheme	Sec. Level	Block Length	Digest Length	Round
SHAKE128	L1	1344	256	24
SHAKE256	L5	1088	512	24

2.2 MPC-in-the-head with Preprocessing

MPC-in-the-head proposed by Ishai et al. [IKOS07] provides a novel method to construct zero-knowledge proof (ZKP) for any NP language L. In this paper, we consider the relation $R(\mathbf{x}, \mathbf{w})$ as $f_{\mathbf{x}}(\mathbf{w}) = 1$ for a function f. An MPCitH proof system (P, V) is built upon an N-party MPC protocol that jointly computes the function f. Here, f takes \mathbf{x} and \mathbf{w} as the public and private inputs, respectively, and computes $f_{\mathbf{x}}(\mathbf{w}) = R(\mathbf{x}, \mathbf{w})$. In PICNIC, $f_{\mathbf{x}}(\mathbf{w}) := \text{LowMC}(sk, p) \stackrel{?}{=} c$, where $\mathbf{x} = (p, c)$ represents a plaintext-ciphertext pair and $\mathbf{w} = sk$ denotes the private key. In this case, the prover P proves knowledge of a private key that generates a specific public ciphertext from the corresponding public plaintext.

At a high level, the MPCitH prover P aims to convince the verifier V that they possess a valid witness \mathbf{w} by demonstrating that the MPC protocol has been correctly executed "in the head" of P using input w. To enhance compatibility with hardware implementation and Picnic3 signatures, we utilize boolean circuits instead of arithmetic circuits for LowMC. We now consider an MPC protocol Π_C for the corresponding circuit C defined over the field \mathbb{F}_2 , where the statement information \mathbf{x} (e.g., the plaintext-ciphertext pair) is hard-coded such that $C(\cdot) = f_{\mathbf{x}}(\cdot)$. We assume that the witness can be represented as an n-dimensional vector and C takes a set of n input wires denoted by IN. Let z_{α} denote the value of wire α of C(w), then $\mathbf{w} = (z_{\alpha})_{\alpha \in \mathbb{IN}} \in \mathbb{F}_{2}^{n}$ be the input of C. To initiate the protocol, the prover P first additively secret shares each input z_{α} as $z_{\alpha} = [z_{\alpha}]_1 \oplus \cdots \oplus [z_{\alpha}]_N$ in \mathbb{F}_2 . Each share $[z_{\alpha}]_i$ is considered as a private input to party P_i . Then, prover P internally runs Π_C for party P_1, \dots, P_N to obtain the views V_1, \dots, V_N , where view V_i consists of P_i 's private input $[z_{\alpha}]_i$, the random tape of P_i , and all incoming messages observed by P_i during the execution of Π_C . The proof system now follows the typical "commit-challenge-response" flow (Σ -protocol [FS87]). Using a secure commitment scheme, P sends $Commit(V_i)$ as the first message for all $i \in [1, N]$. Upon receiving distinct challenges $i_1, \dots, i_t \in [1, N]$ from the verifier V, the prover P responds with the corresponding t views V_{i_1}, \dots, V_{i_t} and the commitment opening information. Finally, the verifier V accepts the proof if and only if the opened views are consistent with each other and they result in an output of 1 from the protocol Π_C . The (honest verifier) zero-knowledge property is guaranteed if the underlying MPC Π_C achieves t-privacy in the semi-honest model.

MPCitH with preprocessing (MPCitH-PP). Katz et al. [KKW18] improved the MPCitH paradigm by using the preprocessing mode. Further improvements can be found in subsequent works [dSGDMOS20, BN20, BdSGK⁺21, KZ20, KZ22, ZWX⁺22]. Loosely speaking, Katz et al.'s protocol (KKW) has two phases, which are the *offline* phase (preprocessing phase) and the *online* phase. We denote Π_{C}^{off} and Π_{C}^{off} as the offline phase

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protocol and the online phase protocol, respectively. The offline phase protocol Π_C^{off} , which is executed independently of the witness, prepares the randomness for the online phase protocol Π_C^{on} . Considering the application in Picnic3, the following descriptions of the MPC protocol and KKW protocol are based on boolean circuits.

Suppose the underlying N-party MPC protocol is Π_C , which is executed by N parties P_1, \dots, P_N . The value of each input wire z_{α} will be masked by a random bit λ_{α} , say, $\hat{z}_{\alpha} = z_{\alpha} \oplus \lambda_{\alpha}$. Each party P_i holds a share of λ_{α} , denoted by $[\lambda_{\alpha}]_i$.

- Offline phase Π_C^{off} . In the offline phase, the prover generates the masks for each party P_i . More precisely, P_i is given the following values.
 - $[\lambda_{\alpha}]_i$ for each input wire α .
 - $[\lambda_{\gamma}]_i$ for the output wire γ of each AND gate.
 - $[\lambda_{\alpha,\beta}]_i$ for each AND gate with input wires α and β such that $\lambda_{\alpha,\beta} = \lambda_\alpha \cdot \lambda_\beta$.

For $i=1,\cdots,N-1$, $[\lambda_{\alpha}]_i$, $[\lambda_{\gamma}]_i$ and $[\lambda_{\alpha,\beta}]_i$ are generated using a pseudorandom generator (PRG) with a random seed \mathbf{seed}_i . Besides, $[\lambda_{\alpha}]_N$, $[\lambda_{\gamma}]_N$ are generated by PRG with a random seed \mathbf{seed}_N . Here $[\lambda_{\alpha}]_1 \oplus \cdots \oplus [\lambda_{\alpha}]_N = \lambda_{\alpha}$, $[\lambda_{\gamma}]_1 \oplus \cdots \oplus [\lambda_{\gamma}]_N = \lambda_{\gamma}$. Notice that $[\lambda_{\alpha,\beta}]_N$ cannot be generated using \mathbf{seed}_N due to $\lambda_{\alpha,\beta} = \lambda_{\alpha} \cdot \lambda_{\beta}$. Actually, $[\lambda_{\alpha,\beta}]_N := \lambda_{\alpha}\lambda_{\beta} \oplus [\lambda_{\alpha,\beta}]_1 \oplus \cdots [\lambda_{\alpha,\beta}]_{N-1}$, which plays the role of "correction bits". In order to reduce the total proof size, it is feasible that \mathbf{seed}_i is given to P_i , and \mathbf{seed}_N and $\mathbf{aux}_N = [\lambda_{\alpha,\beta}]_N$ are given to P_N .

- Online phase $\Pi_C^{\mathbf{on}}$. During the online phase, each party P_i evaluates the circuit C gate-by-gate in topological order. For each gate with input wires α and β and output wire γ ,
 - For an XOR gate, P_i can locally compute $\hat{z}_{\gamma} = \hat{z}_{\alpha} \oplus \hat{z}_{\beta}$ and $[\lambda_{\gamma}]_i = [\lambda_{\alpha}]_i \oplus [\lambda_{\beta}]_i$, since P_i already holds \hat{z}_{α} , $[\lambda_{\alpha}]_i$, \hat{z}_{β} and $[\lambda_{\beta}]_i$.
 - For an AND gate, P_i locally computes $[s]_i = \hat{z}_{\alpha} [\lambda_{\beta}]_i \oplus \hat{z}_{\beta} [\lambda_{\alpha}]_i \oplus [\lambda_{\alpha,\beta}]_i \oplus [\lambda_{\gamma}]_i$, publicly reconstructs $s = [s]_0 \oplus \cdots \oplus [s]_N$, and computes $\hat{z}_{\gamma} = s \oplus \hat{z}_{\alpha} \hat{z}_{\beta}$ which satisfies $\hat{z}_{\gamma} = z_{\gamma} \oplus \lambda_{\gamma} = z_{\alpha} z_{\beta} \oplus \lambda_{\gamma}$. Note that party P_i holds $[\lambda_{\alpha,\beta}]_i$ and $[\lambda_{\gamma}]_i$ in addition to \hat{z}_{α} , $[\lambda_{\alpha}]_i$, \hat{z}_{β} and $[\lambda_{\beta}]_i$ for each AND gate.

KKW Protocol. We briefly recall the basic framework of KKW for one MPC instance, which is a three-round MPCitH-PP system. In Figure 2, we provide a complete description of the KKW proof system that utilizes multiple instances in parallel to achieve a negligible soundness error. The parameter M describes the number of repetitions of MPCitH-PP required to reduce the soundness error to the desired security level. The parameter τ is the opened execution in MPCitH with preprocessing, and N is the number of parties.

- Commit. The prover P begins by sampling a random seed for each P_i and executes protocol Π_C^{off} to obtain the states of all N parties. Then, using these states and the masked witness $(\hat{z}_{\alpha})_{\alpha \in \text{IN}}$ as input, P executes protocol Π_C^{on} to obtain all broadcast messages observed during the online phase. P computes commitments to the states and broadcast messages. Finally, P sends commitments to the verifier V.
- Challenge. V asks P to disclose either the offline or the online phase. In the case of the latter, V also randomly selects a party index p^* , whose view should remain hidden.
- Response. To disclose the offline phase, P sends all random seeds used during protocol Π_C^{off} . To disclose the online phase, P sends the broadcast messages from party P_{p^*} during protocol Π_C^{on} , as well as all the state information of the remaining N-1 parties.

• Verification. To verify the offline phase, V simply uses the random seeds to execute protocol Π_C^{off} as P would, resulting in the states of all N parties. Then, V checks if these states correctly match the commitments of the offline phase. To verify the online phase, V simulates protocol Π_C^{on} with the broadcast messages from P_{p^*} and the states of the other N-1 parties as input, obtaining the broadcast messages from the other N-1 parties. Finally, V checks if these broadcast messages correctly match the commitments of the online phase.

2.3 Picnic and Its Parameters

Using the well-known Fiat-Shamir transform, KKW described above can be transformed into a non-interactive version or a digital signature, where the message m to be signed is hashed and incorporated as the challenge. The signature scheme PICNIC is a concrete instantiation of the non-interactive KKW, where C is instantiated with the boolean circuit of LowMC. More precisely, the signer's secret key sk is the witness \mathbf{w} , and the public key corresponds to the statement $\mathbf{x} = (p, c)$, which is a pair of plaintext and ciphertext. A signature involves a proof of knowledge of sk that satisfies LowMC $_{sk}(p) = c$.

The parameter sets for the algorithms submitted to the NIST competition must meet one of five security levels. Picnic defines parameters for security levels L1, L3 and L5, corresponding to the security of AES 128, 192 and 256, respectively. This work implements the L1 and L5 versions of Picnic3. The corresponding parameters (n, k, m, r) for LowMC in L1 and L5 are (129, 129, 43, 4) and (255, 255, 85, 4), respectively. Table 2 shows the parameters of different Picnic versions. Note that Picnic3 (based on KKW) offers better efficiency in terms of signature size compared to Picnic1 (based on ZKB++), but it has lower runtime performance. Additionally, Table 2 shows the different key and signature sizes for the Picnic instances. Given that our Picnic3 implementation involves four parties, a search for appropriate parameters has been conducted. Two versions have been constructed for each security level: the *fast* version, featuring the minimum number of instances, and the *short* version, designed to optimize signature size. More details of parameter sets for the ZKB++ proof system, KKW proof system, and specific parameters chosen for LowMC are shown in the Picnic specification and NIST submission [Pic20].

1a	ble 2:	PICNI	ic pai	ramet	ers.	
Scheme	Par	amet	ers	Si	izes (byte)
Scheme	M	au	N	pk	$\mathbf{s}\mathbf{k}$	σ
PICNIC1-L1	219	219	3	32	16	34032
Picnic3-L1	206	66	4	34	17	19573
Picnic3-L1	252	36	16	34	17	12590
PICNIC1-L5	438	438	3	64	32	132856
Picnic3-L5	401	133	4	64	32	75721
Picnic3-L5	604	68	16	64	32	53274

Table 2: PICNIC parameters

2.4 Test Platform

To facilitate better comparisons with previous work [KRR⁺20], we utilized the Xilinx Kintex-7 and Artix-7 as our experimental platforms. The latter is one of the optimization platforms recommended by NIST. We use a Xilinx Kintex-7 FPGA which has 298600 lookup-tables (LUTs), and 597200 flip-flops (FFs) available. Moreover, we make all of our code and results publicly available at https://anonymous.4open.science/r/CHES2024-64F9/.

KKW protocol

The prover and verifier receive circuit C as a statement, and the prover holds a witness $\mathbf{w} = (z_{\alpha})_{\alpha \in \text{IN}}$ such that $C(\mathbf{w}) = 1$. Values (M, N, τ) are parameters of the protocol. Let H denote a hash function, which can be modeled as the random oracle.

Commit

- 1. The prover chooses uniform random values ($\mathbf{seed}_1^*, \cdots, \mathbf{seed}_M^*$). For each $j \in [1, M]$, the prover:
 - (a) Use \mathbf{seed}_{j}^{*} to generate $\mathbf{seed}_{j,1}, \dots, \mathbf{seed}_{j,N}$. Compute $\mathbf{aux}_{j} \in \{0,1\}^{|C|}$ by running the offline phase of MPC Π_{C}^{off} . For $i = 1, \dots, N-1$, let $\mathbf{state}_{j,i} := \mathbf{seed}_{j,i}$. Let $\mathbf{state}_{j,N} := \mathbf{seed}_{j,N} \|\mathbf{aux}_{j}$.
 - (b) Commit to the offline phase: For $i \in [1, N]$, compute $\mathbf{com}_{j,i} := \mathrm{H}(\mathbf{state}_{j,i})$. Compute $\mathbf{com}\text{-}\mathrm{off}_j := \mathrm{H}(\mathbf{com}_{j,1}, \cdots, \mathbf{com}_{j,N})$.
 - (c) Simulate the online phase of MPC Π_C^{on} using $\{\mathbf{state}_{j,i}\}$, beginning by computing the masked witness $\{\hat{z}_{j,\alpha}\}$, where $\alpha \in \text{IN}$. Let $\mathbf{msgs}_{j,i}$ denote the messages broadcast by party P_i in this protocol execution.
 - (d) Commit to the online phase: Compute $\mathbf{com}\text{-}\mathbf{on}_{j} := \mathrm{H}\left(\left\{\hat{z}_{j,\alpha}\right\}, \mathbf{msgs}_{j,1}, \cdots, \mathbf{msgs}_{j,N}\right).$
- 2. Compute $h_{\text{off}} = H(\mathbf{com}\text{-}\mathrm{off}_1, \cdots, \mathbf{com}\text{-}\mathrm{off}_M)$ and $h_{\text{on}} = H(\mathbf{com}\text{-}\mathrm{on}_1, \cdots, \mathbf{com}\text{-}\mathrm{on}_M)$. Send $h^* = H(h_{\text{off}}, h_{\text{on}})$ to the verifier.

Challenge The verifier sends the challenge: $(\mathcal{C}, \mathcal{P})$, where $\mathcal{C} \subset [1, M]$ is a set of size τ , and \mathcal{P} is a list $\left\{p_j^{\star}\right\}_{j \in \mathcal{C}}$ with $p_j^{\star} \in [1, N]$.

Response For each $j \in [1, M] \setminus \mathcal{C}$, the prover seeds $\mathbf{seed}_{j}^{*}, \mathbf{com}\text{-on}_{j}$. Also, for each $j \in \mathcal{C}$, the prover seeds $\{\mathbf{state}_{j,i}\}_{i \neq p_{j}^{*}}, \{\hat{z}_{j,\alpha}\}, \{\hat{z}_{j,$

Verification The verifier accepts iff all the following checks succeed:

- 1. Check the offline phase:
 - (a) For every $j \in \mathcal{C}$ and $i \neq p_j^*$, the verifier uses $\mathbf{state}_{j,i}$ to compute $\mathbf{com}_{j,i}$ as the prover would. Then compute $\mathbf{com}\text{-off}_j = \mathrm{H}\left(\mathrm{com}_{j,1}, \cdots, \mathrm{com}_{j,N}\right)$ using the received value com_{j,p_j^*} .
 - (b) For every $j \in [1, M] \setminus \mathcal{C}$ the verifier uses \mathbf{seed}_j^* to compute \mathbf{com} -off_j as the prover would.
 - (c) The verifier computes $h_{\text{off}} = H(\mathbf{com}\text{-off}_1, \cdots, \mathbf{com}\text{-off}_M)$.
- 2. Check the online phase:
 - (a) For $j \in \mathcal{C}$ the verifier simulates the online phase using $\{\mathbf{state}_{j,i}\}_{i \neq p_j^*}$, masked witness $\{\hat{z}_{j,\alpha}\}$, where $\alpha \in \text{IN}$ and $\mathbf{msgs}_{j,i}$ to compute $\{\mathbf{msgs}_{j,i}\}_{i \neq p_j^*}$. Then compute $\mathbf{com}\text{-}\mathrm{on}_j$ as if the prover would do.
 - (b) The verifier computes $h_{\text{on}} = \text{H}(\mathbf{com}\text{-}\text{on}_1, \cdots, \mathbf{com}\text{-}\text{on}_M)$ using the received $\mathbf{com}\text{-}\text{on}_j$ for $j \in [1, M] \setminus \mathcal{C}$.
- 3. The verifier checks that $H(h_{\text{off}}, h_{\text{on}}) \stackrel{!}{=} h^*$.

Figure 2: KKW proof system for a boolean circuit C.

3 Optimizing the Implementation of MPCitH-PP

For typical MPC protocols, communication among parties is not required to compute the linear operations. Hence, there are lightweight nonlinear gates with expensive linear operations for the cryptography primitive in MPC. However, in MPCitH-PP, the linear operations may be too resource-intensive to implement on lightweight FPGA, and determining the length of the critical path can be time-consuming, as the prover needs to simulate computations for N parties. Hence, great attention must also be paid to linear operations in the MPCitH-PP protocol. There are already many techniques [MZ17, MR18, KZ20, KZ22] to optimize linear operations, including the software implementation of Picnic3. We describe a circuit model for conveniently presenting the essential performance of these techniques at the hardware level.

Circuit model. To facilitate the explanation of the hardware level performance of these optimizations, the underlying circuit is abstracted into a structure where linear and nonlinear layers alternate. For the sake of simplicity, the linear layer and the nonlinear layer in Figure 3 are assumed to consist of multiple XOR and AND gates, respectively, with the linear layer exhibiting invertible.

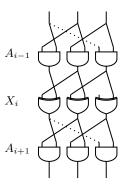


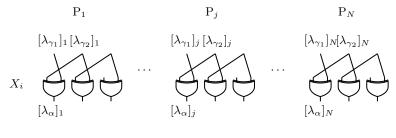
Figure 3: 3 layers of a general circuit.

Optimize the offline phase. Let λ_{α} and λ_{β} be two input masks of an AND gate in a non-linear layer, and λ_{γ} is the output mask. Each party obtains λ_{γ} by sampling for all AND gates. λ_{α} and λ_{β} of layer A_{i+1} are then calculated using the obtained λ_{γ} of layer A_{i-1} through the linear layer X_i . In the offline phase, the goal of Π_C^{off} is to compute the auxiliary information **aux** for each AND gate, which is computed as $\mathbf{aux} = [\lambda_{\alpha\beta}]_N = \lambda_{\alpha} \cdot \lambda_{\beta} \oplus [\lambda_{\alpha\beta}]_1 \oplus \cdots \oplus [\lambda_{\alpha\beta}]_{N-1}$.

For instance, the input mask λ_{α} and λ_{β} of A_{i+1} are obtained from the output mask λ_{γ} of A_{i-1} through the linear calculation of X_r , which may be too costly, such as a linear layer of LowMC. If we compute it for each party and sum the results to obtain the input mask of A_{i+1} , there are N computations of linear operations X_i (see Figure 4).

It is more efficient to swap the order of summing and computing linear layers. Each party sums the output mask share $[\lambda_{\gamma}]$ of each AND gate of A_{i-1} , and then computes the linear operation once to obtain the input mask of A_{i+1} . Hence, in Figure 5 there is only to deploy one linear layer for N parties. This optimization not only improves efficiency by avoiding per-party linear computation but also reduces hardware resource consumption.

Optimize the online phase. We use the optimized mask sampling method given by Kales [KZ20] to avoid the linear operation computation for each party. In the online phase, for each AND gate, each party needs to compute the broadcast message **msgs**, which is $[s] = \hat{z}_{\alpha} [\lambda_{\beta}] \oplus \hat{z}_{\beta} [\lambda_{\alpha}] \oplus [\lambda_{\alpha,\beta}] \oplus [\lambda_{\gamma}]$. However, the input shares $[\lambda_{\alpha}]$ and $[\lambda_{\beta}]$ of A_{i+1} have to be calculated from the output share $[\lambda_{\gamma}]$ of A_{i-1} , so this cannot be directly optimized like the offline phase.



$$\lambda_{\alpha} = [\lambda_{\alpha}]_1 \oplus \cdots \oplus [\lambda_{\alpha}]_N$$

Figure 4: Each party uses its own A_{i-1} output share $[\lambda_{\gamma_1}]$ and $[\lambda_{\gamma_2}]$ to calculate X_i to get the input of A_{i+1} share $[\lambda_{\alpha}]$, and then get the mask λ_{α} .

Figure 5: Each party sum A_{i-1} output share $[\lambda_{\gamma_1}]$ and $[\lambda_{\gamma_2}]$ to get λ_{γ_1} and λ_{γ_2} . Then λ_{γ_1} and λ_{γ_2} calculate X_i to get the input of A_{i+1} mask λ_{α} .

Kales changed the sampling position of shares. that is, sampling is performed before AND gate calculation, rather than after AND gate. The input shares $[\lambda_{\alpha}]$ and $[\lambda_{\beta}]$ are sampled from the random tape. This means that each party does not need to calculate the linear calculation of $[\lambda_{\alpha}]$ and $[\lambda_{\beta}]$, but only needs to sample directly from the random tape when using it. Therefore, only \hat{z}_{γ} is required to calculate the \hat{z}_{α} and \hat{z}_{β} of the latter AND gate, and at the hardware level, only 1 hardware usage is required instead of N. After modifying the position, λ_{γ} needs to be obtained by an invertible linear calculation of the input mask before the calculation of the latter AND gate. In this way, however, each party still needs to calculate $[\lambda_{\gamma}]$, so in the case of using optimizations in the offline phase, there are some modifications in the protocol, that is,

$$\mathbf{aux} = [\lambda_{\alpha,\beta}]_N = \lambda_\alpha \cdot \lambda_\beta \oplus [\lambda_{\alpha\beta}]_1 \oplus \cdots \oplus [\lambda_{\alpha\beta}]_{N-1} \oplus \lambda_\gamma,$$

328 and

$$[s] = \hat{z}_{\alpha} [\lambda_{\beta}] \oplus \hat{z}_{\beta} [\lambda_{\alpha}] \oplus [\lambda_{\alpha,\beta}].$$

Because the calculation of \mathbf{aux} has changed, the offline phase is optimized as shown in Figure 6.

As discussed above, we review software optimizations and reanalyze the hardware performance of these optimizations. These optimizations reduce the computational complexity of the underlying circuit in MPCitH-PP from $\mathcal{O}(2N\cdot(C_L+C_N))$ to $\mathcal{O}(2N\cdot C_N+2C_L)$, where C_N represents the number of nonlinear operations in the circuit, C_L represents the number of linear operations and the factor of 2 arises from preprocessing. As a result, nonlinear operations need to be computed N times, while linear operations only need to be computed once. In terms of hardware implementation, the AND gate of the circuit

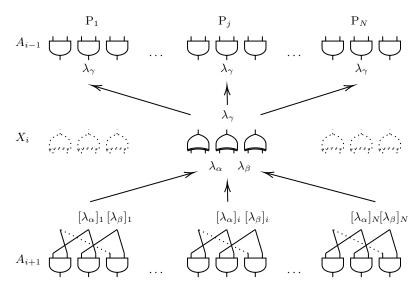


Figure 6: Each party samples $[\lambda_{\alpha}]$ and $[\lambda_{\beta}]$ of A_{i+1} , get λ_{α} and λ_{β} , then compute λ_{γ} of A_{i-1} .

requires an extension to accommodate N parties, whereas the XOR gate only requires "one part". These optimizations have significant implications for hardware resources, particularly in scenarios where the underlying circuit is a symmetric primitive like LowMC, which heavily relies on linear calculations and minimally increases hardware resources with the number of parties. To validate our observation, we implemented the MPCitH-PP protocol with different parties using LowMC as the underlying circuit. Table 3 demonstrates consistent results between the experimental and theoretical observations.

A complete MPCitH-PP protocol based on LowMC (referred to as LowMC-MPC) involves two separate calculations: the offline phase and the online phase, both requiring a normal implementation of LowMC. To optimize this, we merged the two phases by sharing the constant matrix between them. It is important to note that based on the previous optimization, the linear calculation in the offline phase is an inverse operation. Thus, we can only reuse the constant K_i mentioned in Algorithm 1, where $i \in [1, r]$. We analyze LowMC-MPC: to complete the offline phase in r clock cycles, the state first XOR with $K_i \cdot mk$, and then multiplies with L_i^{-1} . This calculation leads to the critical path of LowMC being too long, so we have to divide the calculation into 2 clock cycles to complete one round, and as a result, the offline phase requires 2r clock cycles. To address this, we propose an equivalent representation: $L_i^{-1} \cdot (K_i \cdot mk \oplus state) = (L_i^{-1} \cdot K_i) \cdot mk \oplus L_i^{-1} \cdot state$. Essentially, we give a key scheduling matrix $K_i' = L_i^{-1} \cdot K_i$ specifically for the offline phase. This serves as a trade-off between runtime and hardware usage. Notably, this problem does not arise in the online phase.

In Table 3, as the number of parties increases, the growth of hardware usage is slow, which is consistent with our analysis, which the hardware growth comes from AND gates, not XOR gates. Therefore, we implemented LowMC-MPC with 16 parties, answered the questions we raised in Section 1, and proved that MPCitH-PP with more than 3 parties can be arranged on the FPGA development board.

4 Optimizing the Implementation of Picnic3

In Section 3, we give a hardware-oriented optimization of MPCitH-PP with more than 3 parties, which makes it possible to implement a digital signature based on MPCitH-

					\mathbf{Utiliz}	ation			
Sec.	N		Without	t opt.			With	opt.	
		\mathbf{LUTs}	$\%~{ m LUTs}$	$\overline{\mathbf{F}}\mathbf{F}\mathbf{s}$	$\% \ FFs$	\mathbf{LUTs}	$\%~{ m LUTs}$	\mathbf{FFs}	% FFs
	3	21450	7.18%	2530	0.42%	27186	9.10%	2484	0.42%
Т 1	4	22580	7.56%	3076	0.52%	28240	9.46%	3000	0.50%
L1	8	25924	8.68%	5044	0.84%	32353	10.83%	5035	0.84%
	16	36264	12.14%	9167	1.53%	41378	13.86%	9198	1.54%
	3	81388	27.26%	4859	0.81%	104240	34.91%	4867	0.81%
т г	4	84712	28.37%	5912	0.99%	104859	35.12%	5877	0.98%
L5	8	97018	32.49%	9991	1.67%	116062	38.87%	9963	1.67%
	16	128668	43.09%	18149	3.04%	148211	49.64%	18116	3.03%

Table 3: Utilization of LowMC-MPC for different parties. N denotes the number of parties. Sec. denotes the security level. Without opt. denotes the LowMC-MPC with 2r + r clock cycles, and With opt. denotes the LowMC-MPC with 2r clock cycles

PP with high performance. As an illustration, we implemented PICNIC (PICNIC3) using MPCitH-PP, following the NIST standards. Although we have implemented LowMC-MPC on the FPGA development board to support many parties from 3 to 16, the hardware resources usage of the hash function Keccak in turn begins to restrict the number of parties. It is difficult to implement efficiently for many parties. We built a pipeline architecture to implement the PICNIC3 with 4 parties to maximize performance as much as possible.

In the following sections, we describe several optimizations proposed for Picnic3, which enable it to fully utilize the resources of Kintex-7 for efficient implementation.

4.1 Multi-stage Pipeline and Parallel Implementation of Picnic3

We give a simple analysis of the implementation performance and resource usage of some key parts of the Picnic3. Picnic3 signature algorithm applied the KKW protocol, seen the Figure 2. In order to reduce the size of the public key, the Merkle tree construction is used to generate the random seeds (the leaf nodes of the Merkle tree), and it is also used in the computation of $h_{\rm on}$ to reduce the signature size. A basic hardware implementation process for N=4 parties with M instances is given in the following:

Step 1. PICNIC3 applies KECCAK to generate random seeds \mathbf{seed}_{j}^{*} for M instances in Merkle tree mode and then drive N parties' seeds $\mathbf{seed}_{j,i}$ with seed \mathbf{seed}_{j}^{*} as the root of Merkle tree. Since there are only 4 parties, jth instance generates $\mathbf{seed}_{j,i}$ simultaneously, where $i \in [1,4]$. Therefore, two KECCAK components are required to parallelize the computation.

Step 2. We give a pipeline implementation of instances description of the offline phase and online phase of MPC. We divide this step into 5 parts, which are independent for easy assembly lines. We describe each part and explain the symmetric primitive components required for each part.

- A **Tapes.** It executes the offline phase of MPC Π_C^{off} with Keccak to generate the random tapes required for 4 parties in parallel mode. Here, 4 Keccak components are required, which are also used to drive the random taps in the online phase of MPC Π_C^{off} .
- B **LowMC-MPC.** According to the MPCitH-PP protocol specified in Picnic, the block cipher LowMC is used in the offline phase Π_C^{off} to generate the auxiliary information \mathbf{aux}_j , and it is also used in the online phase Π_C^{on} to simulate N parties to compute the view $\mathbf{msgs}[s]$. Since online and offline phases are performed separately, we give a circuit calculation (LowMC) to support both phases.

- C Commitment of states. It adopts Keccak to compute the commitments $\mathbf{com}_{j,i} = H(\mathbf{state}_{j,i})$, where $\mathbf{state}_{j,i} = \mathbf{seed}_{j,i}$ ($i = 1, \dots, N-1$), $\mathbf{state}_{j,N} = \mathbf{seed}_{j,N} \| \mathbf{aux}_j$. In this part, we need 4 Keccak components to commit to the offline phase for N = 4 parties.
- D Commitment of online phase. After finishing the calculation of the view in step B, a Keccak component is required to commit to the online phase. This is the com-on_i in Figure 2.
- E Commitment of offline phase. Compute com-off_j = $H(\mathbf{com}_{j,1}, \dots, \mathbf{com}_{j,N})$, which needs a components of Keccak.

Step 3. Utilize Keccak to generate $h_{\rm on}$ and $h_{\rm off}$ separately. Subsequently, a Keccak component is needed to hash data, including commitment, public key, salt, and message, and compute the challenge value.

In Step 2, we analyze the executing time of 5 parts, the computation time of LowMC in Step B is less than other parts. Hence, we carry out the LowMC in offline phase and online phase in the serial processing. Figure 7 illustrates the 5-stage pipeline structure of the initial 3 instances. $\mathbf{com}_{i,j}$ (C_1) starts after the calculation of auxiliary information (the first B_1), \mathbf{com} -on (D_1) starts after the calculation of the view (the second B_1). \mathbf{com} -off (E_1) starts after the calculation of $\mathbf{com}_{i,j}$ (C_1). The time t refers to the time required for the longest-running part.

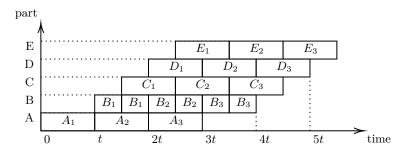


Figure 7: Pipeline of the Step 2 of Picnic3.

Table 4 provides the count of symmetric primitive components utilized in each part, offering a clear representation of the level of parallelism in each step. To maximize speed, the quantity of Keccak instances is directly related to the number of parties. Despite the low hardware utilization of an individual Keccak instance, the substantial number makes it challenging to accommodate them in L5 level Picnic3 with over 4 parties. For the basic pipeline construction, we give more optimation to speed up the implementation of Picnic3, including the optimation of symmetry primitive, extending the pipeline construction with Step 1 and Step 3, and the construction of signature as well.

4.2 Optimization of Symmetric Primitives

The value of t in Figure 7 depends on the longest-running design part. In our initial implementation, the offline phase of LowMC-MPC consists of r or 2r cycles, while the online phase consists of r clock cycles. Here, r represents the number of rounds in LowMC-MPC, which is 4. Additionally, Keccak has 24 rounds, each requiring a cycle. This is significantly more than LowMC's cycles. According to Table 1, Keccak's absorption or squeezing capacity is limited. Hence, certain parts can be computed with one execution of Keccak, such as the generation of random seed. Conversely, some parts require multiple executions of Keccak. For instance, Tapes in the L5 security level require two executions to generate the $255 \times 2 \times r = 2040$ -bit random number, Commitment

\mathbf{Step}	Design Part	Symmetric Primitive	\mathbf{Number}
Step 1	Merkel Tree for seeds	Keccak	2
	Tapes	Keccak	4
	LowMC-MPC	LowMC-MPC	1
Step 2	Commitment of state	Keccak	4
	Commitment of online phase	Keccak	1
	Commitment of offline phase	Keccak	1
	Merkel Tree for $h_{\rm on}$	Keccak	1
Step 3	$h_{ m off}$	Keccak	1
	Challenge	Keccak	1

Table 4: symmetric components used by different parts.

of online phase \mathbf{com} -on_j in L5 security level requires four executions to hash the views with $255 + 255 \times r \times N = 4335$ -bit, and in L1 security level, two executions are necessary. Therefore, we conduct an analysis of symmetric primitives as our initial step. Compared to the round function of Keccak, LowMC requires a significant amount of computation and has a longer critical path. Modifying the clock cycles of Keccak allows for consistency across all pipeline modules. For example, we reduce the clock cycles of Keccak to 12 clock cycles during the Commitment of the online phase and perform the execution twice, resulting in total clock cycles equivalent to that of Commitment of state. Although hardware utilization has increased, pipeline performance has been effectively optimized.

Table 5 present the critical paths and hardware utilization of the Keccak and LowMC on the Kintex-7 platform. Moreover, as the critical path decreases, the hardware utilization gradually increases, which puts a limit on the efficient implementation of Picnic3 on the FPGA platform.

Table 5: Hardware utilization and critical path of symmetric primitives. LowMC-MPC-o denotes optimization of LowMC-MPC in Subsection 4.1.

Design Part	LUTs	%	FFs	%	Clock Cycles	Critical Path (ns)
Keccak-1	3467	1.16%	1606	0.27%	24	2.392
Keccak-2	6964	2.33%	1624	0.27%	12	3.956
Keccak-3	11041	3.70%	1619	0.27%	8	4.897
Keccak-4	13638	4.57%	1617	0.27%	6	6.475
Keccak-6	20525	6.87%	1618	0.27%	4	9.018
LowMC-MPC-L1	22580	7.56%	3076	0.52%	12	5.929
LowMC-MPC-o-L1	28240	9.46%	3000	0.50%	8	6.080

In Section 3, we discuss the trade-off between hardware utilization and runtime for LowMC-MPC, which is also observed in the implementation of Keccak. Furthermore, besides the mentioned pipeline optimization in Figure 7, Step 1 and Step 3 can also be optimized in a similar manner. Additionally, as the number of cycles in LowMC-MPC is fewer than that of Keccak, the pipeline's implementation of Keccak can also be reduced to match the cycle count of LowMC-MPC. However, achieving this requires a carefully chosen trade-off, and we provide optimized versions of Picnic-L1 in Section 5.

4.3 Extension of Multi-stage Pipeline

In Subsection 4.1, the pipeline construction only includes the operations in Step 2. We can extend the pipeline construction to be compatible with the computation of Step 1 and Step 3.

In Step 1 of Subsection 4.1, two independent Keccak components are used to drive all the seeds, which are stored in BRAM. We first generate M instance seeds in Merkle tree mode and then generate N parties' seeds for all instances in the Merkel tree as well,

which is regarded as a big Merkel tree. We first generate all non-leaf nodes in the Merkle tree and store them in BRAM. For every instance, the second-to-last level of the Merkle tree is obtained and used to produce the 4 parties' seeds with one execution of Keccak by 2 Keccak components. The parties' seed generation of an instance is added to the beginning of the pipeline of Step 2 in Figure 7.

In Step 3, the generation of the challenge requires the calculation of $h_{\rm off}$ and $h_{\rm on}$. Because the computation of $h_{\rm off}$ and $h_{\rm on}$ use two independent KECCAK components. We propose incorporating the calculation of $h_{\rm off}$ and $h_{\rm on}$ from Step 3 into the pipeline of Step 2 to reduce the running time. For $h_{\rm off}$, we start the calculation of $h_{\rm off}$ after the calculation of **com**-off_j in pipeline, so there is no extra $h_{\rm off}$ computation time in Step 3. As for $h_{\rm on}$, since we have already computed the leaf nodes of the Merkel tree in Step 2, we can directly calculate the parent nodes of the Merkel tree leaf nodes during the pipeline. Based on the structure of the binary tree, this optimization can approximately halve the computation time required for $h_{\rm on}$. This optimization significantly reduces the time required for generating challenges. It can be seen that the time complexity of $h_{\rm off}$ is $\mathcal{O}(M)$ in Step 3 of the pipeline (see Subsection 4.1), where M represents the number of instances. Once this step is incorporated into the pipeline of Step 2, the extra $\mathcal{O}(M)$ computation time will be saved.

4.4 Optimization of Constructing Signature

We present an optimization for challenge generation. Reviewing the KKW protocol Figure 2, we analyze the computation of h_{off} in more detail. By the computation in step (b) in **Commit**, we know a commitment **com**-off_j = $H(\mathbf{com}_{j,0}, \dots, \mathbf{com}_{j,i}, \dots, \mathbf{com}_{j,N})$. Since the commitment h_{off} is generated for all instances of **com**-off_j, i.e.,

$$h_{\text{off}} = H(\mathbf{com}\text{-off}_0, \dots, \mathbf{com}\text{-off}_j, \dots, \mathbf{com}\text{-off}_N).$$

In the meantime, it has been observed that \mathbf{com} -off_j are not sent to the verifier and are instead calculated by the verifier. Hence, we propose an improved computation to compute the h_{off} directly using $\mathbf{com}_{j,i}$ as following,

```
h_{\text{off}} = H(\mathbf{com}_{0,0}, \dots, \mathbf{com}_{0,N}, \dots, \mathbf{com}_{j,0}, \dots, \mathbf{com}_{j,N}, \dots, \mathbf{com}_{M,0}, \dots, \mathbf{com}_{M,N}). \tag{1}
```

Lemma 1. For the KKW protocol, the computation of commitment h_{off} is instead with Equation 1, which has the same security as the original computation in the KKW protocol in Figure 2.

Here, we use the optimization implementation that can reduce O(M) executions of the hash function Keccak, which is applicable to reduce the running time for software implementation and hardware implementation.

5 Implementation

In this section, we present an FPGA implementation of PICNIC3 on the Kintex-7 by combining the optimizations discussed in Section 3 and Section 4. We first list the specific components used by each module of PICNIC3, and then we give the analysis of their hardware usage and clock cycles.

5.1 Implementation of Picnic3

Initially, we develop a basic implementation of PICNIC3 for security levels L1 and L5, and subsequently design and realize two optimized versions. The primary focus of these optimized versions lies in accelerating the operational speed of KECCAK, utilizing additional

hardware resources to significantly enhance the computational performance of Picnic3. Within this process, a delicate balance must be struck between boosting hardware operation speed and optimizing the utilization of limited hardware resources, thereby guiding the selection of the most appropriate optimization strategy.

For the L1 security level, we devise and implement three different hardware versions of PICNIC3. Among these, version 1 employs a KECCAK operational cycle of 24 clock cycles; version 2 reduces this to a KECCAK operational cycle of 12 clock cycles; and for version 3, we further reduce the KECCAK operation cycle to a mere 8 clock cycles. Due to the KECCAK used in version 3 having a cycle count of 8, we use the 8-cycle LowMC-MPC-o to fully maximize the performance of the pipeline. Additionally, it is important to note that both version 2 and version 3 utilize two KECCAK in the commitment of the online phase. This is because the use of K-4 and K-6 results in longer critical paths, consequently reducing the performance of the entire hardware implementation.

For the L5 security level, we have only implemented one hardware version of Picnic3, namely version 1, which also incorporates a Keccak operational cycle of 24 clock cycles. In Table 6, Tapes we use 3 K-2 and one K-1, because the N-th participant only needs to generate λ_{α} instead of $\lambda_{\alpha,\beta}$. Commitment of state requires 3 K-1 and one K-2, because the Nth party needs to make a commitment to the additional $\lambda_{\alpha,\beta}$. The primary reason behind not implementing version 2 and version 3 for this security level is due to the limitations in available hardware resources that could not accommodate the implementation.

Table 6: Symmetric primitive components in Picnic3. K-1 denotes Keccak-1, K-2 denotes Keccak-2, K-3 denotes Keccak-3, and K-4 denotes Keccak-4. LowMC-MPC-0 denotes optimization of LowMC-MPC.

	Dogious Bont	Sym	metric Primiti	ve
	Design Part	Version 1	Version 2	Version 3
	Merkel Tree for seeds & Seeds	$2 \times \text{K-1}$	$2 \times \text{K-}2$	$2 \times \text{K-}3$
	Tapes	$4 \times \text{K1}$	$4 \times \text{K}2$	$4 \times \text{K}3$
	LowMC-MPC	LowMC-MPC	LowMC-MPC	LowMC-MPC-o
L1	Commitment of state	$4 \times \text{K1}$	$4 \times \text{K}2$	$4 \times \text{K}3$
	Commitment of online phase	K-2	$2 \times \text{K}2$	$2 \times \text{K}3$
	Commitment of offline phase	K-1	K-2	K-3
	Merkel Tree for $h_{\rm on}$	K-1	K-2	K-3
	$h_{ m off}$	K-1	K-2	K-3
	Challenge	K-1	K-1	K-1
	Merkel Tree for seeds & Seeds	2 × K-1	-	-
	Tapes	$3 \times \text{K-}2 + \text{K-}1$	-	-
	LowMC-MPC	LowMC-MPC	_	-
	Commitment of state	$3\times \text{K}1 + 1\times \text{K}2$	_	-
L5	Commitment of online phase	K-4	_	-
	Commitment of offline phase	K-2	-	-
	Merkel Tree for $h_{\rm on}$	K-2	-	-
	$h_{ m off}$	K-2	-	-
	Challenge	K-1	-	-

Hardware Utilization. Table 7 displays the resource utilization of our implemented PICNIC3. The FPGA utilized for the implementation, the Xilinx Kintex-7 board, consists of 298600 LUTs and 597200 FFs. Version 2 and version 3 of PICNIC3-L1 require 1.67 times and 2.41 times more resources compared to version 1, respectively. The resource occupancy rate of version 1 of PICNIC3-L5 is already approaching 70%. Consequently, it is challenging to optimize the L5 security level by reducing the KECCAK cycle. We emphasize that PICNIC3-L1 of version 1 and Version 2 can be deployed on Artix. Artix's hardware volume is 1344600 LUTs and 269200 FFs.

Clock Cycle. Table 8 presents the number of clock cycles necessary for each part within

Scheme	Version	LUTs	%	FFs	%
Picnic3-L1-Sign	1	75524	25.29%	37741	6.32%
Picnic3-L1-Verify	1	97199	32.55%	40369	6.76%
Picnic3-L1-Sign	2	126637	42.41%	40097	6.71%
Picnic3-L1-Sign	3	182084	60.98%	41580	6.96%
Picnic3-L5-Sign	1	192236	64.38%	55636	9.32%
PICNIC3-L5-Verify	1	201441	67.46%	59348	9.94%

Table 7: Implementation of each version of Picnic3 under different security levels.

our Picnic3 implementation. Except for LowMC-MPC, the clock cycles of the other parts depend on the Keccak function it invokes. Our implementation of Keccak requires 24 clock cycles, while the optimized L1 version takes 8 cycles. The Pipeline in the table refers to the time required for the pipeline to calculate an instance. In Table 4, Step 1 is the construction of the Merkel Tree of the seed, Step 2 is the time for the pipeline of all instances, and Step 3 is the total cycle of calculating $h_{\rm off}$, $h_{\rm on}$ and challenge generation. It is evident that Step 2 in Table 8 exceeds $24 \times M$. This is due to the additional control cycles required by Keccak, as well as the need for additional cycles to complete the data storage. It is noted that our cycle analysis does not account for data transmission time.

	rable 8: Clock	cycles analysis	of Fichics.	
Design part	Picnic3-L1	Picnic3-L1	Picnic3-L1	Picnic3-L5
	Version 1	Version 2	Version 3	Version 1
LowMC-MPC	12	12	8	12
Pipeline	24	12	8	24
Step 1	6290	3496	2564	12418
Step 2	8834	5008	3732	18184
Step 3	920	920	920	1788

Table 8: Clock cycles analysis of Picnic3

Picnic3 requires the construction of two Merkle Trees. In the verification, there is no need to generate the Seeds from the root node or construct $h_{\rm off}$ from the leaf nodes. Therefore, the verification takes less time than the signing. Due to the non-deterministic tree construction and challenges, only the timing of the signatures is presented here. Table 9 shows the running time of Picnic3 on software and hardware for signing, which provides showcases the running time comparison between software and FPGA implementations for different versions of the Picnic3 at different security levels. In terms of clock cycles, higher versions of the Picnic3 typically require fewer clock cycles. The critical path column indicates the time in ns consumed per clock cycle. The software implementation takes an average of 5.17 ms for all versions of Picnic3-L1, while the FPGA implementation achieves an impressive speedup, executing the same task in only 0.079 ms. This represents a significant increase in performance, nearly 65 times faster in version 1, and even 112 times faster in version 3. We present three versions of the scheme, with increasing speed and hardware usage. The implementation of this trade-off offers a range of options for various purposes.

Another example is the Picnic3-L5 scheme, where the software implementation takes 18.15 ms, while the FPGA implementation completes the task in just 0.229 ms, making it almost 80 times faster.

These results highlight the advantages of FPGA over software implementation, specifically the significantly improved execution time and performance. FPGA offers a highly parallelized hardware architecture, allowing for the efficient execution of complex algorithms with reduced latency.

Scheme	Version	Clock Cycle	Frequency	Sign time (ms)		
Scheme			$\mathbf{n}\mathbf{s}$	Software	\mathbf{FPGA}	
Picnic3-L1	version 1	16044	5.019	5.17	0.079	
Picnic3-L1	version 2	9424	5.559	5.17	0.052	
Picnic3-L1	version 3	7216	6.416	5.17	0.046	
Picnic3-L5	version 1	32390	7.079	18.15	0.229	

Table 9: Running time of Software (from [KZ20]) and FPGA.

5.2 Comparison to FPGA Implementations of Other Schemes

This section compares our work with other existing FPGA implementations of signature schemes, specifically focusing on the SPHINCS and PICNIC1 schemes. It is important to note that SPHINCS is based on hashing techniques, while PICNIC1 is based on block ciphers. Both of these schemes rely on symmetric primitives. In contrast, our work aligns with the security assumptions of symmetric primitives and is considerably faster than other schemes.

Table 10 provides a detailed comparison of various FPGA implementations for different security levels. We highlight our achievement of superior performance at both security level 1 and security level 5. At security level 1, our PICNIC3-L1 implementation demonstrates substantial speed improvements compared to other schemes. For instance, our design achieves a maximum frequency of 199 MHz, utilizing 75524 LUTs, and 37741 FFs, and completing signing operations in 16044 clock cycles or 79 microseconds. In comparison, the closest competitor is PICNIC1-L1-FS with a maximum frequency of 125 MHz and significantly higher execution times.

At security level 5, our PICNIC3-L5 implementation also showcases impressive performance gains. With a maximum frequency of 141 MHz, utilizing 192236 LUTs and 59348 FFs, our design completes signing operations in 32390 clock cycles or 229 microseconds. Again, we surpass the competing implementations, such as PICNIC1-L5-FS, in terms of both maximum frequency and execution time.

It is worth noting that the other schemes listed in the table are based on lattice ciphers. However, our work surpasses them in terms of speed, reinforcing our claim to being the fastest FPGA implementation for the specified security levels.

Table 10: Comparison to FPGA implementations of other signature schemes (modified from [BNG22]).

G	A 1200 14 10 200	Max Freq.	1111	E E	Sign		7
Design	Algorithm	(MHz)	FOIS	S L L	cycles	μs	ramny
		Security	Security Level 1				
[BNG22]	FALCON-512	142	14500	7287	1	ı	A7
[ALCZ20]	SPHINCS ⁺ -128s-simple	250 & 500	14500	72514	1	12400	A7
[ALCZ20]	SPHINCS ⁺ -128s-robust	250 & 500	14500	73069	1	21100	A7
[ALCZ20]	SPHINCS ⁺ -128f-simple	250 & 500	14500	72505	1	1010	A7
[ALCZ20]	SPHINCS ⁺ -128f-robust	250 & 500	14500	72505	1	1640	A7
$[\mathrm{KRR}^+20]$	Picnic1-L1-FS	125	14500	23516	31300	250	K7
[BNG22]	FALCON-512	314	14500	7314	1	ı	VUS+
$[\mathrm{RMJ}^+21]$	Dilithium-II	1	14500	1	18338/-	1	VUS+
this paper	Picnic3-L1	199	75524	37741	16044	79	K7
this paper	Picnic3-L1	180	126637	40097	32390	52	K7
this paper	Picnic3-L1	156	182084	41580	32390	46	K7
		Security	Security Level 5				
[BNG22]	FALCON-1024	142	13956	6737	1	1	A7
[BNG22]	Dilithium-V	116	53187	28318	24358/55070	210/475	A7
[ALCZ20]	SPHINCS ⁺ -256s-simple	250 & 500	51130	74576		19,300	A7
[ALCZ20]	SPHINCS ⁺ -256s-robust	250 & 500	2000	75738	1	36,100	A7
[ALCZ20]	$SPHINCS^{+}-256f-simple$	250 & 500	51009	74539	1	2,520	A7
[ALCZ20]	SPHINCS ⁺ -256f-robust	250 & 500	50341	75664	1	4,680	A7
[LSG21]	Dilithium-V	140	44653	13814	70376/145912	503/1042	A7
[BNG22]	Dilithium-V	173	54468	28639	24358/55070	141/318	K7
$[\mathrm{KRR}^+20]$	Picnic1-L5-FS	125	167530	33164	154500	1236	K7
[BNG22]	FALCON-1024	314	13729	6771	1	ı	VUS+
[BNG22]	Dilithium-V	256	53907	28435	24358/55070	95/215	VUS+
$[\mathrm{AMJ}^+21]$	$\operatorname{Dilithium-V}$	200	19100	9300	-/00289	342/-	zus+
this paper	Picnic3-L5	141	192236	59348	32390	229	K7

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