Using Loss Functions

You've likely seen a lot of loss functions while you've been working in tensorflow

The loss function is called usually when specified as a parameter in model.compile().

Now the last function itself can be declared using either a string with its name, such as MSE here, which stands from mean squared error. Or you can use a loss object.

model.compile(loss='mse', optimizer='sgd')

or

from tensorflow.keras.losses import mean_squared_error
model.compile(loss=mean_squared_error, optimizer='sgd')

Using Loss Functions

```
model.compile(loss='mse', optimizer='sgd')

The important difference with using the loss object is that you can add parameters to the object call on.

This means that you can have much better flexibility to do things like tuning your hyper parameters.
```

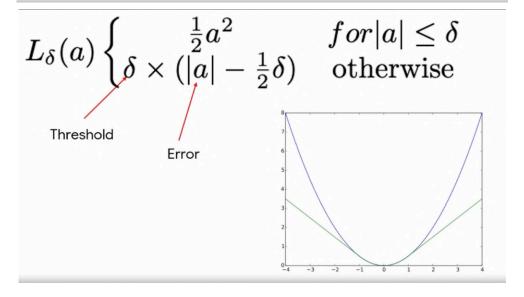
from tensorflow.keras.losses import mean_squared_error
model.compile(loss=mean_squared_error(param=value),
optimizer='sgd')

Creating a custom loss function

```
def my_loss_function(y_true, y_pred):
    return losses
```

Example

Huber Loss



def my_huber_loss(y_true, y_pred):
$$\frac{\text{threshold = 1}}{\text{error = y_true - y_pred}}$$

$$\text{is_small_error = tf.abs(error) <= threshold}$$

$$\text{small_error_loss = tf.square(error) / 2}$$

$$\text{big_error_loss = threshold * (tf.abs(error) - (0.5 * threshold))}$$

$$\text{return tf.where(is_small_error, small_error_loss, big_error_loss)}$$

$$L_{\delta}(a) \begin{cases} \frac{1}{2}a^2 & for |a| \leq \delta \\ \delta \times (|a| - \frac{1}{2}\delta) & \text{otherwise} \end{cases}$$

```
def my_huber_loss(y_true, y_pred):  
    threshold = 1  
    error = y_true - y_pred  
    is_small_error = tf.abs(error) <= threshold  
    small_error_loss = tf.square(error) / 2  
    big_error_loss = threshold * (tf.abs(error) - (0.5 * threshold))  
    return tf.where(is_small_error, small_error_loss, big_error_loss)  
    L_{\delta}(a) \left\{ \delta \times \left( a - \frac{1}{2} \delta \right) \right. \quad \text{otherwise}
```

```
def my_huber_loss(y_true, y_pred):  
    threshold = 1  
    error = y_true - y_pred  
    is_small_error = tf.abs(error) <= threshold  
    small_error_loss = tf.square(error) / 2  
    big_error_loss = threshold * (tf.abs(error) - (0.5 * threshold))  
    return tf.where(is_small_error, small_error_loss, big_error_loss)  
    L_{\delta}(a) \left\{ \delta \times \left( \left| a \right| - \frac{1}{2} \delta \right) \right. \quad \text{otherwise}
```

def my_huber_loss(y_true, y_pred):
 threshold = 1
 error = y_true - y_pred
 is_small_error = tf.abs(error) <= threshold

small_error_loss = tf.square(error) / 2
 big_error_loss = threshold * (tf.abs(error) - (0.5 * threshold))
 return tf.where(is_small_error, small_error_loss, big_error_loss)

$$L_{\delta}(a) \left\{ \delta \times \left(|a| - \frac{1}{2} \delta \right) \right. \quad \text{otherwise}$$

```
def my_huber_loss(y_true, y_pred):  
    threshold = 1  
    error = y_true - y_pred  
    is_small_error = tf.abs(error) <= threshold  
    small_error_loss = tf.square(error) / 2  
    big_error_loss = threshold * (tf.abs(error) - (0.5 * threshold))  
    return tf.where(is_small_error, small_error_loss, big_error_loss)  
    L_{\delta}(a) \left\{ \frac{\frac{1}{2}a^2}{\delta \times (|a| - \frac{1}{2}\delta)} \right\} \quad \text{otherwise}
```

$$L_{\delta}(a) \begin{cases} \frac{1}{2}a^2 & for |a| \leq \delta \\ \delta \times (|a| - \frac{1}{2}\delta) & \text{otherwise} \end{cases}$$

```
model = tf.keras.Sequential([keras.layers.Dense(units=1, input_shape=[1])])
model.compile(optimizer='sgd', loss='my_huber_loss')

def my_huber_loss(y_true, y_pred):
    threshold = 1
    error = y_true - y_pred
    is_small_error = tf.abs(error) <= threshold
    small_error_loss = tf.square(error) / 2
    big_error_loss = threshold * (tf.abs(error) - (0.5 * threshold))
    return tf.where(is_small_error, small_error_loss, big_error_loss)</pre>
```

Adding hyperparameters to custom loss functions

To do this, you can create a wrapper function that contains the original loss function. In this case, I've created my huber loss with threshold that accepts a threshold parameter and you can see all of the other code is within that.

This accepts the threshold parameter so that when you call it, you can pass in that value. That threshold then gets used within the function instead of the hard-coded one.

```
def my_huber_loss_with_threshold(threshold):
```

```
def my_huber_loss(y_true, y_pred):
    error = y_true - y_pred
    is_small_error = tf.abs(error) <= threshold
    small_error_loss = tf.square(error) / 2
    big_error_loss = threshold * (tf.abs(error) - (0.5 * threshold))
    return tf.where(is_small_error, small_error_loss, big_error_loss)
return my_huber_loss</pre>
```

The inner function then gets returned by the outer function. If you call my huber loss with threshold, you'll actually get a lossfunction back that implements that threshold.

```
def my_huber_loss_with_threshold(threshold):
    def my_huber_loss(y_true, y_pred):
        error = y_true - y_pred
        is_small_error = tf.abs(error) <= threshold
        small_error_loss = tf.square(error) / 2
        big_error_loss = threshold * (tf.abs(error) - (0.5 * threshold))
        return tf.where(is_small_error, small_error_loss, big_error_loss)
    return my_huber_loss</pre>
```

```
Now if you want to use the threshold, you call the outer function MyHuberLoss with threshold which can accept the threshold parameter and then returns a reference to a customize my huber loss function, where the threshold is equal to the chosen parameter.

Notice that this is why we introduced the threshold parameter using a wrapper function rather than just modifying the my huber loss function to take in that third parameter for the threshold.

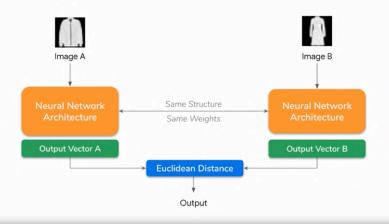
The model.compile parameter loss expects a function that takes in just y_true and y_pred. By including the threshold by using a wrapper, you can still provide a loss function that just gives the expected parameters y, true and y pred. Now if you want to do some hyperparameter tuning within the loss function, you can tweak that threshold.

model.compile(
optimizer='sgd', loss=my_huber_loss_with_threshold(threshold=1))
```

```
from tensorflow.keras.losses import Loss
                                            This syntax means that
MyHuberLoss inherits
from Loss. This lets use
use it as a loss
class MyHuberLoss(Loss):
   threshold = 1
  def __init__(self, threshold):
     super().__init__()
     self.threshold = threshold
  def call(self, y_true, y_pred):
     error = y_true - y_pred
     is_small_error = tf.abs(error) <= self.threshold</pre>
     small_error_loss = tf.square(error) / 2
     big_error_loss = self.threshold * (tf.abs(error) - (0.5 * self.threshold))
     return tf.where(is_small_error, small_error_loss, big_error_loss)
from tensorflow.keras.losses import Loss
class MyHuberLoss(Loss):
                                                              Then within a class, you should have two functions. An __init__() function that initializes a function from the class.
  threshold = 1
  def __init__(self, threshold):
                                                              The second is the call function that gets executed when an object is instantisted from a class.
     super().__init__()
     self.threshold = threshold
                                                              The __init__() function gets the threshold, and the call function gets the y_true and y_pred parameters
  def call(self, y_true, y_pred):
     error = y_true - y_pred
     is_small_error = tf.abs(error) <= self.threshold</pre>
     small_error_loss = tf.square(error) / 2
     big_error_loss = self.threshold * (tf.abs(error) - (0.5 * self.threshold))
     return tf.where(is_small_error, small_error_loss, big_error_loss)
```

```
from tensorflow.keras.losses import Loss
class MyHuberLoss(Loss):
 threshold = 1
 def __init__(self, threshold):
    super().__init__()
 self.threshold = threshold
 def call(self, y_true, y_pred):
    error = y_true - y_pred
    is_small_error = tf.abs(error) <= self.threshold</pre>
    small_error_loss = tf.square(error) / 2
    big_error_loss = self.threshold * (tf.abs(error) - (0.5 * self.threshold))
    return tf.where(is_small_error, small_error_loss, big_error_loss)
from tensorflow.keras.losses import Loss
class MyHuberLoss(Loss):
                                                    And the threshold class variable will be referred to within the class function as self.threshold.
 threshold = 1
 def __init__(self, threshold):
    super().__init__()
    self.threshold = threshold
 def call(self, y_true, y_pred):
    error = y_true - y_pred
    is_small_error = tf.abs(error) <= self.threshold</pre>
    small_error_loss = tf.square(error) / 2
    big_error_loss = self.threshold * (tf.abs(error) - (0.5 * self.threshold)
    return tf.where(is_small_error, small_error_loss, big_error_loss)
model.compile(optimizer='sgd', loss=MyHuberLoss(threshold=1<mark>)</mark>)
```

Siamese Network for Image Similarity



Contrastive Loss

- If images are similar, produce feature vectors that are very similar
- If images are different, produce feature vectors that are dissimilar.
- Based on the paper

"Dimensionality Reduction by Learning an Invariant Mapping"

by R. Hadsell; S. Chopra; Y. LeCun

http://yann.lecun.com/exdb/publis/pdf/hadsell-chopra-lecun-06.pdf

To calculate the loss in this, we needed a new type of loss function that wasn't in our tool care. We called it contrastive loss as we wanted to contrast the images against each other.

The idea is that if two images are similar, we want to produce a feature vector for each image where the vectors are very similar.

If the images are different, we want their respective feature vectors to also be different.

The paper dimensionality reduction by learning an invariant mapping is the basis for loss like this.

Contrastive Loss - Formula

$$Y^* D^2 + (1 - Y)^* max(margin - D, 0)^2$$

The formula for contrastive loss is here. It's Y times D squared plus one minus Y times the max of a margin value minus D or zero squared. Now there's a lot to breakdown here, so let's look at each of these elements in turn.

Here, Y is the tensor of details about image similarities. They are one if the images are similar and they are zero if they're not.

Contrastive Loss - Formula

$$Y * D^{2} + (1 - Y) * max(margin - D 0)^{2}$$

D is the tensor of Euclidean distances between the pairs of images.

Contrastive Loss - Formula

$$Y * D^2 + (1 - Y) * max(margin - D, 0)^2$$

Margin is a constant that we can use to enforce a minimum distance between them in order to consider them similar or different.

Contrastive Loss - Formula

$$Y * D^2 + (1 - Y) * max(margin - D, 0)^2$$



$$1*D^2 + (1-1)*max(margin - D, 0)^2$$



Margin is a constant that we can use to enforce a minimum distance between them in order to consider them similar or different

Contrastive Loss - Formula

$$Y * D^2 + (1 - Y) * max(margin - D, 0)^2$$



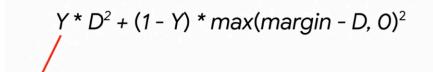
$$0 * D^2 + (1 - 0) * max(margin - D, 0)^2$$



 $max(margin - D, 0)^2$

When Y is zero, and we sub this ir for Y, then our value instead of D squared will be the max between the margin minus D or zero, which is then squared, and this should be a much smaller value than D squared. You can think of the Y and one minus Y in this loss function as weights that will either allow the D squared of the max part of the formula to dominate the overall loss. When Y is close to one, it gives more weight to the D squared term and less weight on the max term. The D squared term will dominate the calculation of the loss. Conversely, when Y is closer to zero, this gives much more weight to the D squared term and less weight to the D squared term so the max term dominates the calculation of the loss.

Contrastive Loss - Formula



When we take into account the parameters that TensorFlow expects for a loss function, let's rewrite like this.

The Y in the original formula becomes the Y true value.

$$Y_{true} * Y_{pred}^{2} + (1 - Y_{true}) * max(margin - Y_{pred}, 0)^{2}$$

Contrastive Loss - Formula

The D in the original formula becomes the Y pred value, and now we have the two values you need.

$$Y_{true} * Y_{pred}^{2} + (1 - Y_{true}) * max(margin - Y_{pred}, 0)^{2}$$

Custom Loss Function

```
def contrastive_loss(y_true, y_pred):
    margin = 1
    square_pred = K.square(y_pred)
    margin_square = K.square(K.maximum(margin - y_pred, 0))
    return K.mean(y_true * square_pred + (1 - y_true) * margin_square)
```

$$Y_{true} * Y_{pred}^{2} + (1 - Y_{true}) * max(margin - Y_{pred}, 0)^{2}$$

Custom Loss Function

```
def contrastive_loss(y_true, y_pred):
    margin = 1
    square_pred = K.square(y_pred)
    margin_square = K.square(K.maximum(margin - y_pred, 0))
    return K.mean(y_true * square_pred + (1 - y_true) * margin_square)
```

$$Y_{true} * Y_{pred}^{2} + (1 - Y_{true}) * max(margin - Y_{pred}, 0)^{2}$$

Custom Loss Function

K.mean[
$$Y_{true} * Y_{pred}^2 + (1 - Y_{true}) * max(margin - Y_{pred}, 0)^2$$
]

Usage of Custom Loss

model.compile(loss=constrastive_loss, optimizer=RMSprop())

Custom Loss Function with Arguments

```
def contrastive_loss_with_margin(margin):
    #Original Loss Function
    def contrastive_loss(y_true, y_pred):
        square_pred = K.square(y_pred)
        margin_square = K.square(K.maximum(margin - y_pred, 0))
        return K.mean(y_true * square_pred + (1 - y_true) * margin_square)
    return contrastive_loss
```

Usage of Wrapper Loss Function

model.compile(loss=contrastive_loss_with_margin(margin=1), optimizer=rms)

Contrastive Loss - Object Oriented

```
class ContrastiveLoss(Loss):
    margin = 0
    def __init__(self,margin):
        super().__init__()
        self.margin = margin

def call(self, y_true, y_pred):
        square_pred = K.square(y_pred)
        margin_square = K.square(K.maximum(self.margin - y_pred, 0))
        return K.mean(y_true * square_pred + (1 - y_true) * margin_square)
```

Contrastive Loss - Object Oriented

```
class ContrastiveLoss(Loss):
    margin = 0
    def __init__(self,margin):
        super().__init__()
        self.margin = margin

def call(self, y_true, y_pred):
        square_pred = K.square(y_pred)
        margin_square = K.square(K.maximum(self.margin - y_pred, 0))
        return K.mean(y_true * square_pred + (1 - y_true) * margin_square)
```

Usage of Object Oriented Loss

```
model.compile(loss=ContrastiveLoss(margin=1), optimizer=rms)
```

Huber Loss:

https://en.wikipedia.org/wiki/Huber_loss

Dimensionality Reduction by Learning an Invariant Mapping:

http://yann.lecun.com/exdb/publis/pdf/hadsell-chopra-lecun-06.pdf