Virtual Integrated Design Project

Mechanical documentation: L102, Team Root g

Material choice

- 6mm plywood

Manufacturing techniques

- The majority of the robot is laser cut from the 6mm plywood
- Some additional holes will need to be drilled and tapped
- The plywood will then be glued together using wood glue
- The arduino, battery box and IR sensor are attached to the robot using nuts and bolts and washers where appropriate

Material justification

- The main goal of our design process was to create a simple and reliable robot
- This is why we went for the cheap and easy to handle plywood as an alternative to sheet metal
- The parts can all be very easily and quickly laser cut out of a single sheet of plywood
- The use of comb joints ensures strength and makes the assembly process fast as pieces slot together only in their correct positions
- We are using 6mm plywood as it is the thickest available and will help make the robot more robust
- The use predominantly of wood also reduces the environmental impact of our robot as it is a sustainable resource

What follows are technical drawings for all of the laser cut parts along with an overall assembly drawing. At the very end is a template with all the parts in their required quantities on a 300mm x 600mm sheet, the same size as the plywood available to us. This is the template that would be used to laser cut the parts

















