

(Projection Thm.) Lecture 14

Theorem: Let W be a subspace of a f.d.l.p.s. V .

Then $V = W \oplus W^\perp$ i.e., $V = W + W^\perp$ and $WW^\perp = \{0\}$.

Proof: Any $x \in V$ can be written as $x = P_W(x) + (x - P_W(x))$.

Therefore $x \in W + W^\perp$. This implies that $V \subseteq W + W^\perp$.

The other inclusion is obvious.

Remarks: (i) Note that $P_W(x)$ exists and it is unique
(ii) If $V = W \oplus W^\perp$ and $v \in V$ then there exist unique $w_1 \in W$
and $w_2 \in W^\perp$ such that $v = w_1 + w_2$. (why?).

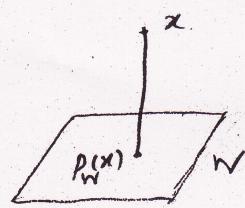
Nearest point: If W is the xy -plane in \mathbb{R}^3 and $x \in \mathbb{R}^3$, then we know that the orthogonal projection $P_W(x)$ is the nearest point for x from W . We will see that this is true in general.

Theorem: Let W be a subspace of a f.d.l.p.s. V &

let $x \in V$. Then $\|x - P_W(x)\| \leq \|x - w\| \forall w \in W$.

Proof: Note that

$$\begin{aligned} \|x - w\|^2 &= \|x - P_W(x) + P_W(x) - w\|^2 = \|x - P_W(x)\|^2 + \|P_W(x) - w\|^2 \text{ (why?)} \\ &\geq \|x - P_W(x)\|^2. \end{aligned}$$



Four Fundamental Subspaces:

Let $A = (a_{ij})_{m \times n}$ be an $m \times n$ matrix & consider $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$.

We will use the following notation:

• $N(A)$ - Null space of A (which is \mathbb{R}^n , i.e., in the domain of A)

• $C(A)$ - Column space of A , generated by column vectors,
- which is nothing but the range of A

• $\bar{R}(A)$ - Row space of A , generated by row vectors.
- which is a subspace of \mathbb{R}^m , the domain of A .

So, $N(A) \& \bar{R}(A) \subseteq \mathbb{R}^n$ and $C(A) \subseteq \mathbb{R}^m$.

Since $A^T = (a_{ji})_{n \times m}$, $A^T: \mathbb{R}^m \rightarrow \mathbb{R}^n$ and hence $N(A^T) \subseteq \mathbb{R}^m$. (1412)

Note that $N(A)$ and $\bar{R}(A)$ are subspaces of \mathbb{R}^n - the domain of A & $C(A)$ & $N(A^T)$ are subspaces of \mathbb{R}^m - the range of A & $\bar{R}(A^T) = C(A)$.

Relations between $N(A)$ and $\bar{R}(A)$ (resp. $C(A)$ & $N(A^T)$):

Lemma: $N(A) \perp \bar{R}(A)$ in \mathbb{R}^n and $N(A^T) \perp C(A)$ in \mathbb{R}^m

Proof: Note that $w \in N(A) \Leftrightarrow Aw = 0$. Therefore if v is a row vector of A , then $v \cdot w = 0$. This proves that $N(A) \perp \bar{R}(A)$.
For the next one, do the same with A^T . \square

From the above lemma and Rank-Nullity Theorem, we have the following orthogonal decomposition.

Theorem: For any $m \times n$ matrix A , we have

$$(1). N(A) \oplus \bar{R}(A) = \mathbb{R}^n \quad (2). N(A^T) \oplus C(A) = \mathbb{R}^m$$

Proof: Since $\dim(\bar{R}(A)) = \dim(\text{row space}) = \dim(\text{column space}) = \dim(\text{range of } A)$, $\dim(\bar{R}(A)) + \dim(N(A)) = n$ by Rank-Nullity Theorem. Therefore, $\dim(N(A)) = \dim(\bar{R}(A))^\perp$. Since $N(A) \subseteq \bar{R}(A)^\perp$ by previous lemma, we have $N(A) = \bar{R}(A)^\perp$. The proof of the other one is similar. \square

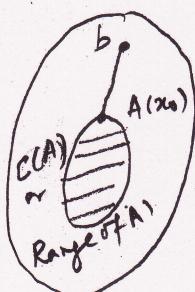
Sometimes the above result is called FT of A .

An Application: (Least square solutions)

Problem: Consider the system $Ax = b$. If $b \in C(A) = \text{range of } A$, then the system is consistent and has a solution.
If $b \notin C(A)$ or the system is inconsistent, then we find a "pseudo" solution or best possible solution in some sense.

Least square solution: Let $A = (a_{ij})_{m \times n}: \mathbb{R}^n \rightarrow \mathbb{R}^m$.

Find $x_0 \in \mathbb{R}^n$ s.t. $\|Ax_0 - b\| = \min_{x \in \mathbb{R}^n} \|Ax - b\|$.



We will show that such x_0 exists (was not be unique, though Ax_0 is unique). The element x_0 is called a least square solution. We will use the FT of LA to find x_0 explicitly. L14 (3)

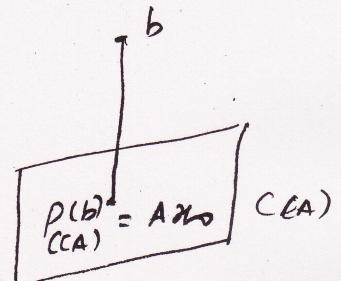
What is x_0 : Since $C(A)$ or the range of A is a subspace of \mathbb{R}^n , $A(x_0)$ has to be the projection of b over $C(A)$ i.e. $P_{C(A)}(b)$. Since $P_{C(A)}(b) \in C(A)$, $\exists x_0 \in \mathbb{R}^n$ s.t. $Ax_0 = P_{C(A)}(b)$. So x_0 exists.

Note that $x_0 + N(A)^\perp$ is the least square solution set.

How to find Ax_0 & x_0 : one way is to find the orthogonal projection of b over $C(A)$. To find the projection, one has to find an orthonormal basis of $C(A)$ using G-S process. Such a computation may be cumbersome. Here we will take a bypass using the FT of LA to find x_0 .

The method: Note that by FT of LA,

$$\mathbb{R}^n = C(A) \oplus N(A^T) \Rightarrow b = P_{C(A)}(b) - P_{C(A)}(b) - b \\ = Ax_0 - (Ax_0 - b)$$



$$\Rightarrow A^T(Ax_0 - b) = 0 \quad \text{as } Ax_0 - b \in N(A^T)$$

$$\Rightarrow A^T A x_0 = A^T b$$

$\Rightarrow x_0$ is a solution of the normal equation $A^T A x_0 = A^T b$.

Remark: (1) We have shown that if x_0 is a least square solution then it satisfies the equation: $A^T A x = A^T b$. One can go back in the previous argument & show the converse. So we have: x_0 is a least square solution $\Leftrightarrow x_0$ satisfies $A^T A x = A^T b$.

(2) Note that $Ax - b$ may not be zero for some x , but $A(Ax - b) = 0$ for some x_0 . So, instead of solving the original equation $Ax = b$, we solve the equation: $A^T A x = A^T b$.