

$$S_x(f) = \int_{-\infty}^{+\infty} R_x(\tau) e^{-j2\pi f\tau} d\tau$$

$$S_x(f) = TCF[R_x(\tau)]$$

PROPRIETÀ della  $S_x(f)$  (DSP)

1)  $S_x(f)$  è reale e pari

poiché la  $R_x(\tau)$  è reale e pari

$$2) \int_{-\infty}^{+\infty} S_x(f) df = P_x$$

Dim.

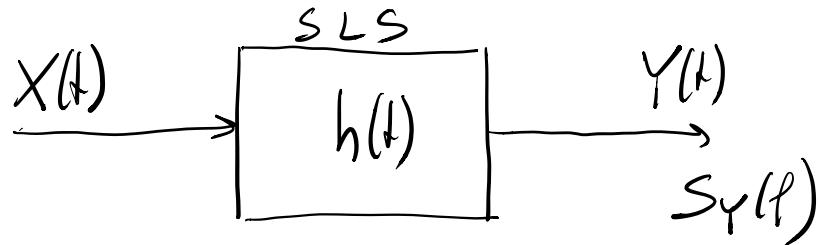
$$P_x \triangleq E[X(t)^2] = R_x(\tau) \Big|_{\tau=0} = R_x(0)$$

$$R_x(0) = R_x(\tau) \Big|_{\tau=0} = \left. \int_{-\infty}^{+\infty} S_x(f) e^{j2\pi f\tau} df \right|_{\tau=0} = \int_{-\infty}^{+\infty} S_x(f) df$$

3)  $S_x(f) \geq 0 \quad \forall f$  non-negativo

Dim. in seguito

FILTRAGGIO DI UN PROCESSO SSL E CALCOLO  
DELLA DSP DEL PROCESSO IN USCITA



$X(t)$  è SSL

$$\begin{aligned}
 S_Y(f) &= TCF [R_Y(\tau)] \\
 &= TCF \left[ R_x(\tau) \underbrace{\otimes h(\tau) \otimes h(-\tau)}_{R_Y(\tau)} \right] \\
 &= S_x(f) |H(f)| H^*(f) = S_x(f) |H(f)|^2
 \end{aligned}$$

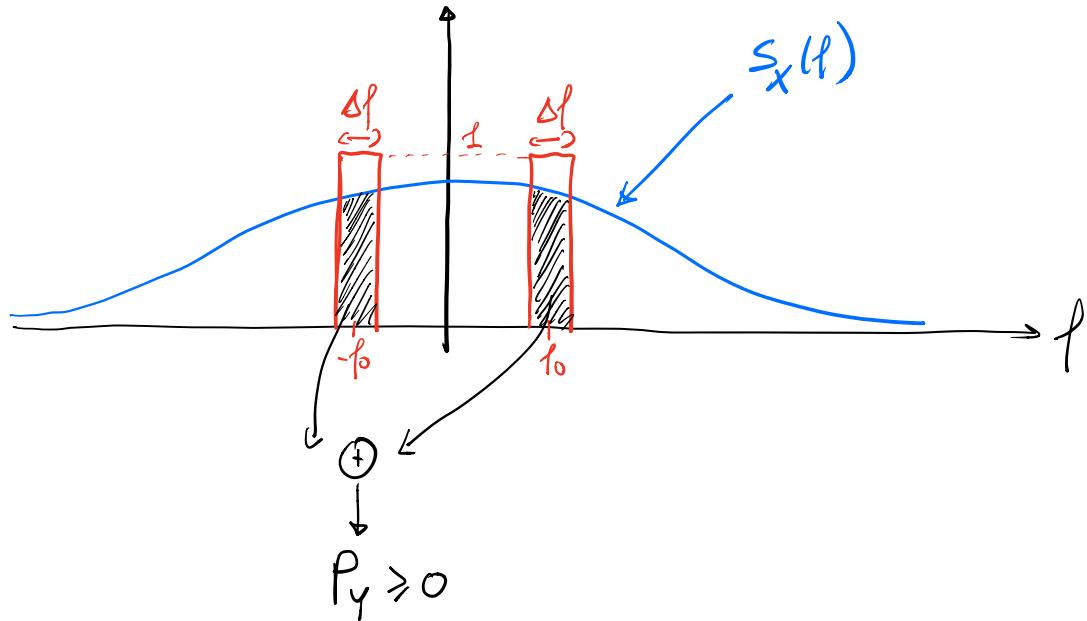
posso già stabilire  
 che  $Y(t)$  è SSL

$$S_Y(f) = S_x(f) |H(f)|^2$$

POTENZA MEDIA DEL P.A. IN USCITA

$$P_Y = \int_{-\infty}^{+\infty} S_Y(f) df = \int_{-\infty}^{+\infty} S_x(f) |H(f)|^2 df$$

$$\Rightarrow P_Y \geq 0$$



$$\Delta f \rightarrow 0 \Rightarrow P_Y = 2 \underbrace{S_X(f_0)}_{\geq 0} \Delta f > 0 \quad \forall f_0$$

$$\Rightarrow S_X(f_0) \geq 0 \quad \forall f_0$$

$$S_X(f) \geq 0 \quad \forall f$$

Dimostrazione  
della 3<sup>a</sup> proprietà  
delle DSP

PROCESSO DI RUMORE BIANCO

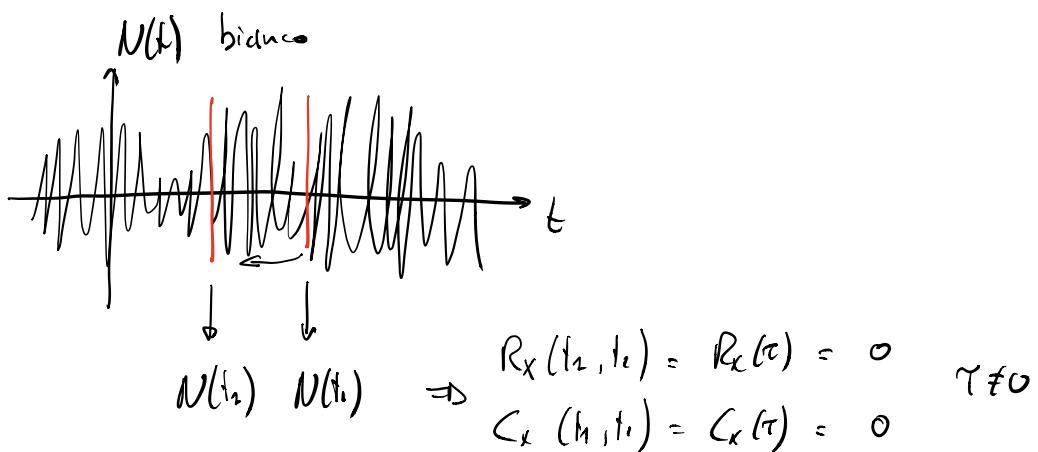
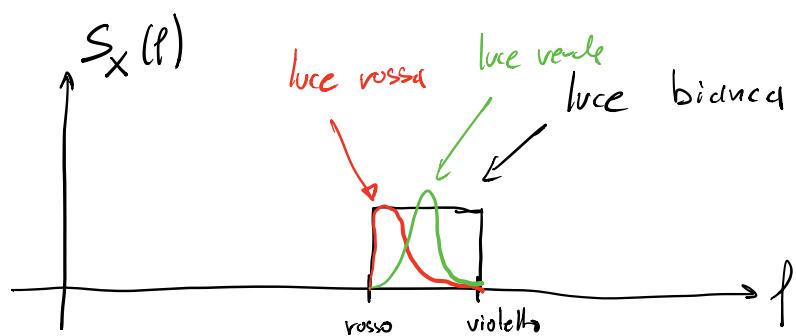
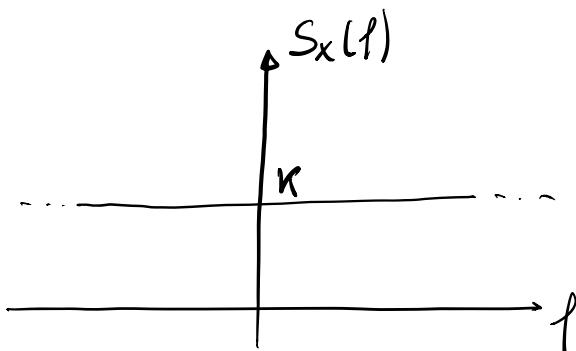
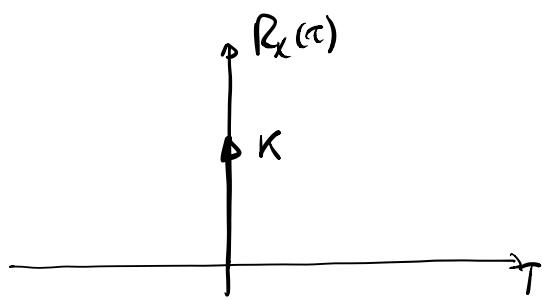
$X(t)$  si dice bianco se

$$\cdot) \mu_X = 0$$

$$\cdot) R_X(\tau) = K \delta(\tau) = C_X(\tau)$$

RUMORE BIANCO  $\Rightarrow$  SSL

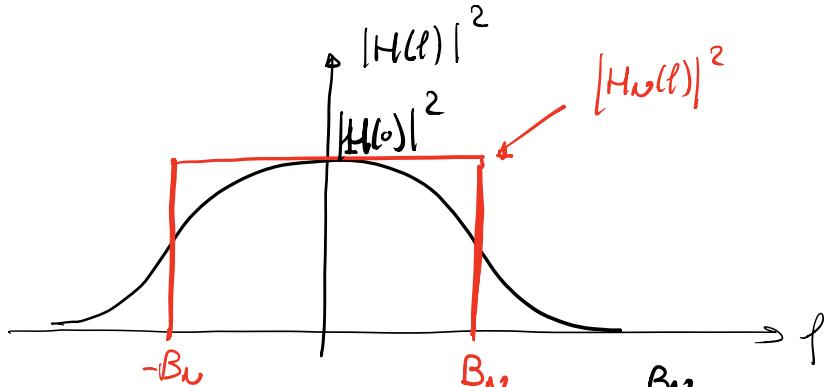
$$S_x(f) = K \quad \forall f$$



$$N(t_2) - N(t_1) \Rightarrow R_x(t_2, t_1) = R_x(\tau) = 0 \quad \gamma \neq 0$$

$$C_x(t_2, t_1) = C_x(\tau) = 0$$

BANDA EQUIVALENTE DI PUNZONI DI UN FILTRO



$$B_N : P_Y = \left| \int_{-\infty}^{+\infty} S_X(f) |H(f)|^2 df \right| = \left| \int_{-B_N}^{B_N} S_X(f) |H(0)|^2 df \right|$$

$S_X(f) = K$

$$\Rightarrow P_Y = K \int_{-B_N}^{B_N} |H(f)|^2 df = K |H(0)|^2 \cdot 2 B_N$$

$$B_N \triangleq \frac{\int_{-\infty}^{+\infty} |H(f)|^2 df}{2 |H(0)|^2}$$

$\Rightarrow$  PROCESSI ALEATORI GAUSSIANI

Definizione: un processo aleatorio si dice gaussiano se, estraendo  $N$  V.A., con  $N$  arbitrario, ad istanti  $t_1, t_2, \dots, t_N$  arbitrari, si ottiene un vettore di dimensione  $N$  di V.A. congiuntamente gaussiane

$\Rightarrow$  Ai fini pratici:

$$\underline{X(t)} \xrightarrow{T} \underline{X(T)}$$

$X(t)$  Gaussiano

$X(T)$  è una V.T.

Gaussiana

$\Rightarrow$  PROPRIETÀ DEI PROCESSI ALEATORI GAUSSIANI

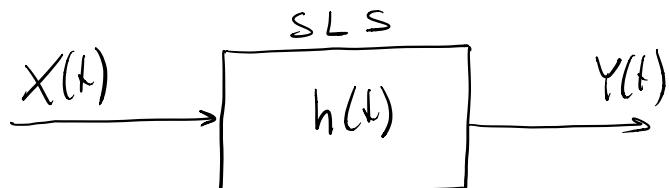
• La conoscenza completa di un processo aleatorio Gaussiano la si ottiene conoscendo solamente

$$\begin{array}{l} \cdot) \mu_X(t) \\ \cdot) R_X(t_1, t_2) \end{array} \quad \left. \begin{array}{l} \text{posso descrivere la} \\ \text{ddp d'ordine } N \end{array} \right\}$$

• Un processo aleatorio Gaussiano SSL è anche SSS

$$SSL \Leftrightarrow SSS$$

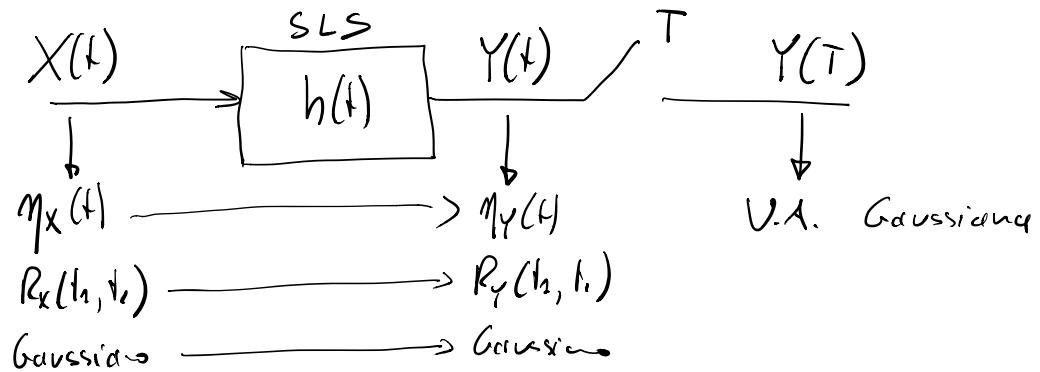
• FILTRAGGIO DI PROCESSI ALEATORI GAUSSIANI



$X(t)$  è Gaussiano

$Y(h)$  è Gaussiano

Per i sistemi di comunicazione



→ RUMORE BIANCO

$$m_x(t) = 0$$

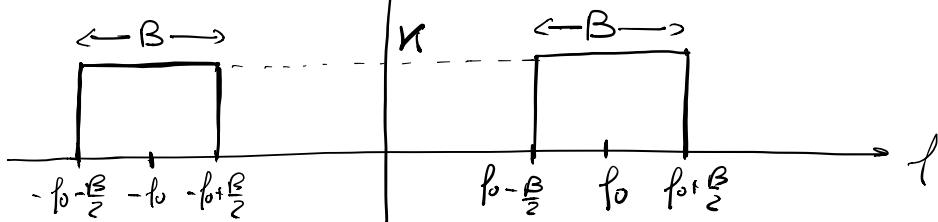
$$R_x(\tau) = K \delta(\tau)$$

$$S_x(f) = K \quad \forall f$$

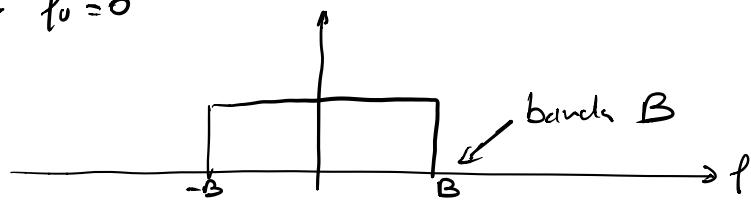
→ RUMORE BIANCO IN BANDA

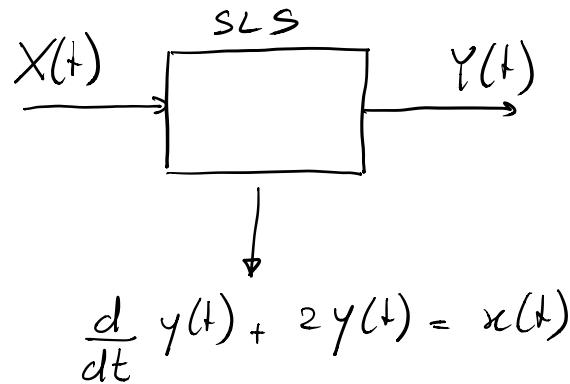
$$m_x(t) = 0$$

$$S_x(f)$$



per  $f_0 = 0$





$X(t)$  è Gaussiano bianco

$$R_x(\tau) = \frac{N_0}{2} \delta(\tau)$$

- 1)  $R_Y(\tau)$ ,  $S_Y(f)$  e disegnare i grafici
- 2) Calcolare  $P_X$ ,  $P_Y$
- 3) Scrivere la dd p di  $Y(t_0)$ , estratta da  $Y(t)$  all'istante  $t_0$
- 4) Calcolare la probabilità che  $Y > \sqrt{\frac{N_0}{2}}$

Soluzione

$$1) \quad \frac{d}{dt} y(t) + 2y(t) = x(t)$$

$$j2\pi f Y(f) + 2Y(f) = X(f)$$

$$Y(f) [2 + j2\pi f] = X(f)$$

$$\frac{Y(f)}{X(f)} = H(f) = \frac{1}{2+j2\pi f}$$

$$S_Y(f) = S_X(f) |H(f)|^2 = \frac{N_0}{2} \left| \frac{1}{2+j2\pi f} \right|^2 = \frac{N_0}{2} \frac{1}{4+4\pi^2 f^2}$$

$$R_Y(\tau) = \text{ATCF} [S_Y(f)]$$

$$e^{-|t|} \stackrel{\text{TCF}}{\iff}$$

$$\begin{aligned} & \int_{-\infty}^{+\infty} e^{-at} e^{-j2\pi ft} dt = \int_{-\infty}^{0} e^{at} e^{-j2\pi ft} dt + \\ & + \int_{0}^{+\infty} e^{at} e^{-j2\pi ft} dt = \int_{-\infty}^{0} e^{(a-j2\pi f)t} dt + \\ & + \int_{0}^{+\infty} e^{-(a+j2\pi f)t} dt = \frac{1}{a+j2\pi f} e^{(a-j2\pi f)t} \Big|_{00}^{00} + \\ & + \left( -\frac{1}{a+j2\pi f} \right) e^{-(a+j2\pi f)t} \Big|_0^{+\infty} \end{aligned}$$

$$= \frac{1}{a-j\pi^2f} + \frac{1}{a+j\pi^2f} = \frac{2a}{a^2+4\pi^2f^2}$$

$$e^{-at} \Leftrightarrow \frac{2a}{a^2+4\pi^2f^2} = \frac{2a}{a^2+4\pi^2f^2} \cdot \frac{1}{1+\frac{4}{a^2}\pi^2f^2}$$

$$S_Y(f) = \frac{N_0}{8} \frac{1}{1+\pi^2f^2}$$

$$e^{-at} \Leftrightarrow \frac{2}{a} \frac{1}{1+\frac{4}{a^2}\pi^2f^2} \Leftarrow \begin{matrix} \text{risultato} \\ \text{generico} \end{matrix}$$

$$a = 2$$

$$R_Y(\tau) = \frac{N_0}{8} e^{-2|\tau|} \Leftrightarrow \frac{N_0}{8} \frac{1}{1+\pi^2f^2} = S_Y(f)$$

$$R_Y(\tau) = \frac{N_0}{8} e^{-2|\tau|}$$

$$H(f) = \frac{1}{2+j\pi^2f} \xrightarrow{\text{Altro strada}} h(t) \Rightarrow R_Y(\tau) = R_X(\tau) \otimes h(\tau) \otimes h(\tau)$$

$$h(t) = \text{ATCF} [H(t)]$$

$$\begin{aligned}
 & \int_{-\infty}^{+\infty} e^{-at} u(t) e^{-j2\pi f t} dt \\
 &= \int_0^{+\infty} e^{-(a+j2\pi f)t} dt = -\frac{1}{a+j2\pi f} e^{- (a+j2\pi f)t} \Big|_0^{+\infty} \\
 &= \frac{1}{a+j2\pi f}
 \end{aligned}$$

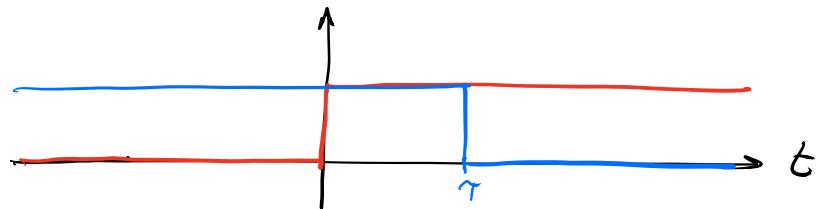
$$a = 2$$

$$h(t) = e^{-2t} u(t) \xrightarrow{\text{TCF}} \frac{1}{2+j2\pi f} = H(f)$$

$$R_x(\tau) = \frac{N_0}{2} \delta(\tau)$$

$$\begin{aligned}
 R_y(\tau) &= \frac{N_0}{2} \underbrace{\delta(\tau)}_{h(\tau)} \otimes h(\tau) \otimes h(-\tau) \\
 &= \frac{N_0}{2} h(\tau) \otimes h(-\tau)
 \end{aligned}$$

$$R_y(\tau) = \frac{N_0}{2} \int_{-\infty}^{+\infty} e^{-2t} e^{-2(\tau-t)} u(t) u(\tau-t) dt$$



$$\tau < 0 \Rightarrow R_Y(\tau) = 0$$

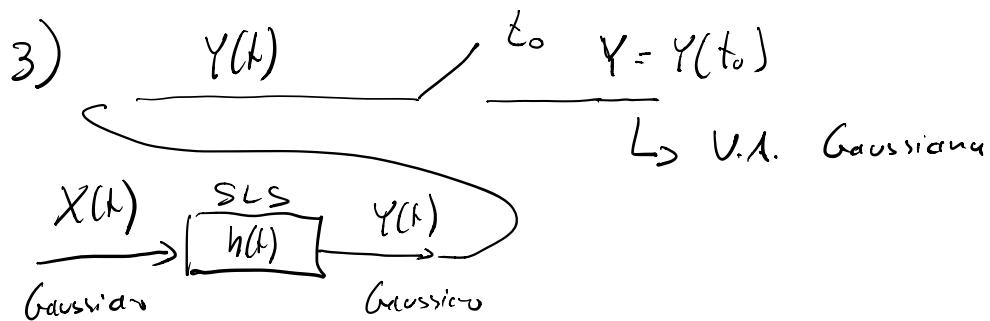
$$R_Y(\tau) = \frac{N_0}{2} \int_0^{\tau} dt e^{-2T}$$

da risolvere  
è una storia più  
complicata della  
precedente

$$2) P_X, P_Y$$

$$P_X = \int_{-\infty}^{+\infty} S_X(f) df = \int_{-\infty}^{+\infty} \frac{N_0}{2} df = \boxed{\infty}$$

$$P_Y = \begin{cases} R_Y(\tau) \Big|_{\tau=0} = R_Y(0) = \boxed{\frac{N_0}{8}} \\ \int_{-\infty}^{+\infty} S_Y(f) df \end{cases}$$



$$d\omega P(Y) = ?$$

$$f_Y(y) = \frac{1}{\sqrt{2\pi\sigma_y^2}} e^{-\frac{(y-\mu_y)^2}{2\sigma_y^2}}$$

$$\begin{aligned} \mu_Y &=? \\ \sigma_y^2 &=? \end{aligned}$$

$$\eta_y = \eta_y(t_0)$$

$$\left. \eta_y(t) \right|_{t=t_0} = \eta_y$$

$$\eta_y(t) = \eta_x(t) \otimes h(t) = 0$$

$\eta_x(t) = 0$  poiché il processo  $X(t)$  è bicastro

$$\sigma_y^2 = \left. \sigma_y^2(t) \right|_{t=t_0}$$

$$\begin{aligned} \eta_x(t) &= 0 & R_x(t_0, t_0) &= R_x(\tau) \\ R_x(\tau) &= \frac{N_0}{2} d(\tau) \end{aligned}$$

$$\sigma_y^2(t) = P_y(t) - \eta_y^2(t) = P_y(t)$$

$$\sigma_y^2(t_0) = P_y(t_0) = P_y = R_y(0) \quad \text{costante}$$

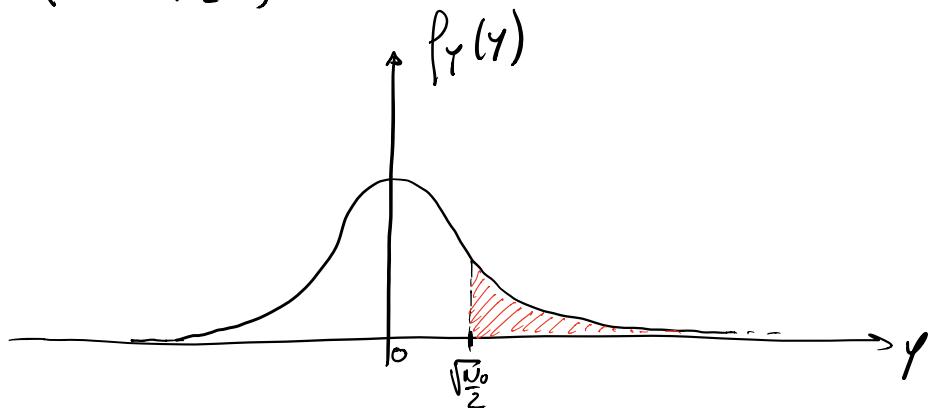
$$\sigma_y^2 = P_y = \frac{N_0}{8}$$

$$f_y(y) = \frac{1}{\sqrt{2\pi \frac{N_0}{8}}} e^{-\frac{y^2}{2\frac{N_0}{8}}} = \boxed{\frac{2}{\sqrt{\pi N_0}} e^{-\frac{y^2}{N_0}}}$$

$$f_y(y; t_0) \Rightarrow f_y(y)$$

non importa dove si campiona  
il risultato è indipendente da  $t_0$

$$a) P(Y > \sqrt{\frac{N_0}{2}})$$



$$P(Y > \sqrt{\frac{N_0}{2}}) = \int_{\sqrt{\frac{N_0}{2}}}^{+\infty} p_Y(y) dy$$

$$Q(x) = \int_x^{+\infty} p_N(u) du \quad N \sim \mathcal{N}(0, 1) \\ Y \sim \mathcal{N}(0, \frac{N_0}{8})$$

$$N = \frac{Y - \mu_Y}{\sigma_Y}$$

$$x = \frac{\sqrt{\frac{N_0}{2}} - 0}{\sqrt{\frac{N_0}{8}}} = \sqrt{4} = 2$$

$$P\{Y > \sqrt{\frac{N_0}{2}}\} = P\{N > 2\} = Q(2)$$

$Q(x)$   $\begin{cases} \text{tabelle} \\ \text{calcolabile con MATLAB o altri tools di calcolo} \end{cases}$

ESERCIZIO - 11/11/2019

$$Y(t) = X(t) + W(t)$$

$X(t) = A$ ,  $A$  v.a. con media nulla e varianza  $\sigma_A^2$

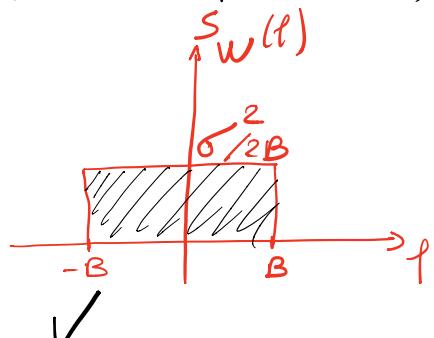
$W(t)$  = rumore bianco in banda  $B$  con potenza  $\sigma^2$   $W(t)$  è indipend. da  $X(t)$

1) Verificare se  $Y(t)$  è SSL

2) Calcolare  $S_Y(t)$

Soluzione

$$\begin{aligned} 1) Y(t) \text{ SSL?} & \quad \stackrel{\eta_Y(t) = \eta_Y}{\longrightarrow} \quad \checkmark \\ & \quad \stackrel{R_Y(t_1, t_2) = R_Y(t_2 - t_1) = R_Y(\tau)}{\longrightarrow} \end{aligned}$$



$$\eta_Y(t) = E[Y(t)] = E[X(t) + W(t)] =$$

$$= E[X(t)] + E[W(t)]$$

$$E[X(t)] = E[A] = 0$$

$\nwarrow$  A è una v.a. con media nulla  
(dato del problema)

$$E[W(t)] = 0 \quad (\text{poiché è un rumore bianco})$$

$$\eta_W = 0, R_W(\tau) = K \delta(\tau)$$

$$\eta_Y(t) = E[Y(t)] = 0 + 0 = 0 \quad \text{constante}$$

$$\begin{aligned} R_Y(t_1, t_2) &= E[Y(t_1) Y(t_2)] = E[(X(t_1) + W(t_1))(X(t_2) + W(t_2))] \\ &= E[X(t_1) X(t_2)] + E[X(t_1) W(t_2)] + E[W(t_1) X(t_2)] + E[W(t_1) W(t_2)] \\ &= R_X(t_1, t_2) + \underset{\text{o}}{E[X(t_1)]} \underset{\text{o}}{E[X(t_2)]} + \underset{\text{o}}{E[W(t_1)]} \underset{\text{o}}{E[W(t_2)]} \\ &\quad + R_W(t_1, t_2) \\ &= R_X(t_1, t_2) + R_W(t_1, t_2) \end{aligned}$$

$$\Rightarrow R_X(t_1, t_2) = E[X(t_1) X(t_2)] = E[\sigma_A^2] = \sigma_A^2 + \underset{\text{o}}{\eta_A^2} = \underline{\underline{\sigma_A^2}}$$

$$R_X(\tau) = \sigma_A^2 \quad \text{constante}$$

$$S_W(f) = \frac{\sigma^2}{2B} \operatorname{rect}\left(\frac{f}{2B}\right)$$

$$\Rightarrow R_W(t_1, t_2) = R_W(\tau) = \sigma^2 \operatorname{sinc}(2B\tau)$$

$$\begin{cases} R_Y(\tau) = \sigma_A^2 + \sigma^2 \operatorname{sinc}[2B(\tau)] & \text{dipende da } \tau = t_1 - t_2 \\ \eta_Y(t) = 0 & \text{constante} \end{cases}$$

\$\rightarrow Y(t)\$ é SSL

$$2) S_Y(f) = ?$$

$$S_Y(f) = TCF[R_Y(\tau)] = \sigma_A^2 \delta(f) + \frac{\sigma^2}{2B} \operatorname{rect}\left(\frac{f}{2B}\right)$$

ESERCIZIO - 06/06/2017

$U(t)$  Gaussiano SSL

$$\eta_U(t) = 0$$

$$R_U(\tau) = \sigma_U^2 \operatorname{sinc}(2B\tau)$$

- 1) Si estragga una v.a.  $U = U(0)$ . Si descriva la dd.p. di  $U$
- 2)  $Y(t) = U(t) + 3U(t-\tau)$ . Calcolare:
  - .)  $S_Y(t)$
  - .)  $R_Y(\tau)$

Soluzione

$$\underbrace{U(t)}_{\text{v.a.}} \xrightarrow{t=0} U$$

$$f_U(u) = ?$$

$$U(t) \text{ Gaussiano} \Rightarrow U \in \mathcal{N}(\eta_U, \sigma_U^2)$$

$$U(t) \text{ a v.m. nullo} \Rightarrow \eta_U(t) = 0 \Rightarrow \eta_U = 0$$

$$\begin{aligned}\sigma_U^2(t) &= P_U(t) - \eta_U^2(t) = P_U - 0 = P_U = R_U(0) \\ &= \sigma_U^2\end{aligned}$$

$$U \in \mathcal{N}(0, \sigma_U^2)$$

$$f_U(u) = \frac{1}{\sqrt{2\pi\sigma_U^2}} e^{-\frac{u^2}{2\sigma_U^2}}$$

$$2) Y(t) = U(t) + 3U(t-\tau)$$

$$S_Y(\ell) = ?$$

$$\begin{aligned}
 R_Y(t_1, t_2) &= E[Y(t_1)Y(t_2)] \\
 &= E[(U(t_1) + 3U(t_1-\tau))(U(t_2) + 3U(t_2-\tau))] \\
 &= E[U(t_1)U(t_2)] + 3[E[U(t_1-\tau)U(t_2)] + \\
 &\quad + 3E[U(t_1)U(t_2-\tau)] + 9E[U(t_1-\tau)U(t_2-\tau)]] \\
 &= R_U(t_1-t_2) + 3R_U(t_1-\tau-t_2) + \\
 &\quad + 3R_U(t_1-t_2+\tau) + 9R_U(t_1-t_2) \\
 &= 10R_U(t_1-t_2) + 3R_U(t_1-t_2-\tau) + \\
 &\quad 3R_U(t_1-t_2+\tau) \\
 &= 10R_U(\tau) + 3R_U(\tau-\tau) + 3R_U(\tau+\tau) \\
 S_Y(\ell) &= 10S_U(\ell) + 3S_U(\ell)e^{-j2\pi f\tau} + 3S_U(\ell)e^{j2\pi f\tau}
 \end{aligned}$$

$$= 10 S_v(f) + 6 S_u(f) \frac{e^{j2\pi fT} + e^{-j2\pi fT}}{2}$$

$$= S_v(f) [10 + 6 \cos(2\pi fT)]$$

$$S_v(f) = TCF[R_v(\tau)] = \frac{\sigma_v^2}{2B} \operatorname{rect}\left(\frac{f}{2B}\right)$$

$$\Rightarrow \boxed{S_y(f) = (10 + 6 \cos(2\pi fT)) \frac{\sigma_v^2}{2B} \operatorname{rect}\left(\frac{f}{2B}\right)}$$