

$$f: A \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$$

1)  $m = 1$  (funzione reale)

2)  $n = 1$   $m \geq 1$  curve

3)  $n = 2$   $m \geq 2$  superfici

4)  $n < m$  varietà  $n$ -dimensionali in  $\mathbb{R}^m$

5)  $n = m$

$$f: A \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$$

cambio di coordinate

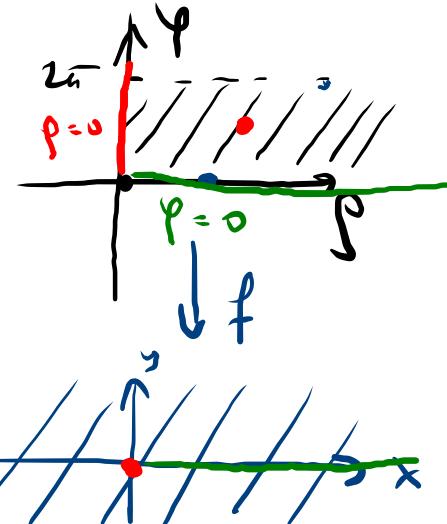
Esempio

1°

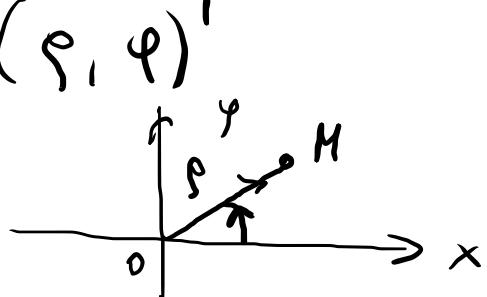
$[0, 2\pi]$ , oppure  $\mathbb{R}$   
cioè identificando  
 $\varphi$  con  $\varphi + 2\pi$ ,  
 $R \subset \mathbb{R}$

$$f : [0, +\infty) \times [0, 2\pi] \subset \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad (n=m=2)$$

$$f(\rho, \varphi) = (\rho \cos \varphi, \rho \sin \varphi)$$



$f$  : coordinate polari in  $\mathbb{R}^2$   $\longmapsto$  coordinate cartesiane  $(x, y)$



$$f(\rho, \varphi) = (x(\rho, \varphi), y(\rho, \varphi))$$

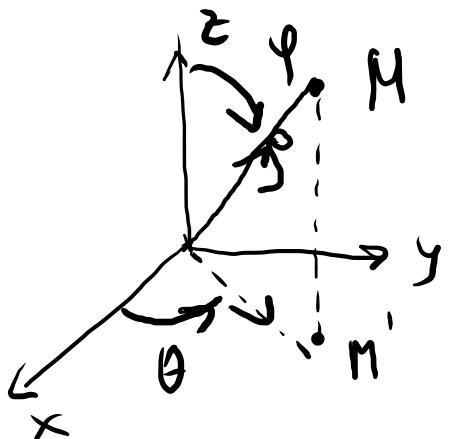
$$\begin{cases} x = \rho \cos \varphi \\ y = \rho \sin \varphi \end{cases}$$

$$Df(\rho, \varphi) = \begin{pmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \varphi} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \varphi} \end{pmatrix} = \begin{pmatrix} \cos \varphi & -\rho \sin \varphi \\ \sin \varphi & \rho \cos \varphi \end{pmatrix}$$

$$\det Df(p, \varphi) = p \cdot \cos^2 \varphi + p \sin^2 \varphi = p$$

jacobian

2°  $f: (\underbrace{\rho, \theta, \varphi}_{\text{koordinat. sferische}}) \in [0, +\infty) \times [0, 2\pi] \times [0, \bar{\pi}] \xrightarrow{\text{IR}} \begin{matrix} \xrightarrow{\quad} \\ \xrightarrow{\quad} \end{matrix} (\rho \cos \theta \sin \varphi, \rho \sin \theta \sin \varphi, \rho \cos \varphi)$



$$Df(\rho, \varphi, \theta) = \begin{pmatrix} x_\rho & x_\theta & x_\varphi \\ y_\rho & y_\theta & y_\varphi \\ z_\rho & z_\theta & z_\varphi \end{pmatrix} =$$

$$= \begin{pmatrix} \cos \theta \sin \varphi & -\rho \sin \theta \sin \varphi & \rho \cos \theta \cos \varphi \\ \sin \theta \sin \varphi & \rho \cos \theta \sin \varphi & \rho \sin \theta \cos \varphi \\ \cos \varphi & 0 & -\rho \sin \varphi \end{pmatrix}$$

$$J(\rho, \varphi, \theta) := \det Df(\rho, \varphi, \theta) = \rho^2 \sin \varphi \begin{vmatrix} \cos \theta \sin \varphi & \sin \theta & \cos \theta \cos \varphi \\ \sin \theta \sin \varphi & \cos \theta & \sin \theta \cos \varphi \\ \cos \varphi & 0 & -\sin \varphi \end{vmatrix}$$

$$= \rho^2 \sin \varphi \left( \cos \varphi (-\sin^2 \theta \underline{\cos \varphi} - \cos^2 \theta \underline{\cos \varphi}) - \sin \varphi (\cos^2 \theta \underline{\sin \varphi} + \sin^2 \theta \underline{\sin \varphi}) \right)$$

$$= \rho^2 \sin \varphi (\cos^2 \varphi \cdot (-1) - \sin^2 \varphi (\cos^2 \theta + \sin^2 \theta)) =$$

$$= -\rho^2 \sin^3 \varphi$$

$$3^{\circ} \quad f: [0, +\infty) \times [0, 2\pi] \times \mathbb{R} \rightarrow \mathbb{R}^3$$

~~$\mathbb{R}$~~

$$(\rho, \varphi, z') \in [0, +\infty) \times [0, 2\pi] \times \mathbb{R} \mapsto$$

coord. cilindriche

$$\mapsto (\rho \cos \varphi, \rho \sin \varphi, z')$$

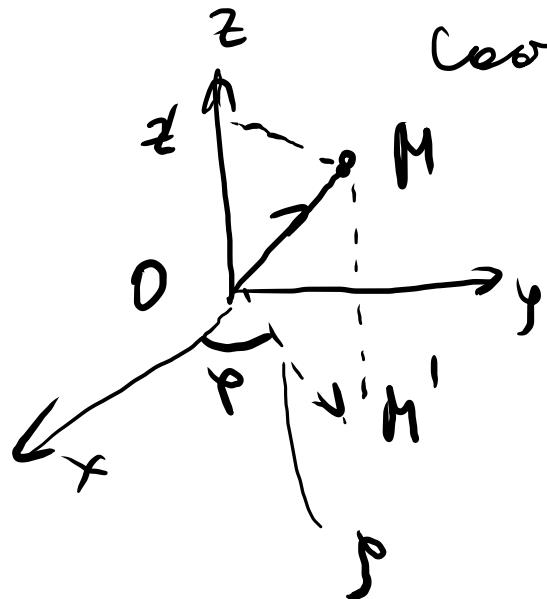
$x \quad y \quad z$

$$x = \rho \cos \varphi$$

$$y = \rho \sin \varphi$$

$$z = z'$$

coordinate cartesiane



$$Df(\rho, \varphi, z') = \begin{pmatrix} \cos \varphi & -\sin \varphi & 0 \\ \sin \varphi & \cos \varphi & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

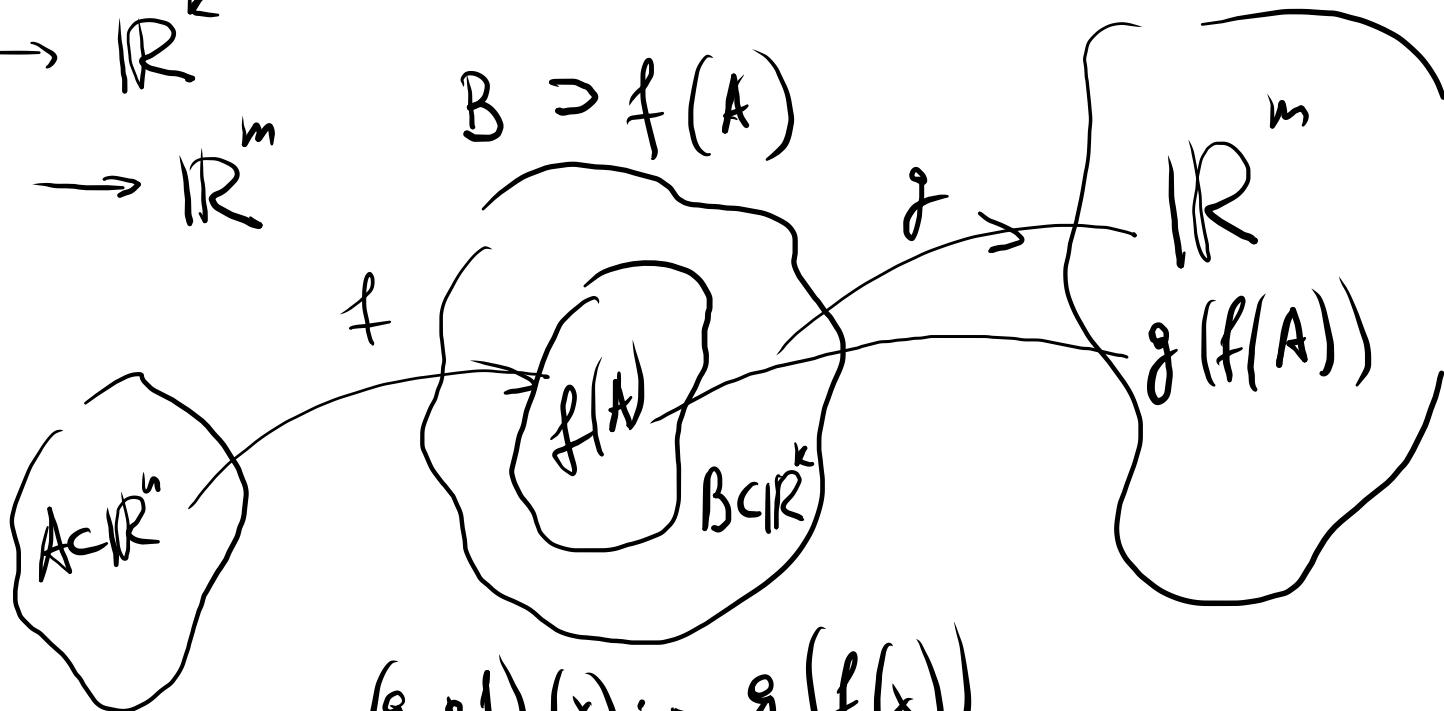
$$J(\rho, \varphi, z') = \det Df(\rho, \varphi, z') = \rho$$

# Differentiabile di funzioni composte

$$f: A \subset \mathbb{R}^n \rightarrow \mathbb{R}^k$$

$$g: B \subset \mathbb{R}^k \rightarrow \mathbb{R}^m$$

$$B \supset f(A)$$



$$(g \circ f)(x) := g(f(x))$$

$$g \circ f: A \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$$

## Teorema

Sia  $x_0$  punto interno di A

$f(x_0)$  punto di B

$f$  differenziabile in  $x_0$

$g$  differenziabile in  $f(x_0)$

Allora,  $g \circ f : A \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$  è  
differenziabile in  $x_0$  e

$$D(g \circ f)(x_0) = \underbrace{(Dg)}_{m \times k}(f(x_0)) \underbrace{(Df)}_{k \times h}(x_0)$$

## Casi particolari

1)  $m = k = n = 1$ , A, B intervalli  
 $(g \circ f)'(x_0) = g'(f(x_0)) f'(x_0)$

2)  $m = 1, n = 1, A$  intervalli

$$f: \mathbb{R}^k \rightarrow \mathbb{R}^k \quad | \quad g \circ f : A \subset \mathbb{R} \rightarrow \mathbb{R}$$

$$g: \bigcup_{t \in f(A)} \mathbb{R}^k \rightarrow \mathbb{R} \quad | \quad (g \circ f)'(t_0) =$$

$$= \nabla g^A(f(t_0)) \cdot \dot{f}(t_0)$$

$$\nabla g(f(t_0))^T \dot{f}(t_0) = \nabla g(f(t_0)) \dot{f}(t_0)$$

vetture  
(colonne)

matrice  
 $1 \times k$

vetture  
colonne  
(ovvero  
matrice  
 $k \times 1$ )

$$3) f: A \subset \mathbb{R}^n \rightarrow \mathbb{R}$$

$$g: \mathbb{R} \rightarrow \mathbb{R}$$

$x_0 \in A$  intern,  $f$  é diff in  $x_0$ ,  
 $g$  --- in  $f(x_0)$

$$g \circ f: A \subset \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\nabla(g \circ f)(x_0) = g'(f(x_0)) \nabla f(x_0)$$

Esercizi

1)  $h(x,y) = \sin(x^2+y^2)$

$$h = g \circ f \quad g(z) = \sin z \\ f(x,y) = x^2+y^2$$

$$\begin{aligned} \nabla g(x,y) &= g'(f(x,y)) \nabla f(x,y) = \\ &= \cos(x^2+y^2) \begin{pmatrix} 2x, 2y \end{pmatrix} = \\ &= \left( 2x \cos(x^2+y^2), 2y \cos(x^2+y^2) \right) \end{aligned}$$

2).

$$f(x,y) = x^2 + y^2$$

$$\gamma(t) = (a \cos t, b \sin t) \quad a, b > 0$$

$$\begin{aligned}
 (f \circ \gamma)(t)' &= \nabla f(\gamma(t)) \cdot \dot{\gamma}(t) = \\
 &= (2\gamma_x(t), 2\gamma_y(t)) \cdot (\dot{\gamma}_x(t), \dot{\gamma}_y(t)) \\
 &= (2a \cos t, 2b \sin t) \cdot (-a \sin t, b \cos t) \\
 &= -2a^2 \cos t \sin t + 2b^2 \sin t \cos t = \\
 &= 2(b^2 - a^2) \sin t \cos t
 \end{aligned}$$

Volendo, si può fare anche direttamente

$$\begin{aligned}
 (f \circ \gamma)(t) &= (a^2 \cos^2 t + b^2 \sin^2 t)' = \\
 &= 2(b^2 - a^2) \sin t \cos t
 \end{aligned}$$

## Applicazioni

Def.  $f: A \subset \mathbb{R}^n \rightarrow \mathbb{R}$  (scalare)

differenziabile

$x_0$  è punto di <sup>massimo</sup> <sub>minimo</sub>

locale di  $f$   
se  $\exists p > 0 : f(x_0) \stackrel{>}{\leq} f(x)$   
 $\forall x \in B_p(x_0)$

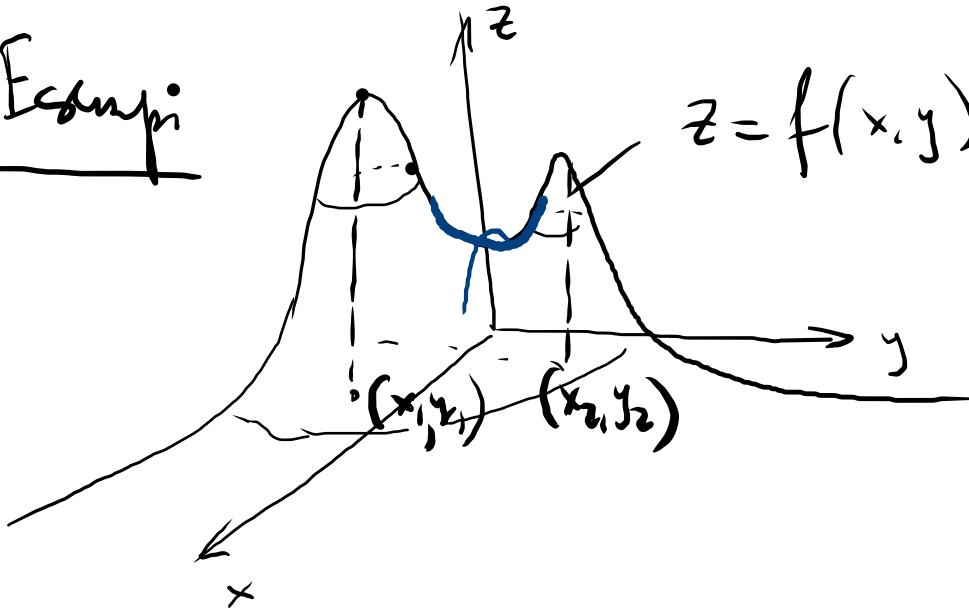
Se inoltre  $f(x_0) \stackrel{>}{\leq} f(x) \quad \forall x \in B_p(x_0), \quad x \neq x_0$ ,  
allora  $x_0$  si dice di <sup>massimo</sup> <sub>minimo</sub>

locale stretto

$x_0$  è punto di <sup>massimo</sup> <sub>minimo</sub> (globale), se  $f(x) \stackrel{>}{\leq} f(x_0)$

Se inoltre  $f(x_0) \stackrel{>}{<} f(x) \quad \forall x \in A, \quad x \neq x_0$   
allora  $x_0$  è di <sup>massimo</sup> <sub>minimo</sub> (globale)  
stretto

Esempio



$$z = f(x, y)$$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$f(x_1, y_1) > f(x_2, y_2) > 0$$

$$\lim_{(x, y) \rightarrow \infty} f(x, y) = 0$$

$$f(x, y) > 0$$

$(x_1, y_1)$  e  $(x_2, y_2)$  sono punti di massimo locale  
di  $f$  (anche stretto)

$(x_1, y_1)$  è anche punto di massimo  
(globale),

$(x_2, y_2)$  non è di massimo globale,  
anche stretto  
solo locale

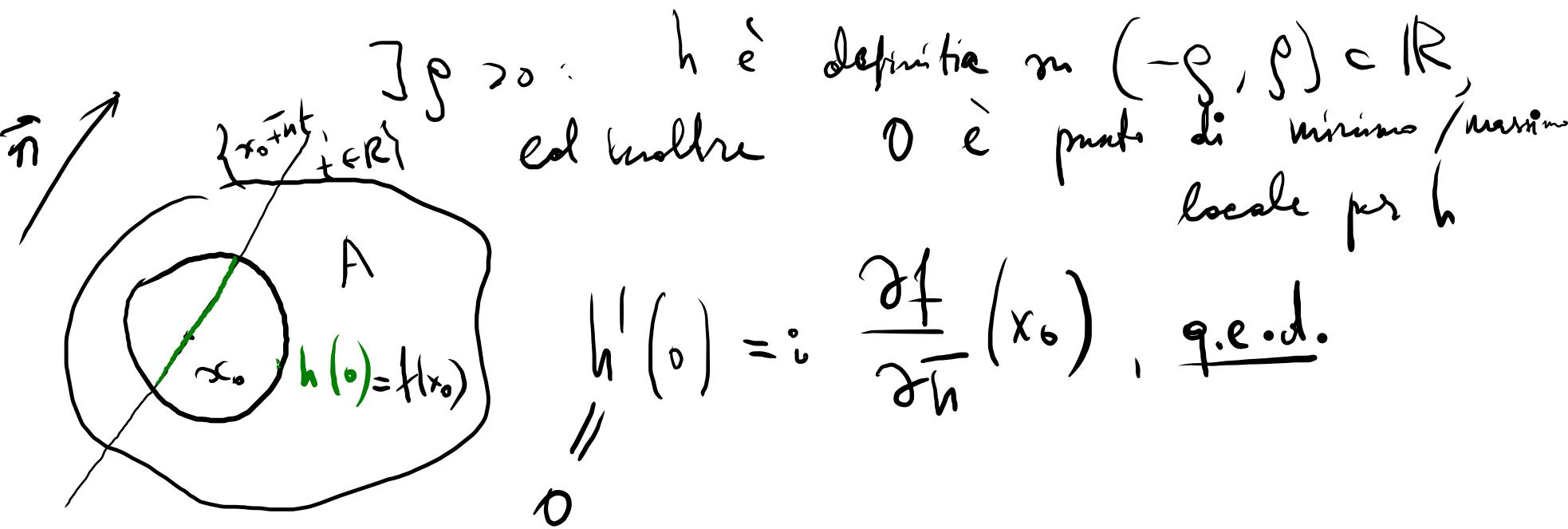
non ci sono minimi globali

Th (Fermat) { Se  $f: A \subset \mathbb{R}^n \rightarrow \mathbb{R}$   
                   aperto  
                   assumette minima (o massima)  
                   locale in  $x_0 \in A$ , ed è  
                   derivabile in direzione di  
                    $\bar{n}$  in  $x_0$ , allora

$$\frac{\partial f}{\partial \bar{n}}(x_0) = 0$$

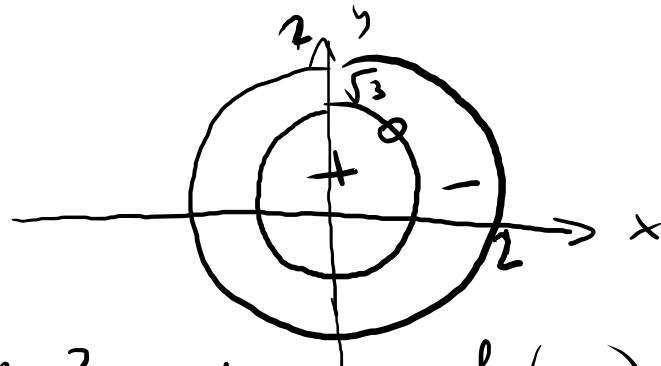
Corollario { Sotto ipotesi del th di Fermat  
                   è  $f$  derivabile in tutte  
                   le direzioni in  $x_0$ , allora  
 $\nabla f(x_0) = 0$   
                   In particolare questo vale per  
                    $f$  differenziabili in  $x_0$ .

$$\text{Defin} \quad h(t) := f(x_0 + \bar{h}t) \quad t \in \mathbb{R}$$



Esempio:  $f(x,y) := \log(4-x^2-y^2) \rightarrow \max$

$$\begin{aligned} D(f) &:= \left\{ (x,y) \in \mathbb{R}^2 : 4-x^2-y^2 > 0 \right\} = \\ &= \left\{ (x,y) \in \mathbb{R}^2 : x^2+y^2 < 4 \right\} \end{aligned}$$



$$4-x^2-y^2 \geq 1 \Leftrightarrow f(x,y) \geq 0$$

$$\begin{matrix} \uparrow \\ x^2+y^2 \leq 3 \end{matrix}$$

$$\begin{cases} \frac{\partial f}{\partial x} = \frac{1}{4-x^2-y^2} \cdot 2x = 0 \\ \frac{\partial f}{\partial y} = \frac{1}{4-x^2-y^2} \cdot 2y = 0 \end{cases} \Leftrightarrow \begin{matrix} (x,y) = 0 \\ | \end{matrix}$$

punto di  
massimo

Da ricordare :  $f: I \subset \mathbb{R} \rightarrow \mathbb{R}$   
intervalli  
aperti

Th. di Fermat

1)  $x_0 \in I$      $\exists f'(x_0)$ ;  $x_0$  punto di  
massimo/minimo  
locale di  $f$   
 $\Rightarrow f'(x_0) = 0$

2)  $x_0 \in I$ ,  $\exists f'(x_0), f''(x_0)$   
 $f'(x_0) = 0$ ,  $f''(x_0) < 0 \Rightarrow x_0$  è di  
massimo  
locale

$f'(x_0) = 0$ ,  $f''(x_0) > 0 \Rightarrow x_0$  è di  
minimo  
locale

Derivate di ordine superiore

$f: A \subset \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $x_0 \in A$   
 \aperto

$$\nabla f(x_0) = \left( \underbrace{f_{x_1}(x_0)}, \dots, \underbrace{f_{x_n}(x_0)} \right)$$

$$\frac{\partial f_{x_j}}{\partial x_k} =: \frac{\partial^2 f}{\partial x_j \partial x_k}$$

$$\frac{\partial f_{x_k}}{\partial x_k} =: \frac{\partial^2 f}{\partial x_k^2}$$

$$\frac{\partial}{\partial x_m} \left( \frac{\partial^2 f}{\partial x_j \partial x_k} \right) =: \frac{\partial^3 f}{\partial x_j \partial x_k \partial x_m}$$

$$k=j$$

$$k=j=m$$

$$\begin{aligned} & \frac{\partial^3 f}{\partial x_j^2 \partial x_m} \\ & \frac{\partial^3 f}{\partial x_j^3} \end{aligned}$$

Notazione comoda

multindice  $(\alpha_1, \dots, \alpha_n)$   $\alpha_j \in \mathbb{N}$

$$\mathcal{D}^\alpha f = \mathcal{D}^{(\alpha_1, \dots, \alpha_n)} f := \frac{\partial^{| \alpha |} f}{\partial x_1^{\alpha_1} \partial x_2^{\alpha_2} \dots \partial x_n^{\alpha_n}}$$

$$| \alpha | = \alpha_1 + \alpha_2 + \dots + \alpha_n$$

Esempio )  $n=3$   $\alpha = (1, 0, 2)$   $| \alpha | = 3$

$$\mathcal{D}^\alpha f = \frac{\partial^3 f}{\partial x_1 \partial x_2^0 \partial x_3^2}$$

)  $n=5$   $\alpha = (2, 1, 0, 1, 3)$ ,  $| \alpha | = 7$

$$\mathcal{D}^\alpha f = \frac{\partial^7 f}{\partial x_1^2 \partial x_2 \partial x_3^0 \partial x_4^1 \partial x_5^3}$$

$$\nabla f = \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) \quad f = f(x, y)$$

$$D^2 f = \text{Hess } f := \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}$$

Ejemplo  $f(x, y) = e^{-x^2 + 3y^2}$

$$\nabla f(x, y) = e^{-x^2 + 3y^2} \begin{pmatrix} -2x & 6y \\ -2x & -x^2 + 3y^2 \end{pmatrix} =$$

$$= \begin{pmatrix} -2x e^{-x^2 + 3y^2} & 6y e^{-x^2 + 3y^2} \\ -2e^{-x^2 + 3y^2} + (2x)^2 e^{-x^2 + 3y^2} & -2x e^{-x^2 + 3y^2} \cdot 6y \end{pmatrix}$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$$