

Baye's Theorem

$$P(E_i | A) = \frac{P(E_i) \cdot P(A|E_i)}{P(E_1) \cdot P(A|E_1) + P(E_2) \cdot P(A|E_2) + P(E_3) \cdot P(A|E_3)}$$

Binomial Distribution

$$P(r) = {}^n C_r p^r q^{n-r}$$

n = Total no. of trials

r = No. of successful trials

Poisson Distribution

$$P(r) = \frac{e^{-m} \cdot m^r}{r!}$$

Conditional Probability

The probability of occurrence of A under the condition that B has already occurred.

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

Counting Principles

$$P(A \text{ or } B) = P(A) + P(B)$$

$$P(AB) = P(A) \cdot P(B)$$

Probability Axioms

$$P(A) \geq 0$$

$$P(S) = 1 \quad S = \text{Sample Space}$$

$$P(A \cup B) = P(A) + P(B)$$

Random Variable \rightarrow A random variable is a numerical outcome of a random process or experiment.

Discrete Probability Distribution \rightarrow Represents probabilities of a discrete random variable, which takes on a countable number of possible values.

Continuous Probability Distributions \rightarrow Represents probabilities of a continuous random variable, which can take any value in a given range or interval.

Expectation (Mean) → The expectation of a random variable is average of all its possible values

Variance → It quantifies how much the values deviate from the expectation

Standard Deviation → It is the square root of variance.

Joint Probability Distribution → It models the likelihood of two or more random variables occurring simultaneously.

Bernoulli Distribution → It is a discrete probability distribution for a random variable that has two possible outcomes : Success (i) with probability p , and failure with probability $1-p$.

$$Z = \frac{\bar{x} - \mu}{\sigma / \sqrt{n}}$$

OR

Sample mean - population mean
Population standard deviation / $\sqrt{\text{Sample Size}}$

Bisection Method

$$x_2 = \frac{x_0 + x_1}{2}$$

Lagrange's Interpolation formula

$$y = (x-x_1)(x-x_2)(x-x_3) y_0 + \frac{(x-x_0)(x-x_2)(x-x_3)}{(x_0-x_1)(x_0-x_2)(x_0-x_3)} y_1 - \frac{(x-x_0)(x-x_1)(x-x_2)}{(x_1-x_0)(x_1-x_2)(x_1-x_3)} y_2 -$$

Regula Falsi Method

$$x_2 = x_1 - \frac{f(x_1)}{f(x_1) - f(x_0)}$$

Newton Raphson's Method

$$x_2 = x_1 - \frac{f(x_1)}{f'(x_1)}$$

Gauss Elimination Method \rightarrow Change matrix to upper triangular matrix and compare values

LU Decomposition Method \rightarrow Change A into two matrices, upper and lower triangular

$$\text{One} \Rightarrow AX = B \Rightarrow A = LU \Rightarrow LUX = B \Rightarrow UX = C \Rightarrow UC = B$$

Newton's Forward Interpolation Formula

$$y = y_0 + P \Delta y_0 + \frac{P(P-1)}{2!} \Delta^2 y_0 + \frac{P(P-1)(P-2)}{3!} \Delta^3 y_0 \dots \quad x$$

Newton's Backward Interpolation Formula

$$y = y_n + P \nabla y_n + \frac{P(P+1)}{2!} \nabla^2 y_n + \frac{P(P+1)(P+2)}{3!} \nabla^3 y_n \dots \quad x$$

$$\text{where } P = \frac{x-x_0}{h} \text{ OR } \frac{x-x_n}{h}$$

(Forward)

(Backward)

Newton's Divided Difference Interpolation

$$y = y_0 + \Delta y_0(x - x_0) + \Delta^2 y_0(x - x_0)(x - x_1) - \dots$$

Derivative using Newton's Forward Difference

$$\frac{dy}{dx} = \frac{1}{h} \left[\Delta y_0 - \frac{1}{2} \Delta^2 y_0 + \frac{1}{3} \Delta^3 y_0 - \frac{1}{4} \Delta^4 y_0 - \dots \right]$$

$$\frac{d^2 y}{dx^2} = \frac{1}{h^2} \left[\Delta^2 y_0 - \Delta^3 y_0 + \frac{11}{12} \Delta^4 y_0 - \frac{5}{6} \Delta^5 y_0 - \dots \right]$$

Derivative using Newton's Backward Difference

$$\frac{dy}{dx} = \frac{1}{h} \left[\nabla y_n + \frac{1}{2} \nabla^2 y_n + \frac{1}{3} \nabla^3 y_n + \frac{1}{4} \nabla^4 y_n - \dots \right]$$

$$\frac{d^2 y}{dx^2} = \frac{1}{h^2} \left[\nabla^2 y_n + \nabla^3 y_n + \frac{11}{12} \nabla^4 y_n + \frac{5}{6} \nabla^5 y_n - \dots \right]$$

Taylor's Series

$$y = y_0 + h y'_0 + \frac{h^2}{2!} y''_0 + \frac{h^3}{3!} y'''_0 + \frac{h^4}{4!} y''''_0 - \dots$$

(where $h = x - x_0$)

Derivative using Newton's Central Difference

$$\frac{dy}{dx} = \frac{1}{h} \left[\frac{(\Delta y_{j+1} + \Delta y_j)}{2} - \frac{1}{6} \left(\frac{\Delta^3 y_{j-2} + \Delta^3 y_{j-1}}{2} \right) - \dots \right]$$

$$\frac{d^2 y}{dx^2} = \frac{1}{h^2} \left[\Delta^2 y_{j-1} - \frac{1}{12} \Delta^4 y_{j-2} \right]$$

Integration using Trapezoidal rule

$$\int_{x_0}^{x_n} f(x) dx = \frac{h}{2} [(y_0 + y_n) + 2(y_1 + y_2 + y_3 + \dots + y_{n-1})]$$

Integration using Simpson's 1/3rd rule

$$\int_{x_0}^{x_n} f(x) dx = \frac{h}{3} [(y_0 + y_n) + 4(y_1 + y_3 + y_5 + \dots + y_{n-1}) + 2(y_2 + y_4 + y_6 + \dots)]$$

Integration using Simpson's 3/8th rule

$$\int_{x_0}^{x_n} f(x) dx = \frac{3h}{8} [(y_0 + y_n) + 3(y_1 + y_2 + y_4 + y_5 + y_7 + y_8) + 2(y_3 + y_6 + y_9 + \dots)]$$

Picard's Iterative method

$$y_1 = y_0 + \int_{x_0}^{x_1} f(x, y_0) dx \quad y_{n+1} = y_0 + \int_{x_0}^{x_{n+1}} f(x, y_n) dx$$

Taylor's Series Method

$$y_2 = y_0 + h y'_0 + \frac{h^2}{2!} y''_0 + \frac{h^3}{3!} y'''_0 + \frac{h^4}{4!} y^{(iv)}_0$$

Euler's Method

$$y_1 = y_0 + h f(x_0, y_0) \quad \left\{ \begin{array}{l} y_{n+1} = y_n + h f(x_n, y_n) \end{array} \right.$$

$$\log(1) = 0$$

$$\log(10) = 1$$

$$e^1 = 2.718$$

$$e^0 = 1$$

$$\log(e) = \text{Undefined}$$

$$\log(100) = 2$$

$$e^{-1} = 0.367$$

Runge's Method

$$y_1 = y_0 + \frac{1}{6} (k_1 + 4k_2 + k_3) \quad | \quad y_{n+1} = y_n + \frac{1}{6} (k_1 + 4k_2 + k_3)$$

$$\text{where } k_1 = h f(x_0, y_0)$$

$$k_2 = h f\left(x + \frac{h}{2}, y + \frac{1}{2} k_1\right)$$

$$k_3 = h f\left(x + h, y + 2k_2 - k_1\right)$$

Runge Kutta's Method

$$y_1 = y_0 + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4), \quad | \quad y_{n+1} = y_n + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4)$$

where

$$k_1 = h f(x, y)$$

$$k_2 = h f\left(x + \frac{1}{2} h, y + \frac{1}{2} k_1\right)$$

$$k_3 = h f\left(x + \frac{1}{2} h, y + \frac{1}{2} k_2\right)$$

$$k_4 = h f(x + h, y + k_3)$$