YSU Statistical ML, Fall 2019 Lecture 01

Michael Poghosyan YSU, AUA michael@ysu.am, mpoghosyan@aua.am

12 November 2019

Contents

► The Supervised Learning Problem

 $\label{eq:condition} \text{Everything starts from Data}.$

Everything starts from Data.

Here we assume we are given:

Everything starts from Data.

Here we assume we are given:

▶ The Input Space X

Everything starts from Data.

Here we assume we are given:

- ▶ The Input Space X
- ightharpoonup The Output Space ${\cal Y}$

Everything starts from Data.

Here we assume we are given:

- ightharpoonup The Input Space ${\mathcal X}$
- ightharpoonup The Output Space ${\cal Y}$

We will assume $\mathcal{X} \subset \mathbb{R}^d$ (or, maybe, in other d-Dim Space), and a typical element \mathbf{x} of \mathcal{X} will have the form

$$\mathbf{x} = (x_1, x_2, ..., x_d)$$

Everything starts from Data.

Here we assume we are given:

- ightharpoonup The Input Space ${\mathcal X}$
- ightharpoonup The Output Space ${\cal Y}$

We will assume $\mathcal{X} \subset \mathbb{R}^d$ (or, maybe, in other d-Dim Space), and a typical element \mathbf{x} of \mathcal{X} will have the form

$$\mathbf{x} = (x_1, x_2, ..., x_d)$$

We will call x_k -s to be the **Features** of **x**.

Everything starts from Data.

Here we assume we are given:

- ightharpoonup The Input Space ${\mathcal X}$
- lacktriangle The Output Space ${\cal Y}$

We will assume $\mathcal{X} \subset \mathbb{R}^d$ (or, maybe, in other d-Dim Space), and a typical element \mathbf{x} of \mathcal{X} will have the form

$$\mathbf{x} = (x_1, x_2, ..., x_d)$$

We will call x_k -s to be the **Features** of **x**.

We will assume also that $\mathcal{Y} \subset \mathbb{R}$, and we will call the elements of \mathcal{Y} to be the **Labels**.

In the Supervised Learning Problems, we have a Data of the form:

$$(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), ..., (\mathbf{x}_n, y_n).$$

In the Supervised Learning Problems, we have a Data of the form:

$$(x_1, y_1), (x_2, y_2), ..., (x_n, y_n).$$

Here we interpret \mathbf{x}_k and y_k as the Feature vector and the Label of the Observation (Object) k.

In the Supervised Learning Problems, we have a Data of the form:

$$(x_1, y_1), (x_2, y_2), ..., (x_n, y_n).$$

Here we interpret \mathbf{x}_k and y_k as the Feature vector and the Label of the Observation (Object) k.

So we know the labels of our n Observations.

In the Supervised Learning Problems, we have a Data of the form:

$$(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), ..., (\mathbf{x}_n, y_n).$$

Here we interpret \mathbf{x}_k and y_k as the Feature vector and the Label of the Observation (Object) k.

So we know the labels of our n Observations.

Problem: Given a Feature vector \mathbf{x} , other than \mathbf{x}_k , predict its Label y.

Recall that our Feature Vector $\mathbf{x} \in \mathcal{X}$ has the form:

$$\mathbf{x} = (x_1, x_2, ..., x_d).$$

Recall that our Feature Vector $\mathbf{x} \in \mathcal{X}$ has the form:

$$\mathbf{x} = (x_1, x_2, ..., x_d).$$

Recall that our Feature Vector $\mathbf{x} \in \mathcal{X}$ has the form:

$$\mathbf{x} = (x_1, x_2, ..., x_d).$$

The Features x_k can be:

▶ Binary, if $x_k \in \{0,1\}$ or $x_k \in \{-1,1\}$

Recall that our Feature Vector $\mathbf{x} \in \mathcal{X}$ has the form:

$$\mathbf{x} = (x_1, x_2, ..., x_d).$$

- ▶ Binary, if $x_k \in \{0,1\}$ or $x_k \in \{-1,1\}$
- Nominal/Categorical, if the set of possible values of x_k is finite, and no intrinsic order exists in that set

Recall that our Feature Vector $\mathbf{x} \in \mathcal{X}$ has the form:

$$\mathbf{x} = (x_1, x_2, ..., x_d).$$

- ▶ Binary, if $x_k \in \{0,1\}$ or $x_k \in \{-1,1\}$
- Nominal/Categorical, if the set of possible values of x_k is finite, and no intrinsic order exists in that set
- ightharpoonup Ordinal, if the set of possible values of x_k is finite, and there is a natural order in that set

Recall that our Feature Vector $\mathbf{x} \in \mathcal{X}$ has the form:

$$\mathbf{x} = (x_1, x_2, ..., x_d).$$

- ▶ Binary, if $x_k \in \{0,1\}$ or $x_k \in \{-1,1\}$
- Nominal/Categorical, if the set of possible values of x_k is finite, and no intrinsic order exists in that set
- ightharpoonup Ordinal, if the set of possible values of x_k is finite, and there is a natural order in that set
- ▶ Numerical/Quantitative, if $x_k \in \mathbb{R}$

The Labels can be:

The Labels can be:

Classification Problems:

 $\blacktriangleright \ \mathcal{Y} = \{-1,1\} \text{ or } \mathcal{Y} = \{0,1\}$ - Binary Classification

The Labels can be:

Classification Problems:

- $\blacktriangleright \ \mathcal{Y} = \{-1,1\} \text{ or } \mathcal{Y} = \{0,1\}$ Binary Classification
- \triangleright $\mathcal{Y} = \{1, 2, ..., K\}$ K-class Classification

The Labels can be:

Classification Problems:

- $\blacktriangleright \ \mathcal{Y} = \{-1,1\} \text{ or } \mathcal{Y} = \{0,1\}$ Binary Classification
- $\blacktriangleright \ \mathcal{Y} = \{1, 2, ..., K\}$ K-class Classification

Regression Problems:

 $ightharpoonup \mathcal{Y} = \mathbb{R}$ - 1D Regression

The Labels can be:

Classification Problems:

- $\blacktriangleright \ \mathcal{Y} = \{-1,1\} \text{ or } \mathcal{Y} = \{0,1\}$ Binary Classification
- $ightharpoonup \mathcal{Y} = \{1, 2, ..., K\}$ K-class Classification

Regression Problems:

 $ightharpoonup \mathcal{Y} = \mathbb{R}$ - 1D Regression

Ranking Problems:

 $\triangleright \mathcal{Y}$ is a finite ordered set

Examples

See Vorontsov's Lecture Slides

So, having a Dataset of Observations with Labels, we want to predict the Label for a new Observation. Of course, we cannot do this unless we will assume there is some structure, some relationship in the Data.

So, having a Dataset of Observations with Labels, we want to predict the Label for a new Observation. Of course, we cannot do this unless we will assume there is some structure, some relationship in the Data. Mathematically, we will assume that behind our Data we have a Probability Distribution, generating our Data.

So, having a Dataset of Observations with Labels, we want to predict the Label for a new Observation. Of course, we cannot do this unless we will assume there is some structure, some relationship in the Data. Mathematically, we will assume that behind our Data we have a Probability Distribution, generating our Data.

We will assume that the observation $(\mathbf{x}, y) \in \mathcal{X} \times \mathcal{Y}$ is a realization of the pair of r.v.s (\mathbf{X}, Y) that is coming from some unknown Distribution \mathcal{F} :

$$(\mathbf{X}, Y) \sim \mathcal{F}.$$

So, having a Dataset of Observations with Labels, we want to predict the Label for a new Observation. Of course, we cannot do this unless we will assume there is some structure, some relationship in the Data. Mathematically, we will assume that behind our Data we have a Probability Distribution, generating our Data.

We will assume that the observation $(\mathbf{x}, y) \in \mathcal{X} \times \mathcal{Y}$ is a realization of the pair of r.v.s (\mathbf{X}, Y) that is coming from some unknown Distribution \mathcal{F} :

$$(X, Y) \sim \mathcal{F}.$$

So we "encode" our Data (\mathbf{x}_k, y_k) as being a realisation of a r.v. (\mathbf{X}_k, Y_k) .

So, having a Dataset of Observations with Labels, we want to predict the Label for a new Observation. Of course, we cannot do this unless we will assume there is some structure, some relationship in the Data. Mathematically, we will assume that behind our Data we have a Probability Distribution, generating our Data.

We will assume that the observation $(\mathbf{x}, y) \in \mathcal{X} \times \mathcal{Y}$ is a realization of the pair of r.v.s (\mathbf{X}, Y) that is coming from some unknown Distribution \mathcal{F} :

$$(X, Y) \sim \mathcal{F}.$$

So we "encode" our Data (\mathbf{x}_k, y_k) as being a realisation of a r.v. (\mathbf{X}_k, Y_k) .

The general idea/Problem is, having Data, to infer \mathcal{F} .

This is a very general problem, so we consider the following:

This is a very general problem, so we consider the following: Given a sequence of $\mbox{IID r.v.s}$

$$(X_1, Y_1), (X_2, Y_2), ..., (X_n, Y_n)$$

construct a "good" Prediction Function

$$g: \mathcal{X} \to \mathcal{Y}$$
,

that will predict the Label of X.

Supervised Learning, Loss Function

Here we need to talk about different things:

Supervised Learning, Loss Function

Here we need to talk about different things:

▶ What is the meaning that g is giving "good" labels, is a "good" Predictor, how to assess that?

Supervised Learning, Loss Function

Here we need to talk about different things:

- ▶ What is the meaning that *g* is giving "good" labels, is a "good" Predictor, how to assess that?
- How to construct good Predictors?

Here we need to talk about different things:

- ▶ What is the meaning that g is giving "good" labels, is a "good" Predictor, how to assess that?
- How to construct good Predictors?

Construction of g, using the Data we have, is called **Training**.

Here we need to talk about different things:

- ▶ What is the meaning that g is giving "good" labels, is a "good" Predictor, how to assess that?
- ► How to construct good Predictors?

Construction of g, using the Data we have, is called **Training**. Predicting the values for new observations is called **Testing**.

Here we need to talk about different things:

- ▶ What is the meaning that *g* is giving "good" labels, is a "good" Predictor, how to assess that?
- How to construct good Predictors?

Construction of g, using the Data we have, is called **Training**. Predicting the values for new observations is called **Testing**.

To assess goodness of the Predictor g, we take a **Loss** function.

Here we need to talk about different things:

- ▶ What is the meaning that g is giving "good" labels, is a "good" Predictor, how to assess that?
- How to construct good Predictors?

Construction of g, using the Data we have, is called **Training**. Predicting the values for new observations is called **Testing**.

To assess goodness of the Predictor g, we take a **Loss** function. We will call any function of the form

$$\ell:\mathcal{Y}\times\mathcal{Y}\to\mathbb{R}$$

a **Loss** function, and we will assume that:

$$\ell(y_1,y_2) \geq 0, \qquad \forall y_1,y_2 \in \mathcal{Y}, \qquad \text{and} \qquad \ell(y,y) = 0.$$

Some known Loss Functions are:

Some known Loss Functions are:

► For The Binary Classification:

$$\ell(y_1, y_2) = \begin{cases} 1, & y_1 \neq y_2 \\ 0, & y_1 = y_2 \end{cases}$$

¹Here we use the Indicator, $\mathbf{1}(x)$ function with $\mathbf{1}(True) = 1$ and $\mathbf{1}(False) = 0$.

Some known Loss Functions are:

► For The Binary Classification:

$$\ell(y_1, y_2) = \begin{cases} 1, & y_1 \neq y_2 \\ 0, & y_1 = y_2 \end{cases}$$

We denote this $\mathbf{1}$ as $\mathbf{1}(y_1 \neq y_2)$.

¹Here we use the Indicator, $\mathbf{1}(x)$ function with $\mathbf{1}(\mathit{True}) = 1$ and $\mathbf{1}(\mathit{False}) = 0$.

Some known Loss Functions are:

► For The Binary Classification:

$$\ell(y_1, y_2) = \begin{cases} 1, & y_1 \neq y_2 \\ 0, & y_1 = y_2 \end{cases}$$

We denote this $\mathbf{1}$ as $\mathbf{1}(y_1 \neq y_2)$.

- ► For 1D Regression:
 - $\ell(y_1, y_2) = (y_1 y_2)^2$ Quadratic Loss;

¹Here we use the Indicator, $\mathbf{1}(x)$ function with $\mathbf{1}(True) = 1$ and $\mathbf{1}(False) = 0$.

Some known Loss Functions are:

► For The Binary Classification:

$$\ell(y_1, y_2) = \begin{cases} 1, & y_1 \neq y_2 \\ 0, & y_1 = y_2 \end{cases}$$

We denote this $\mathbf{1}$ as $\mathbf{1}(y_1 \neq y_2)$.

- ► For 1D Regression:
 - $\ell(y_1, y_2) = (y_1 y_2)^2$ Quadratic Loss;
 - $\ell(y_1, y_2) = |y_1 y_2|$ Absolute Error Loss;

¹Here we use the Indicator, $\mathbf{1}(x)$ function with $\mathbf{1}(True) = 1$ and $\mathbf{1}(False) = 0$.

Now assume we have a Predictor $g: \mathcal{X} \to \mathcal{Y}$, and a Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$.

Now assume we have a Predictor $g: \mathcal{X} \to \mathcal{Y}$, and a Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$.

Assume $(\mathbf{X}, Y) \sim \mathcal{F}$.

Now assume we have a Predictor $g: \mathcal{X} \to \mathcal{Y}$, and a Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$.

Assume $(\mathbf{X}, Y) \sim \mathcal{F}$. So **X** is our Feature Vector, and we Predict its label as $g(\mathbf{X})$.

Now assume we have a Predictor $g: \mathcal{X} \to \mathcal{Y}$, and a Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$.

Assume $(\mathbf{X},Y)\sim\mathcal{F}.$ So \mathbf{X} is our Feature Vector, and we Predict its label as $g(\mathbf{X}).$ Then the Loss incurring will be

$$\ell(Y, g(X)).$$

Now assume we have a Predictor $g: \mathcal{X} \to \mathcal{Y}$, and a Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$.

Assume $(\mathbf{X},Y)\sim\mathcal{F}.$ So \mathbf{X} is our Feature Vector, and we Predict its label as $g(\mathbf{X}).$ Then the Loss incurring will be

$$\ell(Y, g(X)).$$

We want to have this Loss as small as possible.

Now assume we have a Predictor $g: \mathcal{X} \to \mathcal{Y}$, and a Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$.

Assume $(\mathbf{X},Y)\sim\mathcal{F}$. So \mathbf{X} is our Feature Vector, and we Predict its label as $g(\mathbf{X})$. Then the Loss incurring will be

$$\ell(Y, g(X)).$$

We want to have this Loss as small as possible. Well, under our setting, this will be a R.V., so we define the **Average Loss** or the **Risk** of the Predictor g to be

$$Risk(g) = \mathbb{E}(\ell(Y, g(X))).$$

Now assume we have a Predictor $g: \mathcal{X} \to \mathcal{Y}$, and a Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$.

Assume $(\mathbf{X}, Y) \sim \mathcal{F}$. So \mathbf{X} is our Feature Vector, and we Predict its label as $g(\mathbf{X})$. Then the Loss incurring will be

$$\ell(Y, g(X)).$$

We want to have this Loss as small as possible. Well, under our setting, this will be a R.V., so we define the **Average Loss** or the **Risk** of the Predictor g to be

$$Risk(g) = \mathbb{E}(\ell(Y, g(X))).$$

Here the Expectation is over the Distribution of (X, Y), i.e., \mathcal{F} .

Now assume we have a Predictor $g: \mathcal{X} \to \mathcal{Y}$, and a Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$.

Assume $(\mathbf{X}, Y) \sim \mathcal{F}$. So \mathbf{X} is our Feature Vector, and we Predict its label as $g(\mathbf{X})$. Then the Loss incurring will be

$$\ell(Y, g(X)).$$

We want to have this Loss as small as possible. Well, under our setting, this will be a R.V., so we define the **Average Loss** or the **Risk** of the Predictor g to be

$$Risk(g) = \mathbb{E}(\ell(Y, g(X))).$$

Here the Expectation is over the Distribution of (X, Y), i.e., \mathcal{F} .

Now, we can state our Problem of finding a good Predictor: Find g minimizing the Risk, i.e., find

$$g^* \in \operatorname*{argmin}_{g} \mathsf{Risk}(g).$$

Example

Toy Example: Assume $\mathcal{X} = \{1, 2, 3\}$, $\mathcal{Y} = \{0, 1\}$, and we have the Joint Distribution of (X, Y):

| $Y \setminus X$ | 1 | 2 | 3 |
|-----------------|-----|-----|-----|
| 0 | 0.1 | 0.2 | 0.1 |
| 1 | 0.2 | 0.1 | 0.3 |

Assume

$$g(x) = \begin{cases} 0, & \text{if } x \text{ is even} \\ 1, & \text{otherwise} \end{cases}$$

and $\ell(y_1, y_2) = |y_1 - y_2|$. Calculate the Risk(g).

Solution: OTB

The above Minimization Problem is not complete: we need to specify the set of all possible Predictors g.

The above Minimization Problem is not complete: we need to specify the set of all possible Predictors g.

The best case will be if we will take g to be any measurable function from \mathcal{X} to \mathcal{Y} .

The above Minimization Problem is not complete: we need to specify the set of all possible Predictors g.

The best case will be if we will take g to be **any measurable** function from \mathcal{X} to \mathcal{Y} . But, unfortunately, this set is veery large to be able to solve the problem there.

The above Minimization Problem is not complete: we need to specify the set of all possible Predictors g.

The best case will be if we will take g to be **any measurable** function from \mathcal{X} to \mathcal{Y} . But, unfortunately, this set is veery large to be able to solve the problem there.

Usually, we assume that g comes from a Parametric Family of functions, which we call a Predictive Model:

$$g \in \mathcal{G} = \{g(\mathbf{x}|\theta), \ \theta \in \Theta\}, \qquad \text{where} \quad g(\mathbf{x}|\theta) : \mathcal{X} \to \mathcal{Y}.$$

and Θ is some Parameter Set (1D or more).

Predictors, Examples

Say,

▶ In the 1D Linear Regression Problem, we consider

$$g(\mathbf{x}|\theta) = \theta_0 + \theta_1 \cdot x_1 + \dots + \theta_d \cdot x_d;$$

Predictors, Examples

Say,

In the 1D Linear Regression Problem, we consider

$$g(\mathbf{x}|\theta) = \theta_0 + \theta_1 \cdot x_1 + \dots + \theta_d \cdot x_d;$$

In the Binary Classification Problem, with $\mathcal{Y}=\{-1,1\}$, we can consider, say

$$g(\mathbf{x}|\theta) = sgn(\theta_0 + \theta_1 \cdot x_1 + \dots + \theta_d \cdot x_d);$$

Predictors, Examples

Say,

In the 1D Linear Regression Problem, we consider

$$g(\mathbf{x}|\theta) = \theta_0 + \theta_1 \cdot x_1 + \dots + \theta_d \cdot x_d;$$

In the Binary Classification Problem, with $\mathcal{Y}=\{-1,1\}$, we can consider, say

$$g(\mathbf{x}|\theta) = sgn(\theta_0 + \theta_1 \cdot x_1 + ... + \theta_d \cdot x_d);$$

In the general Regression/Classification Problems, we can have $g(\mathbf{x}|\theta)$ to be a Neural Network, where \mathbf{x} is our input, θ is the vector of all NN weights, and $g(\mathbf{x}|\theta)$ is the output of the NN.

Now we can finalize the statement of our Problem:

Now we can finalize the statement of our Problem: We are given

A Dataset of Observations (\mathbf{x}_k, y_k) , k = 1, ..., n, coming as a realization of (\mathbf{X}_k, Y_k) from an unknown Distribution \mathcal{F} ;

Now we can finalize the statement of our Problem: We are given

- A Dataset of Observations (\mathbf{x}_k, y_k) , k = 1, ..., n, coming as a realization of (\mathbf{X}_k, Y_k) from an unknown Distribution \mathcal{F} ;
- ▶ A Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$;

Now we can finalize the statement of our Problem: We are given

- A Dataset of Observations (\mathbf{x}_k, y_k) , k = 1, ..., n, coming as a realization of (\mathbf{X}_k, Y_k) from an unknown Distribution \mathcal{F} ;
- ▶ A Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$;
- ightharpoonup A Predictive Model (set of Functions) ${\cal G}$

Now we can finalize the statement of our Problem: We are given

- A Dataset of Observations (\mathbf{x}_k, y_k) , k = 1, ..., n, coming as a realization of (\mathbf{X}_k, Y_k) from an unknown Distribution \mathcal{F} ;
- ▶ A Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$;
- A Predictive Model (set of Functions) G

and we want to find $g^* \in \mathcal{G}$ such that

$$g^* \in \underset{g \in \mathcal{G}}{\operatorname{argmin}} \operatorname{Risk}(g).$$

Now we can finalize the statement of our Problem: We are given

- A Dataset of Observations (\mathbf{x}_k, y_k) , k = 1, ..., n, coming as a realization of (\mathbf{X}_k, Y_k) from an unknown Distribution \mathcal{F} ;
- ▶ A Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$;
- ightharpoonup A Predictive Model (set of Functions) $\mathcal G$

and we want to find $g^* \in \mathcal{G}$ such that

$$g^* \in \underset{g \in \mathcal{G}}{\operatorname{argmin}} \operatorname{Risk}(g).$$

If \mathcal{G} coincides with the set of all measurable functions, thet g^* , if exists, is called the **Bayes Predictor**.

OK, nice. But, unfortunately, we usually cannot solve the above problem, since we **do not have the Distribution** \mathcal{F} to calculate the Risk.

OK, nice. But, unfortunately, we usually cannot solve the above problem, since we do not have the Distribution $\mathcal F$ to calculate the Risk.

So we do the following: recall that, by the LLN,

$$\frac{1}{n}\cdot\sum_{k=1}^n\ell(Y_k,g(\mathbf{X}_k))\to$$

OK, nice. But, unfortunately, we usually cannot solve the above problem, since we do not have the Distribution $\mathcal F$ to calculate the Risk.

So we do the following: recall that, by the LLN,

$$\frac{1}{n} \cdot \sum_{k=1}^{n} \ell(Y_k, g(\mathbf{X}_k)) \to \mathbb{E}(\ell(Y, g(\mathbf{X}))) = Risk(g) \quad a.s.$$

OK, nice. But, unfortunately, we usually cannot solve the above problem, since we do not have the Distribution $\mathcal F$ to calculate the Risk.

So we do the following: recall that, by the LLN,

$$\frac{1}{n} \cdot \sum_{k=1}^{n} \ell(Y_k, g(\mathbf{X}_k)) \to \mathbb{E}(\ell(Y, g(\mathbf{X}))) = Risk(g) \quad a.s.$$

So, instead of trying to minimize Risk(g), we can try to minimize

$$ERM(g) = \frac{1}{n} \cdot \sum_{k=1}^{n} \ell(Y_k, g(\mathbf{X}_k)),$$

which is called the **Empirical Risk Measure of** g.

The Learning Problem, Empirical Version

Now we change the statement of our Problem like this:

The Learning Problem, Empirical Version

Now we change the statement of our Problem like this: We are given

- ▶ A Dataset of Observations (\mathbf{x}_k, y_k) , k = 1, ..., n, coming as a realization of (\mathbf{X}_k, Y_k) from an unknown Distribution \mathcal{F} ;
- ▶ A Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$;
- ightharpoonup A Predictive Model (set of Functions) $\mathcal G$

The Learning Problem, Empirical Version

Now we change the statement of our Problem like this: We are given

- A Dataset of Observations (\mathbf{x}_k, y_k) , k = 1, ..., n, coming as a realization of (\mathbf{X}_k, Y_k) from an unknown Distribution \mathcal{F} ;
- ▶ A Loss Function $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$;
- ightharpoonup A Predictive Model (set of Functions) $\mathcal G$

and we want to find $g^* \in \mathcal{G}$ such that

$$g^* \in \underset{g \in \mathcal{G}}{\operatorname{argmin}} \operatorname{ERM}(g).$$