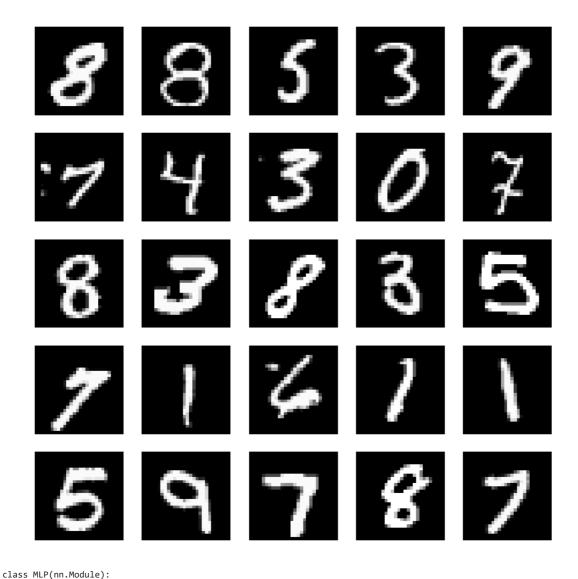
```
import torch
import torch.nn as nn
import torch.optim as optim
import torch.nn.functional as F
from torch.utils.data import DataLoader, SubsetRandomSampler
from torchvision import datasets, transforms
import time
BATCH_SIZE = 64
NUM_EPOCHS = 20
DEVICE = torch.device('cuda:0' if torch.cuda.is_available() else 'cpu')
transform = transforms.Compose([
transforms.ToTensor(),
transforms.Normalize((0.5,), (0.5,))
1)
train_dataset = datasets.MNIST(root='./data',
train=True,
download=True.
transform=transform)
valid_dataset = datasets.MNIST(root='./data',
train=True,
transform=transform)
test_dataset = datasets.MNIST(root='./data',
train=False,
transform=transform)
validation_fraction = 0.1
num = int(validation_fraction * 60000)
train_indices = torch.arange(0, 60000 - num)
valid_indices = torch.arange(60000 - num, 60000)
train_sampler = SubsetRandomSampler(train_indices)
valid_sampler = SubsetRandomSampler(valid_indices)
train_loader = DataLoader(dataset=train_dataset,
batch_size=BATCH_SIZE,
drop_last=True,
sampler=train_sampler)
valid_loader = DataLoader(dataset=valid_dataset,
batch_size=BATCH_SIZE,
sampler=valid_sampler)
test_loader = DataLoader(dataset=test_dataset,
batch_size=BATCH_SIZE,
shuffle=False)
# Checking the dataset
for images, labels in train_loader:
 \verb|print('Image batch dimensions:', images.shape)|\\
  print('Image label dimensions:', labels.shape)
 break
     Image batch dimensions: torch.Size([64, 1, 28, 28])
     Image label dimensions: torch.Size([64])
import matplotlib.pyplot as plt
# Display a grid of sample images
plt.figure(figsize=(10, 10))
for i, (images, labels) in enumerate(train_loader):
 for j in range(25):
    plt.subplot(5, 5, j + 1)
   plt.imshow(images[j].squeeze(), cmap='gray')
   plt.axis('off')
  break
plt.show()
```



```
def __init__(self, num_features, num_hidden_1, num_hidden_2, num_classes):
   super().__init__()
   self.network = torch.nn.Sequential(
    # 1st hidden layer
   torch.nn.Flatten(),
   torch.nn.Linear(num_features, num_hidden_1),
   torch.nn.BatchNorm1d(num_hidden_1),
   torch.nn.ReLU(),
   torch.nn.Dropout(0.5),
   # 2nd hidden layer
   torch.nn.Linear(num_hidden_1, num_hidden_2),
    torch.nn.BatchNorm1d(num_hidden_2),
   torch.nn.ReLU(),
    torch.nn.Dropout(0.3),
   # output layer
   torch.nn.Linear(num_hidden_2, num_classes)
 def forward(self, x):
   logits = self.network(x)
    return logits
model = MLP(num_features=28*28,
num_hidden_1=128,
num_hidden_2=64,
num_classes=10)
model = model.to(DEVICE)
criterion = nn.CrossEntropyLoss()
optimizer = torch.optim.SGD(model.parameters(), lr=0.1, momentum=0.9,
weight_decay=0.0001)
scheduler = torch.optim.lr\_scheduler.ReduceLROnPlateau(optimizer,
factor=0.1,
mode='min')
```

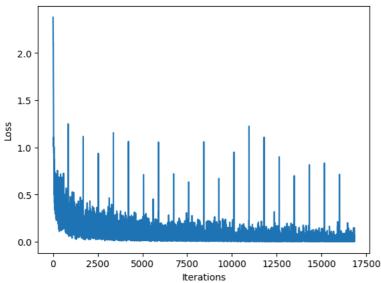
```
# Define your optimizer (using Adam)
optimizer = optim.Adam(model.parameters(), lr=0.001)
import torch.optim as optim
from torch.optim import lr_scheduler
# Create the scheduler with step decay
scheduler = lr_scheduler.StepLR(optimizer, step_size=30, gamma=0.1)
# Create the scheduler with exponential decay
scheduler = lr_scheduler.ExponentialLR(optimizer, gamma=0.95)
def compute_accuracy(data_loader):
 with torch.no_grad():
   correct_pred, num_examples = 0, 0
    for i, (features, targets) in enumerate(data_loader):
     features = features.to(DEVICE)
     targets = targets.float().to(DEVICE)
     logits = model(features)
     _, predicted_labels = torch.max(logits, 1)
     num_examples += targets.size(0)
     correct_pred += (predicted_labels == targets).sum()
 return correct_pred.float()/num_examples * 100
start_time = time.time()
minibatch_loss_list, train_acc_list, valid_acc_list = [], [], []
for epoch in range(NUM_EPOCHS):
   model.train()
   for batch_idx, (features, targets) in enumerate(train_loader):
       features = features.to(DEVICE)
       targets = targets.to(DEVICE)
# ## FORWARD AND BACK PROP
       logits = model(features)
#loss = F.cross_entropy(logits, targets)
       loss = criterion(logits, targets)
       optimizer.zero_grad()
       loss.backward()
# ## UPDATE MODEL PARAMETERS
       optimizer.step()
# ## LOGGING
       minibatch loss list.append(loss.item())
       logging_interval = 100
       if not batch_idx % logging_interval:
            \label{eq:print("Epoch: ", epoch+1,"/", NUM\_EPOCHS,"| Batch ",batch\_idx,} \\
            "/",len(train_loader), f' | Loss: {loss:.4f}')
            model.eval()
            with torch.no_grad():# save memory during inference
                train_acc = compute_accuracy(train_loader)
                valid_acc = compute_accuracy(valid_loader)
                print("Epoch: ", epoch+1, "/",NUM_EPOCHS,
                f'| Train: {train_acc :.2f}% '
                f' | Validation: {valid_acc :.2f}%')
                train_acc_list.append(train_acc.item())
                valid_acc_list.append(valid_acc.item())
                elapsed = (time.time() - start_time)/60
                print("Time elapsed: ",elapsed, " min")
                scheduler.step(minibatch_loss_list[-1])
                elapsed = (time.time() - start_time)/60
                print(f'Total Training Time: {elapsed:.2f} min')
                test_acc = compute_accuracy(test_loader)
                print(f'Test accuracy {test_acc :.2f}%')
```

import matplotlib.pyplot as plt
plt.plot(range(len(minibatch_loss_list)), minibatch_loss_list)
plt.xlabel('Iterations')
plt.ylabel('Loss')

Time elapsed: 61.4774317463239 min Total Training Time: 61.48 min

Text(0, 0.5, 'Loss')

Test accuracy 97.82%



import numpy as np
num_epochs = len(train_acc_list)
plt.plot(np.arange(1, num_epochs+1),
train_acc_list, label='Training')
plt.plot(np.arange(1, num_epochs+1),
valid_acc_list, label='Validation')
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.legend()

<matplotlib.legend.Legend at 0x7fa516a962c0>

