### Implementation of Parareal algorithm

Group 25

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### Parallelization in PDE solvers

#### Methods

- Spatial domain decomposition
- ▶ Time domain decomposition

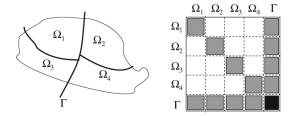


Figure: Spatial Domain Decompostion Illustration [1]

### Parallelization in time - Motivation

$$\frac{\partial y(t)}{\partial t} + Ay(t) = 0, \ t \in [T_0, T_N]$$
$$y(T_0) = y_0$$

#### Run-time Consideration

- c: Time for computing one time step in numerical integration
- T = M c, total time for full simulation, M : Number of fine steps
- For c = 0.04s, M = 1000,000,  $T = 40,000s \approx 11.1 hrs$

### Parallelization in time - Idea



#### Idea

- Split the time domain into a set of subdomains
- Solve the IVP on a coarse grid to get an approx. sol at  $T_1, T_2, \dots, T_{N-1}, T_N$
- This can be used as initial value for the IVP on each sub-domain
- Initial value is only serves as guess (coarse sol)
- Iteratively better solution with better initial guess for initial value in each iteration

## Parareal Algorithm

#### Convention

- $\triangleright$   $\delta t_c$ : coarse grid time step
- $\triangleright$   $\delta t_f$ : fine grid time step
- $\triangleright$   $\mathcal{G}$ : coarse grid integrator
- $\triangleright$   $\mathcal{F}$ : fine grid integrator
- $\triangleright Y_0, Y_1, \dots Y_N$ : numerical solution
- $ightharpoonup Yf_n^k$ ,  $Yc_n^k$ : Fine and Coarse Integrator solutions

#### Construction

$$Y_n^k = \mathcal{F}(Yc_{n-1}^{k-1}) + \mathcal{G}(Y_{n-1}^k) - \mathcal{G}(Y_{n-1}^{k-1})$$

#### where

- k: iteration
- ▶ n : grid index

### Parareal Algorithm

### **Algorithm 1** Parareal Algorithm

```
1: Iteration 0: Y_0^0 = y_0, given initial value
 2: for n = 1 to N do
 3: Y_n^0 = \mathcal{G}(Y_{n-1}^0)
 4: end
 5: for k = 1 to N do
       parallel for n = 1 to N do
          Yf_n^{k-1} = \mathcal{F}(Yc_n^{k-1})
 7:
       end
 8:
 9:
     for n = 1 to N do
         Yc_n^k = \mathcal{G}(Y_n^{k-1})
10:
11:
       end
12: Y_n^k = Yc_n^k + Yf_n^{k-1} - Yc_n^{k-1}
    if |Y^k - Y^{k-1}| < \epsilon then
13:
14.
          break
       end if
15:
16: end
```

## Test problem

### Problem 1

$$\frac{dy}{dt} = A(t) y(t)$$
$$y(0) = y_0, \quad t \in [0, 10]$$

where A = -0.2,  $y_0 = 100$ 

### Problem 2

$$\frac{dy}{dt} = \sin(t) y(t) + t$$
$$y(0) = 1, \quad t \in [0, 14]$$

### **Numerical Method**

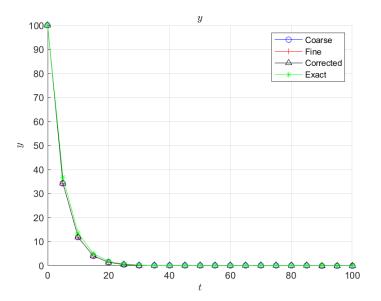
Classical Runge-Kutta scheme of 2<sup>nd</sup> order is used for 1D ODE.

$$k_1 = f(t_n, y_n)$$
 $k_2 = f(t_n + \frac{h}{2}, y_n + \frac{h}{2}k_1)$ 
 $k = \frac{k_1 + k_2}{2}$ 
 $y_{n+1} = y_n + h k$ 

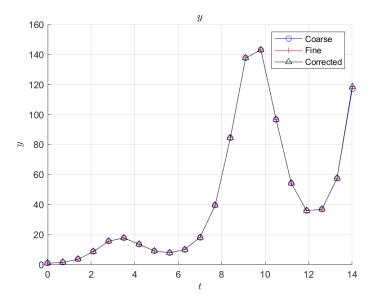
### OpenMP implementation

```
@ parareal.cpp > ...
      #include <stdio.h>
     #include <omp.h>
     #include <math.h>
     // global variables
     int main()
 6
 7
          // coarse grid integrator
 8
          // ...
 9
          while (err > tol and iter < max iter)
10
          #pragma omp parallel num threads(NUM THREADS) shared(t, y) private(i)
11
12
13
              #pragma omp for schedule(dynamic, chunk)
14
                  for (int i = 0; i < n sub; i++)
15
16
                      //fine integrator
17
                      //...
18
19
20
              // predictor: coarse integrator
21
              // corrector
22
              // error check
23
24
          return 0:
25
26
```

### Simulation: Problem 1



### Simulation: Problem 2



# Speedup

CPU	Cores	Multithreading	Num of threads	time serial	time parallel
i5 9500	6 cores	6 way	100	201.222	117.047
i5 8250u	4 cores	8 way	100	201.380	117.070
i3 5010u	2 cores	4 way	100	201.251	117.054

Speedup
1.72
1.72
1.72



Domain decomposition based  $\mathcal{H}\text{-LU}$  preconditioning, Volume 112, Numerische Mathematik, May 2009.

