

## Phase Portrait Analysis of Linear Regression with Two-Weights

$$h(x) = w_0x_0 + w_1x_1$$

where

$$x_0 = 1, x_1 = x$$

Cost Function is

$$J(w) = \frac{1}{2} \sum_{i=1}^N \left( y^{(i)} - h(x^{(i)}) \right)^2$$

Gradient Descent Update Rule

$$w_{j+1} = w_j - \alpha \frac{\partial}{\partial w_j} J(w)$$

$$\frac{\partial}{\partial w_j} J(w) = (h(x) - y) x_j$$

Therefore

$$w_{j+1} = w_j + \alpha \sum_{i=1}^N \left( y^{(i)} - h(x^{(i)}) \right) x_j^{(i)}$$

Approximating to Differential Equation

$$\begin{aligned} \dot{w}_j &= \sum_{i=1}^N \left( y^{(i)} - h(x^{(i)}) \right) x_j^{(i)} \\ \begin{bmatrix} \dot{w}_1 \\ \dot{w}_0 \end{bmatrix} &= - \begin{bmatrix} \sum_{i=1}^N x^{(i)2} & \sum_{i=1}^N x^{(i)} \\ \sum_{i=1}^N x^{(i)} & N \end{bmatrix} \begin{bmatrix} w_1 \\ w_0 \end{bmatrix} + \begin{bmatrix} \sum_{i=1}^N x^{(i)}y^{(i)} \\ \sum_{i=1}^N y^{(i)} \end{bmatrix} \end{aligned}$$

Let

$$\sum_{i=1}^N x^{(i)} = S(x)$$

$$\sum_{i=1}^N y^{(i)} = S(y)$$

$$\sum_{i=1}^N x^{(i)}y^{(i)} = S(xy)$$

$$\sum_{i=1}^N x^{(i)2} = S(x^2)$$

Therefore

$$\begin{bmatrix} \dot{w}_1 \\ \dot{w}_0 \end{bmatrix} = - \begin{bmatrix} S(x^2) & S(x) \\ S(x) & N \end{bmatrix} \begin{bmatrix} w_1 \\ w_0 \end{bmatrix} + \begin{bmatrix} S(xy) \\ S(y) \end{bmatrix}$$

## 1 STABILITY ANALYSIS

This is of the form

$$\dot{W} = AW + B$$

Here B is a constant with respect to w. Hence can be ignored for Stability Analysis.

Consider A

$$\tau = -[N + S(x^2)]$$

$$\Delta = NS(x^2) - [S(x)]^2$$

Here we can see that  $\tau < 0$

Consider  $\Delta$

$$\Delta = \sum_{i=1}^N Nx_i [x_i - \mu_x] \quad \text{where } \mu_x = \frac{S(x)}{N}$$

Let

$$\delta_i = Nx_i [x_i - \mu_x]$$

Hence

$$\Delta = \sum_{i=1}^N \delta_i$$

There are two cases .(1)  $x_i > \mu_x$  (2)  $x_i < \mu_x$ . In Both the cases

$$S(x) [x_i - \mu_x] < \delta_i$$

Therefore

$$\sum_{i=1}^N S(x) [x_i - \mu_x] < \Delta$$

$$S(x) [S(x) - N\mu_x] < \Delta$$

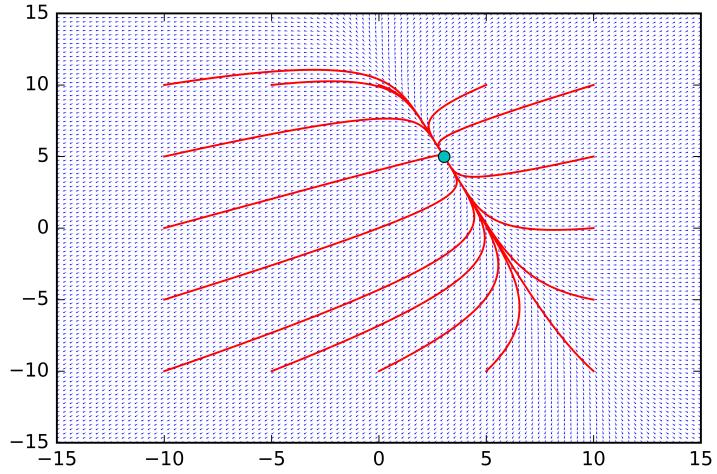
$$0 < \Delta$$

Therefore No Saddle Points.

Consider  $\tau^2 - 4\Delta$

$$\begin{aligned} &= [N + S(x^2)]^2 - 4 [NS(x^2) - [S(x)]^2] \\ &= [N - S(x^2)] + 4 [S(x)] \\ &\quad \tau^2 - 4\Delta > 0 \end{aligned}$$

Hence Fixed Point is Stable Node



**Figure:** Phase Portrait showing the Stable Node.

**Special Case :** If

$$\frac{1}{N} S(x^2) = 1, S(x) = 0$$

$$A = - \begin{bmatrix} N & 0 \\ 0 & N \end{bmatrix}$$

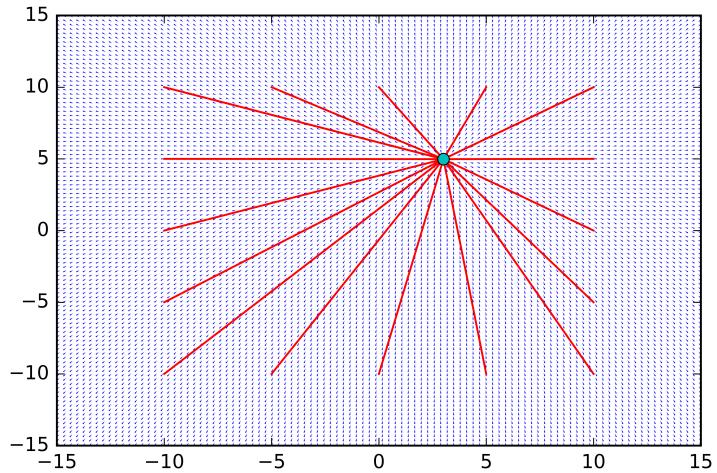
$$\tau = -2N \quad \tau < 0$$

$$\Delta = N^2 \quad \Delta > 0$$

$$\tau^2 - 4\Delta = (-2N)^2 - 4N^2 = 0$$

$$\tau^2 - 4\Delta = 0$$

Hence Fixed Points are stable stars



**Figure:** Phase Portrait showing the Stable Star.

## 2 FIXED POINT CALCULATION

$$\begin{bmatrix} \dot{w}_1 \\ \dot{w}_0 \end{bmatrix} = - \begin{bmatrix} S(x^2) & S(x) \\ S(x) & N \end{bmatrix} \begin{bmatrix} w_1 \\ w_0 \end{bmatrix} + \begin{bmatrix} S(xy) \\ S(y) \end{bmatrix}$$

At Fixed Points

$$\begin{bmatrix} \dot{w}_1 \\ \dot{w}_0 \end{bmatrix} = 0$$

Therefore

$$\begin{bmatrix} S(x^2) & S(x) \\ S(x) & N \end{bmatrix} = \begin{bmatrix} S(xy) \\ S(y) \end{bmatrix}$$

$$AX^* = B$$

**Cases :**

1) If  $\Delta \neq 0$  A is Square-Invertible.

So Fixed Point is

$$X^* = A^{-1}B$$

$$X^* = \frac{1}{\Delta} \begin{bmatrix} N & -S(x) \\ -S(x) & S(x^2) \end{bmatrix} \begin{bmatrix} S(xy) \\ S(y) \end{bmatrix}$$

**Special Case :** If

$$\frac{1}{N} S(x^2) = 1, S(x) = 0$$

$$A = - \begin{bmatrix} N & 0 \\ 0 & N \end{bmatrix}$$

Therefore

$$X^* = \frac{1}{N} \begin{bmatrix} S(xy) \\ S(y) \end{bmatrix}$$

2) If  $\Delta = 0$  Two Possibilities

i) A is a Rank Zero matrix. A=0

Then whole Plane is Full of Fixed Points.

ii) A is a Rank 1 matrix.

Nullspace of A  $N(A)$  is a Line.

$$Ax_n = 0$$

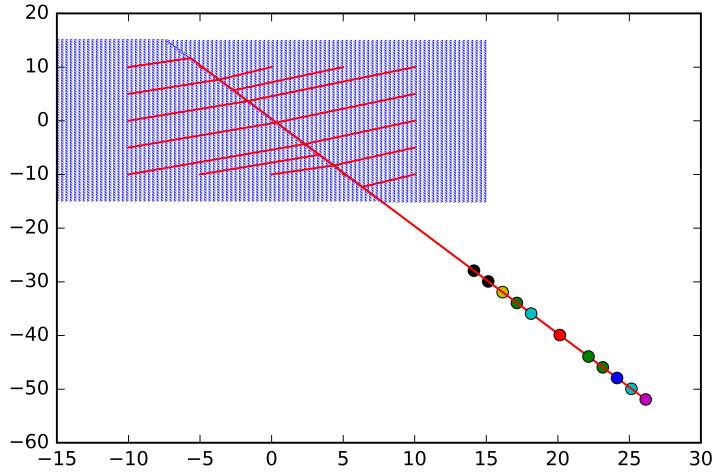
Since

$$\begin{bmatrix} S(x^2) & S(x) \\ S(x) & N \end{bmatrix} \begin{bmatrix} N \\ S(x) \end{bmatrix} = 0$$

Therefore

$$x_n = \begin{bmatrix} N \\ S(x) \end{bmatrix}$$

If  $\frac{N}{S(x)} = \frac{S(x)}{S(x^2)} \neq \frac{S(y)}{S(xy)}$  then No Fixed Point Exists.

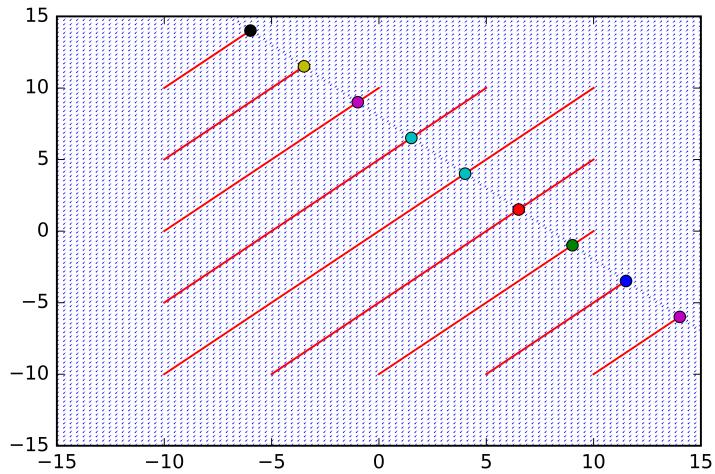


**Figure:** Phase Portrait showing absence of Fixed point and depicting the solutions running away to infinity.

Else if  $\frac{N}{S(x)} = \frac{S(x)}{S(x^2)} = \frac{S(y)}{S(xy)}$  then there exists a Line of Fixed Points.  
The Line of Fixed Points is  $x_p + cx_n$  where c is any constant

$$\begin{bmatrix} S(x^2) & S(x) \\ S(x) & N \end{bmatrix} \begin{bmatrix} z \\ 0 \end{bmatrix} = \begin{bmatrix} S(xy) \\ S(y) \end{bmatrix}$$

$$x_p = \begin{bmatrix} z \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{S(y)}{S(x)} \\ 0 \end{bmatrix}$$



**Figure:** Phase Portrait showing the Line of Fixed Points.