

ASEN 5050 Spring 2021 HW 2 Solutions

Problem 1

given: $P = 15345 \text{ km}$, $\theta_b^* = 112^\circ$ because the SLC is located at the top of the minor axis.

assume: $2BP$, $m_{SLC} \ll m_\oplus$

a) let's calculate e first.

$$e = -\cos(\theta_b^*)$$

$$= -\cos(112^\circ)$$

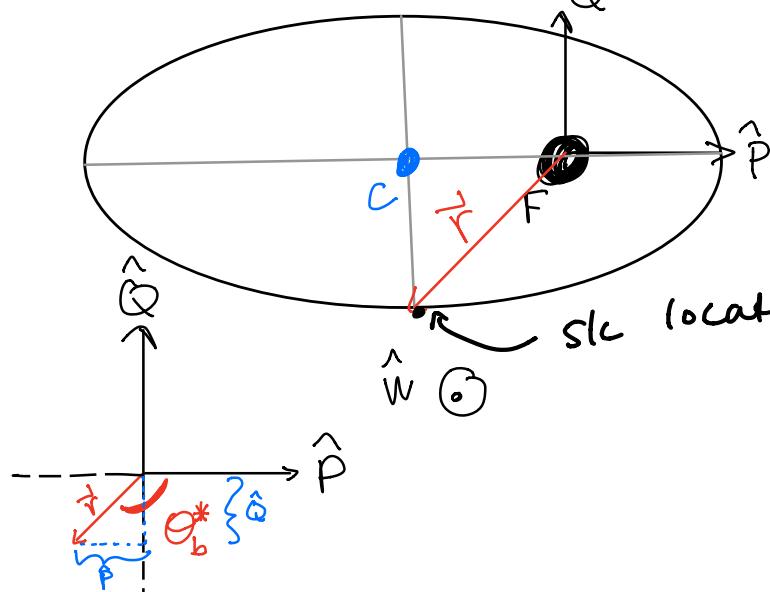
$$e = 0.3746$$

$$P = a(1-e^2)$$

$$a = \frac{P}{(1-e^2)}$$

$$a = 17849.87 \text{ km}$$

b) given $r = a$, so $r = r_b$, $\theta^* = \pm 112^\circ$
 "moving towards periapsis", so
 $\theta^* = -112^\circ$



Position:

$$\begin{aligned}\vec{r} &= r \sin(\theta_b^* + 90^\circ) \hat{P} - r \cos(\theta_b^* + 90^\circ) \hat{Q} + O \hat{W} \\ &= r \cos(\theta_b^*) \hat{P} + r \sin(\theta_b^*) \hat{Q} + O \hat{W}\end{aligned}$$

← this equation always works for $\hat{P}\hat{Q}\hat{W}$ frame!

$$\vec{r} = -6686.68 \hat{P} - 16550.12 \hat{Q} + O \hat{W} \text{ km}$$

Velocity in $\hat{P}\hat{Q}\hat{W}$:

$$v_r = \frac{\mu}{h} e \sin \theta^*$$

$$v_\theta = \frac{\mu}{h} (1 + e \cos \theta^*)$$

We know $P = h^2/\mu$, so rearrange!

$$\left(\frac{\mu}{h}\right)^2 = \frac{\mu^2}{h^2} = \mu \left(\frac{\mu}{h^2}\right) = \frac{\mu}{P}$$

therefore if we take the square root,

$\frac{\mu}{h} = \sqrt{\frac{\mu}{P}}$ now we have values we can work with.

$$v_r = \sqrt{\frac{\mu}{P}} e \sin\theta^*, \quad v_\theta = \sqrt{\frac{\mu}{P}} (1 + e \cos(\theta^*)) \quad * \text{use } \mu_{\oplus} \text{ for this problem}$$

$$\vec{v} = v_r \hat{r} + v_\theta \hat{\theta} + 0 \hat{h}$$

$$\vec{v} = -1.7702 \hat{r} + 4.3814 \hat{\theta} + 0 \hat{h} \quad \text{km/s}$$

Problem 2

assumptions: regular 2BP
 $m_{\text{sat}} \ll m_{\oplus}$

$$\vec{r} = 4981.75 \hat{x} - 4121.90 \hat{y} + 22.70 \hat{z} \quad \text{km}$$

$$\vec{v} = -0.60359 \hat{x} + 0.56812 \hat{y} - 2.24093 \hat{z} \quad \text{km/s}$$

where $\hat{x}\hat{y}\hat{z}$ is an inertial frame

given that $\mu_{\text{mars}} = 4.305 \times 10^4 \text{ km}^3/\text{s}^2$
 $r_{\text{mars}} = 3397.2 \text{ km}$

a) calculate $a, e, i, \Omega, \omega, \Theta^*$

$$|\vec{r}| = r = \sqrt{r_1^2 + r_2^2 + r_3^2} = \sqrt{4981.75^2 + (-4121.9)^2 + 22.7^2} \\ = 6.4659 \times 10^3 \text{ km}$$

$$|\vec{v}| = v = \sqrt{v_1^2 + v_2^2 + v_3^2} = \sqrt{(-0.60359)^2 + (0.56812)^2 + (-2.24093)^2} \\ = 2.38932 \text{ km/s}$$

$$\vec{h} = \vec{r} \times \vec{v} \\ = \underbrace{9223.993}_{h_1} \hat{x} + \underbrace{11150.05}_{h_2} \hat{y} + \underbrace{342.29}_{h_3} \hat{z} \text{ km}^2/\text{s}$$

$$h = |\vec{h}| = 1.4475 \times 10^4 \text{ km}^2/\text{s}$$

$$e = \frac{v^2 - \frac{\mu}{r}}{\frac{2}{r}} = \frac{(2.38932)^2}{2} - \frac{4.305 \times 10^4}{6.4659 \times 10^3} \\ = -3.8035 \text{ km}^2/\text{s}^2$$

$$a = \frac{-\mu_{\oplus}}{2e} = \frac{-4.305 \times 10^4}{2(-3.8035)}$$

$$a = 5659.20 \text{ km}$$

$$i = \cos^{-1}\left(\frac{h_3}{h}\right) = \cos^{-1}\left(\frac{342.29}{1.4475 \times 10^4}\right) \\ = 1.547 \text{ rads}$$

$$i = 88.04^\circ$$

$$e = \sqrt{1 + \frac{2h^2 \Omega^2}{\mu^2}} = \sqrt{1 + \frac{2(1.4475 \times 10^4)^2 (-3.8035)}{(4.305 \times 10^4)^2}}$$

$$e = 0.37415$$

$$\begin{aligned}\vec{n} &= \hat{z} \times \vec{h} = [0 \ 0 \ 1] \times [9223.99 \quad 1150.1 \quad 342.29] \text{ in } \mathbb{R}^3 \\ &= -[1150.05 \hat{x} + 9223.99 \hat{y} + 0 \hat{z}] \\ n &= |\vec{n}| = 14470.86\end{aligned}$$

$$\Omega = \cos^{-1}\left(\frac{\vec{n} \cdot \hat{x}}{n}\right) = \pm 140.4^\circ \quad \text{Sign check: } \vec{n} \cdot \hat{y} = 9223.99 > 0 \therefore \Omega(+)$$

$$\Omega = +140.4^\circ$$

$$\omega = \cos^{-1}\left(\frac{\vec{n} \cdot \vec{e}}{ne}\right) = \pm 48.83^\circ \quad \text{Sign check: } \vec{e} \cdot \hat{z} = -0.2816 < 0 \therefore \omega(-)$$

$$\omega = -48.83^\circ$$

$$\theta^* = \cos^{-1}\left(\frac{\vec{r} \cdot \vec{e}}{re}\right) = \pm 131.37^\circ \quad \text{Sign check: } \vec{r} \cdot \hat{v} = -5399 < 0 \therefore \theta^*(-)$$

$$\theta^* = -131.37^\circ$$

- b) write \vec{r}, \vec{v} in $(\hat{r}, \theta, \hat{h})$
i) using direction cosine matrix

$$\vec{r}_{reh} = [C]^T \vec{r}_{xyz} , \quad \theta = \theta^* + \omega = -180.2^\circ$$

$$[C] = \begin{bmatrix} C_x C_\theta - S_x C_i S_\theta & -C_x S_\theta - S_x C_i C_\theta & S_x S_i \\ S_x C_\theta + C_x C_i S_\theta & -S_x S_\theta + C_x C_i C_\theta & -C_x S_i \\ S_i S_\theta & S_i C_\theta & C_i \end{bmatrix}$$

$$[C] = \begin{bmatrix} 0.7705 & 0.0178 & 0.6372 \\ -0.6375 & 0.016 & 0.7703 \\ 0.0035 & -0.9997 & 0.0236 \end{bmatrix}$$

$$\vec{r}_{reh} = [C]^T \vec{r}_{xyz} = 6.4659 \times 10^3 \hat{r} + 0\hat{\theta} + 0\hat{h} \text{ km}$$

$$\vec{v}_{reh} = [C]^T \vec{v}_{xyz} = \begin{bmatrix} 0.7705 & -0.6375 & 0.0035 \\ 0.0178 & 0.016 & -0.9997 \\ 0.6372 & 0.7703 & 0.0236 \end{bmatrix} \begin{bmatrix} -0.6036 \\ 0.5681 \\ -2.2409 \end{bmatrix}$$

$$\vec{v}_{reh} = -0.8351 \hat{r} + 2.2386 \hat{\theta} + 0\hat{h} \text{ km/s}$$

$$2) r = |\vec{r}| = 6.4659 \times 10^3 \text{ km}$$

$$\vec{r}_{reh} = r \hat{r}$$

$$\vec{r} = (6.4659 \times 10^3 \hat{r} + 0\hat{\theta} + 0\hat{h}) \text{ km}$$

matches w/ 2b1!

$$\begin{aligned}\vec{v}_{reh} &= v_r \hat{r} + v_\theta \hat{\theta} \\ v_r &= \frac{m}{h} e \sin(\theta^*) \\ &= \left(\frac{4.305 \times 10^4}{1.4475 \times 10^4} \right) (0.3742) \sin(-131.37^\circ)\end{aligned}$$

$$V_\theta = \frac{\mu}{h} (1 + e \cos \theta^*)$$

$$V_\theta = 2.2386$$

$$\vec{V}_{\text{reh}} = -0.8351 \hat{r} + 2.2386 \hat{\theta} \text{ km/s}$$

matches with part 2b1!

c) definition of ω is angle from \vec{n} to \vec{e} or $\vec{r}_{\text{periapsis}}$.
when s/c is at the ascending node, $\theta^* = -\omega$

we can get $\hat{r}\hat{\theta}\hat{h}$ frame and use DCM to put \vec{r} and \vec{v} in $\hat{x}\hat{y}\hat{z}$
2BP, so \vec{h}, \vec{e}, E are ~~constant~~ constant

$$r = \frac{h^2/\mu_\oplus}{1 + e \cos \theta^*} = \frac{h^2/\mu_\oplus}{1 + e \cos(-\omega)} = 3.9051 \times 10^3 \text{ km}$$

$$\vec{r} = 3.9051 \times 10^3 \hat{r} + 0 \hat{\theta} + 0 \hat{h} \text{ km}$$

$$V_r = \frac{\mu}{h} e \sin(-\omega) = 0.8377 \text{ km/s}$$

$$V_\theta = \frac{\mu}{h} (1 + e \cos(-\omega)) = 3.7067 \text{ km/s}$$

$$\vec{v} = 0.8377 \hat{r} + 3.7067 \hat{\theta} + 0 \hat{h} \text{ km/s}$$

$$[C] = \begin{bmatrix} C_x C_\theta - S_x C_i S_\theta & -C_x S_\theta - S_x C_i C_\theta & S_x S_i \\ S_x C_\theta + C_x C_i S_\theta & -S_x S_\theta + C_x C_i C_\theta & -C_x S_i \\ S_i S_\theta & S_i C_\theta & C_i \end{bmatrix}$$

$$\theta = \theta^* + \omega = -\omega + \omega = 0^\circ$$

$$[C] = \begin{bmatrix} -0.705 & -0.0151 & 0.6372 \\ 0.6374 & -0.0182 & 0.7703 \\ 0 & 0.9997 & 0.0236 \end{bmatrix}$$

$$\vec{r}_{xyz} = [C] \vec{r}_{\text{reh}}$$

$$\vec{r}_{xyz} = -3.009 \times 10^3 \hat{x} + 2.4892 \times 10^3 \hat{y} + 0 \hat{z} \text{ km}$$

$$\vec{v}_{xyz} = [C] \vec{v}_{\text{reh}}$$

$$\vec{v}_{xyz} = -0.7013 \hat{x} + 0.4664 \hat{y} + 3.7056 \hat{z} \text{ km/s}$$

Check: $\vec{r}_{xyz} \cdot \hat{z} = 0$
and $\vec{v}_{xyz} \cdot \hat{z} > 0$
 \therefore s/c at
ascending node

d) Check your diagram using STK/GMAT -

were you able to draw it with approx. the right direction of $\vec{e}, \vec{h}, \vec{n}$?