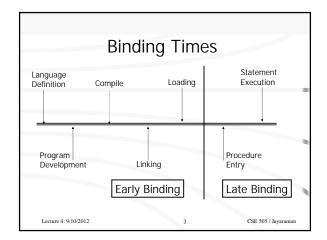


# Binding Time Definition: Binding time is the time at which an attribute is bound, or fixed, to an entity of a programming language. Entity Attributes Variable Type, Storage, Value, ... Procedure Body, Storage, ... Binding Time: ..., compile-time, ..., run-time, ...

Lecture 4: 9/10/2012



Binding Time	Attribute Bound *
Language Definition	Set of well-formed statements
Program Development	Set of variables
Compile	Code generated for expression
Linking	Code for library functions
Loading	Storage locations for program
Procedure Entry	Formal parameter value
Statement Execution	Value of an expression
* These ex	amples don't hold for all languages
e 4: 9/10/2012	4 CSE 505

# Structured\* Types and Data Objects

Simple Types – int, real, bool, ...

Structured Types - array, record/struct, ...

We will examine how contour models can help understand how data objects are allocated and bound to variables, and different forms of assignment and equality rules.

\* - Structured type = Concrete Type

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#### **Key Terms**

Variable, Object, Value, Type

Declaration: <Type> <Variable>

A variable is bound to an object, which is a container of a value of some specified type.

An object has a temporal dimension. An object can be created, shared, updated, destroyed.

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#### **Object Allocation Schemes**

Allocation Scheme	When Object Allocated
Static	Loading Time
Quasi Dynamic	Procedure-Entry Time
Fully Dynamic	Stmt-Execution* Time

<sup>\* -</sup> Typically done via a statement such as: new <Type>

ecture 4: 9/10/2012 7 CSE :

# Object Allocation (cont'd)

Allocation Scheme	Where Object Allocated
Static	Outermost Contour
Quasi Dynamic	Contour*
Fully Dynamic	Неар

\* - This scheme is also called "Stack Allocation"

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#### How PLs specify Binding Schemes

Fortran - Static allocation for all variables: e.g. INTEGER A[100,100]

- C Quasi-dynamic is the default.
  - Static and Fully-dynamic also permitted:

Java - Fully-dynamic is default for structured types - Static and Quasi-dynamic also permitted

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#### **Object Allocation Schemes**

Allocation Scheme	When Object Allocated
Static	Loading Time
Quasi Dynamic	Procedure-Entry Time
Fully Dynamic	Stmt-Execution* Time

\* - Typically done via a statement such as: new(var)

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## Object Allocation (cont'd)

Allocation Scheme	Where Object Allocated	
Static	Outermost Contour	
Quasi Dynamic	Contour*	
Fully Dynamic	Неар	

\* - This scheme is also called "Stack Allocation"

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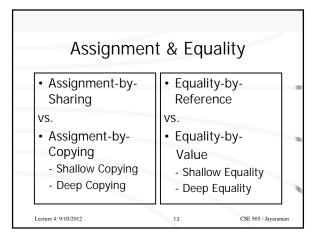
#### Object Binding - Syntax\*

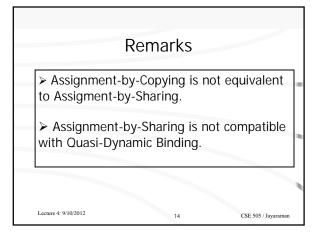
T – Type, V – Variable

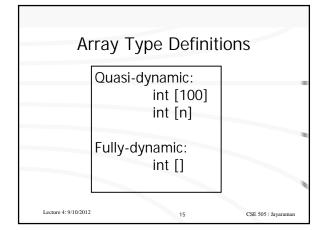
Object Binding Scheme	Syntax	
Static	T↓ V	
Quasi Dynamic	T V	
Fully Dynamic	T↑ V	

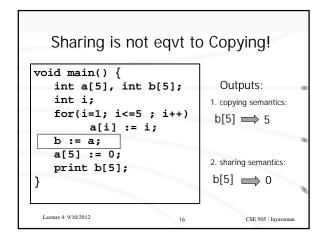
\* - This syntax is just for the examples in Chapter 2.

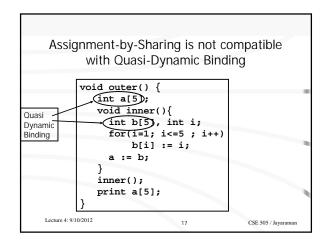
cture 4: 9/10/2012 12 CSE 505 / Jayaramar

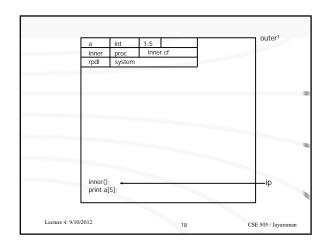


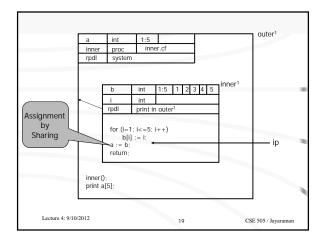


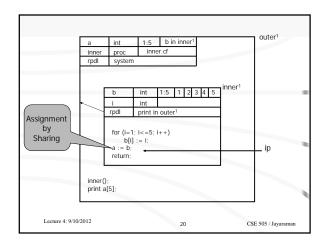


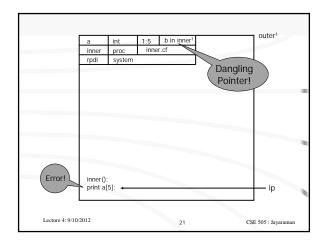


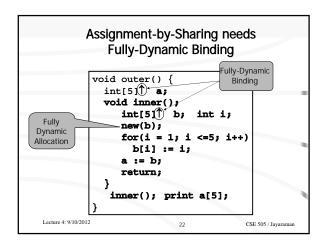


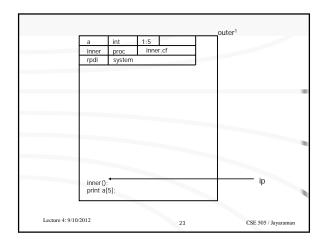


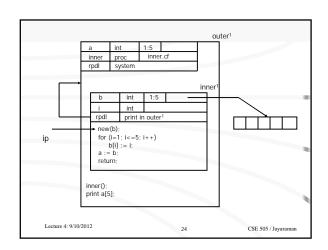


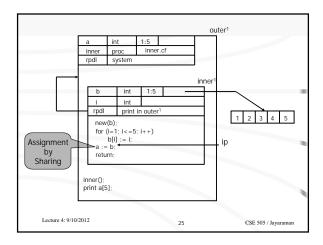


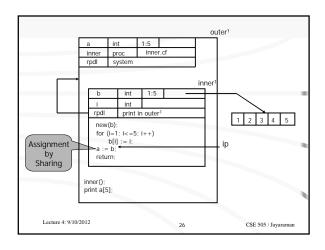


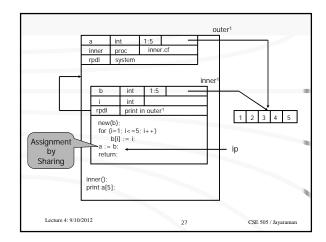


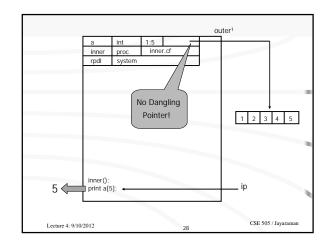












Stacks and Heaps

• Stack Management

- Relating contours and stack frames

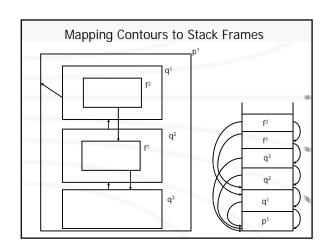
- Keeping track of static and dynamic links

• Heap Management (discussed later)

- Reference Counting

- Garbage Collection

- Compaction



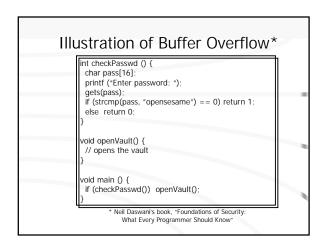
#### Stack Storage Management

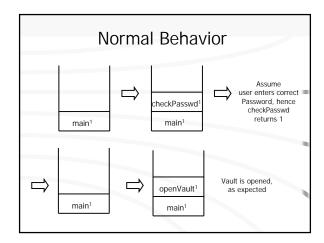
Each frame is called an 'activation record', which holds the local vars, parameters, together with the return ptr, static and dynamic links.

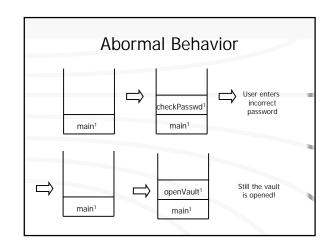
Stack Management is easy:

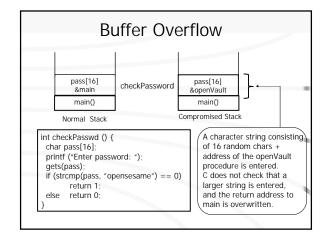
- push a.r. when procedure is called
- pop a.r. when procedure completes

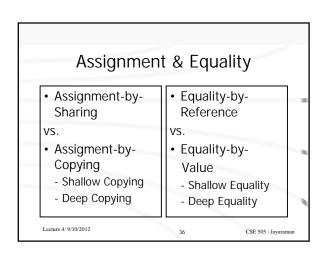
Lately, stack storage format has been exploited to create security violations.

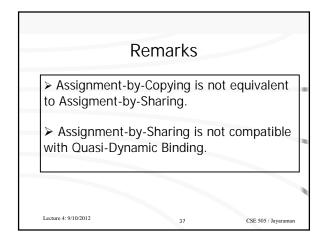


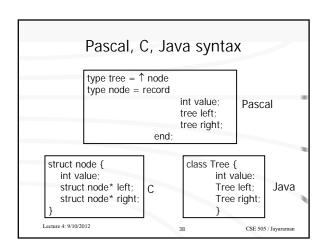


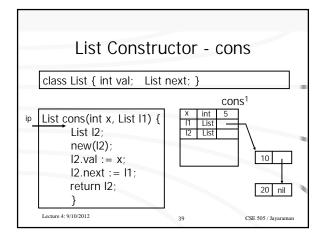


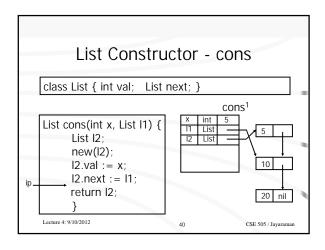


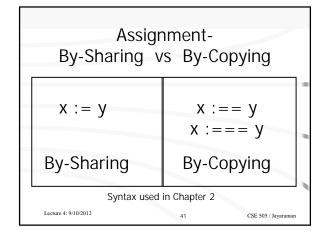


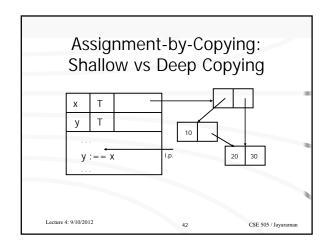


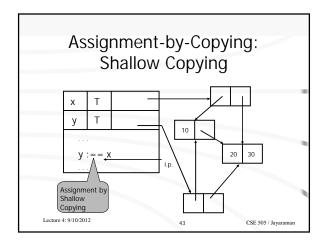


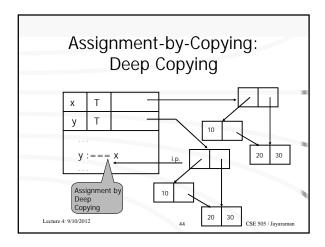


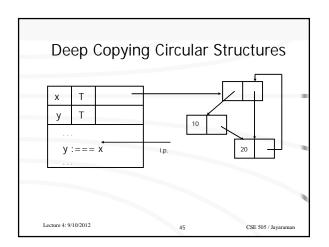


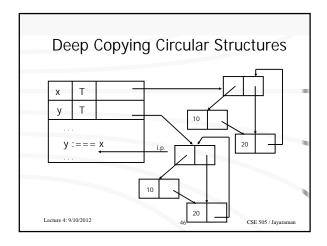


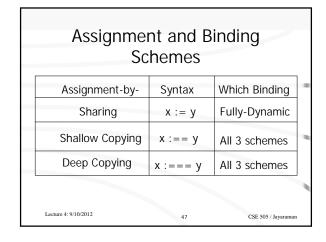


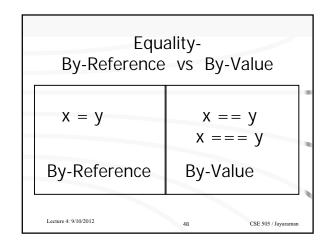


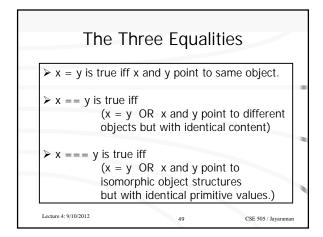


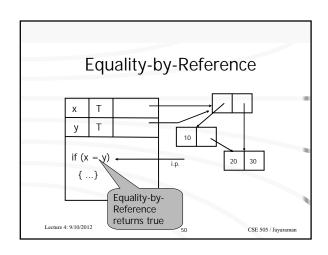


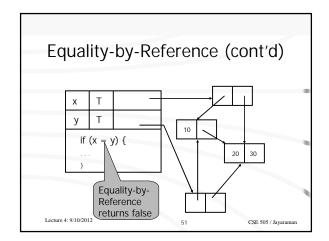


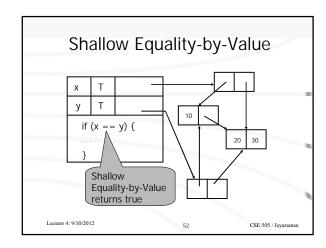


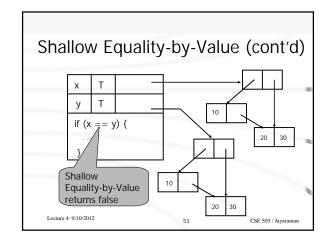


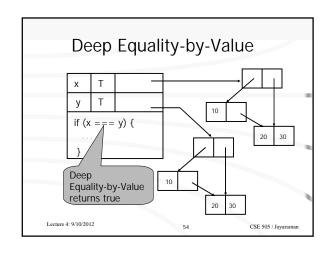


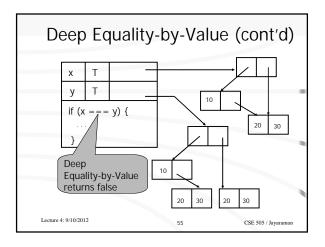


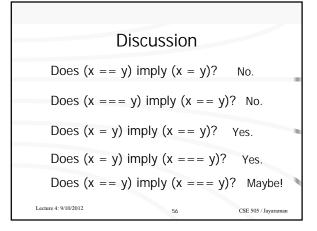


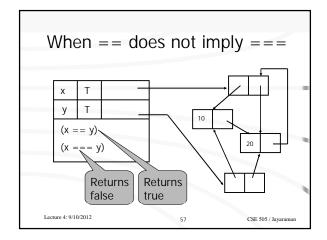


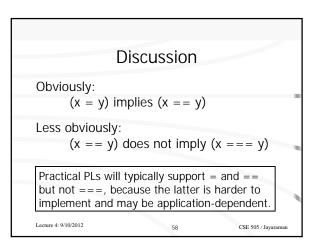






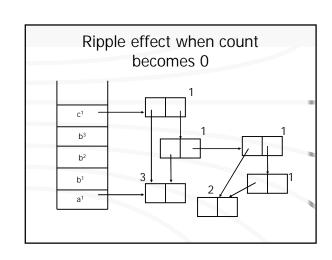


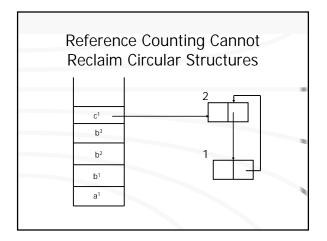




### Heap Storage Management

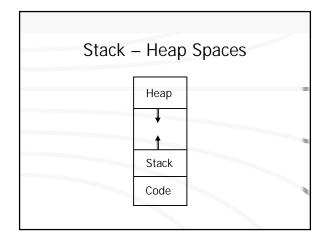
- Reference Counting
  - each heap cell maintains an integer count
  - initialize to 1
  - increment and decrement upon pointer assignment/re-assignment
  - reclaim cell when count reaches 0
  - cannot reclaim circular structures
  - slows down program due to reference mgmt

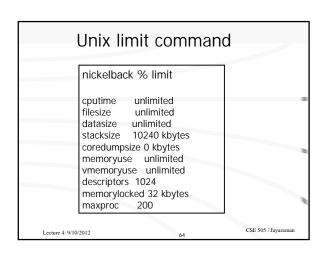




#### Heap Storage Management

- · Mark-scan Garbage Collection
  - No reference counting
  - When memory runs low, traverse heap objects from stack and mark all reachable objects
  - Sequentially scan memory and reclaim un-marked memory cells
  - Can reclaim circular structures
  - Time taken is inversely proportional to amount of garbage





```
How much recursion with 10MB stack?

#include <stdio.h>

void recurse() {
    int data[262144];  // 1 MB
    recurse();
}

int main() {
    recurse();
}

Can change setting: % unlimit stacksize
```

```
Testing heap allocation

#include <stdio.h>
#include <stdiib.h>

typedef struct list { // will take about 1MB of storage int data[262144]; struct list *next; } LIST;

int main() { while (1) { LIST* node = (LIST*) malloc(sizeof(LIST)); if (node == (LIST*) NULL) { printf("Ran out of heap space\n"); exit(1); } printf("%d\n", sizeof(LIST)); }

}
```