Outline

- Max-Flow Problems
- Interpretation
- Variations of Max-Flow Problem
- Properties
- Max-Flow Algorithm Outline
- Residual Network and Augmenting paths
- Ford-Fulkerson Algorithm
- Max-Flow Min-Cut Theorem
- Sarp-Edmonds Algorithm
- Maximum Matching
- MM Problem for Bipartite Graphs
- Connectivity Problems



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Note: The last condition is not essential. It is included here for convenience.



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f(u, v) is called the net flow from u to v.







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• The flow value is: |f| = 11 + 8 = 19.



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- In the formulation of the max-flow problem, shipping 3 units flow from v_2 to v_1 , and 2 units flow from v_1 to v_2 is equivalent to shipping 1 unit flow from v_2 to v_1 , and nothing from v_1 to v_2 . In other words, the 2 units flow from v_2 to v_1 , then from v_1 back to v_2 are canceled.

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- So we have: $f(v_2, v_1) = 1$ and $f(v_1, v_2) = -1$



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- In other words, |f| is the total amount of oil that flow through the pipeline system from s to t.

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Find: A flow function f(*) so that |f| is maximum.

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- We discuss a few examples.

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Applications

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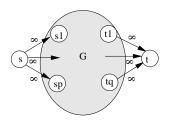
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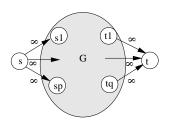
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The max flow function of the converted network gives the answer of the original problem.

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Application

In the oil pipeline application, each vertex u is an oil pumping station. c(u) is the capacity of the pump.

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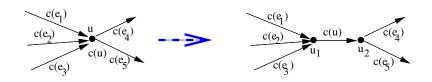
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- For each edge u → w, replace it by u₂ → w with the same capacity.



Max-Flow: With Flow Cost

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- For each edge $u \to v$, in addition to capacity, there is a $cost(u \to v) \ge 0$. (Meaning: you must pay $cost(u \to v)$ in order to ship 1 unit flow through the edge $u \to v$.)
- The goal of the problem is to find a flow function f(*) such that:
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- It can be solved by using similar idea.



Max-Flow: Multi-commodity Flow Problem

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- We define a flow for commodity $i: f_i: V \times V \to R$. $f_i(*)$ must satisfy the Capacity, Skew Symmetry and Flow Conservation constraints.
- In addition, we require Aggregate Capacity constraint: For any edge
 e = u → v ∈ E:

$$f(u,v) = \sum_{i=1}^{t} f_i(u,v) \le c(u,v)$$



Question:

Can we find flow functions f_1, f_2, \dots, f_t that satisfy all of these constraints, and also satisfy the demands for all commodities?

Application

In the Internet connetion network example, we must transmit d_i units data from the site s_i to the site t_i .

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This problem cannot be converted to the basic max-flow problems, and is significantly harder to solve.

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Definition

Let $X \subseteq V$ and $Y \subseteq V$ be two subsets of V. The total flow from X to Y is:

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- The Flow Conservation Constraint is: For any $u \neq s, t$ we must have f(u, V) = 0.

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- **4** If $X \cap Y = \emptyset$, then $f(Z, X \cup Y) = f(Z, X) + f(Z, Y)$.

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- Statement 1: the total flow from a subset into itself is 0.
- Statement 2: the total flow from X into Y is equal to the negative of the total flow from Y into X.
- Statement 3: If X and Y are disjoint, then the total flow from $X \cup Y$ to Z is the sum of the flow from X to Z and the flow from Y to Z.

Proof.

2.

$$\begin{array}{lcl} f(X,Y) & = & \sum_{x \in X} \sum_{y \in Y} f(x,y) & \text{(by skew symmetry property)} \\ & = & \sum_{x \in X} \sum_{y \in Y} -f(y,x) = -\sum_{y \in Y} \sum_{x \in X} f(y,x) \\ & = & -f(Y,X) & \text{(by the definition of } f(Y,X).) \end{array}$$

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$$\begin{array}{lcl} f(X \cup Y, Z) & = & \sum_{x \in X \cup Y} \sum_{z \in Z} f(x, z) & (\text{because } X \cap Y = \emptyset) \\ & = & \sum_{x \in X} \sum_{z \in Z} f(x, z) + \sum_{x \in Y} \sum_{z \in Z} f(x, z) \\ & = & f(X, Z) + f(Y, Z) \end{array}$$

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4. Similar to 3.



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$$= f(V, t) + \sum_{u \in V} \int_{u \neq s} f(V, u) \quad \text{(because } f(V, u) = 0 \text{ for all } u \neq s, t)$$

Fact

$$\begin{split} |f| &= f(s,V) \quad (\mathsf{because}\, f(s,V) + f((V-\{s\}),V) = f(V,V)) \\ &= f(V,V) - f((V-\{s\}),V) \quad (\mathsf{because}\, f(V,V) = 0) \\ &= 0 - f((V-\{s\}),V) = -f((V-\{s\}),V) (\mathsf{because}\, f(X,Y) = -f(Y,X)) \\ &= f(V,(V-\{s\})) \\ &= f(V,t) + f(V,(V-\{s,t\})) \\ &= f(V,t) + \sum_{u \in V, u \neq s,t} f(V,u) \quad (\mathsf{because}\, f(V,u) = 0 \; \mathsf{for} \; \mathsf{all} \; u \neq s,t) \\ &= f(V,t) + \sum_{u \in V, u \neq s,t} 0 \\ &= f(V,t) \end{split}$$

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How an edge $e = u \rightarrow v$ can be used to increase the flow?

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In this example, the capacity is c(e)=14, the current flow is f(e)=6. It is possible we can increase the flow by c(e)-f(e)=14-6=8. (This is the maximum amount of additional flow that can be pushed through e without exceeding the capacity.)

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- The net effect is that we can push $c(u \to v) + a$ units flow from u to v. which is $c(u \to v) f(u \to v)$.



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- Cancel the a units flow from v to u.
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- The net effect is that we can push $c(u \to v) + a$ units flow from u to v. which is $c(u \to v) f(u \to v)$.



In this example $f(u \to v)$ is changed from -4 to 3. The net change is $7 = 3 - (-4) = c(u \to v) - f(u \to v)$.

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Residual Network

Let G = (V, E) be a flow network and f(*) a flow function of G. The residual network of G (with respect to f) is $G_f = (V, E_f)$ where:

$$E_f = \{(u, v) \in V \times V \mid c_f(u, v) > 0\}$$

where

$$c_f(u,v) = c(u,v) - f(u,v)$$

is called the residual capacity of (u, v).

Note: $c_f(u,v)$ is the maximum amount of additional flow that can be pushed from u to v.



Augmenting Path

- Let G = (V, E) be a flow-network, f a flow function of G.
- Let G_f be the residual network of G with respect to f.
- Let P be a path in G_f from s to t. P is called an augmenting path of G_f .
- Define: $c_f(P) = \min\{c_f(u,v) \mid (u,v) \text{ is an edge on } P\}.$
- Define a flow function $f_P(*)$ on G_f by:

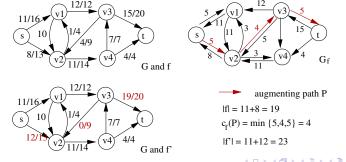
$$f_P(u,v) = \left\{ \begin{array}{ll} c_f(P) & \text{if } (u,v) \text{ is on } P \\ -c_f(P) & \text{if } (v,u) \text{ is on } P \\ 0 & \text{otherwise} \end{array} \right.$$

• Define a new flow function f'(*) of G by:

$$f'(e) = f(e) + f_P(e)$$
 for all $e \in E$

• Along the path P, we can push more flow from s to t.

- Along the path *P*, we can push more flow from *s* to *t*.
- $c_f(P)$ is the maximum amount of additional flow we can push along P. This is because there is an edge (u, v) on P whose residual capacity is $c_f(P)$. This is the bottle neck edge.
- f'(*) is a new flow function with $|f'| = |f| + |f_P| = |f| + c_f(P)$. In other words, we increased the flow value by the amount $c_f(P)$.



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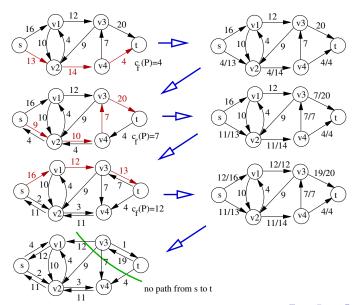
Ford-Fulkerson Algorithm

Ford-Fulkerson Algorithm

- **1 for** each $e = (u, v) \in E$ **do**
- f(u, v) = f(v, u) = 0
- **3** while there's a path P from s to t in G_f do:
- $c_f(P) = \min\{c_f(u, v) \mid (u, v) \text{ is on } P\}$
- for each e = (u, v) on P do
- $f(u,v) = f(u,v) + c_f(P)$
- f(v,u) = -f(u,v)
- end while
- return f



Max-Flow: Example



We will show:

Theorem

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Definition

Let G = (V, E) be a flow network with source s and sink t. A cut of G is a partition of the vertex set V into two subsets S and T such that:

- $S \cap T = \emptyset$ and $S \cup T = V$.
- $s \in S$ and $t \in T$.
- The capacity of the cut is: $c(S,T) = \sum_{u \in S, v \in T, (u \to v) \in E} c(u,v)$
- The flow cross the cut is: $f(S,T) = \sum_{u \in S, v \in T, (u \to v) \in E} f(u,v)$



Lemma (26.5)

Let G be a flow network with source s and sink t. Let f be a flow function of G. Let (S,T) be any cut of G. Then:

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Proof.

$$\begin{array}{lll} f(S,T) &=& f(S,V)-f(S,S) & \text{(because } S\cup T=V \ S\cap T=\emptyset)\\ &=& f(S,V) & \text{(because } f(S,S)=0)\\ &=& f(s,V)+f((S-\{s\}),V) & \text{(because } S=\{s\}\cup(S-\{s\})\\ &=& f(s,V) & \text{(because the flow conservation constraint, the 2nd term is 0)} \end{array}$$

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Proof.

$$\begin{array}{lll} |f| &=& f(S,T) & \text{(because Lemma 26.5)} \\ &=& \sum_{u \in S, v \in T, (u \to v) \in E} f(u,v) & \text{(by definition of } f(S,T)) \\ &\leq& \sum_{u \in S, v \in T, (u \to v) \in E} c(u,v) & \text{(by capacity constraint)} \\ &=& c(S,T) & \text{(by definition of } c(S,T)) \end{array}$$



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Max-Flow Min-Cut Theorem (26.6)

The following three statements are equivalent:

- \bigcirc f is a max flow of G.
- **2** The residual network G_f contains no $s \to t$ path.
- |f| = c(S,T) for some cut (S,T) of G.

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Proof (1) \Rightarrow (2): Suppose (2) is not true. Then we can find an augmenting path P in the residual network G_f . We can push more flow along P to increase the flow value of f. Then f is not a maximum flow.

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Proof (1) \Rightarrow (2): Suppose (2) is not true. Then we can find an augmenting path P in the residual network G_f . We can push more flow along P to increase the flow value of f. Then f is not a maximum flow.

(2) \Rightarrow (3): Define: $S = \{v \in V \mid \text{ there is a path in } G_f \text{ from } s \text{ to } v\}$ and T = V - S. We show (S, T) is a cut of G:

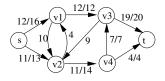
- $s \in S$: This is trivial because s itself is a path from s to s.
- $t \in T$: Because the condition (2), $t \notin S$. Hence $t \in T$.
- By the definition of T, we have $S \cap T = \emptyset$ and $S \cup T = V$.

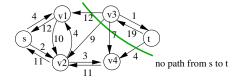
Hence (S, T) is a cut of G.



Proof (continued): For each edge $u \to v$ with $u \in S$ and $v \in T$, we have f(u,v) = c(u,v). This is because if f(u,v) < c(u,v), then $u \to v$ would be an edge in G_f with residual capacity c(u,v) - f(u,v) > 0. That means there is a path $s \to u \to v$ in G_f . This contradicts to the fact that $v \in T$. Therefore |f| = f(S,T) = c(S,T).

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- This theorem is a fundamental theorem in mathematics. It appears in different branches, in different forms, by different names.

Now we can prove:

Theorem

When Ford-Fulkerson algorithm terminates, f is a max-flow function of G.

Proof.

The algorithm stops only when there is no $s \to t$ path in G_f can be found. By Max-Flow Min-Cut Theorem (the equivalence of the statements (1) and (2)), f is a max flow.

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No! There's a catch here: When the algorithm terminates ... How do we know the algorithm will stop?

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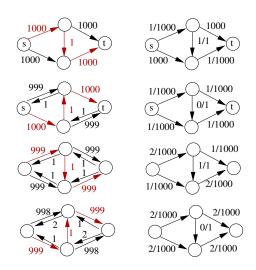
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 - So it takes 2000 iterations.
- If the capacities can be real numbers, there are examples of flow network and sequence of bad choices of augmenting paths for which the algorithm will never stop!

A Bad Example



Outline

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- Interpretation
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- Properties
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- 6 Residual Network and Augmenting paths
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Karp-Edmonds Theorem

The while loop in Karp-Edmonds Algorithm runs at most $|V| \cdot |E| = nm$ iterations.

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- So the total run time is $O(nm(n+m)) = O(nm^2)$. (This is because $n \le m$).
- Note: Max-flow is a fundamental problem. Great efforts have been made to reduce the runtime. But for general cases, only small improvements have been made.

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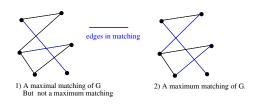
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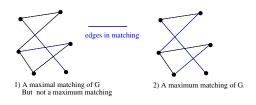
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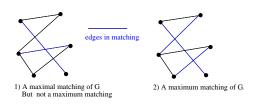


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- This problem is much harder than it looks. It can be solved in polynomial time, but quite complicated.
- If the problem is to find a maximal matching, it can be solved by the following easy algorithm:

Maximal Matching(G = (V, E))

- **2** while $E \neq \emptyset$ do
- \odot pick any edge e in E, add e into M
- delete from E all edges that share a common vertex with e
- output M



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Maximum Matching for Bipartite Graph (MMBG) Problem

Given a bipartite graph G = (X, Y, E), find a maximum matching of G.

The following Fig shows a bipartite graph G = (X, Y, E) and a matching M of G. Is M maximum? It's not clear.



Application 1 of MMBG: Marriage Problem

Given a bipartite graph G = (X, Y, E):

• $X = \{x_1, x_2, \dots, x_p\}$ is the set of boys.

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- If you run an on-line match-making web-site, you need this algorithm.

Application 2 of MMBG: Distinct Representative Problem

- UB has p student clubs C_1, C_2, \ldots, C_p .
- A student may be a member of several clubs.
- Need to select a committee so that:
 - Each club has one representative in the committee.
 - Each student in the committee represents only one club (even if he/she is a member of multi-clubs.)

How to do this?

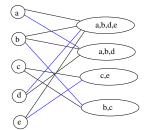
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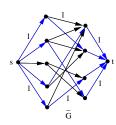
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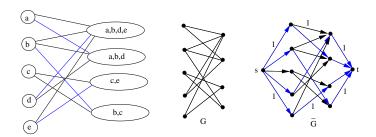
This is a MMBG problem. Define a bipartite graph G = (X, Y, E):

- $X = \{C_1, C_2, \dots, C_p\}$ (each element of X is a club.)
- $Y = \{y_1, y_2, \dots, y_q\}$ (each element of Y is a student.)
- $(C_i, y_j) \in E$ if and only if y_j is a member of C_i .
- Find a MM M of G. If every C_i is incident to an edge in M, then we can select the committee. If not, this is impossible.









Converting MMBG to Max-Flow

Given an input instance G = (X, Y, E) of MMBG, we construct a flow network \bar{G} as follows:

- $V(\bar{G}) = X \cup Y \cup \{s, t\}$
- $\bullet \ E(\bar{G}) = \{s \to x \mid \forall x \in X\} \cup \{y \to t \mid \forall y \in Y\} \cup \{x \to y \mid \forall (x, y) \in E\}$
- All edges have capacity 1.

Lemma

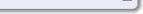
Let M be a MM of G=(V,E). Let f be a max-flow function of \bar{G} . Then |M|=|f|.

Proof.

Let M be a MM of G. Suppose $M = \{e_1, e_2, \dots, e_k\}$, where $e_i = (x_i, y_i)$. Let $f_M(*)$ be defined as follows:

- $f_M(s \to x_i) = 1$ for all $1 \le i \le k$
- $f_M(y_i \to t) = 1$ for all $1 \le i \le k$
- $f_M(x_i \rightarrow y_i) = 1$ for all $1 \le i \le k$
- $f_M(e) = 0$ for all other edges.

It is easy to check f_M is a flow function of \bar{G} and $|f_M|=k$. Since f is a max flow, we have $|f|\geq |f_M|=k=|M|$.



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Proof.

Conversely, let f be a max flow function of \bar{G} . Because all edge capacities of $E(\bar{G})$ are 0/1, it is easy to see that f(e) is 0/1 for all edges e. Define:

$$M_f = \{(x, y) \mid x \in X, y \in Y \text{ and } f(x \to y) = 1\}$$

We show M_f is a matching of G. It's enough to show each vertex of G is incident to at most one edge in M_f . Suppose $M_f = \{(x_1, y_1), (x_2, y_2), \dots, (x_t, y_t)\}$. Consider an edge $(x_i, y_i) \in M_f$.

- $(x_i, y_i) \in M_f$ is because $f(x_i \to y_i) = 1$.
- Because f(e)=0 or 1 for all edges, and the flow conservation constraint at x_i , we must have: (a) $f(s \to x_i)=1$ and (b) $f(x_i,y_j)=0$ for all $y_j \neq y_i$.
- So $(x_i, y_j) \notin M$ for all $j \neq i$. Namely x_i is incident to exactly one edge in M_f
- Similarly, we can show y_i is incident to exactly one edge in M_f .

So M_f is a matching of G. But M is a MM of G. Thus $|M| \ge |M_f| = t = |f|$.



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- Currently, the best algorithm for solving MMBG is Karp-Hopcroft algorithm, with runtime $O(n^{1/2}m)$.

Weighted MM and MMBG Problem

Weighted MM Problem

Input: An undirected graph G=(V,E) . Each edge $e\in E$ has a weight $w(e)\geq 0$.

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Weighted MMBG Problem

The weighted version of the MMBG problem



The Weighted MMBG Problem is also called:

Personnel Assignment Problem

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Problem: How to assign the workers to jobs in order to maximize total profit.

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Personnel Assignment Problem

A bipartite edge weighted graph G = (X, Y, E) represents the following:

- $X = \{x_1, x_2, \dots, x_p\}$ is the set of workers.
- $Y = \{y_1, y_2, ..., y_p\}$ is the set of jobs.
- $(x_i, y_j) \in E$ means the worker x_i can do the job y_j .
- $w(x_i, y_j)$ is the profit we get if x_i is assigned to job y_j .
- We assume each job only needs one worker and one worker can only be assigned to one job.

Problem: How to assign the workers to jobs in order to maximize total profit.

A maximum weight matching M of G is the optimal worker assignment.



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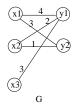
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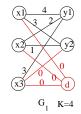
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 - Interpretation: $(x, y) \notin E$ means the worker x cannot do the job y. Adding (x, y) means we pretend x can do y. But w(x, y) = 0 means we get no profit if x is assigned to y. So nothing is really changed!
- Then, we construct a flow-network \bar{G}_2 from G_1 .
 - Add a new source s and a new sink t.

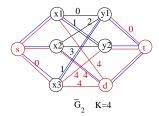
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 - Add a new source s and a new sink t.
 - For each $x \in X$, add a new edge (s,x). For each $y \in Y$, add a new edge (y,t). All these edges have capacity c(s,x) = c(y,t) = 1 and cost(s,x) = cost(y,t) = 0.

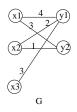


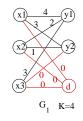
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 - Let K be the largest w(e) value for all edges e in G_1 . For each edge e in G_1 , define capacity c(e) = 1 and cost(e) = K w(e).

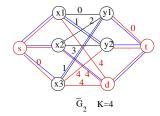




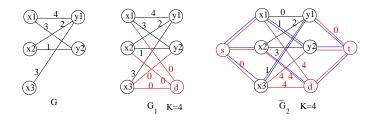




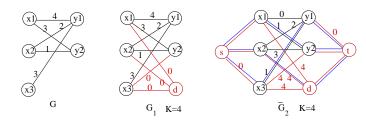




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- \bar{G}_2 is the flow-network constructed from G_1 . All edges have capacity 1. The edges adjacent to s and t have cost = 0. The cost of other edges are as marked. The flow on each of the three blue paths is 1. The flow on all other edges are 0. The corresponding assignment is: x_1 is assigned to y_2 . x_3 is assigned to y_1 . x_2 has no real assignment.

We can argue this procedure indeed solves the personnel assignment problem. Let f be the min-cost max-flow function of G_2 .

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- For each edge e in G_1 , cost(e) = K w(e). So minimizing cost is the same as maximizing the profit (i.e. weight w(e).)

Outline

- Max-Flow Problems
- Interpretation
- Variations of Max-Flow Problem
- Properties
- Max-Flow Algorithm Outline
- 6 Residual Network and Augmenting paths
- Ford-Fulkerson Algorithm
- Max-Flow Min-Cut Theorem
- Sarp-Edmonds Algorithm
- Maximum Matching
- MM Problem for Bipartite Graphs
- Connectivity Problems



Vertex Connectivity

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The vertex connectivity and the edge connectivity can also be defined for directed graphs with similar meaning.



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- But for a general k, how do we determine if $\kappa(G) \ge k$ or not?

Brute-Force-Vertex-Connectivity(G = (V, E))

- Enumerate all subsets $C \subset V$.
- 2 for each $C \subset V$ generated do
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However, there are 2^n vertex subsets. This would take $\Omega(2^n)$ time.

Connectivity Problems: Using Max-Flow

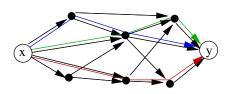
We consider the computation of $\kappa'(G)$ for directed graph G first.

Definition

Let G = (V, E) be a directed graph and x, y two vertices of G.

 $\kappa'_G(x,y)$ = the minimum number of edges that must be deleted from G in order to disconnect x from y.

= the maximum number of edge disjoint paths from x to y.



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- Treat G = (V, E) as a flow network.
- x is the source and y is the sink.
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- Find a max flow f for G. Then $|f| = \kappa'_G(x, y)$.

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$$\kappa'(G) = \min_{x, y \in V, x \neq y} \kappa'_G(x, y)$$

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Fact

Let T(n,m) be the run time for solving the max-flow problem for this special case. (Because of the special structure of the input, it is easier than the general max-flow problem). Then the edge connectivity problem can be solved in $\Theta(n^2T(n,m))$ time.

The edge connectivity problem for undirected graph is very similar.

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We can calculate $\kappa'_G(x,y)$ by using max-flow algorithm. The only difference is that G=(V,E) is an undirected network with source x and sink y. Then we can change it to the basic max-flow problem as we discussed before.

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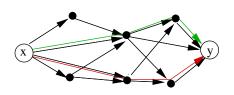
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- Find a max flow f for G. Then $|f| = \kappa'_G(x, y)$.
- So this is the max-flow problem for directed network, with both edge and vertex capacities.
- It can be converted to the basic max-flow problem as discussed before.
- $\kappa_G(x,y)$ can be computed in $\Theta(T(n,m))$ time.
- $\kappa(G) = \min_{x,y \in V} \kappa_G(x,y)$ can be computed in $\Theta(n^2T(n.m))$ time.
- The vertex connectivity problem for directed graph is almost identical