Query Evaluation

R&G Chapter 12,14

(slides adapted from content by J.Gehrke, J.Shanmugasundaram, and/or C.Koch)

- A tree of relational algebra operators
 - Multiple algorithms for some operators
 - Some algorithms only for special cases.
- Each operator "pulls" tuples from operators below it in the query plan when needed.
 - Contrast with operators "pushing" tuples as they become available (used in Streaming)

General Strategies

- Indexing: Build a datastructure to organize your data, then access the data.
- Iteration: Look at each data value individually.
- Partitioning: If your data is too big, break it up into smaller chunks and process each chunk individually.

- Search through "equivalent" query plans.
- Two main issues:
 - Should we consider all equivalent plans?
 - How do we compute the cost of a plan?
- Ideally: Find the best plan!
- Practically: Avoid the worst plans!

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(We'll soon cover the approach taken by System R)

```
SELECT O.FirstName
FROM Officers O, Ships S
WHERE O.Ship = S.ID
AND S.Name = 'Enterprise'
```

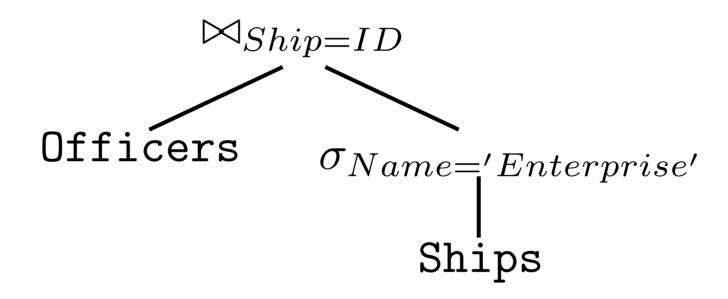
```
SELECT O.FirstName
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```

```
\pi_{FirstName}(\texttt{Officers} \bowtie_{Ship=ID} (\sigma_{Name='Enterprise'} \texttt{Ships}))
```

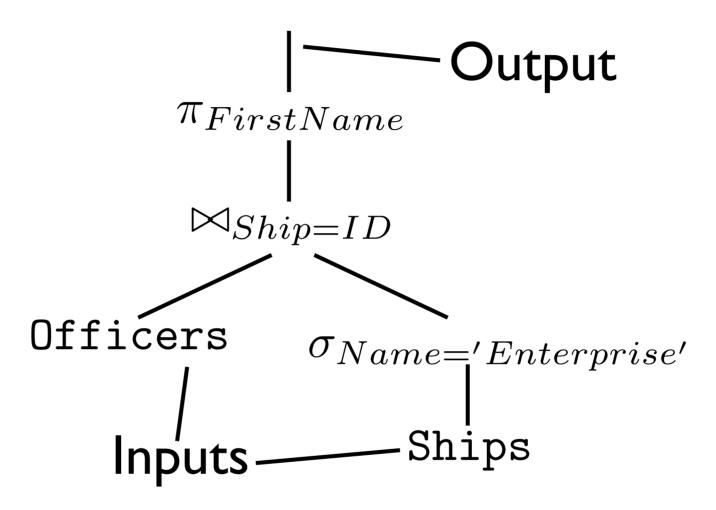
$$\pi_{FirstName}(\texttt{Officers} \bowtie_{Ship=ID} (\sigma_{Name='Enterprise'} \texttt{Ships}))$$

$$\sigma_{Name='Enterprise'}$$
Ships

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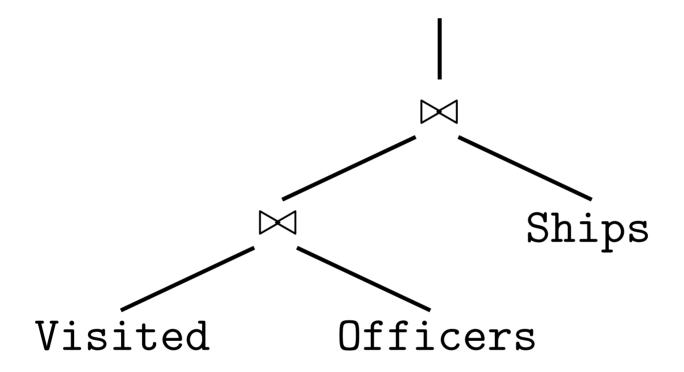
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Left-Deep Query Plans

Visited \bowtie Officers \bowtie Ships



Make the join-tree as deep as possible (to the left)

Left-Deep Query Plans

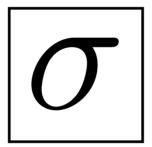
- Easy to construct/optimize
 - Small(er) search space of plans
- Easy to pipeline the output of one join directly into the next.
 - Joins are half-blocking.
- The only type of plan used in System R
 - Works well for < 10 joins (Widely used)

The Iterator Interface

- void open()
- Tuple get_next()
- void close()
- [optional] void reset()

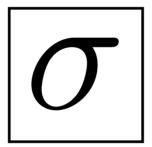
Solution I (Naive/On-the-fly)

Remove tuples from the stream as they arrive

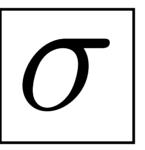


Solution I (Naive/On-the-fly)

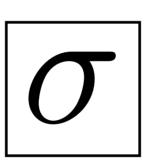
Remove tuples from the stream as they arrive



Solution 2 (Point/Range Lookup)



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Materialize the inputs (if necessary)



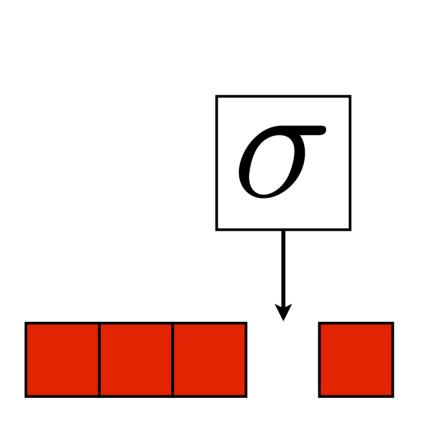
Solution 2 (Point/Range Lookup)

Binary search to find the desired value(s)

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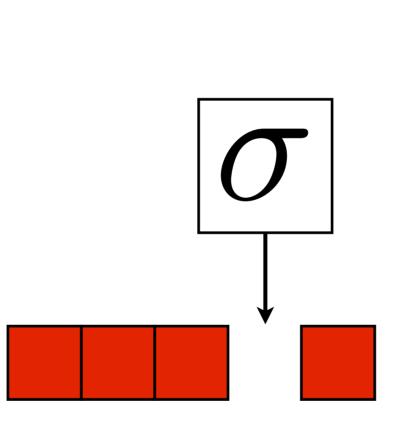


Binary search to find the desired value(s)

Solution 2 (Point/Range Lookup)

When is it not necessary to materialize the inputs?

Materialize the inputs (if necessary)



Binary search to find the desired value(s)

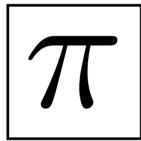
Materialization

- Materialization: Fully computing an operator's output before proceeding.
- Files are already materialized.
- Some operators <u>must</u> materialize their output.
 - (Group-by) Aggregation
 - Sorting
 - Projection (but only set-projection)
 - Set Difference
- Some operators <u>must</u> materialize their input.
 - Joins, Cross Product

Implementing: Projection

Solution I (Naive/On-the-fly)

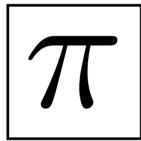
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Implementing: Projection

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Implementing: Projection

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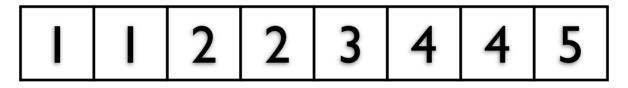
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Problem! This is Bag-projection

2 | 3 | I | 5 | I | 4 | 2 | 4

Sort Inputs



Sort Inputs

Scan for (adjacent) duplicates while reading out values

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Scan for (adjacent) duplicates while reading out values

If the data is already sorted, can compute distinct pipelined

Hash Functions

- A hash function is a function that maps a large data value to a small fixed-size value
 - Typically is deterministic & pseudorandom
- Used in Checksums, <u>Hash Tables</u>, <u>Partitioning</u>, <u>Bloom</u>
 <u>Filters</u>, Caching, Cryptography, Password Storage, ...
- Examples: MD5, SHA1, SHA2

Implementing: Distinct

Solution 2 (Hash Table)

3

2

5

4

18

Implementing: Distinct

Solution 2 (Hash Table)

18

Implementing: Distinct

Solution 2 (Hash Table)

```
1
3
2
5
4
4
```

(Only the current hash bucket needs to fit in memory)

Distinct

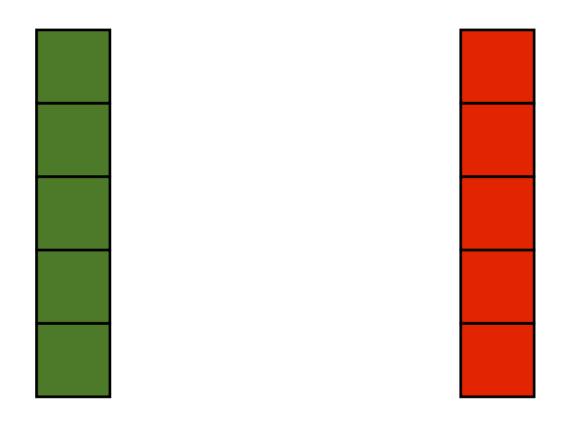
Sort vs Hash

When should either be used?

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Solution I (Nested-Loop)

For Each (a in A) { For Each (b in B) { emit (a, b); }}

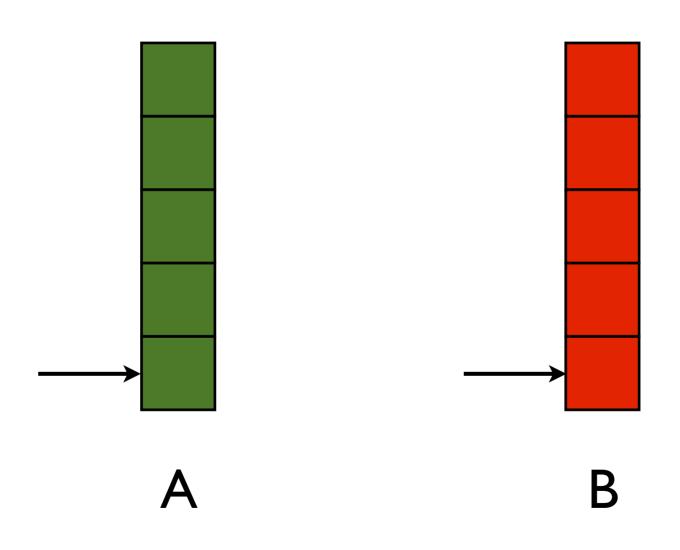


A

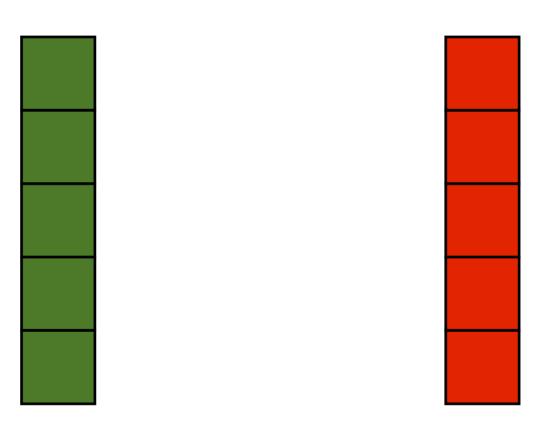
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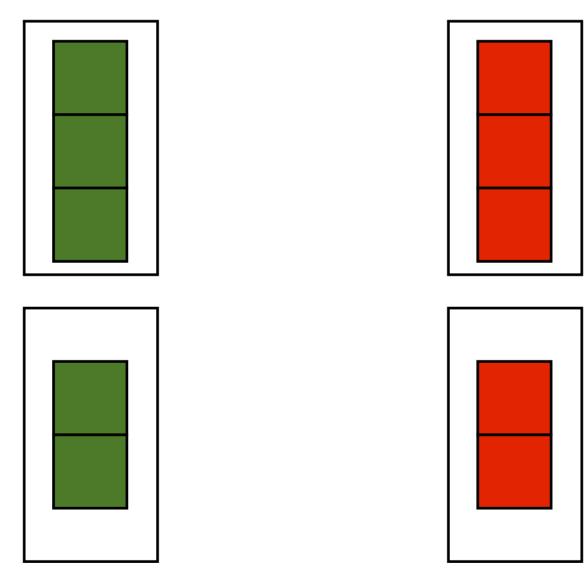


Solution 2 (Block-Nested-Loop)



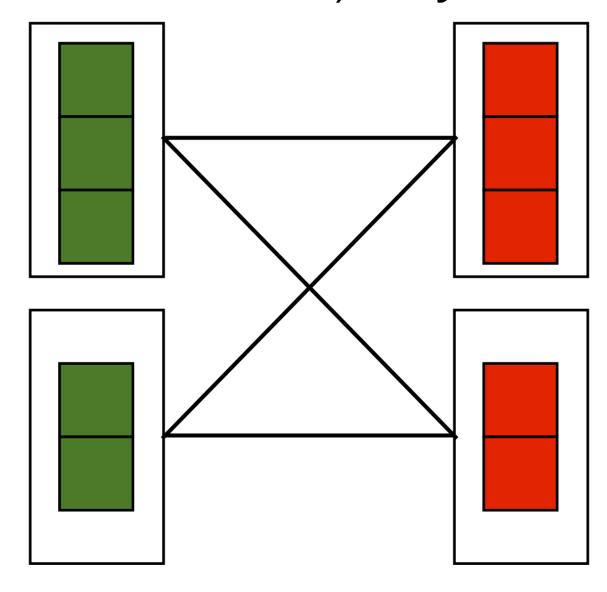
Solution 2 (Block-Nested-Loop)

1) Partition into Blocks



Solution 2 (Block-Nested-Loop)

- 1) Partition into Blocks
- 2) NLJ on each pair of blocks



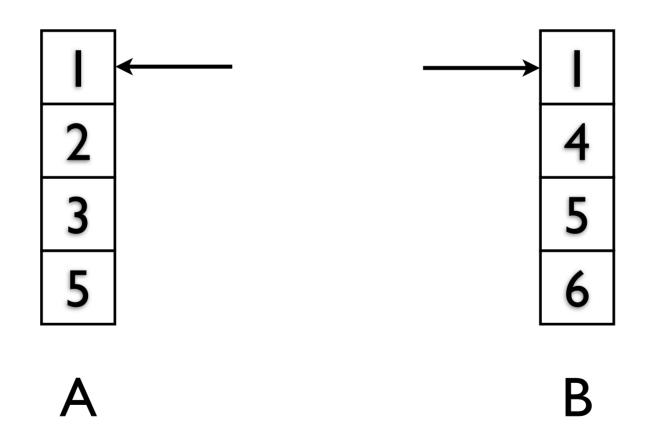
Solution 3 (Index-Nested-Loop)

Like nested-loop, but use an index to make the inner loop much faster!

(We'll return to this soon)

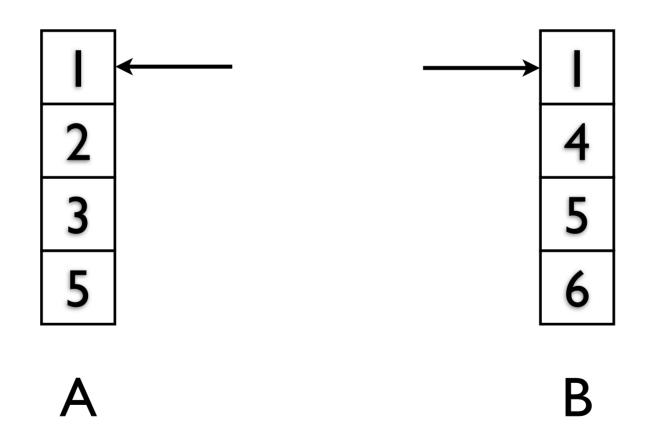
Solution 4 (Sort-Merge Join)

Keep iterating on the set with the lowest value. When you hit two that match, emit, then iterate both

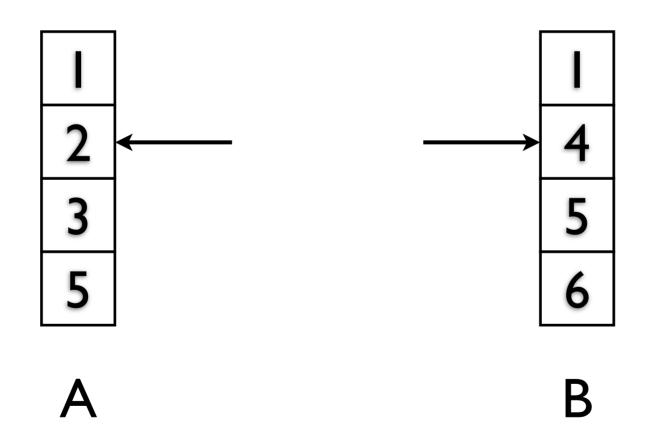


Solution 4 (Sort-Merge Join)

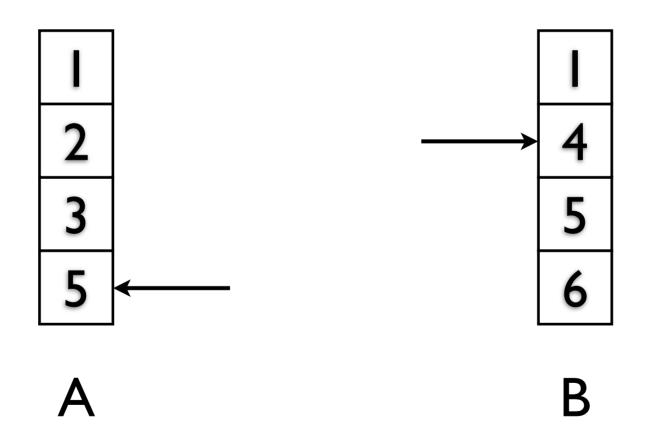
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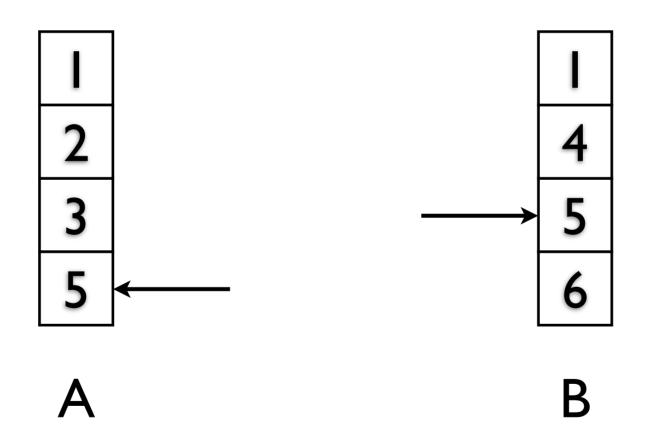
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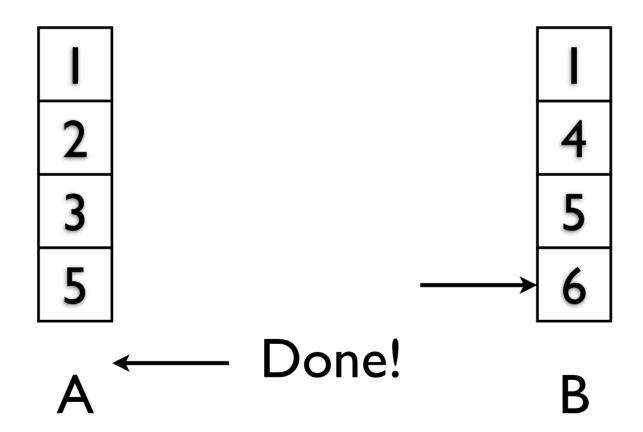
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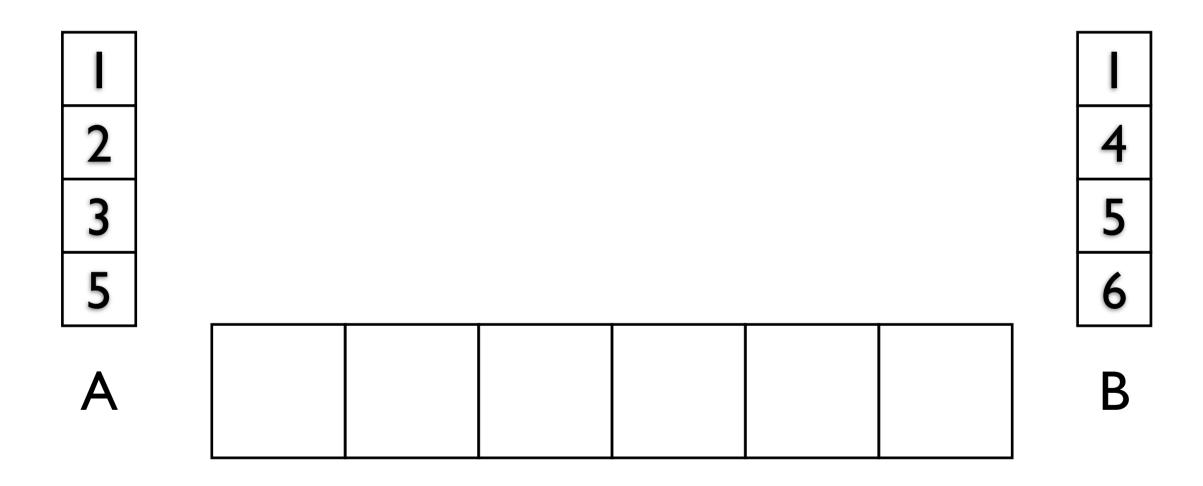
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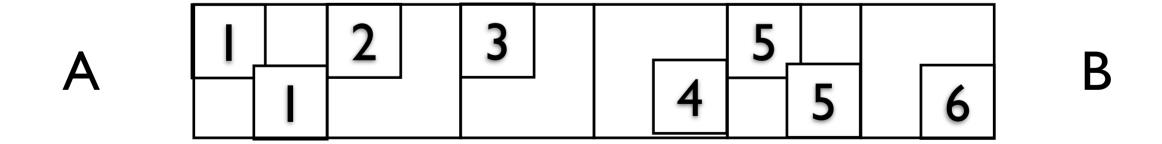


Implementing: Joins Solution 5 (Hash)



Solution 5 (Hash)

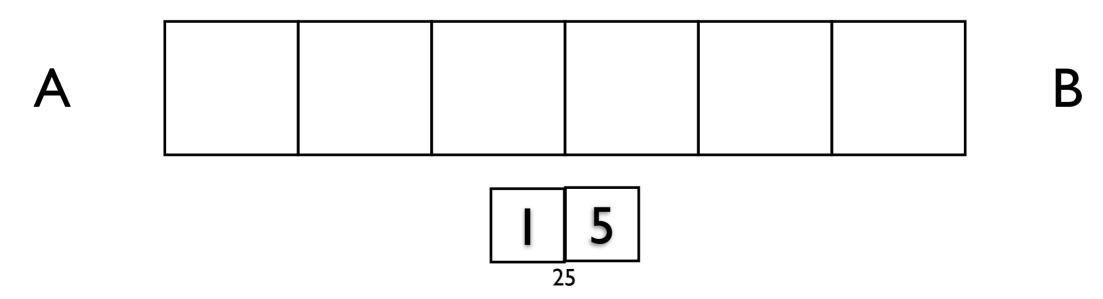
1) Build a hash table on both relations



Solution 5 (Hash)

- 1) Build a hash table on both relations
- 2) In-Memory Nested-Loop Join on each hash bucket

(subdivide buckets using a different hash fn if needed)



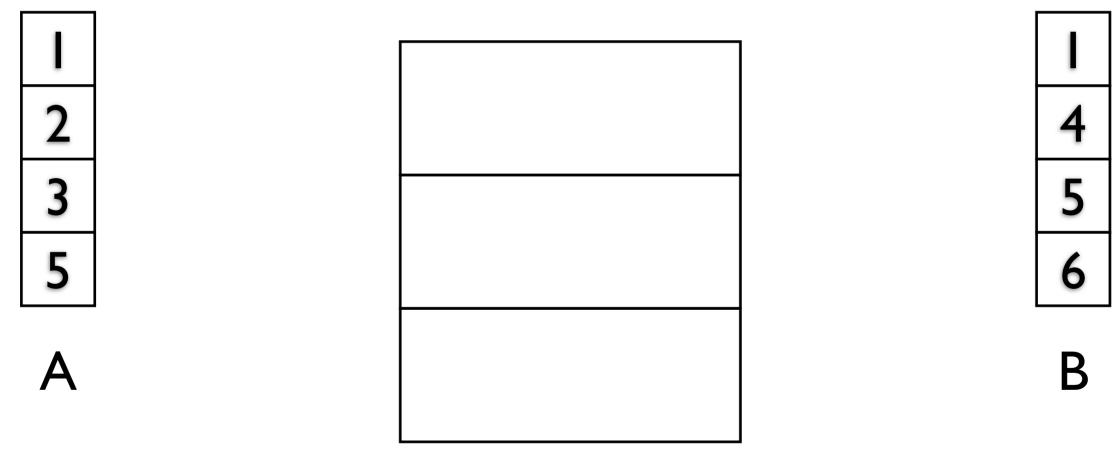
Friday, March 1, 13

What is a significant limitation of hash-joins?

- It only support equality predicates

Solution 6 (Hybrid Hash)

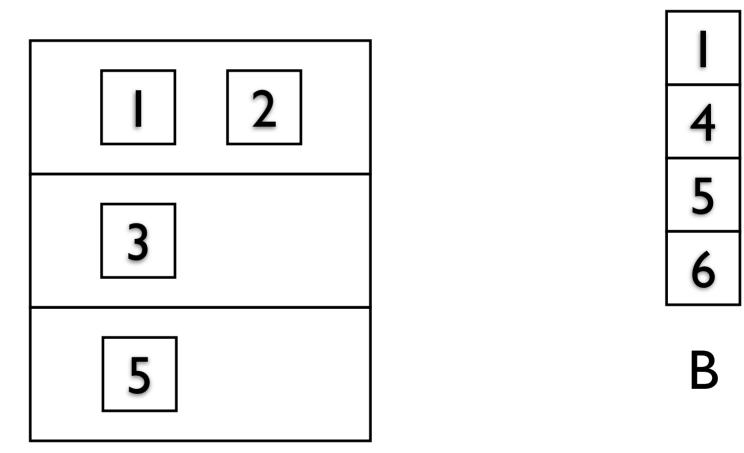
Keep the hash table in memory



(Essentially a more efficient nested loop join)

Solution 6 (Hybrid Hash)

Keep the hash table in memory

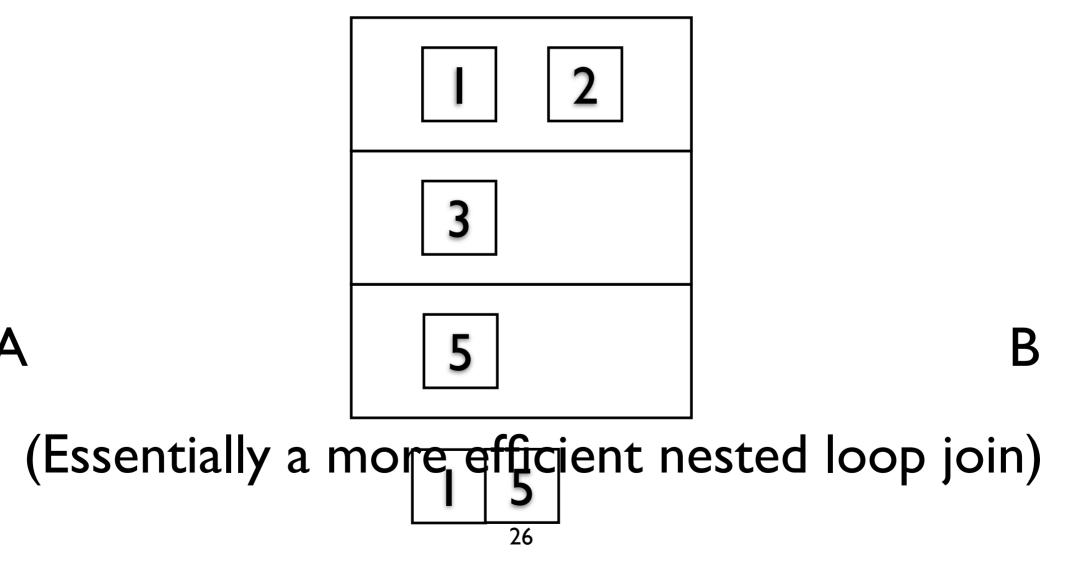


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(Essentially a more efficient nested loop join)

Solution 6 (Hybrid Hash)

Keep the hash table in memory



Tradeoffs

Pipelined?	<u>Memory</u>	Predicate
	Requirements?	Limitation?
1/2	I Table	No
No	2 'Blocks'	No
1/2	I Tuple (+Index)	Single Comparison
If Data Sorte	Same as reqs. of Sorting Inputs	Equality Only
No man	lax of I Page per Buc d All Pages in Any Bu	ket Equality Only
1/2	Hash Table	Equality Only
	I/2 No I/2 If Data Sorte No Man	Requirements? I/2 I Table No 2 'Blocks' I/2 I Tuple (+Index) If Data Sorted Same as reqs. of Sorting Inputs No Max of I Page per Buc and All Pages in Any Buc