Sorting

Bubble Sort 冒泡排序

Repeatedly steps through the list to be sorted, compares each **pair of adjacent items** and swaps them if they are in the wrong order.

重复遍历要排序的列表,比较**每对相邻项**,如果它们的顺序错误,则交换它们。

但是潜在的情况是如果列表本身就已经是排序好的,但是最初的算法设计中没有检测中断的机制,因此会一直循环下去知道直到到达循环的终止条件,但实际上由于已经排序好了,所以迭代的过程中并没有发生位置转换。因此可以考虑添加一个中断判断。

```
boolean needNextPass = true;
for (int k = 1; k < list.length && needNextPass; k++) {
    // Array may be sorted and next pass not needed
    needNextPass = false;
    for (int i = 0; i < list.length - k; i++){
        if (list[i] > list[i + 1]){
            //swap list[i] with list[i + 1];
            needNextPass = true;
        }
    }
}
```

添加一个参数 **needNextPass**,如果每进入一轮外循环就将值设置为 false,然后如果再当前整个内循环过程中都没有满足过 if (list[i] > list[i + 1]),那么就不会修改 needNextPass,这样就不会开启下一轮的外循环。这样假如列表是是先排序好的,那么实际上只会进行完最开始的一轮遍历之后就结束了

Time complexity of Bubble Sort 冒泡排序的时间复杂度

• **Best case**: Since the number of comparisons is **n - 1** in the first pass, the best- case time for a bubble sort is **O(n)**.

最佳情况:由于第一次比较的次数为n - 1,因此冒泡排序的最佳时间为**O(n)**。

• Worst case: example: Initial list: [5,4,3,2,1]

最差情况

- [5,4,3,2,1] -> [4,3,2,1,5] 1st pass, 4 comparsions (5 v.s. 4,3,2,1, 5 is sorted)
- [4,3,2,1,5] -> [3,2,1,4,5] 2nd pass, 3 comparsions (4 v.s. 3,2,1, 4 is sorted)
- [3,2,1,4,5] -> [2,1,3,4,5] 3rd pass, 2 comparsions (3 v.s. 1,2, 3 is sorted)
- [2,1,3,4,5] -> [1,2,3,4,5] 4th pass, 1 comparisons (2 v.s. 1, 2 is sorted)
- So, 5 elements, we do 4+3+2+1 comparisons
 - If n elements, in the worst case, we compare (n 1) + (n 2) + ... + 2 + 1 = n(n 1) / 2 times. The Big(O) is $O(n^2)$

```
public class BubbleSort {
   public static void bubbleSort(int[] list) {
```

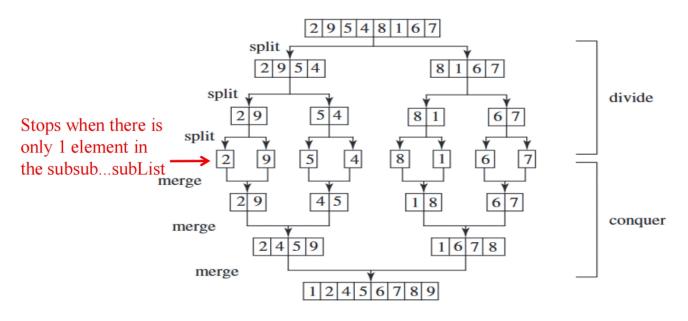
```
boolean needNextPass = true;
        for (int k = 1; k < list.length && needNextPass; <math>k++) {
            // Array may be sorted and next pass not needed
            needNextPass = false;
            // Perform the kth pass
            for (int i = 0; i < list.length - k; i++) {
                if (list[i] > list[i + 1]) {
                    int temp = list[i];
                    list[i] = list[i + 1];
                    list[i + 1] = temp;
                    needNextPass = true; // Next pass still needed
                }
            }
       }
    }
    public static void main(String[] args) {
        int size = 100000;
        int[] a = new int[size];
        randomInitiate(a);
        long startTime = System.currentTimeMillis();
        bubbleSort(a);
        long endTime = System.currentTimeMillis();
        System.out.println((endTime - startTime) + "ms");
    // 随机生成一个数组
    private static void randomInitiate(int[] a) {
        for (int i = 0; i < a.length; i++)
            a[i] = (int) (Math.random() * a.length);
    }
}
```

Merge Sort 归并排序

The merge-sort algorithm can be described recursively as follows:

合并排序算法可以递归地描述如下:

- The algorithm divides the array into two halves and applies a merge sort on each half recursively. 该算法将数组分为两半,并递归地对每一半应用合并排序。
- After the two halves are sorted, the algorithm then merges them. 在对两半部分进行排序后,算法会将它们合并。



```
public class MergeSortTest {
    // 拆分排序
    public static void mergeSort(int[] list) {
        if (list.length > 1) { // Recursive base case: stop when condition unsatisfied
            // Split the 1st half (recursive step)
            int[] firstHalf = new int[list.length / 2];
            System.arraycopy(list,0,firstHalf,0,list.length / 2);
            mergeSort(firstHalf);
            // Split the 2nd half (recursive step)
            int secondHalfLength = list.length - list.length / 2;
            int[] secondHalf = new int[secondHalfLength];
            System.arraycopy(list,list.length / 2 ,secondHalf, 0 ,
                             secondHalfLength);
            mergeSort(secondHalf);
            // SortMerge (only happens AFTER both recursive calls
            finish)
                merge( firstHalf, secondHalf, list) ;
        }
   }
    // 合并
    public static void merge(int[] list1, int[] list2, int[] temp){
        int current1 = 0; // Current index in list1, the first half
        int current2 = 0; // Current index in list2, the 2nd half
        int current3 = 0; // Current index in temp, storing data temporarily
        // While the indices are in the list
        while (current1 < list1.length && current2 < list2.length) {</pre>
            if (list1[current1] < list2[current2])</pre>
                // If current element in list1 is smaller, add it to temp
                temp[current3++] = list1[current1++];
            else
                // Otherwise, add the current element in list2 to temp
                temp[current3++] = list2[current2++];
        // list2 finished, but there are remaining elements in list1, add
```

```
them to temp
            while (current1 < list1.length)</pre>
                temp[current3++] = list1[current1++];
        // list1 finished, but there are remaining elements in list2, add
        them to temp
            while (current2 < list2.length)</pre>
                temp[current3++] = list2[current2++];
    }
    public static void main(String[] args) {
        int size = 100000;
        int[] a = new int[size];
        randomInitiate(a);
        long startTime = System.currentTimeMillis();
        mergeSort(a);
        long endTime = System.currentTimeMillis();
        System.out.println( (endTime - startTime) + "ms" ) ;
    }
    private static void randomInitiate(int[] a) {
        for (int i = 0; i < a.length; i++)
            a[i] = (int) (Math.random() * a.length);
    }
}
```

Time complexity of merge sort 归并排序的时间复杂度

• Let $\mathbf{T}(\mathbf{n})$ denote the time required for sorting an array of \mathbf{n} elements using merge sort.

设T(n)表示使用合并排序对n个元素数组进行排序所需的时间。

$$T(n) = T(\frac{n}{2}) + T(\frac{n}{2}) + 2n - 1$$

• The first **T(n/2)** is the time for sorting the first half of the array and the second **T(n/2)** is the time for sorting the second half

第一个 T(n/2) 是对数组的前半部分进行排序的时间,第二个 T(n/2) 是对后半部分进行排序的时间

Merging cost 2n-1 because n - 1 comparisons (for comparing the elements of the two subarrays) and n
moves (to place each element into the temporary array)

合并成本为 2n-1,因为 n 1 比较(用于比较两个子数组的元素)和 n 移动(将每个元素放入临时数组中)

Repeatedly substitute T(n/2) into the formula we will find the time complexity of merge sort is O(nlogn).
 在公式中反复代入 T (n/2),我们会发现归并排序的时间复杂度为 O (nlogn)

Quick Sort 快速排序

• A quick sort works as follows:

快速排序的工作原理如下

The algorithm selects an element, called the **pivot**, in the array.
 该算法在数组中选择一个名为 **枢轴** 的元素。

• It partitions (divides) the array into two parts so all the elements in the **first part** are less than or equal to the pivot, and all the elements in the **second part** are greater than the pivot.

它将数组划分为两部分,因此 **第一部分** 中的所有元素都小于或等于枢轴,**第二部分** 中所有元素都大于枢 轴。

• The quick-sort algorithm is then **recursively** applied to the first part and then the second part to sort them out.

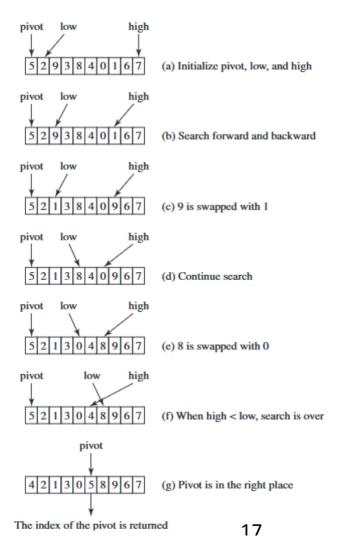
然后 **递归地** 将快速排序算法应用于第一部分,然后再应用于第二部分以对其进行排序。



```
public class QuickSortTest {
    public static void quickSort(int[] list) {
        quickSort(list, 0, list.length - 1);
    public static void quickSort(int[] list, int first, int last) {
        if (last > first) {
            int pivotIndex = partition(list, first, last);
            quickSort(list, first, pivotIndex - 1);
            quickSort(list, pivotIndex + 1, last);
        }
    }
    public static int partition(int[] list, int first, int last) {
        int pivot = list[first];
        int low = first + 1; // position, not value
        int high = last; // position, not value
        while (high > low) {
            //low pointer moves right when
            //1. low <=high and 2. list[low] <= pivot</pre>
            while (low <= high && list[low] <= pivot)</pre>
                low++;
            //high pointer moves left when
            //1. low <=high and 2. list[high] > pivot
            while (low <= high && list[high] > pivot)
                high--;
            // If low < high, swap the two elements.</pre>
            if (high > low) {
                int temp = list[high];
                list[high] = list[low];
                list[low] = temp;
            }
        }
        // Ensure high pointer point at an element
        // less than or equal to pivot
        while (high > first && list[high] >= pivot){
            high--;
        }
```

```
// Swap pivot with list[high]
        if (pivot > list[high]) {
            list[first] = list[high];
            list[high] = pivot;
            return high;
        } else // e.g., a sotred list
            return first;
    }
    public static void main(String[] args) {
        int size = 100000;
        int[] a = new int[size];
        randomInitiate(a);
        long startTime = System.currentTimeMillis();
        quickSort(a);
        long endTime = System.currentTimeMillis();
        System.out.println((endTime - startTime) + "ms");
    }
    private static void randomInitiate(int[] a) {
        for (int i = 0; i < a.length; i++)
            a[i] = (int) (Math.random() * a.length);
    }
}
```

这个 quickSort() 定义了 Quick Sort 的递归结构,因为它不断调用自身。partition() 也会在进程中递归调用,直到基本情况(last>first)。这确保了列表可以递归地分为左和右子列表、子子列表、子子子列表……



Time Complexity of Quick Sort

• To partition an array of **n** elements, it takes **n** comparisons and **n** moves. Thus, the time required for partition is **O(n)**.

要对一个包含 n 个元素的数组进行分区,需要进行 n 次比较和 n 次移动。因此,分区所需的时间是 O(n)。

- In the **best case**, each time the pivot divides the array into two parts of the same size. **O(nlogn)** 在 **最好的情况**下,每次pivot将数组分成大小相同的两部分。**O(nlogn)**
- In the average case, maybe not exactly the same, but the size of the two sub arrays are very close.
 O(nlogn)

在 平均情况 下,可能不完全相同,但两个子数组的大小非常接近 O(nlogn)

- In the worst case, the pivot divides the array each time into one big subarray with the other array empty. The size of the big subarray is one less than the one before divided. O(n²)
 在最坏的情况下,枢轴每次将数组划分为一个大子数组,另一个数组为空。大子阵列的大小比分割前的小一个O(n²)
 - For example (assuming the 1st element is the pivot for partition):例如(假设第一个元素是分区的枢轴):
 - [1,2,3,4,5...n], size=n
 - In the first partition, pivot=1, we have ->

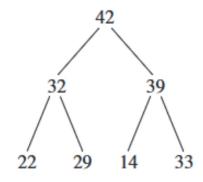
- left: [empty], right [2,3,4,5...n], right sub array size = n-1
- In the next partition, pivot=2, we have ->
 - left: [empty], right [3,4,5,6...n], right sub array size = n-2
- ... continues this way, we will have to recursively divide the arrary n-1 times till the sub array
 size =1
- Recall that the time complexity of each partition is O(n), as it compares all elements during each division.
- So we did n-1 times O(n), so, we get the worst time complexity to be O(n^2)

Heap Sort: Binary Tree 堆排序

- A **binary tree** is a hierarchical structure: it either is empty or it consists of an element, called the **root**, and two distinct binary trees, called the **left subtree** and **right subtree**
 - **二叉树** 是一种层次结构:它要么是空的,要么由一个元素(称为 **根**)和两个不同的二叉树(称为 **左子树** 和 **右 子树**)组成。
 - o The **length** of a path is the number of the edges in the path 路径的 **长度** 是路径中的边数
 - The **depth** of a node is the length of the path from the root to that node
 节点的 深度 是从根节点到该节点的路径长度

The length from 32 to 22: 1 (32 - 22)

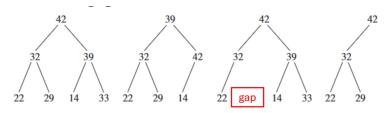
The depth of node 29: 2 (42(root)-32, 32-29)



Complete Binary Tree 完全二叉树

A binary tree is **complete** if:

- All levels are completely filled except **possibly** the last level 除可能最后一级外,所有上层级别都已完全填满
- Even though the last level may not be full, it must be filled from left to right, **without gaps** 即使最后一关可能没有填满,也必须从左到右填满,**没有空隙**



• 1st - complete, as all levels are completely filled

因为所有级别都已完全填满

• 2nd - complete, although the last level is not full (missing one node next to 14), it is filled from left to right, without gaps

尽管最后一级没有填满(缺少14旁边的一个节点),但它是从左到右填充的,没有间隙

• 3rd, incomplete, a gap from left to right (next to node 22)

从左到右存在间隙(在节点 22 旁边)

4th, incomplete, the 2nd level is not full, while we only allow the last level (level 3 in this case) not to be full
 第二级未满,而我们只允许最后一级(本例中为第3级)未满

Binary Heap 二叉堆

- A **binary heap** is a binary tree with the following properties:
 - 二进制堆是具有以下属性的二叉树
 - It is a complete binary tree, and

它是一个 完全二叉树

Each node is greater than or equal to any of its children
 每个节点都大于或等于其任何子节点

Heap Sort 堆排序

• **Heap sort** uses a binary heap and the process consists of **two** main phases:

堆排序使用二叉堆,该过程由两个主要阶段组成:

• Heap construction:

堆构造:

- All the elements are first inserted into a max heap 首先将所有元素插入到最大堆中
- Repeated removal:

重复移除:

Repeatedly remove the **root node**, which is the current largest element in the heap. The removed element is actually moved to the end of the array, forming a sorted array that grows from the back.

重复删除 **根**节点,这是堆中当前最大的元素。删除的元素实际上被移动到数组的末尾,形成一个从后面增长的排序数组。

Example:

• For example: [10,5,3,4,1]

o 1st removal: [..., 10]

o 2nd removal: [..., 5, 10]

o 3rd removal: [..., 4, 5, 10]

o (do removal repeatedly)

o Final: [1,3,4,5,10]

Sorting a Heap 对一个堆进行排序

- A heap can be stored in an **ArrayList** or an **array** if the heap size is known in advance
 如果堆大小预先已知,则可以将堆存储在 **ArrayList** 或 **数组** 中
 - For a node at position i, its left child is at position 2i+1 and its right child is at position 2i+2, and its parent is at index (i-1)/2

对于位于位置 i 的节点,其左子节点位于位置 2i+1,右子节点位于地址 2i+2,其父节点位于索引(i-1)/2

• For example: the for a nood at position **4**, and its two children are at positions 2 * 4+1=**9** and 2 * 4+2 =**10**, and its parent is at index (4-1)/2=**1** (not 1.5, integer division)

举例来说:对于位置为 4 节点,其两个子节点位于位置2 * 4+1=9 和2 * 4+2 =10,其父节点位于索引(4-1)/2=1 (不是1.5,整数除法,向下取整)

Adding elements to a Heap 向堆中添加一个元素

• To add a new node to a heap, first add it to the end of the heap and then rebuild the tree with this algorithm:

要将新节点添加到堆中,请先将其添加到堆的末尾,然后使用以下算法重建树:

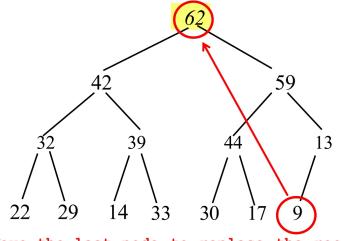
```
// Let the last node be the current node;
while (the current node is greater than its parent) {
   Swap the current node with its parent;
   Now the current node is one level up;
}
```

Removing the Root and Rebuild the Heap 从堆中移除根并重构堆

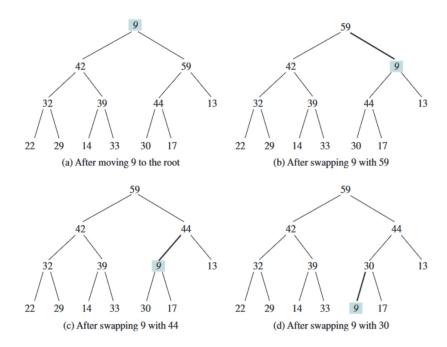
- Often we need to remove the maximum element, which is the **root in a heap**
- After the root is removed, the tree must be rebuilt to maintain the heap property (e.g., parent>=child)
 using this algorithm:

Example:

• Removing root 62 from the heap (replaces it with the last node in the heap: 9)



Move the last node to replace the root; Let the root be the current node;



- (a-b) 9<42; 9<59; 59>42; Swap 9 and 59
- (b-c) 9<44; 9<13; 44>13; Swap 9 and 44
- (c-d) 9<30; 9<17; 30>17; Swap 9 and 30

The heap is rebuilt now, and ready for the next removal

```
public class Heap<E extends Comparable> {
    private java.util.ArrayList<E> list = new java.util.ArrayList<E>();
    /** Create a default heap */
    public Heap() {
    }
    /** Create a heap from an array of objects */
    public Heap(E[] objects) {
        for (int i = 0; i < objects.length; i++)
            add(objects[i]);
    }
    /** Add a new object into the heap */
    public void add(E newObject) {</pre>
```

```
list.add(newObject); // Append to the end of the heap
        int currentIndex = list.size() - 1; // The index of the last node
        while (currentIndex > 0) {
            int parentIndex = (currentIndex - 1) / 2;
            // Swap if the current object is greater than its parent
            if (list.get(currentIndex).compareTo(
                list.get(parentIndex)) > 0) {
                E temp = list.get(currentIndex);
                list.set(currentIndex, list.get(parentIndex));
                list.set(parentIndex, temp);
            } else
                break; // the tree is a heap now
            currentIndex = parentIndex;
        }
    }
    /** Remove the root from the heap */
    public E remove() {
        if (list.size() == 0) return null;
        E removedObject = list.get(0);
        list.set(0, list.get(list.size() - 1));
        list.remove(list.size() - 1);
        int currentIndex = 0;
        while (currentIndex < list.size()) {</pre>
            int leftChildIndex = 2 * currentIndex + 1:
            int rightChildIndex = 2 * currentIndex + 2;
            // Find the maximum between two children
            if (leftChildIndex >= list.size())
                break; // The tree is a heap
            int maxIndex = leftChildIndex;
            if (rightChildIndex < list.size())</pre>
                if (list.get(maxIndex).compareTo(
                    list.get(rightChildIndex)) < 0)</pre>
                    maxIndex = rightChildIndex;
            // Swap if the current node is less than the maximum
            if (list.get(currentIndex).compareTo(
                list.get(maxIndex)) < 0) {</pre>
                E temp = list.get(maxIndex);
                list.set(maxIndex, list.get(currentIndex));
                list.set(currentIndex, temp);
                currentIndex = maxIndex;
            }
            else
                break; // The tree is a heap
        }
        return removedObject;
    /** Get the number of nodes in the tree */
    public int getSize() {
        return list.size();
}
public class HeapSort {
```

```
public static <E extends Comparable> void heapSort(E[] list) {
        // Create a Heap of E
        Heap < E > heap = new Heap < E > ();
        // Add elements to the heap
        for (int i = 0; i < list.length; i++)</pre>
            heap.add(list[i]);
        // Remove the highest elements from the heap
        // and store them in the list from end to start
        for (int i = list.length - 1; i >= 0; i--)
            list[i] = heap.remove();
    }
    /** A test method */
    public static void main(String[] args) {
        Integer[] list = \{2, 3, 2, 5, 6, 1,
                           -2, 3, 14, 12};
        heapSort(list);
        for (int i = 0; i < list.length; i++)</pre>
            System.out.print(list[i] + " ");
    }
}
```

Time complexity of Heap Sort 堆排序的时间复杂度

Heap SortTime: O(nlog n)

• Space Complexity

• Both merge and heap sorts require O(n logn) time.

合并和堆排序都需要O(n logn)时间。

• A merge sort requires a temporary array for merging two subarrays; a heap sort does not need additional array space.

合并排序需要一个临时数组来合并两个子数组; 堆排序不需要额外的数组空间。

• Therefore, a heap sort is more **space efficient** than a merge sort.

因此,**堆排序比合并排序更节省空间**。