1.1.
$$A = \begin{pmatrix} -0.5 & -0.5 & 0 \\ -0.5 & -0.5 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$\det(A - \lambda I) \stackrel{!}{=} 0 = (-0.5 - \lambda)(-0.5 - \lambda)(\frac{2}{0.5} - \lambda) - (2 - \lambda) \not= 0.5 \cdot 0.5$$

$$= (0.25 + \lambda + \lambda^{2})(2 - \lambda) - 0.5 + 0.25\lambda$$

$$= 0.5 + 2\lambda + 2\lambda^{2} - 0.25\lambda - \lambda^{2} - \lambda^{3} - 0.5 + 0.25\lambda$$

$$= -\lambda^{3} + \lambda^{2} + 2\lambda = \lambda(-\lambda^{2} + \lambda + 2)$$

$$\downarrow \lambda_{1} = 0 \Rightarrow \lambda_{2} = \begin{pmatrix} -1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\downarrow \lambda_{2} = -1 \Rightarrow \lambda_{2} = \begin{pmatrix} -1 & 1 \\ 0 & 1 \\ 0 & 1 \end{pmatrix}$$

$$\downarrow \lambda_{3} = 2 \Rightarrow \lambda_{3} = \begin{pmatrix} 8 \\ 1 \\ 0 & 1 \end{pmatrix}$$

$$\downarrow \lambda_{3} = 2 \Rightarrow \lambda_{3} = \begin{pmatrix} -1 & 1 & 1 \\ 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

 $\lambda_3 = 2$

$$\Rightarrow$$
 $x(t) = c_1 \cdot v_1 + c_2 e^{-1/4} v_2 + c_3 e^{-1/2} v_3$

$$T \dot{v}_1(t) = -v_1(t) - c[v_2 - \theta]_+ + s_1$$

 $T \dot{v}_2(t) = -v_2(t) - c[v_4 - \theta]_+ + s_2$

$$\widetilde{U}_{1} = U_{1} - O \qquad \widetilde{U}_{2} = U_{2} - O$$

$$T\widetilde{v}_{2}(t) = -(\widetilde{v}_{2} + \theta) - c[\widetilde{v}_{1}]_{+} \widetilde{s}_{2}$$

$$= \sum_{i} \widehat{V}_{1}(\widehat{+}) = -\widehat{V}_{1}(\widehat{+}) - c[\widehat{V}_{2}(\widehat{+})]_{+} \widehat{S}_{1}$$

$$\widehat{V}_{2}(\widehat{+}) = -\widehat{V}_{2}(\widehat{+}) - c[\widehat{V}_{1}(\widehat{+})]_{+} \widehat{S}_{2}$$

$$J = \begin{pmatrix} \frac{\partial \dot{U}_1}{\partial U_1} & \frac{\partial \dot{U}_2}{\partial U_2} \\ \frac{\partial \dot{U}_2}{\partial U_1} & \frac{\partial \dot{U}_2}{\partial U_2} \end{pmatrix} = \begin{pmatrix} -1 - c \frac{\partial (U_2)_+}{\partial U_1} & -c \frac{\partial (U_2)_+}{\partial U_2} \\ -c \frac{\partial (U_4)_+}{\partial U_1} & -1 - c \frac{\partial (U_4)_+}{\partial U_2} \end{pmatrix}$$

3 Ma \$0, uz >0 = no fixed point in this quadrant = Galculation usetess

Computing Fixed points

(a) fixed point outside of quadrant

(b) fixed point outside of quadrant

(c) -11

(d) fixed point outside of quadrant

(d)
$$u_1 = -2u_2 + 1$$

(e) $u_1 = -2u_2 + 1$

(f) $u_1 = -2u_2 + 1$

(f) $u_1 = -2u_2 + 1$

(g) $u_1 = -$

2.6

Eigenvalues are always 1/12=-1 => always stable

Computing fixed points: and Eigenvalus:

Computing tixed points and city
$$0 = -U_1 - c + 1$$

$$+1$$
 $\begin{pmatrix} -1 \\ -1 \end{pmatrix}$ $\begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix}$

(4)
$$v_1 < 0$$
 $v_2 < 0 \Rightarrow$ (1) for all c