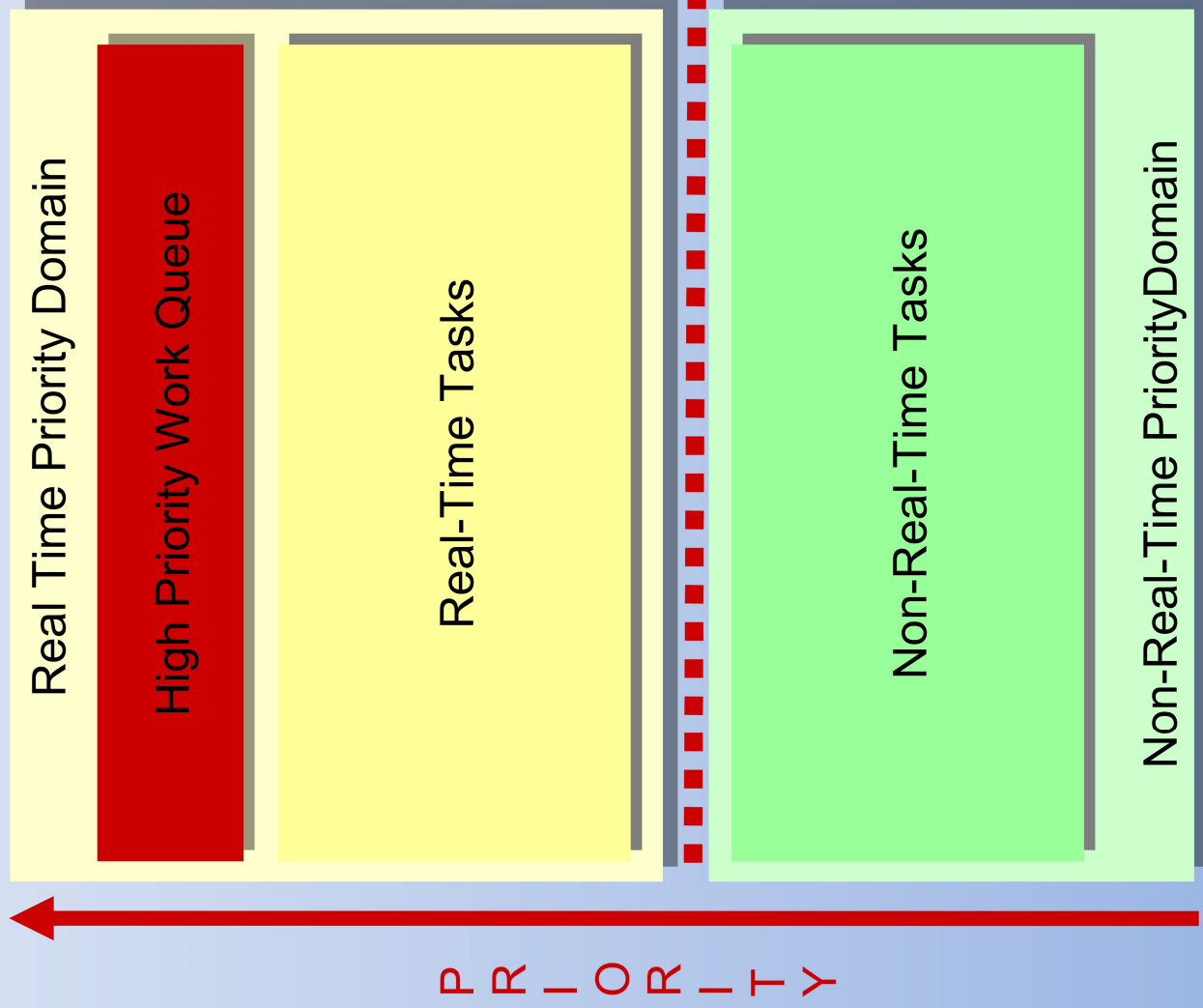


Mixing Real-Time and non-Real-Time Tasks



Work Queue should be highest priority because it services the interrupt *"bottom half"*

Real Time tasks need to be higher priority than any non-real-time task

Non-real-time tasks must be lower priority than all Real time tasks so that they cannot interfere with Real-time behavior

