

Likelihood Ratios

It's from Radon-Nikodym Thm. — change measure.

e.g. in ch. 3). P_1, P_2 are prob. measure s.t. $P_1 \ll P_2$.

Then for r.v. X : $E_{P_1}(x) = E_{P_2}(xL)$. $L = \frac{dP_1}{dP_2}$

Applications:

① Monte Carlo:

To estimate the prob. of an event. The accuracy depends on the frequency of the event.

e.g. For $X \stackrel{P_0}{\sim} N(0, 1)$: $P_0(X > 2.5)$ is small. So

$\{X > 2.5\}$ seldom occurs under P_0 . but if consider:

$$E_{P_0}(I_{\{X > 2.5\}}) = E_{2.5}(L(x) I_{\{X > 2.5\}})$$

$$L(x) = f_{2.5}(x) / f_{2.5}(x) = \frac{\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}}}{\frac{1}{\sqrt{2\pi}} e^{-(x-2.5)^2/2}} = e^{-2.5x + \frac{25}{2}}$$

$X \sim N(2.5, 1)$ under $dP_{2.5} = f_{2.5}(x) dx$.

$$\Rightarrow \text{Estimated by: } \sum_i^n L(x_i) I_{\{X > 2.5\}}(x_i) / n.$$

② Gamble's Ruin:

Suppose $X_k \stackrel{i.i.d.}{\sim} N(m, 1)$. $S_n = \sum_1^n X_k$. $m < 0$

$$T_b = \min \{n \mid S_n > b\}$$

prop: $P_{m_1} \left(Z_b < \infty \right) \leq e^{-M_1 b}$.

Pf: Note RHS = $P_{m_1} \left(\tilde{Z}_b < \infty \right)$, $\tilde{Z}_b = \inf \{t \mid X_{(t)} = b\}$.

where $X_{(t)} = M_1 t + W(t)$.

Next, prove: $P_{m_1} \left(Z_b = \infty \right) \geq P_{m_1} \left(\tilde{Z}_b = \infty \right)$

Note $X_{(n)} \sim S_n \sim N(nM_1, n)$ $n \in \mathbb{Z}^+$.

$$\begin{aligned} \text{RHS} &= P_{m_1} \forall t \geq 0, X_{(t)} < b \leq P_{m_1} \forall n \in \mathbb{Z}^+, X_{(n)} < b \\ &= P_{m_1} \forall n \in \mathbb{Z}^+, S_n < b \\ &= P_{m_1} \left(Z_b = \infty \right) \end{aligned}$$

Note: $X_k \xrightarrow{P_1} N(m_1, 1)$, $X_k \xrightarrow{P_2} N(m_2, 1)$. Then: we have.

$$L(\vec{x}) = \lambda P_1 / \lambda P_2 = e^{-\frac{1}{2} \sum_i (x_i - m_1)^2} / e^{-\frac{1}{2} \sum_i (x_i - m_2)^2} \text{ for } \vec{x} = (x_1, \dots, x_n)$$

$$P_{m_1} \left(B(x_1, \dots, x_n) \right) = E_{m_1} \left(L(\vec{x}) I_B \right).$$

Next, we will extend "n" to stopping time Z :

Def: i) $\mathcal{G}_n = \{Y \mid Y = h(x_1, \dots, x_n)\}$.

ii) $\mathcal{G}_Z = \{Y \mid Y I_{\{Z=n\}} \in \mathcal{G}_n, \forall n\}$. Z is a stopping time.

Thm: (Wald's LR Identity)

$Y \in \mathcal{G}_Z$. b/w. If $(x_1, \dots, x_n) \sim f_i^n$, $i = 1, 2$.

$$L_n = f_1^n / f_2^n. \text{ Then: } E_1 \left(Y I_{\{Z=n\}} \right) = E_Z \left(Y L_Z I_{\{Z=n\}} \right)$$

$$\text{Pf: LHS} = \sum E_1 \left(Y I_{\{Z=n\}} \right)$$

$$= \sum E_Z \left(Y I_{\{Z=n\}} L_n \right)$$

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$$= E_Z \left(Y L_Z I_{\{Z=n\}} \right)$$

i) Apply on Z_b . Set $M_2 = -M_1$. $B = \{Z_b < \infty\}$.

$$\text{Then: } P_{M_1} \circ Z_b < \infty = \bar{E}_2 e^{-2M_1 S_{Z_b}} I_{\{Z_b < \infty\}}$$

$$\leq e^{-2M_1 b} \text{ directly.}$$

ii) Consider $T = Z_a \wedge Z_b$. $B = \{S_T > b\}$. $M_2 = -M_1$.

$$\text{Then: } P_{M_1} \circ S_T > b = \bar{E}_{M_2} e^{-2M_1 S_T} I_{\{S_T > b\}}$$

$$= e^{-2M_1 b} \bar{E}_{M_2} e^{-2M_1 R_b} I_{\{S_T > b\}}$$

$R_b = S_{Z_b} - b$. $e^{-2M_1 b}$ is small which will influence accuracy if we want to simulate S_T .

(3) Brownian Motion:

Def: $\mathcal{F}_2 = \sigma Y \mid Y I_{\{Z \leq t\}} \in \mathcal{F}_t \cdot \forall t \geq 0$.

$\mathcal{F}_t = \sigma Y \mid Y = h \ll W_s \mid s \leq t$, for process $(W_t)_{t \geq 0}$.

For $\sigma = t_0 < t_1 < \dots < t_n = t$. if $W_t \sim N(M_i(t), t)$, $i=1,2$.

$$P_{M_1} \circ W(t_i) \in \Lambda_{W_i}, \quad (1 \leq i \leq n) / P_{M_2} \circ W(t_i) \in \Lambda_{W_i}, \quad (1 \leq i \leq n)$$

$$= \exp(-\frac{1}{2} \sum_{i=1}^n \frac{1}{t_i - t_{i-1}} (W_i - W_{i-1} - M_i(t_i - t_{i-1}))^2) / \bar{E}_{M_2} = e^{(M_1 - M_2)W_t - \frac{t}{2}(M_1^2 - M_2^2)}$$

To obtain L_t . Set $n \rightarrow \infty$ to approxi. by finite set

$$\Rightarrow L_t = \exp((M_1 - M_2)W(t) - \frac{t}{2}(M_1^2 - M_2^2))$$

prop. $Y \geq 0$. $Y \in \mathcal{F}_2$. $E_{M_1} \circ Y I_{\{Z \leq t\}} = \bar{E}_{M_2} \circ Y L_t I_{\{Z \leq t\}}$

Pf. Set $Z_n = \lfloor 2^n z \rfloor + 1 / 2^n$. Obtain equation

L_t $n \rightarrow \infty$ by MCT. ($Y \geq 0$)

i) For $b > 0$, $m > 0$, $M_1 = -m = -M_2$. If $Y \in \mathcal{I}_{Z_b}$.

$$E_{-m}^c(Y|_{\mathcal{I}_{Z_b \leftarrow \rightarrow}}) = E_m^c(Y e^{-2mV(Z_b)})|_{\mathcal{I}_{Z_b \leftarrow \rightarrow}},$$

$$= e^{-2mb} E_m^c(Y|_{\mathcal{I}_{Z_b \leftarrow \rightarrow}})$$

$$\text{By } P_m^c(Z_b \leftarrow \rightarrow) = 1 \quad (m > 0), \quad RNS = e^{-2mb} E_m^c(Y).$$

$$\Rightarrow E_{-m}^c(Y|_{Z_b \leftarrow \rightarrow}) = E_{-m}^c(Y|_{\mathcal{I}_0}) / P_m^c(Z_b \leftarrow \rightarrow) = E_m^c(Y)$$

$$\text{Set } Y = \{Z_b \leq t\}. \quad \text{So: } P_{-m}^c(Z_b \leq t | Z_b \leftarrow \rightarrow) = P_m^c(Z_b \leq t)$$

i.e. drift $-m$ of $Z_b | Z_b \leftarrow \rightarrow \sim$ drift m of Z_b

ii) From i). and reflection principle. We have:

$$P_{-m}^c(Z_b \leq t) = 1 - \phi\left(\frac{b+mt}{\sqrt{t}}\right) + e^{-2mb} \phi\left(\frac{-b+mt}{\sqrt{t}}\right). \quad \text{It's}$$

called inverse Gaussian dist. ($W_t \stackrel{P_{-m}}{\sim} N(-mt, t)$)

$$LHS = P_{-m}^c(Z_b \leq t, W_t \geq b) + P_{-m}^c(Z_b \leq t, W_t \leq b)$$

$$1') P_{-m}^c(Z_b \leq t, W_t \geq b) = P_{-m}^c(W_t \geq b) = 1 - \phi\left(\frac{b+mt}{\sqrt{t}}\right)$$

$$2') P_{-m}^c(Z_b \leq t, W_t \leq b) = \int_0^t P_{-m}^c(W_t \leq b | Z_b = s) P_{-m}^c(Z_b \leq t | s)$$

$$P_{-m}^c(W_t \leq b | Z_b = s) \stackrel{AP}{=} P_{-m}^c(W_t \leq b | W_s = b)$$

$$= P(N(-m(t-s), t-s) \leq 0)$$

$$= P(N(m(t-s), t-s) \geq 0)$$

$$\stackrel{AP}{=} P_m^c(W_t \geq b | Z_b = s)$$

$$\text{Combined with: } P_{-m}^c(Z_b \leq t | s) = e^{-2mb} P_m^c(Z_b \leq t | s)$$

follows from i).