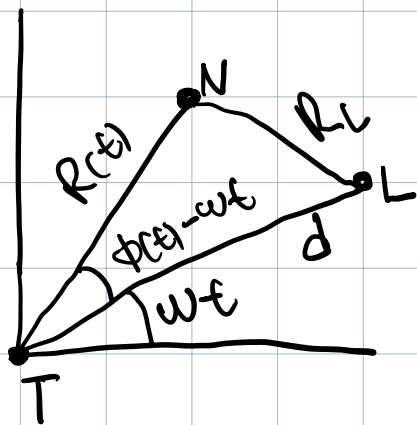


Metodos Computacionales II: Cohete Lunar



Por el teorema del coseno:

$$a^2 = b^2 + c^2 - 2bc \cos A$$

$$a = R_L \quad b = R(t) \quad c = d \quad A = \phi(t) - \omega t$$

$$\therefore R_L^2 = R(t)^2 + d^2 - 2R(t)d \cos(\phi(t) - \omega t)$$

$$\Rightarrow R_L = \sqrt{R(t)^2 + d^2 - 2R(t)d \cos(\phi(t) - \omega t)}$$

$$L = K - V \quad K = \frac{1}{2} m v^2 = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2)$$

$$x(t) = r(t) \cos(\phi(t)) \quad \dot{x}(t) = \dot{r} \cos \phi - r \sin \phi \cdot \dot{\phi}$$

$$y(t) = r(t) \sin(\phi(t)) \quad \dot{y}(t) = \dot{r} \sin \phi + r \cos \phi \cdot \dot{\phi}$$

$$\begin{aligned} \dot{x}^2(t) + \dot{y}^2(t) &= \dot{r}^2 \sin^2 \phi + r^2 \cos^2 \phi \dot{\phi}^2 + 2\dot{r} \sin \phi r \cos \phi \dot{\phi} \\ &+ \dot{r}^2 \cos^2 \phi + r^2 \sin^2 \phi \dot{\phi}^2 - 2\dot{r} \cos \phi r \sin \phi \dot{\phi} \\ &= \dot{r}^2 \sin^2 \phi + r^2 \cos^2 \phi \dot{\phi}^2 + \dot{r}^2 \cos^2 \phi + r^2 \sin^2 \phi \dot{\phi}^2 \\ &= \dot{r}^2 + r^2 \dot{\phi}^2 \end{aligned}$$

$$\therefore K = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\phi}^2)$$

$$V = U_T + U_L = -G \frac{m M_T}{r} - G \frac{m M_L}{r_L}$$

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\phi}^2) + G m \left(\frac{M_T}{r} + \frac{M_L}{r_L} \right)$$

$$H = p_r \dot{r} + p_\phi \dot{\phi} - L \quad p_r = \frac{\partial L}{\partial \dot{r}} = m \dot{r} \quad p_\phi = \frac{\partial L}{\partial \dot{\phi}} = m r^2 \dot{\phi}$$

$$\Rightarrow H = \frac{p_r^2}{m} + \frac{p_\phi^2}{m r^2} - L$$

$$H = \frac{p_r^2}{m} + \frac{p_\phi^2}{m r^2} - \frac{m \dot{r}^2}{2} - \frac{m r^2 \dot{\phi}^2}{2} - G \frac{m M_T}{r} - G \frac{m M_L}{r_L}$$

$$H = \frac{p_r^2}{m} + \frac{p_\phi^2}{m r^2} - \frac{p_r \dot{r}}{2} - \frac{p_\phi \dot{\phi}}{2} - G m \left(\frac{M_T}{r} + \frac{M_L}{r_L} \right)$$

$$H = \frac{p_r^2}{m} + \frac{p_\phi^2}{m r^2} - \frac{p_r^2}{2m} - \frac{p_\phi^2}{2m r^2} - G m \left(\frac{M_T}{r} + \frac{M_L}{r_L} \right)$$

$$H = \frac{p_r^2}{2m} + \frac{p_\phi^2}{2m r^2} - G \frac{m M_T}{r} - G \frac{m M_L}{r_L}$$

$$\dot{r} = \frac{\partial H}{\partial p_r} = \frac{p_r}{m}$$

$$\dot{\phi} = \frac{\partial H}{\partial p_\phi} = \frac{p_\phi}{m r^2}$$

$$\dot{p}_r = -\frac{\partial H}{\partial r} = -\left(-\frac{p_\phi^2}{mr^3} + G\frac{mM_T}{r^2} + G\frac{mM_L}{r_L^2} \cdot \frac{\partial r_L}{\partial r}\right)$$

$$\frac{\partial r_L}{\partial r} = \frac{r - d \cos(\phi - \omega t)}{r_L}$$

$$\dot{p}_r = \frac{p_\phi^2}{mr^3} - G\frac{mM_T}{r^2} - G\frac{mM_L}{r_L^3} (r - \cos(\phi - \omega t))$$

$$\dot{p}_\phi = -\frac{\partial H}{\partial \phi} = G\frac{mM_L}{r_L^2} \cdot \frac{\partial r_L}{\partial \phi}$$

$$\frac{\partial r_L}{\partial \phi} = \frac{-r d \sin(\phi - \omega t)}{r_L}$$

$$\Rightarrow \dot{p}_\phi = -\frac{G m M_L r d \sin(\phi - \omega t)}{r_L^3}$$

$$\tilde{r} = \frac{r}{d} \quad \tilde{p}_r = \frac{p_r}{m d} \quad \tilde{p}_\phi = \frac{p_\phi}{m d^2} \quad \mathcal{U} = \frac{M_L}{M_T} \quad \Delta = G \frac{M_T}{d^3}$$

$$\frac{\dot{r}}{d} = \frac{p_r}{m d} \Rightarrow \underline{\dot{\tilde{r}} = \tilde{p}_r}$$

$$\dot{\phi} = \frac{p_\phi}{m r^2} = \frac{p_\phi}{m d^2 \frac{r^2}{d^2}} \Rightarrow \underline{\dot{\phi} = \frac{\tilde{p}_\phi}{\tilde{r}^2}}$$

$$\frac{\dot{p}_r}{m d} = \frac{p_\phi^2}{m^2 d r^3} - \frac{G M}{m d} \left(\frac{M_T}{r^2} + \frac{M_L}{r_L^3} (r - \cos(\phi - \omega t)) \right)$$

$$\dot{p}_r = \frac{\tilde{p}_\phi^2}{\tilde{r}^3} - \frac{G M_T}{d} \left(\frac{1}{\tilde{r}^2 d^2} + \frac{\mu}{r_L^3} (r - \cos(\phi - \omega t)) \right)$$

$$\dot{p}_r = \frac{\tilde{p}_\phi^2}{\tilde{r}^3} - \Delta \left(\frac{1}{\tilde{r}^2} + \frac{\mu d^2}{r_L^3} (r - \cos(\phi - \omega t)) \right)$$

$$\dot{p}_r = \frac{\tilde{p}_\phi^2}{\tilde{r}^3} - \Delta \left(\frac{1}{\tilde{r}^2} + \frac{\mu}{\tilde{r}^3} (\tilde{r} - \cos(\phi - \omega t)) \right)$$

$$\dot{p}_\phi = \frac{-G M M_L r d \sin(\phi - \omega t)}{r_L^3}$$

$$\frac{\dot{p}_\phi}{m d^2} = \frac{-G M_L r \sin(\phi - \omega t)}{d r_L^3}$$

$$\dot{p}_\phi = \frac{-G M_T M_L \tilde{r} \sin(\phi - \omega t) d^3}{M_T r_L^3 d^3}$$

$$\dot{p}_\phi = - \frac{\Delta \mu \tilde{r}}{\tilde{r}^3} \sin(\phi - \omega t)$$
