# Gustavo Moran Diaz

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## **EDUCATION**

## Stevens Institute of Technology

August 2021 – May 2025 (Expected)

Bachelor of Engineering in Electrical Engineering, Minor in Pure & Applied Mathematics

Hoboken, NJ

Cumulative GPA: 3.94

Dean's List: Aug. 2021 - May 2023

## EXPERIENCE

## **Automation Engineer Intern**

June 2023 - August 2023

GlobalFoundries - Automated Materials Handling System Department

Malta, NY

- Developed a system to remotely backup hard drives on critical lithography automation equipment responsible for transporting silicon wafers using FTP servers
- Developed a written procedure for creating hard drive backups and simplifying system architecture
- Demonstrated effectiveness of procedure through testing, downtime during emergency events reduced from hours to less than 15 minutes
- Collaborated with multiple departments in order to schedule tests on wafer handling systems
- Queried overhead track error database using SQL in order to locate potential faults in the track

## Electrical and Computer Engineering Lab Monitor

Sep. 2021 - Present

Stevens Institute of Technology

Hoboken, NJ

- Work with professors, teacher's assistants and professors providing assistance upon request
- Maintain upkeep of computers and lab equipment including multimeters, oscilloscopes, and 3D printers
- Helped students with lab assignments in Microprocessor Systems class with AVR assembly, x86
  Intel assembly, and C++

## Projects

## Interactive Spotify Button | Python, AVR, Spotify API, Git

January 2023

- Developed an interactive button for Spotify powered by an AVR Microcontroller and a Python script
- Used the Spotify API to add currently playing songs into user's "Liked Songs" playlist upon use of the button
- Implemented feedback in the form of an LED light that indicates if the process was successful or if errors were encountered.
- Learned Git in order to document code that allows the button to function

## **Autonomous Robot** | C++, AVR, SolidWorks (CAD), IoT

January 2022 - May 2022

- Developed a robot with a group with the goal of traversing a small obstacle course to reach specified locations in order
- Used LiDAR technology in order to monitor location of robot with respect to the course
- Sent current location information to the robot using Wi-Fi in order to facilitate automatic course correction
- Wired robot under very tight size constraints
- Designed 3D printed enclosure in order to hold all components of the robot including an AVR microcontroller, motor controller, OLED screen, and ultrasonic sensors

## TECHNICAL SKILLS

Languages: C++, Python, SQL, x86 Assembly, HTML, JavaScript, CSS

Programs: Solidworks, Autodesk Suite, Matlab

Tools: 3D Printer, Oscilloscope, Multimeter, AVR Microcontrollers, ARM Microprocessors