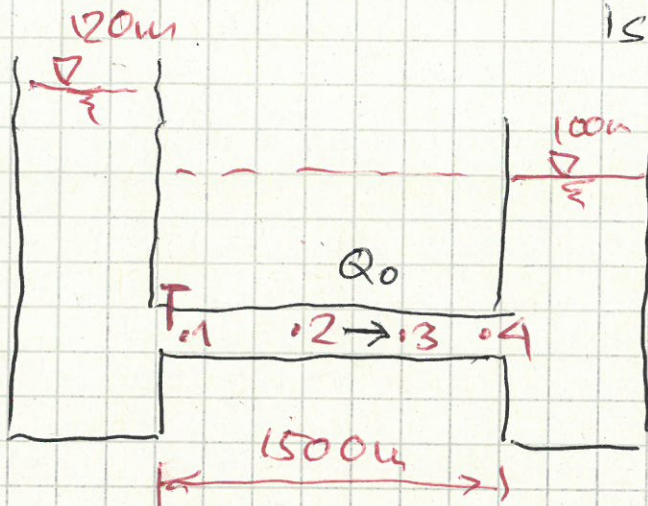


24-11-23

EXAMPLE PIPES - SIMILAR TO PIPE 2
EXCEPT THAT THE VALVE CLOSURE
IS GRADUAL



$$C = 1000 \text{ m/s}$$

$$g \approx 10 \text{ m/s}^2$$

$$A = 0.01 \text{ m}^2$$

$$A_{v0} = \frac{1}{4} A$$

$$C_Q = 0.125$$

$$Z_0 = \frac{C}{gA} = 10^4 \text{ s/m}^2$$

$$M_0 = \frac{1}{2g C_Q^2 A_{v0}^2} = 512000 \frac{\text{s}^2}{\text{m}^5}$$

IC - STEADY STATE

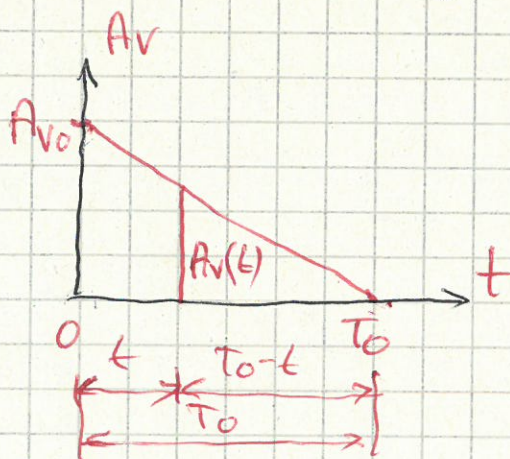
$$M_0 Q_0^2 = 120 \text{ m} - 100 \text{ m} = 20 \text{ m}$$

$$Q_0 = 6.25 \times 10^{-3} \text{ m}^3/\text{s}$$

L.B.C. GRADUAL VALVE CLOSURE DURING TIME T_0
 $T_0 = 3\text{s}; 6\text{s}$

• FOR $0 \leq t < T_0$

← IMPORTANT TO APPLY FOR
 $t < T_0$, NOT $t = T_0$



WE ASSUME THAT A_v
CHANGES LINEARLY WITH TIME.

$$\frac{A_v(t)}{A_{v0}} = \frac{T_0 - t}{T_0}$$

$$A_v(t) = A_{v0} \left(1 - \frac{t}{T_0} \right)$$

THE L.B.C. IS THE VALVE:

$$M^{n+1} Q_1^{n+1} |Q_1^{n+1}| = H_T - H_1 \quad (1)$$

COMBINING (1) WITH THE C⁻ BETWEEN (n,2) & (n+1,1)
 WE GET:

$$M^{n+1} Q_1^{n+1} |Q_1^{n+1}| + Z_0 Q_1^{n+1} = N^n \quad N^n = 120u - H_2^n + Z_0 Q_2^n$$

SOLUTION

$$Q_1^{n+1} = \frac{N^n}{g}$$

$$g = \frac{1}{2} \left[Z_0 + \sqrt{Z_0^2 + 4 M^{n+1} |N^n|} \right]$$

$$M^{n+1} = \frac{1}{2g Q^2 (A_V(t)^{n+1})^2}$$

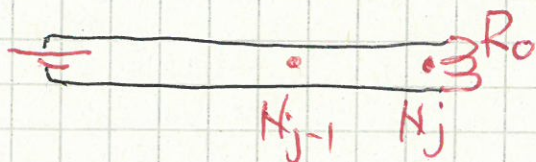
$$(1) \rightarrow H_1^{n+1} = H_T - M^{n+1} Q_1^{n+1} |Q_1^{n+1}|$$

• FOR $T_0 \leq t$ THE L.B.C $Q_1^{n+1} = 0$

FROM C⁻
 WE GET

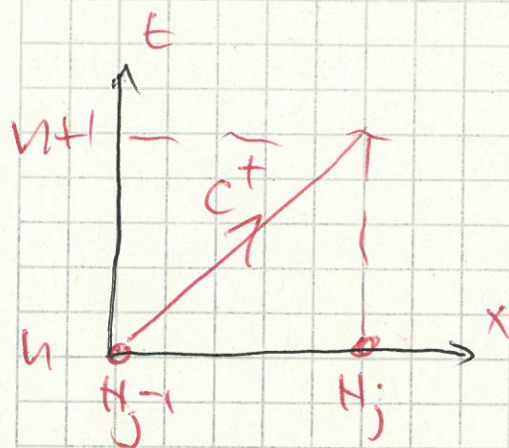
$$H_1^{n+1} = H_2^n - Z_0 Q_2^n$$

2.5.2 LINEAR BOUNDARY CONDITIONS



$V_{N_j} = R_0 I_{N_j}$
VALID AT ANY TIME SO:

$$V_{N_j}^{u+1} = R_0 I_{N_j}^{u+1}$$



$$c^+ dV + z_0 dI = 0$$

INTEGRATED BETWEEN (u, N_{j-1}) & $(u+1, N_j)$

$$V_{N_j}^{u+1} - V_{N_{j-1}}^u + z_0 (I_{N_j}^{u+1} - I_{N_{j-1}}^u) = 0$$

$$R_0 I_{N_j}^{u+1} - V_{N_{j-1}}^u + z_0 I_{N_j}^{u+1} - z_0 I_{N_{j-1}}^u = 0$$

$$I_{N_j}^{u+1} = I_{N_{j-1}}^u \frac{z_0}{z_0 + R_0} + V_{N_{j-1}}^u \frac{1}{z_0 + R_0}$$

$$V_{N_j}^{u+1} = R_0 I_{N_j}^{u+1}$$

2.6 LAX SCHEME FOR SYSTEMS OF TWO EQUATIONS

$$\frac{\partial p}{\partial t} + E \frac{\partial v}{\partial x} = 0 \quad (1)$$

$$\frac{\partial v}{\partial t} + \frac{1}{\rho} \frac{\partial p}{\partial x} = 0 \quad (2)$$

CHARACTERISTIC FORM:

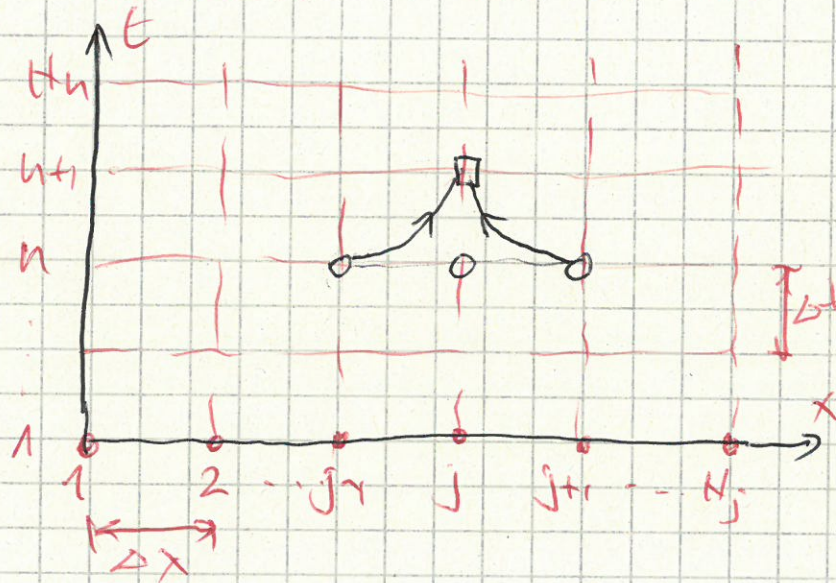
$$dp + z_0 dv = 0 \quad \text{ALONG} \quad \frac{dx}{dt} = c$$

$$dp - z_0 dv = 0 \quad \text{ALONG} \quad \frac{dx}{dt} = -c$$

$$z_0 = \sqrt{E\rho} \quad c = \sqrt{\frac{E}{\rho}}$$

CONTINUOUS FORM OF THE MATHEMATICAL MODEL

DISCRETE FORM OF THE SYSTEM (1), (2)



TO APPLY THE LAX SCHEME

$$\left(\frac{\partial p}{\partial t}\right)_j \approx \frac{1}{\Delta t} \left[P_j^{n+1} - \frac{1}{2}(P_{j-1}^n + P_{j+1}^n) \right]$$

$$\left(\frac{\partial p}{\partial x}\right)_j \approx \frac{1}{2\Delta x} (P_{j+1}^n - P_{j-1}^n)$$

APPROXIMATE EQUATIONS FOR $\frac{\partial v}{\partial t}$, $\frac{\partial v}{\partial x}$ ARE ANALOGOUS

MIDDLE POINTS

$$\frac{1}{\Delta t} \left[P_j^{n+1} - \frac{1}{2}(P_{j-1}^n + P_{j+1}^n) \right] + \frac{E}{2\Delta x} (V_{j+1}^n - V_{j-1}^n) = 0 \rightarrow P_j^{n+1}$$

$$\frac{1}{\Delta t} \left[V_j^{n+1} - \frac{1}{2}(V_{j-1}^n + V_{j+1}^n) \right] + \frac{1}{\rho 2\Delta x} (P_{j+1}^n - P_{j-1}^n) = 0 \rightarrow V_j^{n+1}$$

$$P_j^{n+1} = \frac{1}{2} (P_{j-1}^n + P_{j+1}^n) + \frac{E\Delta t}{2\Delta x} (V_{j-1}^n - V_{j+1}^n)$$

$$V_j^{n+1} = \frac{1}{2} (V_{j-1}^n + V_{j+1}^n) + \frac{\Delta t}{2\rho\Delta x} (P_{j+1}^n - P_{j-1}^n)$$

$$\frac{E \Delta t}{\Delta x} \frac{c}{c} = E C_r \frac{\sqrt{\rho}}{\sqrt{E}} = C_r \sqrt{E \rho} = Z_0 C_r$$

$$\frac{c \Delta t}{\rho \Delta x} \frac{c}{c} = \frac{1}{\rho} C_r \frac{\sqrt{\rho}}{\sqrt{E}} = \frac{C_r}{\sqrt{E \rho}} = \frac{C_r}{Z_0}$$

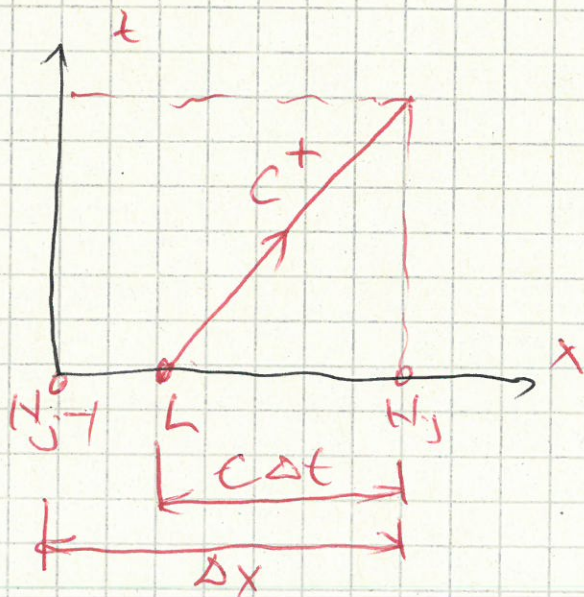
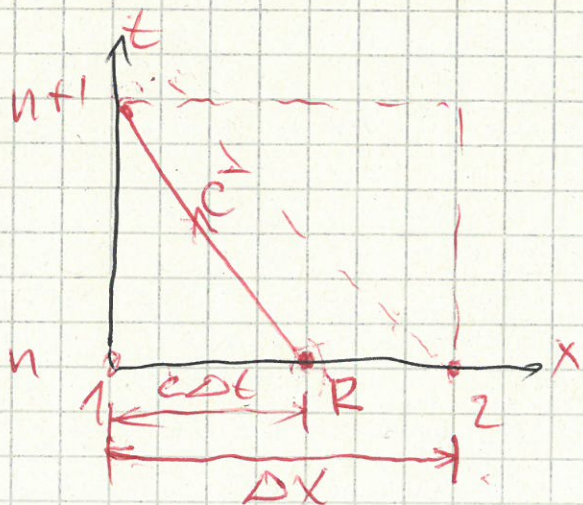
$$P_j^{n+1} = \frac{1}{2} (P_{j-1}^n + P_{j+1}^n) + \frac{C_r Z_0}{2} (V_{j-1}^n - V_{j+1}^n)$$

$$V_j^{n+1} = \frac{1}{2} (V_{j-1}^n + V_{j+1}^n) + \frac{C_r}{2 Z_0} (P_{j-1}^n - P_{j+1}^n)$$

FOR $C_r = 1$ THE LAX SCHEME GIVES THE SAME DISCRETISED EQUATIONS AS THE MOC

$C_r \leq 1$ HAS TO BE SATISFIED FOR STABILITY

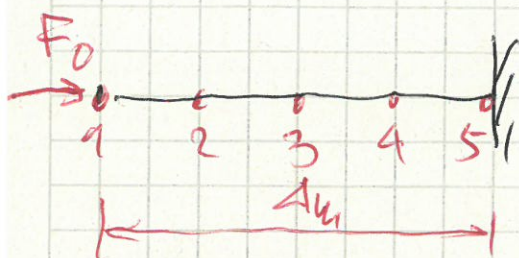
FOR BOUNDARY CONDITIONS IT IS STILL BETTER TO USE THE MOC



$$C_r = \frac{c \Delta t}{\Delta x}$$

$$\Delta x^c = c \Delta t$$

EXAMPLE ROD 2 - SAME AS ROD 1 EXCEPT THAT WE USE THE LAX SCHEME
 $C_r = 0.8$



$$\Delta x = 1 \text{ m}$$

$$C_r = 0.8$$

$$E = 200 \text{ GPa}$$

$$\rho = 8000 \text{ kg/m}^3$$

$$A = 10^{-3} \text{ m}^2$$

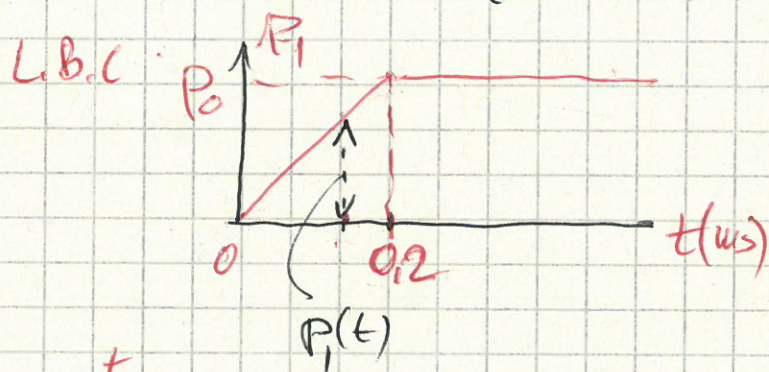
$$c = \sqrt{\frac{E}{\rho}} = 5000 \frac{\text{m}}{\text{s}}$$

$$Z_0 = \sqrt{E\rho} = 40 \frac{\text{MPa}}{\text{s}}$$

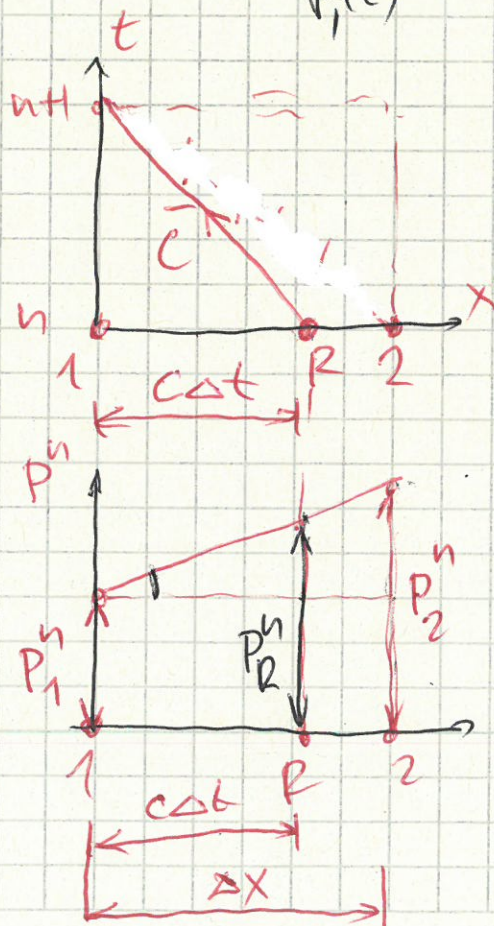
$$P_0 = \frac{F_0}{A_0} = 1 \text{ MPa}$$

$$\frac{c\Delta t}{\Delta x} = 0.8 \rightarrow$$

$$\Delta t = 0.16 \text{ ms}$$



$$P = \begin{cases} t \leq 0.2 \text{ ms} & P_1(t) = P_0 \frac{t}{0.2} \\ t > 0.2 \text{ ms} & P_1 = P_0 \end{cases}$$



$$c: dp - Z_0 dV = 0$$

INTEGRATED BETWEEN (n, R) & $(n+1, 1)$

$$P_1^{n+1} - P_R^n - Z_0 (V_1^{n+1} - V_R^n) = 0$$

$$P_1^{n+1} - P_R^n - Z_0 V_1^{n+1} + Z_0 V_R^n = 0$$

$$V_1^{n+1} = V_R^n + \frac{1}{Z_0} (P_1^{n+1} - P_R^n)$$

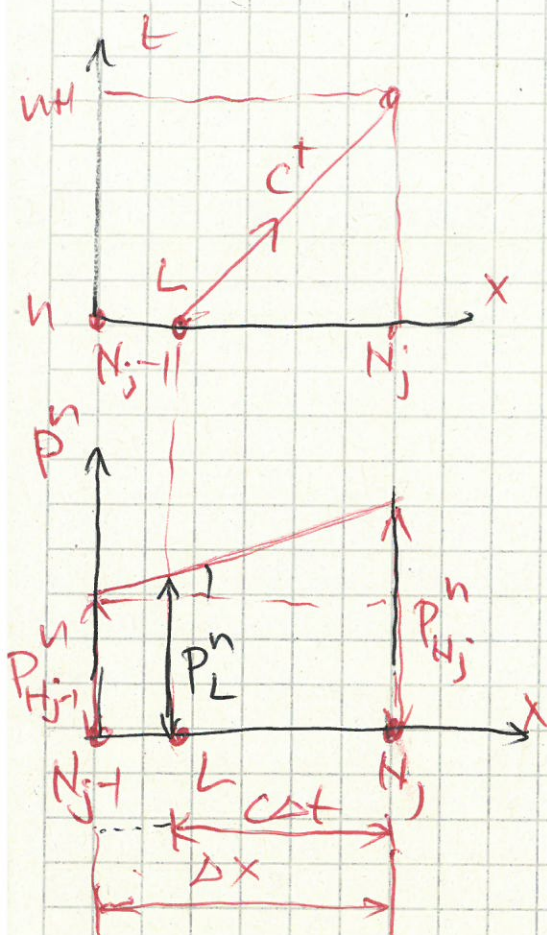
WE FIND P_R^n BY INTERPOLATION

$$P_R^n = P_1^n + \frac{P_2^n - P_1^n}{\Delta x} c\Delta t \quad C_r$$

$$P_R^n = P_1^n + C_r (P_2^n - P_1^n)$$

$$P_R^n = P_1^n (1 - C_r) + P_2^n C_r$$

RIGHT BC



$$c^t: dp + z_0 dV = 0$$

INTEGRATED BETWEEN (n, L) & $(n+1, N_j)$

$$P_{N_j}^{n+1} - P_L^n + z_0 (V_{N_j}^{n+1} - V_L^n) = 0$$

$\underbrace{V_{N_j}^{n+1}}_{=0}$

$$P_{N_j}^{n+1} = P_L^n + z_0 V_L^n$$

$$P_L^n = P_{N_{j-1}}^n + \frac{P_{N_j}^n - P_{N_{j-1}}^n}{\Delta x} (\Delta x - c \Delta t)$$

$$P_L^n = P_{N_{j-1}}^n + (P_{N_j}^n - P_{N_{j-1}}^n) (1 - Cr)$$

$$P_L^n = \cancel{P_{N_{j-1}}^n} + P_{N_j}^n - \cancel{P_{N_{j-1}}^n} - Cr P_{N_j}^n + Cr P_{N_{j-1}}^n$$

$$P_L^n = P_{N_j}^n (1 - Cr) + P_{N_{j-1}}^n Cr$$

$$V_L^n = V_{N_j}^n (1 - Cr) + V_{N_{j-1}}^n Cr$$

RESULTS

$x(m)$ j	0 1	0.8 R	1 2	2 3	3 4	3.2 L	4 5			
t (ms)	P MPa	V $\frac{mm}{s}$	P MPa	V $\frac{mm}{s}$	P MPa	V $\frac{mm}{s}$	P MPa	V $\frac{mm}{s}$	P MPa	V $\frac{mm}{s}$
0	0	0	0	0	0	0	0	0	0	0
0.16	0.8	20	0.16	4.0	0	0	0	0	0	0
0.32	1.0	25	0.77	19.4	0.72	18	0	0	0	0
0.48	1.0	25	0.92	23.0	0.90	22.5	0.65	16.2	0	0
0.60	1.0	25	0.97	24.3	0.96	24.1	0.81	20.2	0.58	14.6
0.72	1.0	25	0.98	24.6	0.98	24.5	0.93	23.2	0.73	18.2
0.80	1.0	25	0.99	24.9	0.99	24.8	0.96	23.9	1.30	11.5

↑
LBC

↑
RBC