Additional Experiments for Paper 5433

In this report we present the additional experiments for DSPL/DSEPL on robust nonlinear regression problem with larger size. We also kindly remind the reviewer of our additional experiments on blind deconvolution problem, which is available in the appendix section ${\bf C}$.

Given sample data $\{a_i \in \mathbb{R}^n\}_{i=1,\ldots,m}$ and corresponding observations $\{y_i\}_{i=1,\ldots,m}$, the robust nonlinear regression problem aims to fit y_i using nonlinear model $y = f(\langle a, x \rangle)$ by solving

$$\min_{x \in \mathbb{R}^n} \frac{1}{m} \sum_{i=1}^m |f(\langle a_i, x \rangle) - b_i|,$$

where f is a given nonlinear function. When $f(x) = x^2$, we get the robust phase retrieval problem. We report the performance in asynchronous environment.

Experiment setup

- 1) **Dataset.** We take m = 7500, n = 2500 in the experiment. Given some nonlinear function f, we generate sample data $A \in \mathbb{R}^{m \times n}$, true signal x^* as in phase retrieval and let $y_i = f(a^\top x)$.
- **2) Initial point.** We generate $x' \sim \mathcal{N}(0, I_n)$ and start from $x^0 = x^1 = \frac{x'}{\|x'\|}$.
- 3) Stepsize. We tune the stepsize parameter setting $\gamma = \sqrt{K/\alpha}$, $\alpha \in \{0.1, 0.5, 1.0\}$ for asynchronous environment and $\alpha \in [10^0, 10^1]$ for the simulated experiment.
- 4) Nonlinear function. We choose functions $f \in \{f_1 = 2x + \cos x, f_2 = 10 + e^x, f_3 = x^3 + x^2, f_4 = x^2\}$ to characterize the nonlinear relation. Note that f_4 corresponds to larger phase retrieval data.
- **5) Others.** The rest of the setup is consistent with phase retrieval.

Asynchronous environment

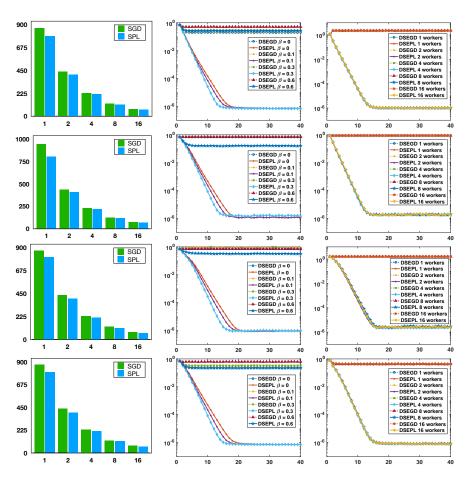


Figure 1. From the first row to the last: $f_1 = 2x + \cos x$, $f_2 = 10 + e^x$, $f_3 = x^3 + x^2$, $f_4 = x^2$. In each row, the first figure indicates speedup as the number of workers increases; the second plots $||x^k - x^*||$ for $\alpha = 0.5$ and different β ; the last plots $f(x^k) - f^*$ for $\alpha = 0.5$, $\beta = 0.3$ (f_4 uses $\alpha = 0.1$).

Simulated delay

Table 1. Experiments of simulated delay for the robust nonlinear regression problem using $f_2 = 10 + e^x$, $\kappa = 10$, $p_{\text{fail}} = 0.2$. Two figures on the left: the number of iterations with different stepsize α and $\beta = 0.3$, $\tau \in \{216, 360\}$; Two figures on the right: the number of iterations with different $\tau \in [1, 1000]$ and $\beta = 0.3$, $\alpha \in \{3.60, 4.65\}$.