

# Generic Notes

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## 1 Introduction to the propagator

Consider the classical mechanics problem of two blocks of mass  $m$  in a well coupled by springs to the walls and a spring between them (three springs in total). Denoting  $x_1$  and  $x_2$  as the displacement of each block from the equilibrium position, (note there is a unique equilibrium configuration of the masses, since we can set up two equations with two unknowns and solve them) Hooke's law implies that

$$\begin{aligned}\ddot{x}_1 &= -2\frac{k}{m}x_1 + \frac{k}{m}x_2 \\ \ddot{x}_2 &= \frac{k}{m}x_1 - 2\frac{k}{m}x_2\end{aligned}$$

Written in matrix form, this is

$$\begin{bmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{bmatrix} = \begin{bmatrix} \Omega_{11} & \Omega_{12} \\ \Omega_{21} & \Omega_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \begin{aligned} \Omega_{11} &= -\frac{2k}{m} & \Omega_{12} &= \frac{k}{m} \\ \Omega_{21} &= \frac{k}{m} & \Omega_{22} &= -\frac{2k}{m} \end{aligned}$$

From which it is apparent that the matrix  $\Omega$  is hermitian. This can be represented in a more abstract form as

$$|\ddot{x}(t)\rangle = \Omega |x(t)\rangle$$

In this representation, the equivalent of  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  is  $|1\rangle$ , representing displacement of the first mass from its equilibrium position and the equivalent of  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$  is  $|2\rangle$ , representing displacement of the second mass from its equilibrium position. Therefore

$$|x(t)\rangle = x_1 |1\rangle + x_2 |2\rangle$$

The abstract vector equation can be put into a form that more closely relates to the original matrix equation by projecting onto  $|1\rangle$  and  $|2\rangle$ , and using the completeness relation  $|1\rangle\langle 1| + |2\rangle\langle 2| = I$ :

$$\begin{aligned}\ddot{x}_1 &= \langle 1|\ddot{x}(t)\rangle = \langle 1|\Omega(|1\rangle\langle 1| + |2\rangle\langle 2|)|x(t)\rangle = \langle 1|\Omega|1\rangle\langle 1|x(t)\rangle + \langle 1|\Omega|2\rangle\langle 2|x(t)\rangle = \Omega_{11}x_1 + \Omega_{12}x_2 \\ \ddot{x}_2 &= \langle 2|\ddot{x}(t)\rangle = \langle 2|\Omega(|1\rangle\langle 1| + |2\rangle\langle 2|)|x(t)\rangle = \langle 2|\Omega|1\rangle\langle 1|x(t)\rangle + \langle 2|\Omega|2\rangle\langle 2|x(t)\rangle = \Omega_{21}x_1 + \Omega_{22}x_2\end{aligned}$$

To be continued.

## 2 Green's Function, Equation of Motion

The Schrödinger picture considers the wavefunction time-dependent and the operator time-independent. On the other hand, the Heisenberg picture considers the wavefunction time-independent and the operator time-dependent. These viewpoints are mathematically equivalent, because the Heisenberg time-dependent operator  $\hat{o}_{\mathcal{H}}$  is defined in terms of the Schrödinger time independent operator  $\hat{o}_{\mathcal{S}}$  as

$$\hat{o}_{\mathcal{H}} = e^{i\hat{H}t}\hat{o}_{\mathcal{S}}e^{-i\hat{H}t}$$

so that the evolution of the expectation of an operator remains the same, as seen in

$$\langle \Psi(t)|\hat{o}_{\mathcal{S}}|\Psi(t)\rangle = \langle e^{-i\hat{H}t}\psi_0|\hat{o}_{\mathcal{S}}|e^{-i\hat{H}t}\psi_0\rangle = \langle \psi_0|e^{i\hat{H}t}\hat{o}_{\mathcal{S}}e^{-i\hat{H}t}|\psi_0\rangle = \langle \psi_0|\hat{o}_{\mathcal{H}}|\psi_0\rangle$$

Heisenberg's equation can be derived using the chain rule as follows:

$$\frac{\partial \hat{o}_{\mathcal{H}}}{\partial t} = (i\hat{H})e^{i\hat{H}t}\hat{o}_{\mathcal{S}}e^{-i\hat{H}t} + e^{i\hat{H}t}\hat{o}_{\mathcal{S}}e^{-i\hat{H}t}(-i\hat{H}) = i[\hat{H}, \hat{o}_{\mathcal{H}}]$$

This equation may appear without the factor of  $i$  attached to the commutator when working with imaginary time. A useful property is that

$$[\hat{a}_{\mathcal{H}}, \hat{b}_{\mathcal{H}}] = [\hat{a}_{\mathcal{S}}, \hat{b}_{\mathcal{S}}]_{\mathcal{H}}$$

Similarly

$$\{\hat{a}_{\mathcal{H}}, \hat{b}_{\mathcal{H}}\} = \{\hat{a}_{\mathcal{S}}, \hat{b}_{\mathcal{S}}\}_{\mathcal{H}}$$

The Green's function can be approached using the framework of equation of motion. As a reminder, the Green's function was

$$G(\tau, \tau') = -\frac{1}{z} \text{Tr} [e^{-\beta\hat{H}} T_{\tau} C(\tau) C^{\dagger}(\tau')] = -\langle T_{\tau} C(\tau) C^{\dagger}(\tau') \rangle \quad \langle \hat{o} \rangle := \frac{1}{z} \text{Tr} e^{-\beta\hat{H}} \hat{o}$$

For now, as a notation that may come in handy in the future, let the subscripts  $ij$  in  $G_{ij}(\tau, \tau')$  denote subscripts of the  $C(\tau)$  and  $C^{\dagger}(\tau')$  respectively. Also, for the purpose of taking a derivative, it's helpful to rewrite the function as

$$G_{ij}(\tau, \tau') = -\theta(\tau - \tau') \langle C(\tau) C^{\dagger}(\tau') \rangle + \theta(\tau' - \tau) \langle C^{\dagger}(\tau') C(\tau) \rangle$$

Since the derivative of the heaviside function is the delta function. Then (using time-translational invariance and an implicit 0 for the second argument of Green's function)

$$\begin{aligned} \frac{\partial G_{ij}(\tau)}{\partial \tau} &= -\delta(\tau) \langle C_i(\tau) C_j^{\dagger}(0) + C_j^{\dagger}(0) C_i(\tau) \rangle - \theta(\tau) \langle [\hat{H}, C_i(\tau)] C_j^{\dagger}(0) \rangle + \theta(-\tau) \langle C_j^{\dagger}(0), [\hat{H}, C_i(\tau)] \rangle \\ &= -\delta(\tau) \delta_{ij} - \theta(\tau) \langle \mu C_i(\tau) C_j^{\dagger}(0) \rangle + \theta(-\tau) \langle C_j^{\dagger}(0), \mu C_i(\tau) \rangle \\ &= -\delta(\tau) \delta_{ij} + \mu G_{ij}(\tau) \end{aligned}$$

Rearranging this:

$$\implies (\mu - \frac{\partial}{\partial \tau}) G_{ij} = \delta(\tau) \delta_{ij}$$

If the right side is interpreted to be “unity,” then one might interpret the left side as “ $G^{-1}G$ ”. Now, what happens when the Hamiltonian is switched from  $-\mu c_{\uparrow}^{\dagger} c$  to, say,

$$-\mu(c_{\uparrow}^{\dagger} c_{\uparrow} + c_{\downarrow}^{\dagger} c_{\downarrow}) + U \hat{n}_{\uparrow} \hat{n}_{\downarrow}$$

The only thing that changes in the above derivation is  $[\hat{H}, C(\tau)]$ . Recalling some commutator algebra with creation/annihilation operators:

$$\begin{aligned} [\hat{n}_{i\sigma}, c_{j\sigma'}] &= c_{i\sigma}^{\dagger} \{c_{i\sigma}, c_{j\sigma'}\} - \{c_{i\sigma}^{\dagger}, c_{j\sigma}\} c_{i\sigma} \\ &= -\delta_{ij} \delta_{\sigma\sigma'} c_{i\sigma} \\ [\hat{n}_{i\uparrow} \hat{n}_{i\downarrow}, c_{j\sigma}] &= \hat{n}_{i\uparrow} [\hat{n}_{i\downarrow}, c_{j\sigma}] + [\hat{n}_{i\uparrow}, c_{j\sigma}] \hat{n}_{i\downarrow} \\ &= -\delta_{ij} (\delta_{\sigma\downarrow} \hat{n}_{i\uparrow} c_{i\downarrow} + \delta_{\sigma\uparrow} \hat{n}_{i\downarrow} c_{i\uparrow}) \end{aligned}$$

Therefore, the final equation of motion doesn't change much. Concluding the derivation

$$\begin{aligned} \frac{\partial G_{\sigma\sigma'}}{\partial \tau} &= -\delta(\tau) - \theta(\tau) \langle [\hat{H}, C_{\sigma}(\tau)] C_{\sigma'}^{\dagger}(0) \rangle + \theta(-\tau) \langle C_{\sigma'}^{\dagger}(0), [\hat{H}, C_{\sigma}(\tau)] \rangle \\ &= -\delta(\tau) - \theta(\tau) \langle (\mu C_{\sigma}(\tau) - U \hat{N}_{\bar{\sigma}} C_{\sigma}(\tau)) C_{\sigma'}^{\dagger}(0) \rangle + \theta(\tau) \langle C_{\sigma'}^{\dagger}(0) (\mu C_{\sigma}(\tau) - U \hat{N}_{\bar{\sigma}} C_{\sigma}(\tau)) \rangle \\ &= -\delta(\tau) + \mu G_{\sigma\sigma'} + U \theta(\tau) \langle \hat{N}_{\bar{\sigma}} C_{\sigma}(\tau) C_{\sigma'}^{\dagger}(0) \rangle - U \theta(\tau) \langle C_{\sigma'}^{\dagger}(0) \hat{N}_{\bar{\sigma}} C_{\sigma}(\tau) \rangle \\ &= -\delta(\tau) + (\mu - U \hat{N}_{\bar{\sigma}}) G_{\sigma\sigma'} \end{aligned}$$

$\hat{N}$  is the number operator so it can be moved out of the expectation freely (? prove this later). Therefore the obtained equation of motion is

$$(\mu - U \hat{N}_{\bar{\sigma}} - \frac{\partial}{\partial \tau}) G_{\sigma\sigma'} = \delta(\tau)$$

## 2.1 Action

What if you introduce a disturbance to your system over a period of time? Say the hamiltonian is

$$\hat{H} = -\mu c^\dagger c$$

and the disturbance is modeled by

$$S(U) = e^{-i \int \theta(t) \theta(t_0-t) U c^\dagger(t) c(t) dt} = e^{-i \int_0^{t_0} U c^\dagger(t) c(t) dt}$$

which changes the Green's function (this one is the real time version) to

$$G(t, t') = -i \langle T_t C(t) C^\dagger(t') S(U) \rangle$$

The presence of the  $S(U)$  modifies the value of the normalization constant  $z$  (so that  $S(U)$  really defines a new expectation) to

$$\begin{aligned} z(u) &= \text{Tr} [e^{-i \int_0^{t_0} U c^\dagger c dt} e^{\mu \beta c^\dagger c}] \\ &= 1 + e^{\mu \beta} e^{-i \int_0^{t_0} U dt} \\ &= 1 + e^{\mu \beta - i U t_0} \end{aligned}$$

Now let's compute this Green's function for a specific order of  $0, t_0, t, t'$ . There are essentially 12 orders. The order we will compute Green's function for is  $t < 0 < t' < t_0$ . The first step is to find an expression for  $C(t) = e^{i\hat{H}t} c e^{-i\hat{H}t}$  and one for  $C^\dagger(t') = e^{i\hat{H}t'} c^\dagger e^{-i\hat{H}t'}$ . Using Heisenberg's equation:

$$\begin{aligned} \frac{\partial C(t)}{\partial t} &= i[-\mu c^\dagger c, C(t)] \\ &= i\mu C(t) \\ \Rightarrow C(t) &= e^{i\mu t} c \\ \frac{\partial C^\dagger(t')}{\partial t'} &= i[-\mu c^\dagger c, C^\dagger(t')] \\ &= -i\mu C^\dagger(t') \\ \Rightarrow C^\dagger(t') &= e^{-i\mu t'} c^\dagger \end{aligned}$$

Evaluating Green's function supposing  $t < 0 < t' < t_0$ :

$$\begin{aligned} G(t, t') &= -i \theta(t' > t_{int} > t) \langle C^\dagger(t') e^{-i \int_0^{t'} U c^\dagger c dt} C(t) \rangle + i \theta(t_{int} > t' > t) \langle e^{-i \int_{t'}^{t_0} U c^\dagger c dt} C^\dagger(t') C(t) \rangle \\ &= -\frac{i}{z} \text{Tr} [e^{-\beta \hat{H}} e^{-i\mu t'} c^\dagger e^{-i \int_0^{t'} U c^\dagger c dt} e^{i\mu t} c] + \frac{i}{z} \text{Tr} [e^{-\beta \hat{H}} e^{-i \int_{t'}^{t_0} U c^\dagger c dt} e^{-i\mu t'} c^\dagger e^{i\mu t} c] \\ &= -\frac{i e^{i\mu(t-t')}}{z} [\langle 0 | c^\dagger e^{-i \int_0^{t'} U c^\dagger c dt} c | 0 \rangle + e^{\beta \mu} \langle 1 | e^\dagger e^{-i \int_0^{t'} U c^\dagger c dt} c | 1 \rangle - e^{\beta \mu - i U(t_0-t')}] \\ &= -\frac{i e^{i\mu(t-t')}}{z} (0 + e^{\beta \mu} (1) - e^{\beta \mu - i U(t_0-t')}) \\ &= -\frac{i e^{\mu(\beta + i(t-t'))}}{z} (1 - e^{-i U(t_0-t')}) \end{aligned}$$