

Deep Learning Issues

Challenges in Deep Learning

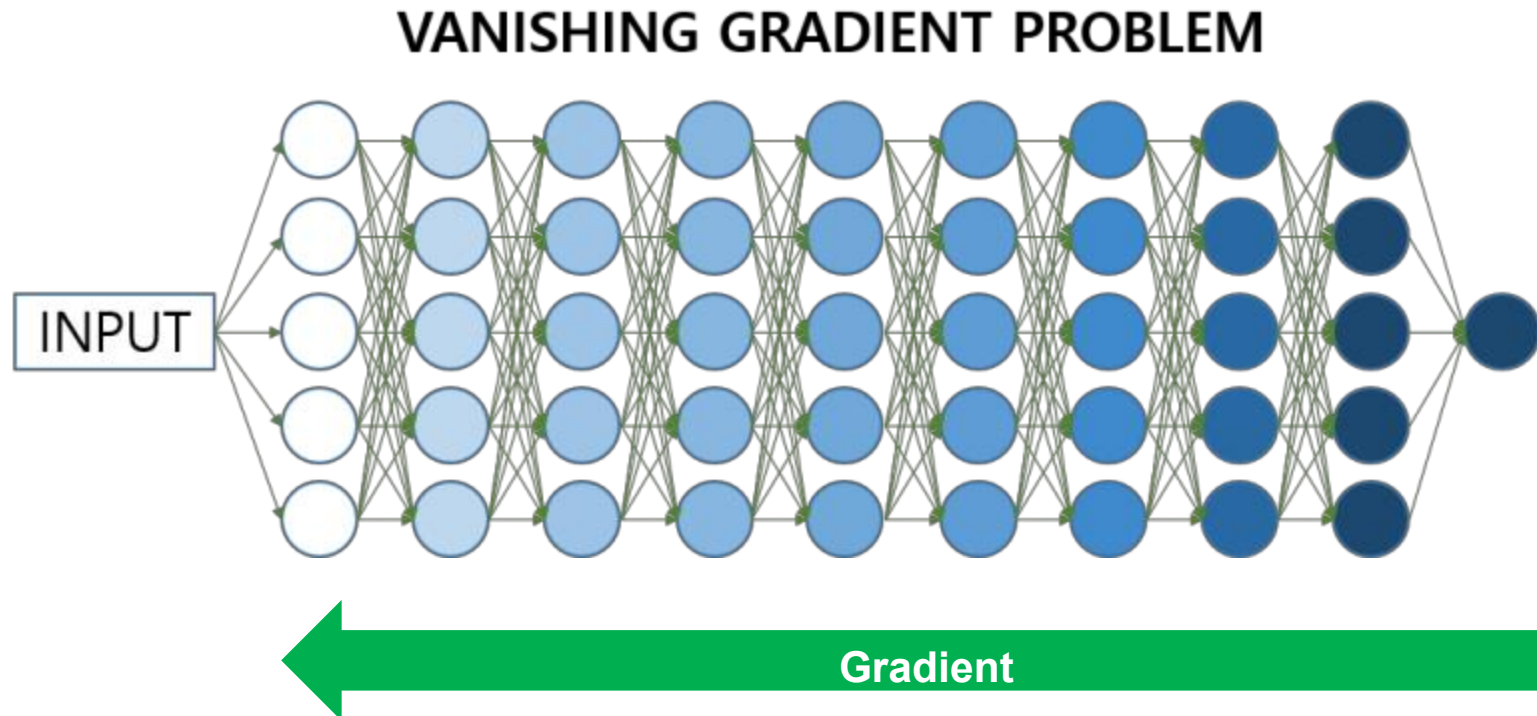


- Difficulties in deep learning
 - Backpropagation algorithm does not work or slow
 - Not better than shallow networks
- Why?
 - **The vanishing/exploding gradient problem**
 - Local minima, saddle points, plateaus
 - Overfitting
 - Internal covariate shift [Ioffe15]
 - Scattered gradient problem [Balduzzi17]
 - Many unknown reasons

Vanishing Gradient Problem

- Conventional back-propagation algorithm does not work well for deep networks.

⇒ Gradient가 0이 되면
아래층에 정보가 잘 안된다.



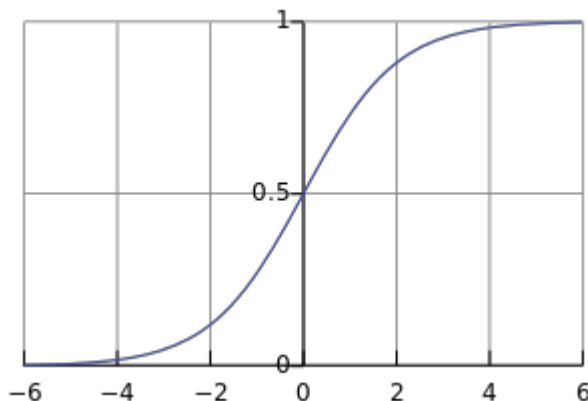
Vanishing Gradient Problem

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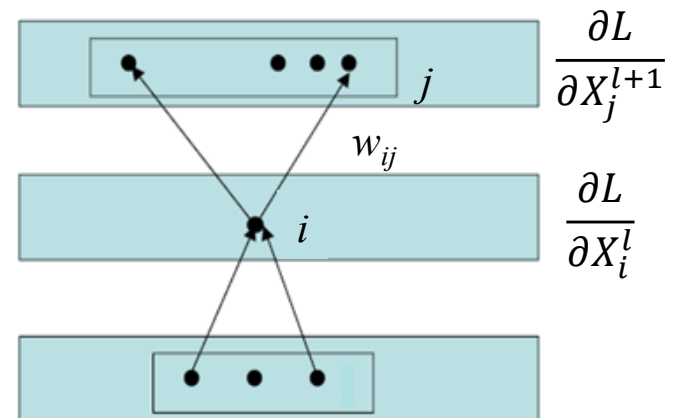
- Backpropagation formula

$$\frac{\partial L}{\partial X_i^l} = \underbrace{\frac{\partial L}{\partial X_i^{l+1}} \frac{\partial X_i^{l+1}}{\partial X_i^l}}_{\text{Chain rule}} = \underbrace{f'(net_j^{l+1}) \sum_j w_{ij}^{l+1} \frac{\partial L}{\partial X_j^{l+1}}}_{\text{Vanishing gradient \& zero}} \quad \left[\text{CME vanishing gradient \& zero} \right]$$

Saturated regime of
Activation functions



Blended gradient



Vanishing/Exploding Gradient on RNN

- One step propagation on RNN

$$h^{(t)} = W^T h^{(t-1)}$$

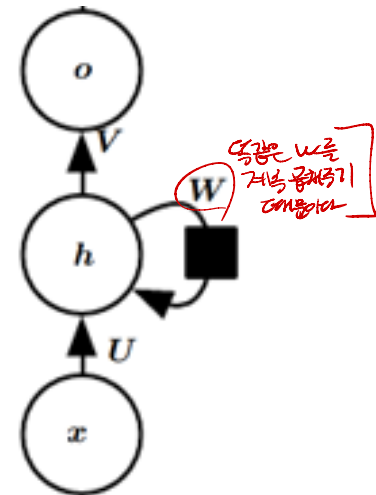
$$h^{(t)} = (W^t)^T h^{(0)}$$

↳ w 가 1이상이면 ∞ , 1미만이면 0으로 수렴

- Eigen decomposition of W

$$W = Q\Lambda Q^T$$

$$h^{(t)} = Q^T \Lambda^t Q h^{(0)}$$



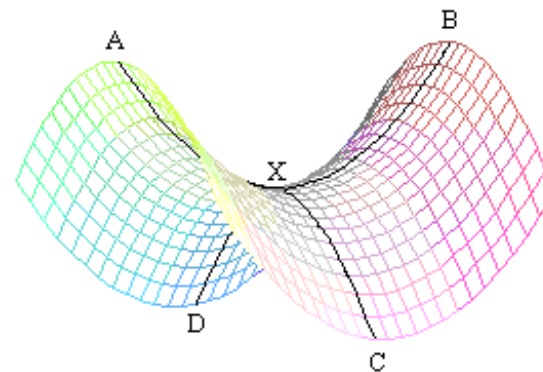
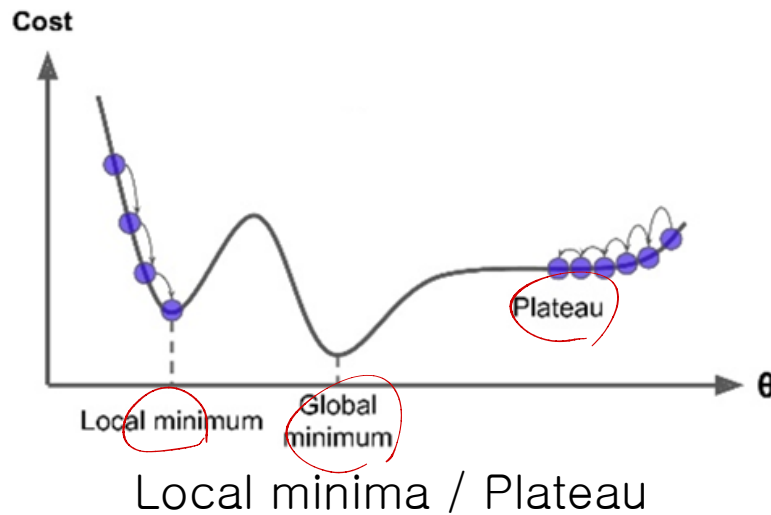
- Gradients propagated over many stages tend to either **vanish** ($|\lambda_i| < 1$) or **explode** ($|\lambda_i| > 1$)

Solutions of Vanishing Gradient Problem

- Layer-wise unsupervised pre-training
 - DBN, stacked auto-encoders
- Architectures to avoid vanishing gradient problem
 - Convolutional neural networks (CNN)
 - Sparse connection, shared weights
 - Gated units (LSTM, GRU, GLU)
- Improved structures and learning algorithms
 - Piece-wise linear activation functions
 - max-out, ReLU, LReLU, PReLU, ELU, etc...
 - Skip connection (ResNet, DenseNet, DPN)
 - input layer과 hidden layer이 연결됨
 - ① 더 빠른 학습
 - ② 더 깊은 layer의 학습
 - Batch normalization
 - Xavier initialization, He initialization, LL-initialization
 - Transfer learning, multi-task learning
 - Auxiliary networks, deeply supervised network

Local Minima, Saddle Point, Plateau

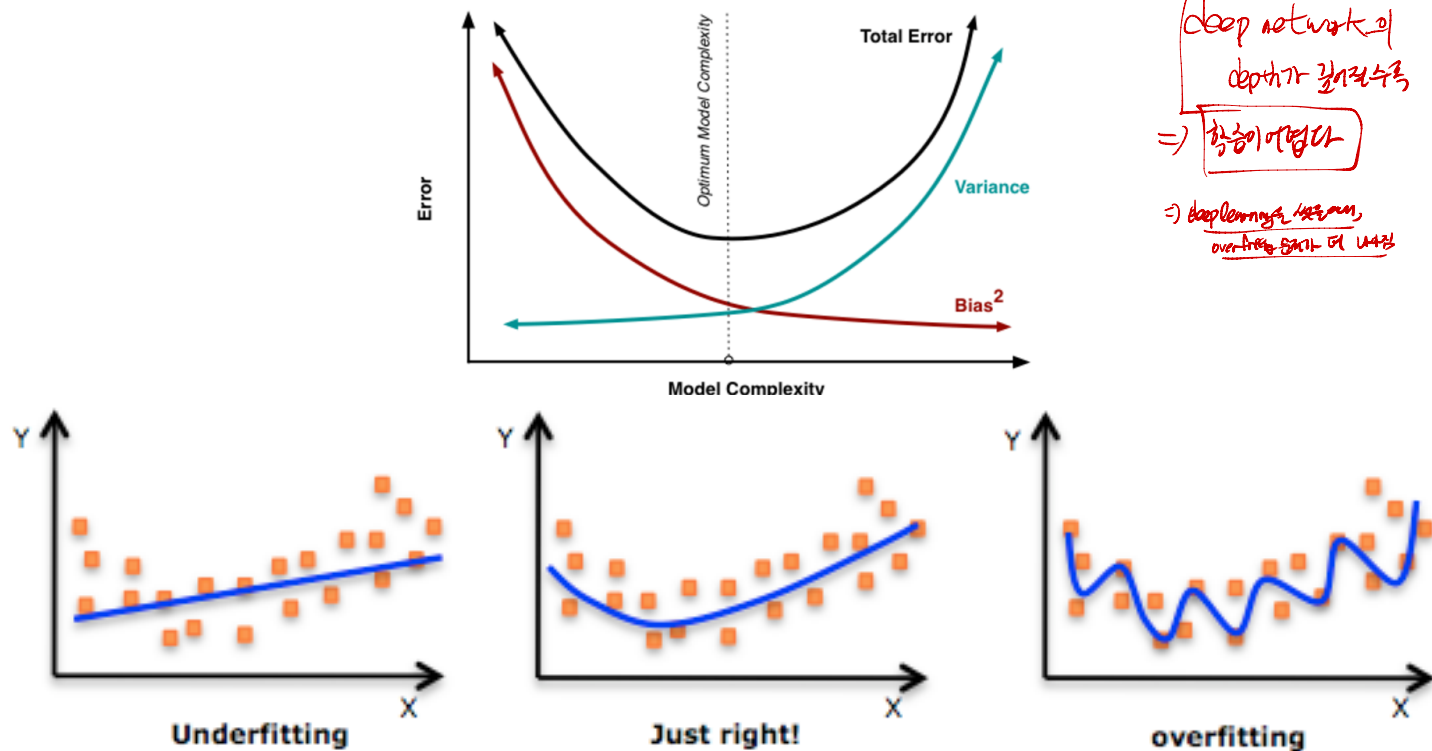
- Learning sometimes stops at local minima, saddle points or plateaus
 - Small networks: local minima is major issues
 - Large networks: plateau or saddle points are major issues



Saddle point

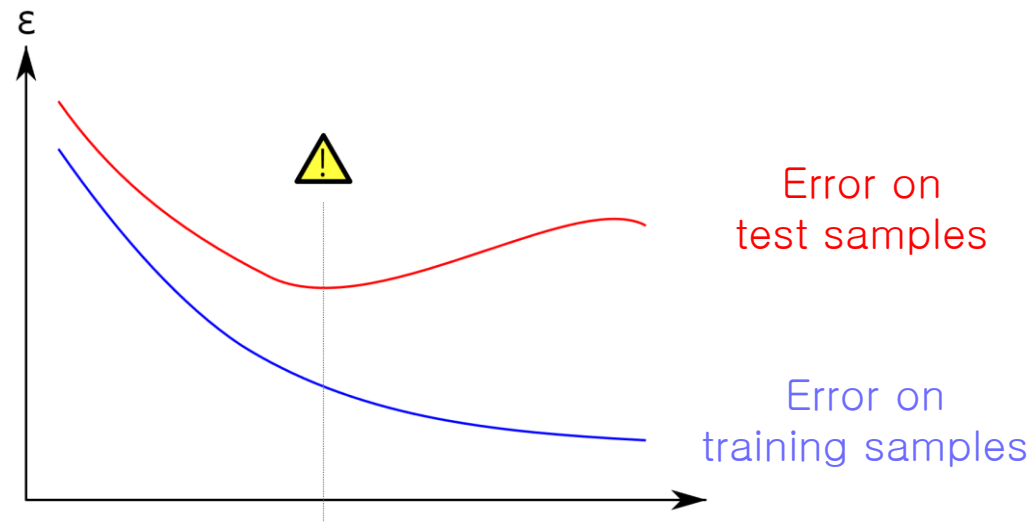
Overfitting

- Overfitting occurs when a model is excessively complex relative to the number of observations.
 - Large capacity model + insufficient data



Overfitting

- Large gap between training and test accuracy



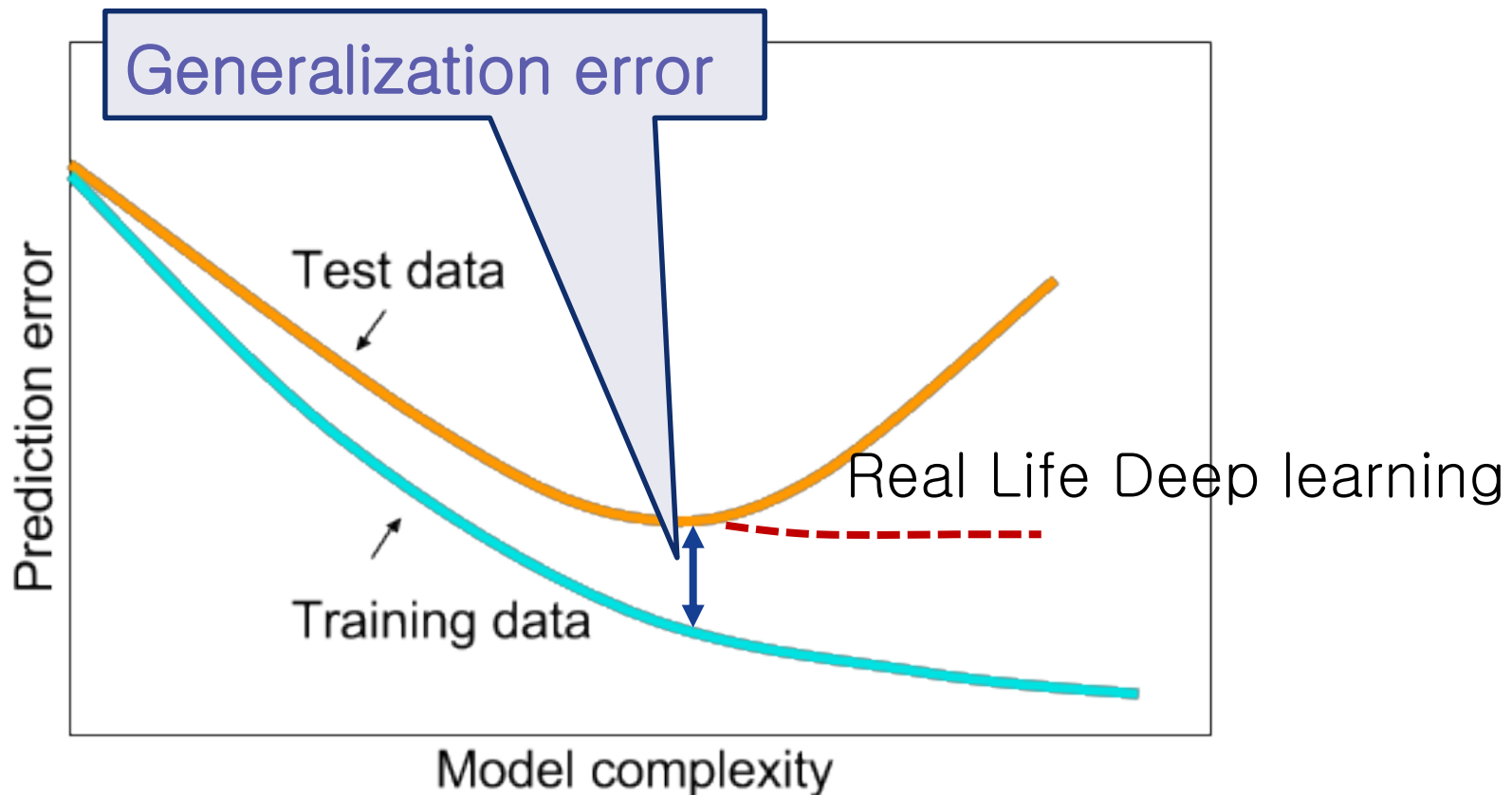
- Remedies
 - More data or simpler model
 - Regularization, transfer learning, batch norm, dropout, etc.

Generalization of Deep Networks

- Traditional knowledge
 - Model with too large capacity does not generalize well
- New observations in deep learning
 - Network depth helps improve generalization
 - Many huge networks generalize well.
 - Train VGG19 (20M parameters) on CIFAR10 (50K samples)
 - ➔ Generalization of deep networks is not explainable with conventional knowledge
- Current trend: powerful model + additional techniques
 - Regularization techniques
 - Data augmentation *by data → 37-Data*
 - Unsupervised pretraining / semi-supervised learning

Overfitting in Deep Learning

- In deep learning, over-parameterization is often successful



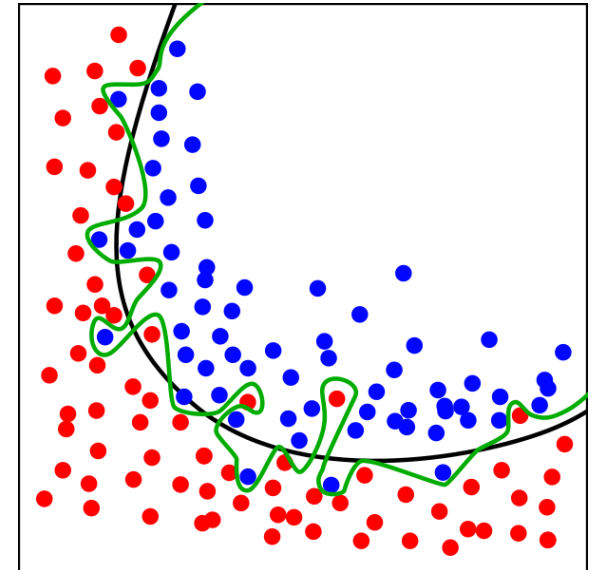
Regularization

- Introduce additional information to solve ill-posed problems or reduce overfitting
- Add regularization term to loss function

$$E(W) + \lambda \|W\|$$

- $E(W)$: main loss function
 - λ : regularization factor
 - $\|W\|$: norm of W
 - L2-norm is more popular
 - L1-norm is used for some models (e.g. sparse autoencoder)
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- Related topics
 - Support vector machines
 - Prior probability

[Wikipedia]





Thank you
for your attention!

